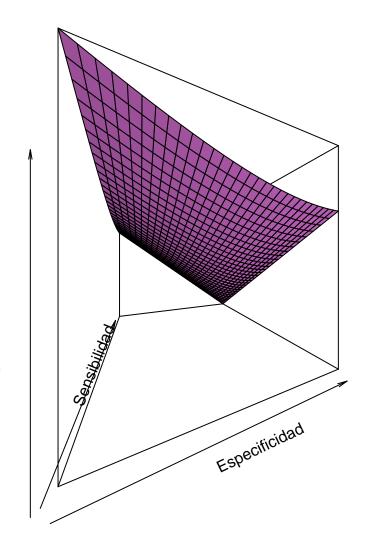
Distance to corner y punto óptimo



Distance ro Corner