```
In [1]: | import numpy as np
        import math as m
        import matplotlib.pyplot as plt
        %matplotlib inline
        from mpl_toolkits.mplot3d import Axes3D
In [2]: def plotter(x,y,z):
            fig = plt.figure()
            ax = fig.add_subplot(111, projection='3d')
            ax.scatter(x,y,z,s=5)
            ax.set_xlabel('AU x-axis')
            ax.set_ylabel('AU y-axis')
            ax.set_zlabel('AU z-axis')
            plt.tight_layout()
In [3]: def gravforcex(planet1, planet2):
            x1 = planet1.x
            y1 = planet1.y
            z1 = planet1.z
            x2 = planet2.x
            y2 = planet2.y
            z2 = planet2.z
            rsep = ((x1-x2)**2+(y1-y2)**2+(z1-z2)**2)**(0.5)
            return -4*m.pi**2*(x1-x2)*planet2.mass/(rsep)**3
        def gravforcey(planet1, planet2):
            x1 = planet1.x
            y1 = planet1.y
            z1 = planet1.z
            x2 = planet2.x
            y2 = planet2.y
            z2 = planet2.z
            rsep = ((x1-x2)**2+(y1-y2)**2+(z1-z2)**2)**(0.5)
            return -4*m.pi**2*(y1-y2)*planet2.mass/(rsep)**3
        def gravforcez(planet1, planet2):
            x1 = planet1.x
            y1 = planet1.y
            z1 = planet1.z
            x2 = planet2.x
            y2 = planet2.y
```

rsep = ((x1-x2)**2+(y1-y2)**2+(z1-z2)**2)**(0.5)return -4*m.pi**2*(x1-x2)*planet2.mass/(rsep)**3

z2 = planet2.z

In [4]: class makeplanet: def __init__(self, name,mass,x,y,z,vx,vy,vz): self.name = name self.x = xself.y = yself.z = zself.vx = 365*vxself.vy = 365*vyself.vz = 365*vzself.mass = massdef accx(self,x,y,z): r = ((x)**2+(y)**2+(z)**2)**(0.5)accx = -4*m.pi**2*x/(r**3)return accx def accy(self,x,y,z): r = ((x)**2+(y)**2+(z)**2)**(0.5)accy = -4*m.pi**2*y/(r**3)return accy def accz(self,x,y,z): r = ((x)**2+(y)**2+(z)**2)**(0.5)accz = -4*m.pi**2*z/(r**3)return accz def movex(self,xnew): self.x=xnew def movey(self, ynew): self.y=ynew def movez(self,znew): self.z=znew def movevx(self,vxnew): self.vx=vxnew def movevy(self, vynew): self.vy=vynew def movevz(self,vznew): self.vz=vznew

```
In [5]: test = makeplanet("Test", 1, 1,1,1,1,1)
         mercury = makeplanet("Mercury", 1.65E-07, 2.80E-01, 1.73E-01, -1.18E-02, -2.0
         1E-02, 2.53E-02, 3.91E-03)
         venus = makeplanet("Venus", 2.45E-06, -7.02E-01, 1.36E-01, 4.24E-02, -3.
         81E-03, -1.99E-02, -5.40E-05)
         earth = makeplanet("Earth", 3.0E-06, -9.88E-01, 8.50E-02, -1.52E-04, -1.
         68E-03, -1.71E-02, 4.35E-07)
         mars = makeplanet("Mars", 3.3E-07, 7.78E-01, 1.28, 7.56E-03, -1.14E-02,
         8.47E-03, 4.58E-04)
         jupiter = makeplanet("Jupiter", 0.00095, -5.23, -1.53, 1.23E-01,2.02E-3,
          -6.88E-03, -1.67E-05)
         saturn = makeplanet("Saturn", 0.000275, -1.48,-9.93, 2.32E-01, 5.212E-
         03, -8.39E-04, -1.93E-04
         uranus = makeplanet("Uranus", 0.000044, 1.82E01, 8.08, -2.06E-01, -1.62E
         -03, 3.41E-03, 3.38E-05)
         neptune = makeplanet("Neptune", 0.0000515, 2.84E01, -9.47, -4.60E-01,9.7
         11E-04, 2.997E-03, -8.38E-05)
         pluto = makeplanet("Pluto", 6.55E-09, 9.89, -3.18E01, 5.396E-01, 3.06E-0
         3, 2.906E-04, -9.09E-04
 In [6]: print(test.x)
         print(test.accx(test.x,test.y, test.z))
         -7.5976250103520755
 In [7]: | #Functionality is working for changing the x coordinate
         test.movex(2)
         test.x
Out[7]: 2
 In [8]: test.accx(test.x,test.y, test.z)
Out[8]: -5.372332165732466
 In [9]: test.accy(test.x,test.y, test.z)
Out[9]: -2.686166082866233
In [10]: test.accz(test.x,test.y, test.z)
Out[10]: -2.686166082866233
In [11]: test.movez(3)
         test.accz(test.x,test.y, test.z)
Out[11]: -2.260939482359547
```

```
In [12]: def buildaccx(planet, list of planets):
             accel x = planet.accx(planet.x, planet.y, planet.z)
             for i in list_of_planets:
                 if i.name!=planet.name:
                      #print(i.name)
                      accel x += gravforcex(planet, i)
             return accel_x
         def buildaccy(planet, list_of_planets):
             accel_y = planet.accy(planet.x, planet.y, planet.z)
             for i in list of planets:
                  if i.name!=planet.name:
                      accel_y += gravforcey(planet, i)
             return accel_y
         def buildaccz(planet, list_of_planets):
             accel z = planet.accz(planet.x, planet.y, planet.z)
             for i in list of planets:
                 if i.name!=planet.name:
                      accel z += gravforcez(planet, i)
             return accel z
In [13]: earth.x
Out[13]: -0.988
In [14]: | earth.accx(earth.x, earth.y, earth.z)
Out[14]: 39.99833339111919
In [15]: planets = [mercury, venus, earth, mars, jupiter, saturn, uranus,
         neptune, pluto]
In [16]: #Just testing a function to make sure that the x acceleration makes sens
         buildaccx(earth, planets)
Out[16]: 39.99773374665994
In [17]: | buildaccy(earth,planets)
Out[17]: -3.4417092456222957
```

```
In [18]: def coorx(xi, h,vxi, axi):
    return xi + h*vxi+h**2*axi/2

def velx(vxi, h, ax_i_1,ax_i):
    return vxi + (h/2)*(ax_i_1+ax_i)

def coory(yi, h,vyi, ayi):
    return yi + h*vyi+h**2*ayi/2

def vely(vyi, h, ay_i_1,ay_i):
    return vyi + (h/2)*(ay_i_1+ay_i)

def coorz(zi, h,vzi, azi):
    return zi + h*vzi+h**2*azi/2

def velz(vzi, h, az_i_1,az_i):
    return vzi + (h/2)*(az_i_1+az_i)
```

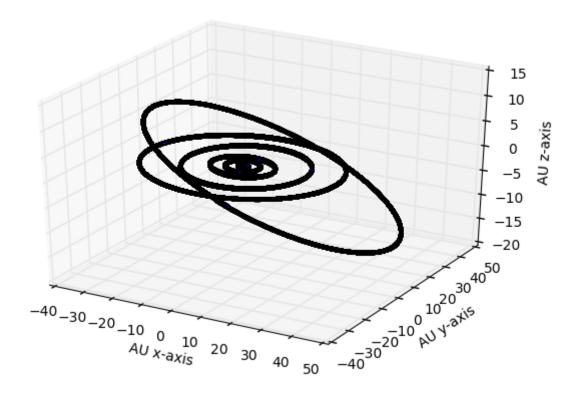
```
In [19]: planets = [mercury, venus, earth, mars, jupiter, saturn, uranus,
         neptune, pluto]
         def solar_system(time):
             #The number of years we want to loop over, 10 years for this test
             h = 1/365 #The step size, defined as one day
             n = int(time/h) #The total numbers of iterations
             all_x = []
             all_y = []
             all_z = []
             for obj in planets:
                 coordinatesx = np.zeros(n+1)
                 coordinatesy = np.zeros(n+1)
                 coordinatesz = np.zeros(n+1)
                 velocitiesx = np.zeros(n+1)
                 velocitiesy = np.zeros(n+1)
                 velocitiesz = np.zeros(n+1)
                 coordinatesx[0] = obj.x
                 coordinatesy[0] = obj.y
                 coordinatesz[0] = obj.z
                 velocitiesx[0] = obj.vx
                 velocitiesy[0] = obj.vy
                 velocitiesz[0] = obj.vz
                 for j in range(n):
                      x_j = coordinatesx[j]
                     vx_j = velocitiesx[j]
                     y_j = coordinatesy[j]
                     vy j = velocitiesy[j]
                      z j = coordinatesz[j]
                     vz_j = velocitiesz[j]
                      ax_j = buildaccx(obj, planets)
                      ay_j = buildaccy(obj, planets)
```

```
az_j = buildaccz(obj, planets)
        x_j_1 = coorx(x_j, h, vx_j, ax_j)
        y_j_1 = coory(y_j, h, vy_j, ay_j)
        z_{j_1} = coorz(z_j, h, vz_j, az_j)
        coordinatesx[j+1] = x_j_1
        coordinatesy[j+1] = y_j_1
        coordinatesz[j+1] = z_j 1
        obj.movex(x_j_1)
        obj.movey(y_j_1)
        obj.movez(z_j_1)
        ax_j_1 = buildaccx(obj, planets)
        ay_j_1 = buildaccy(obj, planets)
        az_j_1 = buildaccz(obj, planets)
        vx_j_1 = velx(vx_j,h,ax_j_1,ax_j)
        vy_j_1 = vely(vy_j,h,ay_j_1,ay_j)
        vz_j_1 = velz(vz_j,h,az_j_1,az_j)
        velocitiesy[j+1] = vy_j_1
        velocitiesx[j+1] = vx_j_1
        velocitiesz[j+1] = vz_j_1
        obj.movevx(vx_j_1)
        obj.movevy(vy_j_1)
        obj.movevz(vz_j_1)
    all_x.append(coordinatesx)
    all_y.append(coordinatesy)
    all_z.append(coordinatesz)
    print(obj.name, "is done!")
plotter(all_x, all_y, all_z)
```

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In [20]: solar_system(250)

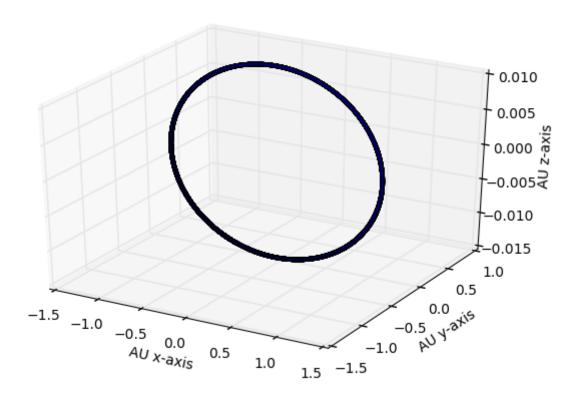
Mercury is done! Venus is done! Earth is done! Mars is done! Jupiter is done! Saturn is done! Uranus is done! Neptune is done! Pluto is done!

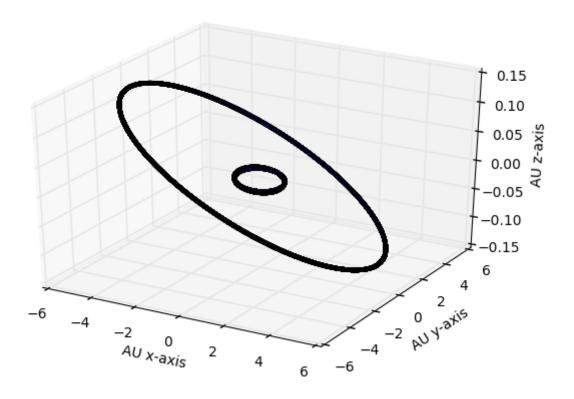


When we start to look at interactions with other planets, then things get a little bit hairy. What we do know is that the alogirthm works, and we know that the effects of Mercury may be altering the orbits of the inner planets.

```
In [21]: planets = [earth]
    solar_system(100)
    planets = [earth, jupiter]
    solar_system(100)
```

Earth is done!
Earth is done!
Jupiter is done!

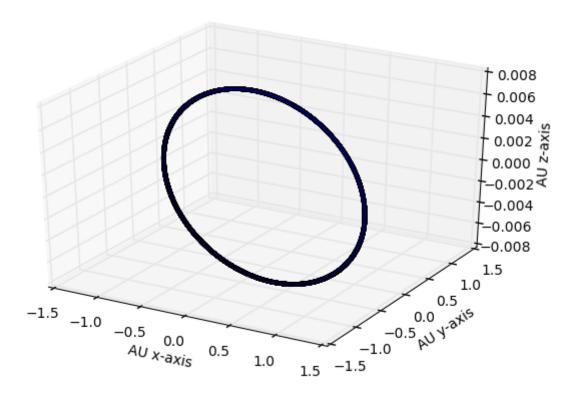


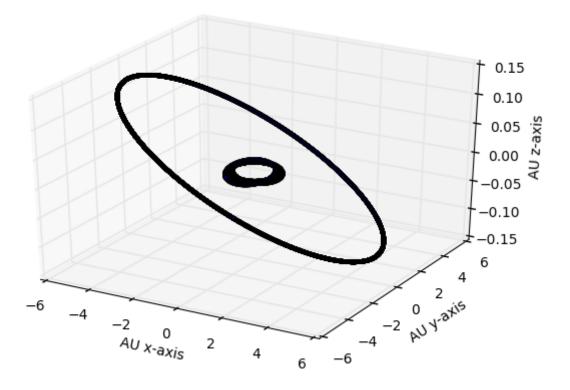


We can see that over the course of a century, there can be some efects on the orbit of Earth. It appears as though Jupiter is pulling the Earth towards it over the course of time. Now I want to rescale the mass of Jupiter.

```
In [22]: jupiter.mass = 0.0095
    planets = [earth]
    solar_system(100)
    planets = [earth, jupiter]
    solar_system(100)
```

Earth is done!
Earth is done!
Jupiter is done!

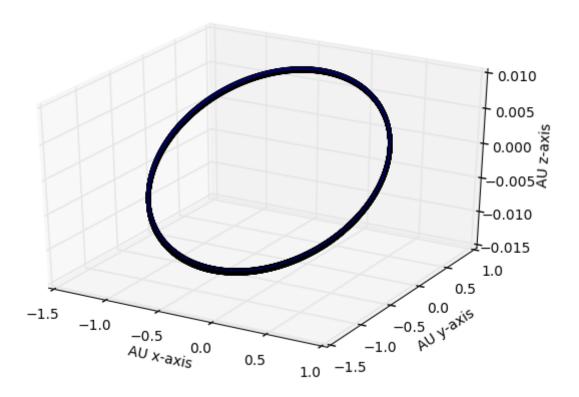


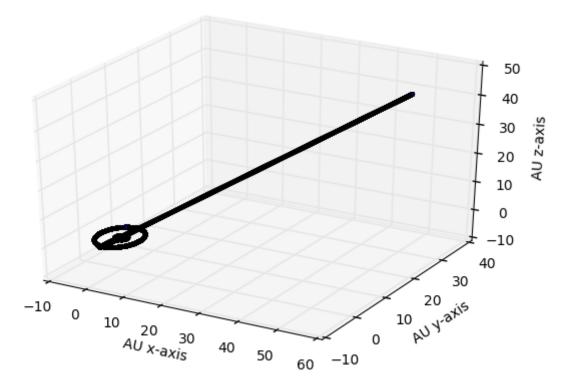


The verlet method is unstable, and we are quickly approaching that threshold. Also, we can see that with just the three body system, there is a significant contribution from Jupiter on Earth's orbit. Since Jupiter is so massive, we hardly notice any difference in its trajectory.

```
In [23]: jupiter.mass = 0.095
    planets = [earth]
    solar_system(100)
    planets = [earth, jupiter]
    solar_system(100)
```

Earth is done!
Earth is done!
Jupiter is done!





The above plot is the one that we were looking for. If we look at the mass of Jupiter scaled to be 1000 times it's original mass, then the Verlate algorithm breaks down and we lose stability. Here, we see the Earth sprial out of the galaxy. This tells us that there is some limitation to the stability of the verlet solver.

```
mercury = makeplanet("Mercury", 1.65E-07, 2.80E-01, 1.73E-01, -1.18E-02, -2.0
In [27]:
         1E-02,2.53E-02,3.91E-03)
         venus = makeplanet("Venus", 2.45E-06, -7.02E-01, 1.36E-01, 4.24E-02, -3.
         81E-03, -1.99E-02, -5.40E-05)
         earth = makeplanet("Earth", 3.0E-06, -9.88E-01, 8.50E-02, -1.52E-04, -1.
         68E-03, -1.71E-02, 4.35E-07)
         mars = makeplanet("Mars", 3.3E-07, 7.78E-01, 1.28, 7.56E-03, -1.14E-02,
         8.47E-03, 4.58E-04)
         jupiter = makeplanet("Jupiter", 0.00095, -5.23, -1.53, 1.23E-01,2.02E-3,
          -6.88E-03, -1.67E-05)
         saturn = makeplanet("Saturn", 0.000275, -1.48,-9.93, 2.32E-01, 5.212E-
         03, -8.39E-04, -1.93E-04
         uranus = makeplanet("Uranus", 0.000044, 1.82E01, 8.08, -2.06E-01, -1.62E
         -03, 3.41E-03, 3.38E-05)
         neptune = makeplanet("Neptune", 0.0000515, 2.84E01, -9.47, -4.60E-01,9.7
         11E-04, 2.997E-03, -8.38E-05)
         pluto = makeplanet("Pluto", 6.55E-09, 9.89, -3.18E01, 5.396E-01, 3.06E-0
         3, 2.906E-04, -9.09E-04)
```

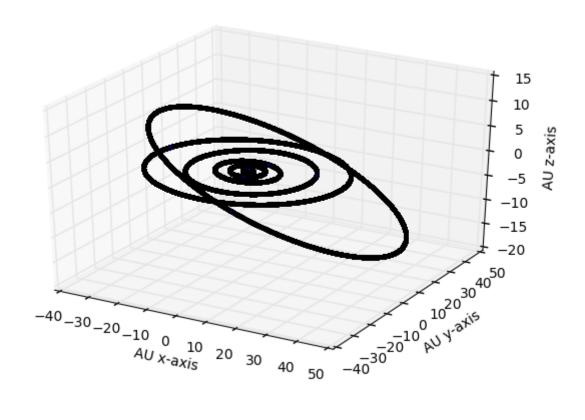
```
In [28]: def solar system no interaction(time):
             #The number of years we want to loop over, 10 years for this test
             h = 1/365 #The step size, defined as one day
             n = int(time/h) #The total numbers of iterations
             all_x = []
             all_y = []
             all z = []
             for obj in planets:
                 coordinatesx = np.zeros(n+1)
                 coordinatesy = np.zeros(n+1)
                 coordinatesz = np.zeros(n+1)
                 velocitiesx = np.zeros(n+1)
                 velocitiesy = np.zeros(n+1)
                 velocitiesz = np.zeros(n+1)
                 coordinatesx[0] = obj.x
                 coordinatesy[0] = obj.y
                 coordinatesz[0] = obj.z
                 velocitiesx[0] = obj.vx
                 velocitiesy[0] = obj.vy
                 velocitiesz[0] = obj.vz
                 for j in range(n):
                     x j = coordinatesx[j]
                     vx_j = velocitiesx[j]
                     y_j = coordinatesy[j]
                     vy j = velocitiesy[j]
```

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```
z_j = coordinatesz[j]
        vz_j = velocitiesz[j]
        ax_j = obj.accx(x_j,y_j,z_j)
        ay_j = obj.accy(x_j,y_j,z_j)
        az_j = obj.accz(x_j,y_j,z_j)
        x_j_1 = coorx(x_j, h, vx_j, ax_j)
        y_j_1 = coory(y_j, h, vy_j, ay_j)
        z_{j_1} = coorz(z_j, h, vz_j, az_j)
        coordinatesx[j+1] = x_j_1
        coordinatesy[j+1] = y_j_1
        coordinatesz[j+1] = z_j_1
        \#obj.movex(x j 1)
        #obj.movey(y j 1)
        \#obj.movez(z_j_1)
        ax j_1 = obj.accx(x_j_1,y_j_1,z_j_1)
        ay_j_1 = obj.accy(x_j_1,y_j_1,z_j_1)
        az j 1 = obj.accz(x j 1, y j 1, z j 1)
        vx_j_1 = velx(vx_j,h,ax_j_1,ax_j)
        vy_j_1 = vely(vy_j,h,ay_j_1,ay_j)
        vz_j_1 = velz(vz_j,h,az_j_1,az_j)
        velocitiesy[j+1] = vy_j_1
        velocitiesx[j+1] = vx_j_1
        velocitiesz[j+1] = vz_j_1
        #obj.movevx(vx j 1)
        #obj.movevy(vy j 1)
        #obj.movevz(vz j 1)
    all_x.append(coordinatesx)
    all_y.append(coordinatesy)
    all_z.append(coordinatesz)
    print(obj.name, "is done!")
plotter(all_x, all_y, all_z)
```

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Mercury is done!
Venus is done!
Earth is done!
Mars is done!
Jupiter is done!
Saturn is done!
Uranus is done!
Neptune is done!
Pluto is done!



We can see that the program handles both the interacting case and non interacting case wonderfully.

I'm calling it good with this one.

JK I'm still not happy with something. I'm updating 1 planet at a time and I don't think that's correct.

```
In [30]: mercury = makeplanet("Mercury",1.65E-07,2.80E-01,1.73E-01,-1.18E-02,-2.0
1E-02,2.53E-02,3.91E-03)
    venus = makeplanet("Venus", 2.45E-06, -7.02E-01, 1.36E-01, 4.24E-02, -3.
81E-03, -1.99E-02, -5.40E-05)
    earth = makeplanet("Earth", 3.0E-06, -9.88E-01, 8.50E-02, -1.52E-04, -1.
68E-03, -1.71E-02, 4.35E-07)
    mars = makeplanet("Mars", 3.3E-07, 7.78E-01, 1.28, 7.56E-03, -1.14E-02,
8.47E-03, 4.58E-04)
    jupiter = makeplanet("Jupiter", 0.00095, -5.23, -1.53, 1.23E-01,2.02E-3,
-6.88E-03, -1.67E-05)
```

```
saturn = makeplanet("Saturn", 0.000275, -1.48,-9.93, 2.32E-01, 5.212E-
03, -8.39E-04, -1.93E-04
uranus = makeplanet("Uranus", 0.000044, 1.82E01, 8.08, -2.06E-01, -1.62E
-03, 3.41E-03, 3.38E-05)
neptune = makeplanet("Neptune", 0.0000515, 2.84E01, -9.47, -4.60E-01,9.7
11E-04, 2.997E-03, -8.38E-05)
pluto = makeplanet("Pluto", 6.55E-09, 9.89, -3.18E01, 5.396E-01, 3.06E-0
3, 2.906E-04, -9.09E-04
planets = [mercury, venus, earth, mars, jupiter, saturn, uranus, neptune,
plutol
def solar_system_retry(time):
    h = 1/365 #The step size, defined as one day
    n = int(time/h) #The total numbers of iterations
    all x = []
    all y = []
    all z = []
    for obj in planets:
        all x.append(obj.x)
        all y.append(obj.y)
        all_z.append(obj.z)
    for j in range(n):
        for obj in planets:
            x j = obj.x
            vx_j = obj.vx
            y_j = obj.y
            vy_j = obj.vy
            z_j = obj.z
            vz j = obj.vz
            ax_j = buildaccx(obj, planets)
            ay_j = buildaccy(obj, planets)
            az_j = buildaccz(obj, planets)
            x_j_1 = coorx(x_j, h, vx_j, ax_j)
            y_j = coory(y_j, h,vy_j,ay_j)
            z_{j_1} = coorz(z_j, h, vz_j, az_j)
            all x.append(x j 1)
            all_y.append(y_j_1)
            all_z.append(z_j_1)
            \#coordinatesx[j+1] = x j 1
            \#coordinatesy[j+1] = y_j_1
            \#coordinatesz[j+1] = z_j_1
            obj.movex(x j 1)
            obj.movey(y j 1)
            obj.movez(z j 1)
            ax_j_1 = buildaccx(obj, planets)
            ay_j_1 = buildaccy(obj, planets)
```

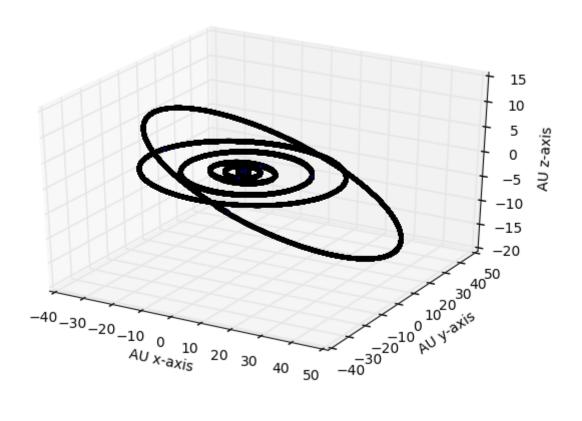
```
az_j_1 = buildaccz(obj, planets)

vx_j_1 = velx(vx_j,h,ax_j_1,ax_j)
vy_j_1 = vely(vy_j,h,ay_j_1,ay_j)
vz_j_1 = velz(vz_j,h,az_j_1,az_j)

#velocitiesy[j+1] = vy_j_1
#velocitiesx[j+1] = vx_j_1
#velocitiesz[j+1] = vz_j_1

obj.movevx(vx_j_1)
obj.movevy(vy_j_1)
obj.movevz(vz_j_1)

#print(obj.name, "is done!")
plotter(all_x, all_y, all_z)
solar_system_retry(250)
```



I fixed it.

In []: