```
In [1]: import numpy as np
        import math as m
        import matplotlib.pyplot as plt
        %matplotlib inline
        from mpl toolkits.mplot3d import Axes3D
In [2]: def plotter(x,y,z):
            fig = plt.figure()
            ax = fig.add subplot(111, projection='3d')
            ax.scatter(x,y,z,s=5)
            ax.set_xlabel('AU x-axis')
            ax.set_ylabel('AU y-axis')
            ax.set zlabel('Au z-axis')
In [3]: def gravforcex(planet1, planet2):
            x1 = planet1.x
            y1 = planet1.y
            z1 = planet1.z
            x2 = planet2.x
            y2 = planet2.y
            z2 = planet2.z
            rsep = ((x1-x2)**2+(y1-y2)**2+(z1-z2)**2)**(0.5)
            return -4*m.pi**2*(x1-x2)*planet2.mass/(rsep)**3
        def gravforcey(planet1, planet2):
            x1 = planet1.x
            y1 = planet1.y
            z1 = planet1.z
            x2 = planet2.x
            y2 = planet2.y
            z2 = planet2.z
            rsep = ((x1-x2)**2+(y1-y2)**2+(z1-z2)**2)**(0.5)
            return -4*m.pi**2*(y1-y2)*planet2.mass/(rsep)**3
        def gravforcez(planet1, planet2):
```

rsep = ((x1-x2)\*\*2+(z1-z2)\*\*2+(z1-z2)\*\*2)\*\*(0.5)return -4\*m.pi\*\*2\*(x1-x2)\*planet2.mass/(rsep)\*\*3

x1 = planet1.x
y1 = planet1.y
z1 = planet1.z
x2 = planet2.x
y2 = planet2.y
z2 = planet2.z

## In [28]: class makeplanet: def \_\_init\_\_(self, name,mass,x,y,z,vx,vy,vz): self.name = name self.x = xself.y = yself.z = zself.vx = 365\*vxself.vy = 365\*vyself.vz = 365\*vzself.mass = massdef accx(self,x,y,z): r = ((x)\*\*2+(y)\*\*2+(z)\*\*2)\*\*(0.5)accx = -4\*m.pi\*\*2\*x/(r\*\*3)return accx def accy(self,x,y,z): r = ((x)\*\*2+(y)\*\*2+(z)\*\*2)\*\*(0.5)accy = -4\*m.pi\*\*2\*y/(r\*\*3)return accy def accz(self,x,y,z): r = ((x)\*\*2+(y)\*\*2+(z)\*\*2)\*\*(0.5)accz = -4\*m.pi\*\*2\*z/(r\*\*3)return accz def movex(self,xnew): self.x=xnew def movey(self, ynew): self.y=ynew def movez(self,znew): self.z=znew def movevx(self,vxnew): self.vx=vxnew def movevy(self,vynew): self.vy=vynew def movevz(self,vznew): self.vz=vznew

```
In [29]: test = makeplanet("Test", 1, 1,1,1,1,1,1)
         mercury = makeplanet("Mercury", 1.65E-07, 2.80E-01, 1.73E-01, -1.18E-02, -2.0
         1E-02, 2.53E-02, 3.91E-03)
         venus = makeplanet("Venus", 2.45E-06, -7.02E-01, 1.36E-01, 4.24E-02, -3.
         81E-03, -1.99E-02, -5.40E-05)
         earth = makeplanet("Earth", 3.0E-06, -9.88E-01, 8.50E-02, -1.52E-04, -1.
         68E-03, -1.71E-02, 4.35E-07)
         mars = makeplanet("Mars", 3.3E-07, 7.78E-01, 1.28, 7.56E-03, -1.14E-02,
         8.47E-03, 4.58E-04)
         jupiter = makeplanet('Jupiter', 0.00095, -5.23, -1.53, 1.23E-01,2.02E-3,
          -6.88E-03, -1.67E-05)
         saturn = makeplanet("Saturn", 0.000275, -1.48,-9.93, 2.32E-01, 5.212E-
         03, -8.39E-04, -1.93E-04
         uranus = makeplanet("Uranus", 0.000044, 1.82E01, 8.08, -2.06E-01, -1.62E
         -03, 3.41E-03, 3.38E-05)
         neptune = makeplanet("Neptune", 0.0000515, 2.84E01, -9.47, -4.60E-01,9.7
         11E-04, 2.997E-03, -8.38E-05)
         pluto = makeplanet("Pluto", 6.55E-09, 9.89, -3.18E01, 5.396E-01, 3.06E-0
         3, 2.906E-04, -9.09E-04
```

```
In [30]: print(test.x)
  print(test.accx(test.x,test.y,test.z))
```

-7.5976250103520755

In [31]: #Functionality is working for changing the x coordinate
 test.movex(2)
 test.x

Out[31]: 2

In [32]: test.accx(test.x,test.y,test.z)

Out[32]: -5.372332165732466

```
In [43]: def buildaccx(planet, list_of_planets):
             accel x = planet.accx(planet.x, planet.y, planet.z)
             for i in list_of_planets:
                 if i.name!=planet.name:
                      #print(i.name)
                      accel x += gravforcex(planet, i)
             return accel_x
         def buildaccy(planet, list_of_planets):
             accel_y = planet.accy(planet.x, planet.y, planet.z)
             for i in list_of_planets:
                 if i.name!=planet.name:
                      accel_y += gravforcey(planet, i)
             return accel y
         def buildaccz(planet, list_of_planets):
             accel z = planet.accz(planet.x, planet.y, planet.z)
             for i in list of planets:
                 if i.name!=planet.name:
                      accel z += gravforcez(planet, i)
             return accel z
In [44]: earth.x
Out[44]: -0.988
In [45]: earth.accx(earth.x, earth.y, earth.z)
Out[45]: 39.99833339111919
In [46]: #Just testing a function to make sure that the x acceleration makes sens
         buildaccx(earth, planets)
Out[46]: 39.99663403025657
In [47]: buildaccy(earth,planets)
Out[47]: -3.4417991391787393
```

In [48]: def coorx(xi, h,vxi, axi):

```
return xi + h*vxi+h**2*axi/2
        def velx(vxi, h, ax_i_1,ax_i):
            return vxi + (h/2)*(ax_i_1+ax_i)
        def coory(yi, h,vyi, ayi):
            return yi + h*vyi+h**2*ayi/2
        def vely(vyi, h, ay_i_1,ay_i):
            return vyi + (h/2)*(ay_i_1+ay_i)
        def coorz(zi, h,vzi, azi):
            return zi + h*vzi+h**2*azi/2
        def velz(vzi, h, az_i_1,az_i):
            return vzi + (h/2)*(az_i_1+az_i)
In [16]: def makearrays(n):
            coor_x = np.zeros(n+1)
            coor_y = np.zeros(n+1)
            coor_z = np.zeros(n+1)
            vel x = np.zeros(n+1)
            vel_y = np.zeros(n+1)
            vel_z = np.zeros(n+1)
            return coor_x, coor_y, coor_z, vel_x, vel_y, vel_z
In [17]: x = makearrays(10)[0]
Out[17]: array([ 0., 0., 0., 0., 0., 0., 0., 0., 0., 0.])
In [18]: x[0]=1
```

I now have the array functionalit that I will need to store my data.

```
coordinatesz = makearrays(n)[2]
velocitiesx = makearrays(n)[3]
velocitiesy = makearrays(n)[4]
velocitiesz = makearrays(n)[5]
coordinatesx[0] = obj.x
coordinatesy[0] = obj.y
coordinatesz[0] = obj.z
velocitiesx[0] = obj.vx
velocitiesy[0] = obj.vy
velocitiesz[0] = obj.vz
for j in range(n):
    x_j = coordinatesx[j]
    vx j = velocitiesx[j]
    y_j = coordinatesy[j]
    vy_j = velocitiesy[j]
    z_j = coordinatesz[j]
    vz_j = velocitiesz[j]
    ax j = buildaccx(obj, planets)
    ay j = buildaccy(obj, planets)
    az j = buildaccz(obj, planets)
    x_j_1 = coorx(x_j, h, vx_j, ax_j)
    y_j_1 = coory(y_j, h,vy_j,ay_j)
    z_{j_1} = coorz(z_j, h, vz_j, az_j)
    coordinatesx[j+1] = x_j_1
    coordinatesy[j+1] = y_j_1
    coordinatesz[j+1] = z j 1
    obj.movex(x j 1)
    obj.movey(y j 1)
    obj.movez(z_j_1)
    ax j 1 = buildaccx(obj, planets)
    ay_j_1 = buildaccy(obj, planets)
    az_j_1 = buildaccz(obj, planets)
    vx_j_1 = velx(vx_j,h,ax_j_1,ax_j)
    vy_j_1 = vely(vy_j,h,ay_j_1,ay_j)
    vz_j_1 = velz(vz_j,h,az_j_1,az_j)
    velocitiesy[j+1] = vy_j_1
    velocitiesx[j+1] = vx_j_1
    velocitiesz[j+1] = vz j 1
    obj.movevx(vx_j_1)
    obj.movevy(vy j 1)
    obj.movevz(vz j 1)
all x.append(coordinatesx)
all y.append(coordinatesy)
all_z.append(coordinatesz)
```