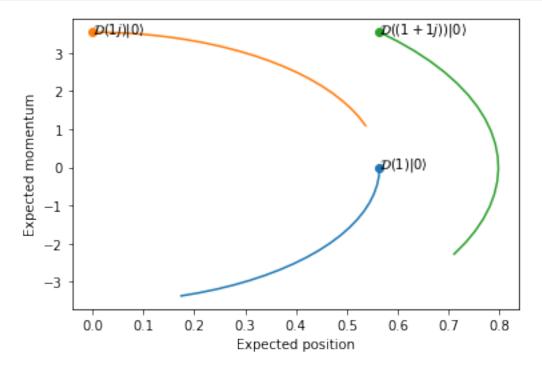
## notebook

## November 3, 2024

```
[3]: import qutip as qt
import matplotlib.pyplot as plt
import numpy as np
```

```
[50]: # Problem 2
      N = 10
      m = 1
      omega = 2 * np.pi
      hbar = 1
      def coherent state(alpha):
          return qt.displace(N, alpha) * qt.basis(N, 0)
      a = qt.destroy(N)
      x = np.sqrt(hbar / 2 / m / omega) * (a + a.dag())
      p = (-1j) * np.sqrt(hbar * m * omega / 2) * (a - a.dag())
      for alpha in [1, 1j, 1+1j]:
          Psi = coherent_state(alpha)
          expected_x = qt.expect(x, Psi)
          expected_p = qt.expect(p, Psi)
          plt.scatter(expected_x, expected_p)
          plt.annotate(f"$\\mathcal {{ D }} ({alpha})| 0 \\rangle$", [expected_x,__
       ⇔expected_p])
      # Don't call plt.show() yet, because we want to see how these states change in_{f L}
       \hookrightarrow time
      def U(t):
          return (-1j * omega * t * (a.dag() * a + qt.qeye(N) / 2.)).expm()
      for alpha in [1, 1j, 1+1j]:
          expected_x = []
          expected_p = []
          for t in np.linspace(0, 0.2, 20):
              Psi = U(t) * coherent_state(alpha)
              expected_x.append(qt.expect(x, Psi))
              expected_p.append(qt.expect(p, Psi))
          plt.plot(expected_x, expected_p)
      plt.xlabel("Expected position")
```

plt.ylabel("Expected momentum")
plt.show()



[]: