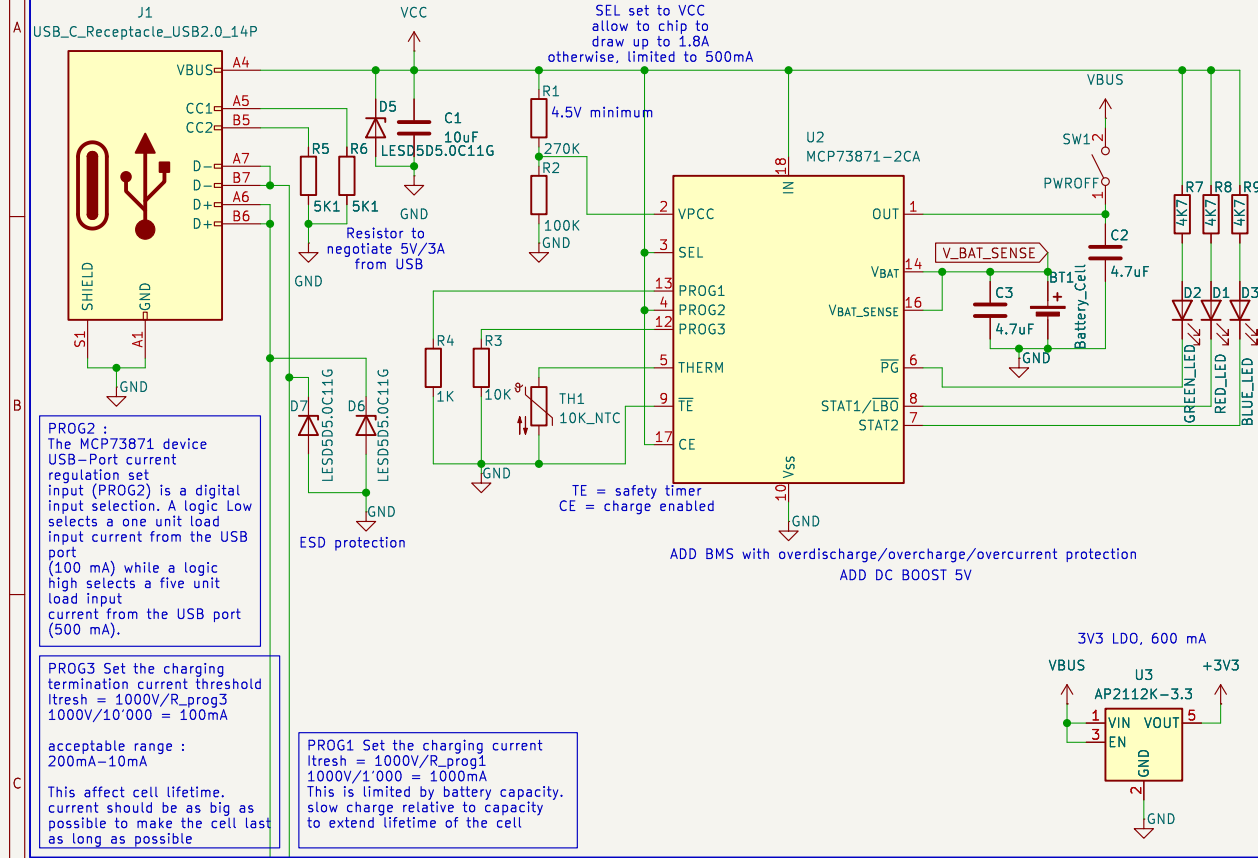


ENERGY

Bat + BMS + Power

up to 5.5A charge current
given 1.5A Max during motor usage,
we can charge the robot for a 45 min lesson in less than 10 min

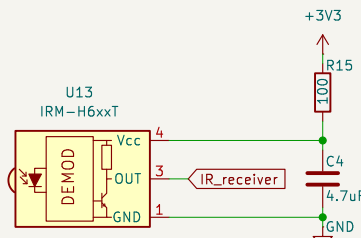


SENSORS

Microphone

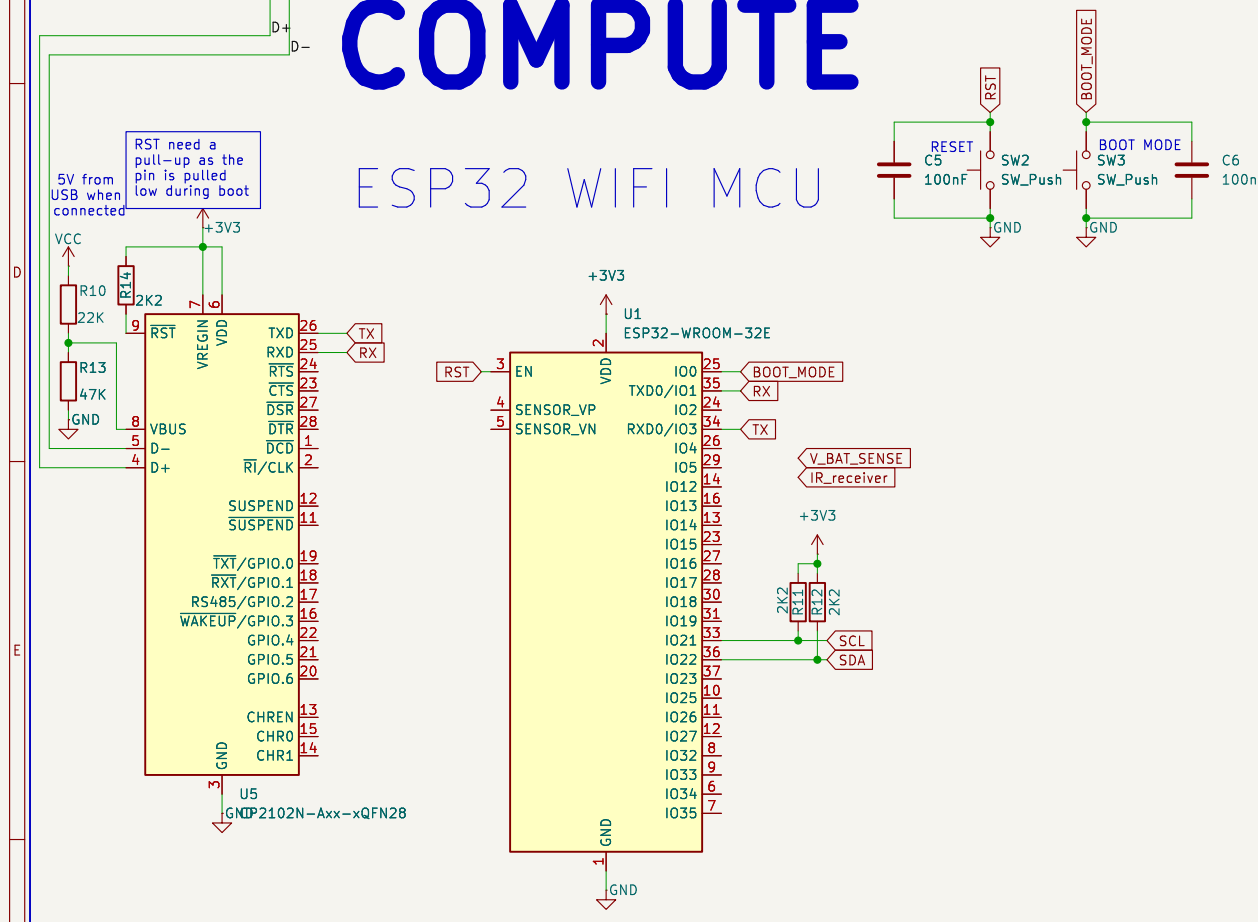
Capacitive Buttons

IR Remote Receiver



COMPUTE

ESP32 WIFI MCU



6 AXIS IMU

IR Proximity sensor

On the daughterboard

Color Sensor (over I2C)

On the daughterboard

Motors / H-bridge

use

SX1509

PCA9685

they work over I2C
and can be paired
to an H bridge