

# Example: Linear LS

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$$\mathbf{Y} = \mathbf{X}w + \epsilon$$

$$\text{if } y_i = x_i^T w + \epsilon_i \quad \text{and} \quad \epsilon_i \stackrel{i.i.d.}{\sim} \mathcal{N}(0, \sigma^2)$$

# Example: Linear LS: compute bias

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$$\text{if } y_i = x_i^T w + \epsilon_i \quad \text{and} \quad \epsilon_i \stackrel{i.i.d.}{\sim} \mathcal{N}(0, \sigma^2)$$

$$\hat{w}_{MLE} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{Y} = w + (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \epsilon$$

$$\eta(x) = \mathbb{E}_{Y|X}[Y|X = x]$$

$$\hat{f}_{\mathcal{D}}(x) = \hat{w}^T x = w^T x + \epsilon^T \mathbf{X}(\mathbf{X}^T \mathbf{X})^{-1} x$$

$$\underline{(\eta(x) - \mathbb{E}_{\mathcal{D}}[\hat{f}_{\mathcal{D}}(x)])^2}.$$

**bias squared**

# Example: Linear LS: compute variance

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$$\mathbf{Y} = \mathbf{X}w + \epsilon$$

$$\text{if } y_i = x_i^T w + \epsilon_i \quad \text{and} \quad \epsilon_i \stackrel{i.i.d.}{\sim} \mathcal{N}(0, \sigma^2)$$

$$\hat{w}_{MLE} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{Y} = w + (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \epsilon$$

$$\hat{f}_{\mathcal{D}}(x) = \hat{w}^T x = w^T x + \epsilon^T \mathbf{X}(\mathbf{X}^T \mathbf{X})^{-1} x$$

$$\underline{\mathbb{E}_{\mathcal{D}}[(\mathbb{E}_{\mathcal{D}}[\hat{f}_{\mathcal{D}}(x)] - \hat{f}_{\mathcal{D}}(x))^2]} =$$

**variance**

# Example: Linear LS

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$$\eta(x) = \mathbb{E}_{Y|X}[Y|X = x]$$

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$$\underbrace{\mathbb{E}_{XY}[(Y - \eta(x))^2 | X = x]}_{\text{irreducible error}} = \sigma^2 \qquad \underbrace{(\eta(x) - \mathbb{E}_{\mathcal{D}}[\hat{f}_{\mathcal{D}}(x)])^2}_{\text{bias squared}} = 0$$

$$\mathbb{E}_{X=x} \left[ \underbrace{\mathbb{E}_{\mathcal{D}}[(\mathbb{E}_{\mathcal{D}}[\hat{f}_{\mathcal{D}}(x)] - \hat{f}_{\mathcal{D}}(x))^2]}_{\text{variance}} \right] = \frac{p\sigma^2}{n}$$

# Overfitting



# Bias-Variance Tradeoff

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- > Choice of hypothesis class introduces learning bias
  - More complex class → less bias
  - More complex class → more variance
- > But in practice??

# Bias-Variance Tradeoff

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- > Choice of hypothesis class introduces learning bias
  - More complex class → less bias
  - More complex class → more variance
- > But in practice??
- > Before we saw how increasing the feature space can increase the complexity of the learned estimator:

$$\mathcal{F}_1 \subset \mathcal{F}_2 \subset \mathcal{F}_3 \subset \dots$$

$$\hat{f}_D^{(k)} = \arg \min_{f \in \mathcal{F}_k} \frac{1}{|\mathcal{D}|} \sum_{(x_i, y_i) \in \mathcal{D}} (y_i - f(x_i))^2$$

Complexity grows as k grows

# Training set error as a function of model complexity

$$\mathcal{F}_1 \subset \mathcal{F}_2 \subset \mathcal{F}_3 \subset \dots$$

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**TRAIN error:**

$$\mathcal{D} \stackrel{i.i.d.}{\sim} P_{XY}$$

$$\frac{1}{|\mathcal{D}|} \sum_{(x_i, y_i) \in \mathcal{D}} (y_i - \hat{f}_{\mathcal{D}}^{(k)}(x_i))^2$$

**TRUE error:**

$$\mathbb{E}_{XY}[(Y - \hat{f}_{\mathcal{D}}^{(k)}(X))^2]$$



# Training set error as a function of model complexity

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**TRAIN error:**

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**TRUE error:**

$$\mathbb{E}_{XY}[(Y - \hat{f}_{\mathcal{D}}^{(k)}(X))^2]$$

**TEST error:**

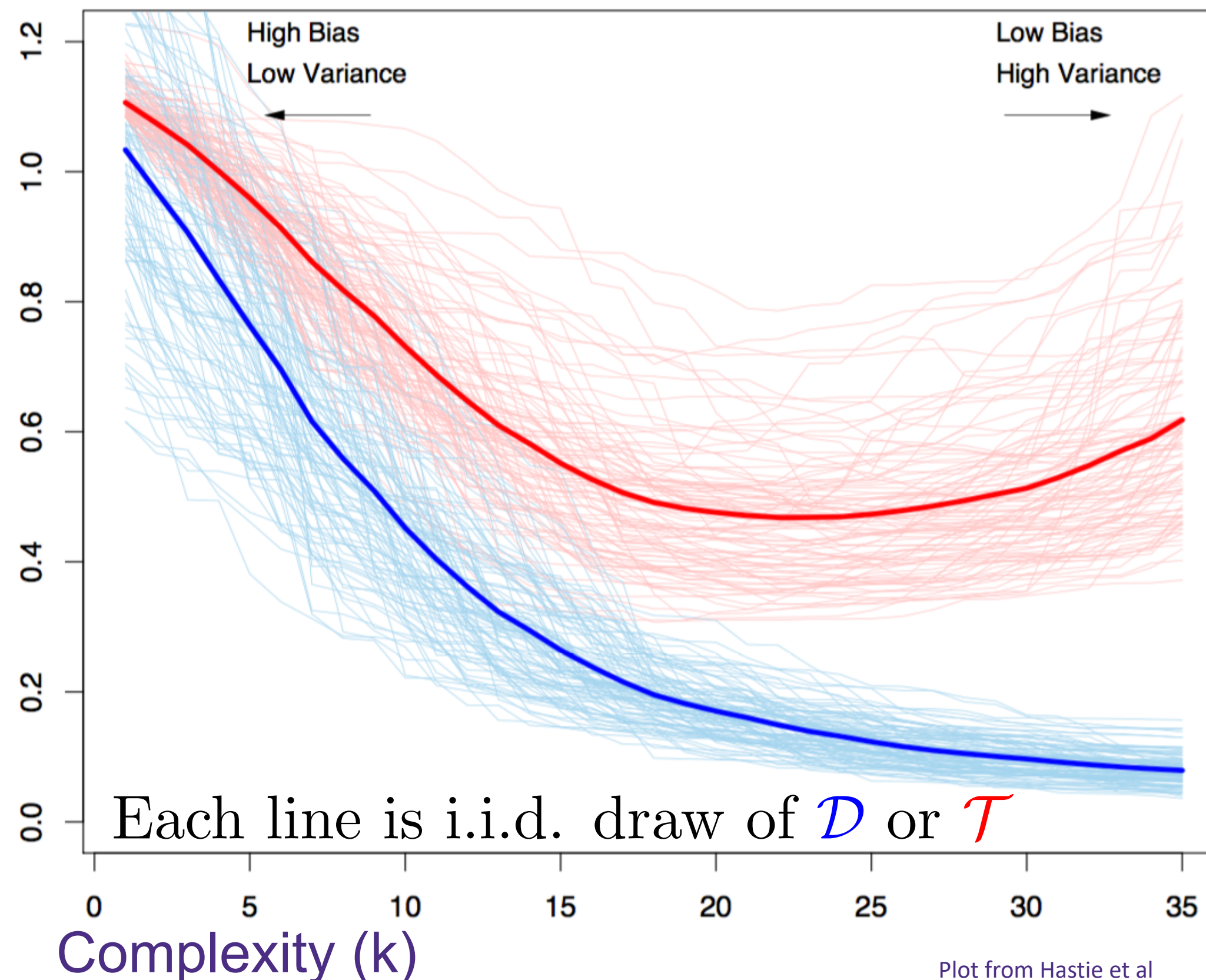
$$\mathcal{T} \stackrel{i.i.d.}{\sim} P_{XY}$$
$$\frac{1}{|\mathcal{T}|} \sum_{(x_i, y_i) \in \mathcal{T}} (y_i - \hat{f}_{\mathcal{D}}^{(k)}(x_i))^2$$

Important:  $\mathcal{D} \cap \mathcal{T} = \emptyset$

# Training set error as a function of model complexity

$$\mathcal{F}_1 \subset \mathcal{F}_2 \subset \mathcal{F}_3 \subset \dots$$

$$\hat{f}_{\mathcal{D}}^{(k)} = \arg \min_{f \in \mathcal{F}_k} \frac{1}{|\mathcal{D}|} \sum_{(x_i, y_i) \in \mathcal{D}} (y_i - f(x_i))^2$$



**TRAIN error:**

$$\mathcal{D} \stackrel{i.i.d.}{\sim} P_{XY}$$

$$\frac{1}{|\mathcal{D}|} \sum_{(x_i, y_i) \in \mathcal{D}} (y_i - \hat{f}_{\mathcal{D}}^{(k)}(x_i))^2$$

**TRUE error:**

$$\mathbb{E}_{XY}[(Y - \hat{f}_{\mathcal{D}}^{(k)}(X))^2]$$

**TEST error:**

$$\mathcal{T} \stackrel{i.i.d.}{\sim} P_{XY}$$

$$\frac{1}{|\mathcal{T}|} \sum_{(x_i, y_i) \in \mathcal{T}} (y_i - \hat{f}_{\mathcal{D}}^{(k)}(x_i))^2$$

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# Training set error as a function of model complexity

$$\mathcal{F}_1 \subset \mathcal{F}_2 \subset \mathcal{F}_3 \subset \dots$$

$$\hat{f}_{\mathcal{D}}^{(k)} = \arg \min_{f \in \mathcal{F}_k} \frac{1}{|\mathcal{D}|} \sum_{(x_i, y_i) \in \mathcal{D}} (y_i - f(x_i))^2$$

**TRAIN error** is **optimistically biased** because it is evaluated on the data it trained on. **TEST error** is **unbiased** only if  $\mathcal{T}$  is never used to train the model or even pick the complexity  $k$ .

**TRAIN error:**

$$\mathcal{D} \stackrel{i.i.d.}{\sim} P_{XY}$$

$$\frac{1}{|\mathcal{D}|} \sum_{(x_i, y_i) \in \mathcal{D}} (y_i - \hat{f}_{\mathcal{D}}^{(k)}(x_i))^2$$

**TRUE error:**

$$\mathbb{E}_{XY}[(Y - \hat{f}_{\mathcal{D}}^{(k)}(X))^2]$$

**TEST error:**

$$\mathcal{T} \stackrel{i.i.d.}{\sim} P_{XY}$$

$$\frac{1}{|\mathcal{T}|} \sum_{(x_i, y_i) \in \mathcal{T}} (y_i - \hat{f}_{\mathcal{D}}^{(k)}(x_i))^2$$

Important:  $\mathcal{D} \cap \mathcal{T} = \emptyset$

# How many points do I use for training/testing?

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- > **Very hard question to answer!**
  - Too few training points, learned model is bad
  - Too few test points, you never know if you reached a good solution
- > **More on this later the quarter, but still hard to answer**
- > **Typically:**
  - If you have a reasonable amount of data 90/10 splits are common
  - If you have little data, then you need to get fancy (e.g., bootstrapping)