

# CSCI 534: Homework 05

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## Problem 1

In Homework 1, we considered a plane-sweep algorithm for determining whether there is any intersection among a collection of  $n$  circles in the plane. Here we consider a variant of this problem. The input consists of a collection of  $n$  closed circular disks, all having the same radius. (Via scaling, we may assume that they are all unit disks.) Let  $C = \{c_1, \dots, c_n\}$  denote the center points of these disks, and let  $\{D_1, \dots, D_n\}$  denote the actual disks. Thus,  $D_i$  consists of the points that lie within unit distance of  $c_i$ . Let  $U = D_1 \cup \dots \cup D_n$  denote the union of these disks. The boundary of  $U$  may generally consist of multiple parts, each of which consists of a cycle of circular arcs connected by vertices. (In Fig. 4 the boundary consists of three cycles. The vertices are shown as white dots).

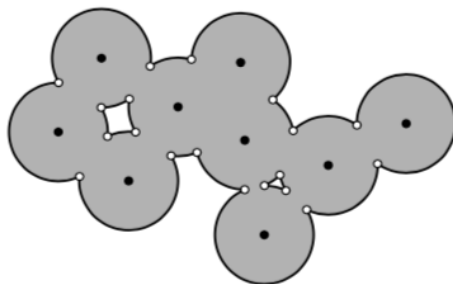


Figure 1: Problem 4: Union of disks

1. Present an algorithm that reports all the vertices on the boundary of  $U$ . (Note that circle intersection points in the interior of the union are explicitly excluded.) Your algorithm should run in time  $O(n \log n)$ . The order in which the vertices are output is arbitrary. (Hint: Don't try to modify the algorithm from Homework 2. A different approach is needed.... think giraffes)
2. Prove that the number of vertices reported by your algorithm is  $O(n)$ .

## Problem 2

Suppose we are given a subdivision of the plane into  $n$  convex regions. We suspect that this subdivision is a Voronoi diagram, but we do not know the sites. Develop an algorithm that finds a set of  $n$  point sites whose Voronoi diagram is exactly the given subdivision, if such a set exists.

**Answer:** So we are given a subdivision of the plane into convex regions and we wish to report a set of  $n$  sites whose Voronoi diagram is the subdivision (if it possible). Let's consider two trivial cases before giving an algorithm. If  $n = 1$ , then any point works and if  $n = 2$  we can just take any point not on the edge of the subdivision and its reflection. From here on out, we will assume  $n > 2$ . For general position, we will assume that no vertex in the subdivision has degree higher than 3.

Label the subdivision  $D$ . Suppose for some face in  $D$ , we have a single point  $p$  that must be the site of the face (if  $D$  is a Voronoi diagram). Assume that the faces of  $D$  are labeled  $1, 2, \dots, n$ . We will prove that we can compute that point  $p$  later in the problem.

Here is a quick prose description of the algorithm. We take  $D$  to be a DCEL,  $p$  is the site we know must exist, and  $k$  is the label for the face that  $p$  belongs to. We are going to start at  $p$  and reflect it across each edge of the face  $k$ . If  $p$  is a site in a voronoi diagram, its reflection across an edge must also be a site. We record every reflected point in an array and add faces to a processing queue as we come across them (note each face can only be added once). If we ever find that a newly reflected point conflicts with a point already found in that face, we know that the subdivision is not a voronoi diagram. We now present the algorithm in pseudocode.

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### Algorithm 1 Computing the Voronoi Sites

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1: function VORONOSITES( $D, p = (p_x, p_y), k$ )
2:    $S \leftarrow [\text{null}, \dots, \text{null}]$  // empty array of size  $n$ 
3:    $S[k] \leftarrow p$ 
4:    $\text{queue} \leftarrow [k]$  // a queue for face labels
5:   while  $\text{queue}$  is not empty do
6:      $i \leftarrow \text{pop the queue}$ 
7:     for every edge  $e$  of face  $i$  do
8:        $j \leftarrow \text{label of the face across } e$ 
9:        $q \leftarrow \text{reflection of the point } S[i] \text{ across } e$ 
10:      if  $S[j] = \text{null}$  then
11:         $S[j] \leftarrow q$ 
12:        add  $j$  to the queue
13:      else if  $S[j] \neq q$ 
14:        return NOT VORONOI
15:      end if
16:    end for
17:  end while
18:  return  $S$ 
19: end function

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Let's discuss run time. As noted in the prose description, each face can only be added to the processing queue once. This is because once a face is in the queue, it's value in  $S$  is no longer null.

Thus the while loop runs  $n$  times: once for each face. As a gross upper bound for the for loop, it can run at most  $E$  times where  $E$  is the number of edges in the DCEL. Since a DCEL represents a planar graph,  $E = O(n)$  so our algorithm runs in  $N * O(n) = O(n^2)$  time.

And now for correctness!

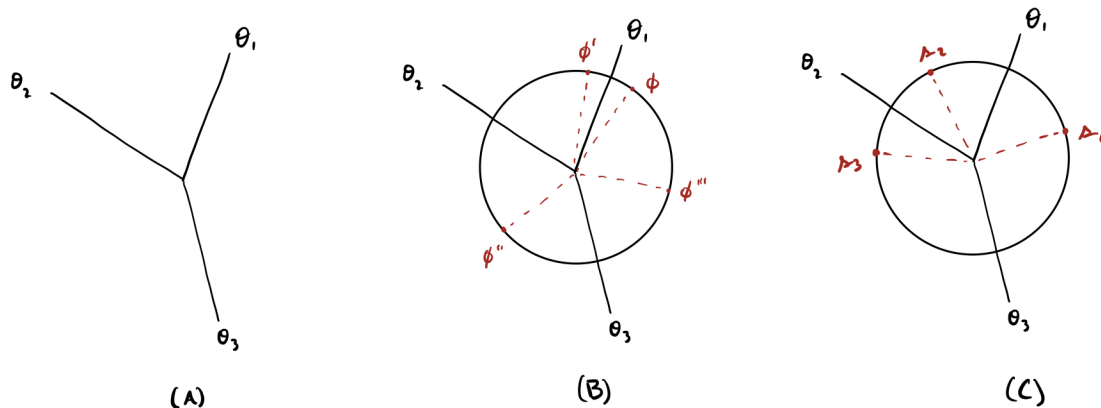


Figure 2: Solving for  $\phi$

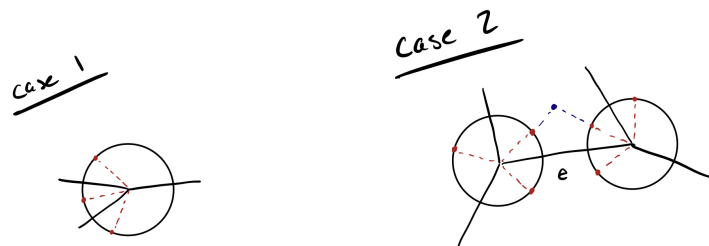


Figure 3: Computing the site