

# Chapter 1

## Replicating John Philip 1972

The first known expression for an effective slip length appeared in 1972, in a paper in ZAMP by John R. Philip entitled “Flows Satisfying Mixed No-Slip and No-Shear Conditions” [1].

In the paper, John R. Philip says that the limit of

$$W_3 = \Im \left[ \alpha^{-1} \cos^{-1} \left\{ \frac{\cos(\alpha\Theta)}{\cos \alpha} \right\} - \Theta \right] \quad (1.1)$$

as  $y \rightarrow \infty$  is

$$W_3 = \alpha^{-1} \ln \sec \alpha \quad (1.2)$$

Let us prove this forthwith.

$\Theta = x + iy$  is a complex number,  $\alpha$  is real. Trig identities for *complex* cosine and exponential:

$$\cos z = \frac{e^{iz} + e^{-iz}}{2} \quad (1.3)$$

$$e^{i\theta} = \cos \theta + i \sin \theta \quad (1.4)$$

## 1.1 Expand cosine term, dump negligible parts

In Euler's formula  $e^{i\theta} = \text{cis}(\theta)$ , if  $\theta$  is *real*, then  $e^{i\theta}$  traces out the unit circle in  $\mathbb{C}$ , with  $\theta$  being the angle.

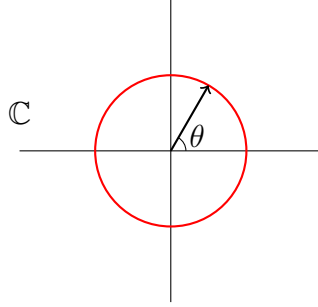


Figure 1.1: Euler's formula  $e^{i\theta}$  for real  $\theta$ .

This gives insight into the  $\cos z$  function. If  $z$  is real, then  $\frac{1}{2}e^{iz}$  and  $\frac{1}{2}e^{-iz}$  are two vectors of length  $\frac{1}{2}$  that cycle in opposite directions, with  $z$  being the angle. Then  $\cos z$  is the sum of the two vectors, which always ends on the real line between -1 and 1, as shown in Figure (1.2).

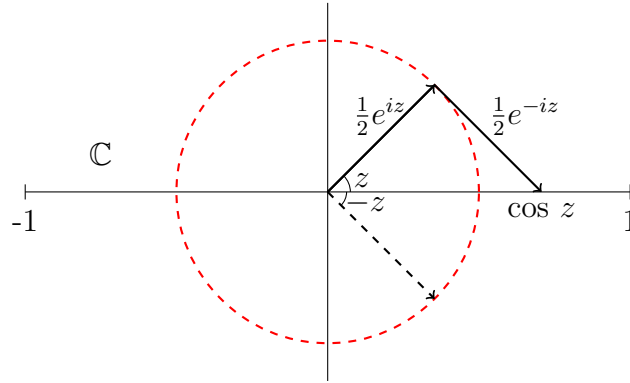


Figure 1.2: The complex cosine.

With this insight, it is useful to rewrite  $\cos z$  as:

$$\cos(x + iy) = \frac{e^{i(x+iy)} + e^{-i(x+iy)}}{2} = e^y \frac{1}{2}e^{-ix} + e^{-y} \frac{1}{2}e^{ix} \quad (1.5)$$

Then it is clear that  $\cos(x + iy)$  is the sum of two rotating vectors in  $\mathbb{C}$  with amplitudes  $e^y$  and  $e^{-y}$ . A consequence is that for large  $y$ ,  $e^y$  is *very*

large, while  $e^{-y}$  is negligible, therefore  $\cos(x + iy)$  is dominated by the vector  $e^y \frac{1}{2} e^{-ix}$ . See Figure (1.3).

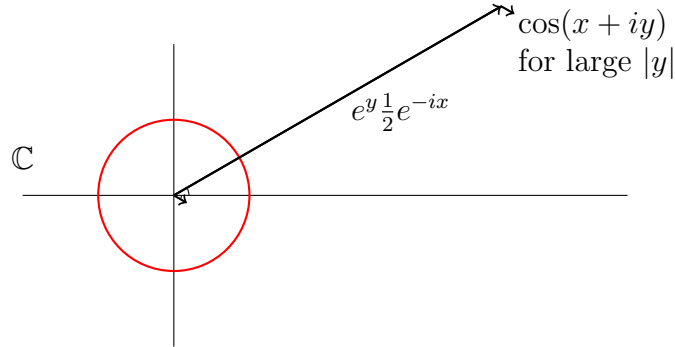


Figure 1.3: Complex cosine at large  $|y|$ .

$$\text{Therefore } \cos(x + iy) \rightarrow \frac{e^y e^{-ix}}{2} \quad \text{as } y \rightarrow \infty \quad (1.6)$$

$$\cos z \rightarrow \frac{1}{2} e^{-iz} \quad \text{as } y \rightarrow \infty \quad (1.7)$$

## 1.2 Inverse Cosine at Large $y$

As  $y \rightarrow \infty$ :

$$w = \cos z \rightarrow \frac{1}{2} e^{-iz} \quad (1.8)$$

Solve  $w = \cos z$  for  $z$  to get:

$$\arccos w = z$$

Likewise solve  $w = \frac{1}{2} e^{-iz}$  for  $z$ :

$$w = \frac{1}{2} e^{-iz}$$

$$2w = e^{-iz}$$

$$\ln(2w) = -iz$$

$$i \ln(2w) = -i^2 z$$

$$i \ln(2w) = z$$

Equate the two expressions to obtain the inverse cosine in terms of a logarithm:

$$\arccos z = i \ln(2z) \quad (1.9)$$

### 1.3 Put into J. R. Philip's Expression

$$W_3 = \Im \left[ \alpha^{-1} \cos^{-1} \left\{ \frac{\cos(\alpha\Theta)}{\cos \alpha} \right\} - \Theta \right] \quad (1.10)$$

As  $y \rightarrow \infty$ , the cosine expression may be substituted:

$$W_3 = \Im \left[ \alpha^{-1} \cos^{-1} \left\{ \frac{\frac{1}{2}e^{-i\alpha\Theta}}{\cos \alpha} \right\} - \Theta \right] \quad (1.11)$$

And the inverse cosine expression may also be substituted:

$$W_3 = \Im \left[ i\alpha^{-1} \ln \left\{ 2 \frac{\frac{1}{2}e^{-i\alpha\Theta}}{\cos \alpha} \right\} - \Theta \right] \quad (1.12)$$

$$W_3 = \Im \left[ i\alpha^{-1} \ln \left\{ e^{-i\alpha\Theta} \frac{1}{\cos \alpha} \right\} - \Theta \right] \quad (1.13)$$

Recall that  $\ln ab = \ln a + \ln b$ .

$$W_3 = \Im \left[ i\alpha^{-1} \ln \{ e^{-i\alpha\Theta} \} + i\alpha^{-1} \ln \left\{ \frac{1}{\cos \alpha} \right\} - \Theta \right] \quad (1.14)$$

Invoke definition of logarithm:  $\ln e^z = z$ .

$$W_3 = \Im \left[ i\alpha^{-1} \{-i\alpha\Theta\} + i\alpha^{-1} \ln \left\{ \frac{1}{\cos \alpha} \right\} - \Theta \right] \quad (1.15)$$

$$W_3 = \Im \left[ \Theta + i\alpha^{-1} \ln \left\{ \frac{1}{\cos \alpha} \right\} - \Theta \right] \quad (1.16)$$

$$W_3 = \Im \left[ i\alpha^{-1} \ln \left\{ \frac{1}{\cos \alpha} \right\} \right] \quad (1.17)$$

$$W_3 = \alpha^{-1} \ln \sec \alpha \quad (1.18)$$

We have demonstrated that which we set out to prove.

# Bibliography

- [1] John R. Philip. Flows satisfying mixed no-slip and no-shear conditions.  
*Journal of Applied Mathematics and Physics (ZAMP)*, 23:353, 1972.