

Q1 - MODELAGEM DE SISTEMAS LINEARES

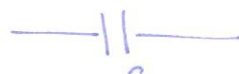
RELEMBRANDO

RESISTOR

$$V = Ri$$




CAPACITOR



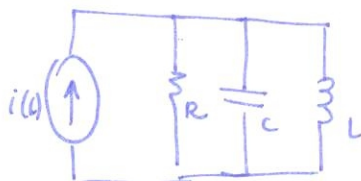
$$i_c(t) = C \frac{dV_c(t)}{dt}$$

INDUTOR



$$V_L(t) = L \frac{di_L}{dt}$$

a) CIRCUITO 1



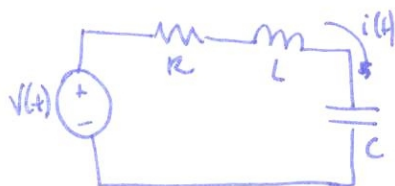
PELA LKC

$$i(t) = i_R(t) + i_C(t) + i_L(t)$$

$$i(t) = \frac{V(t)}{R} + C \frac{dV(t)}{dt} + \frac{1}{L} \int_{-\infty}^t V(t) dt$$

10pts

CIRCUITO 2



PELA LKT

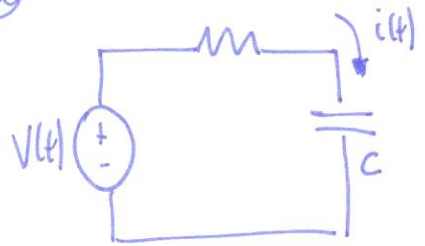
$$V(t) = V_R + V_L + V_C$$

$$V(t) = Ri(t) + L \frac{di(t)}{dt} + \frac{1}{C} \int_{-\infty}^t i(t) dt$$

10pts

Q2

a)



Modelagem:

$$V(t) = V_R(t) + V_C(t)$$

$$V(t) = R i(t) + \frac{1}{C} \int_{-\infty}^t i(t) dt$$

ESTADO ZERO $\rightarrow V(t) = 0$

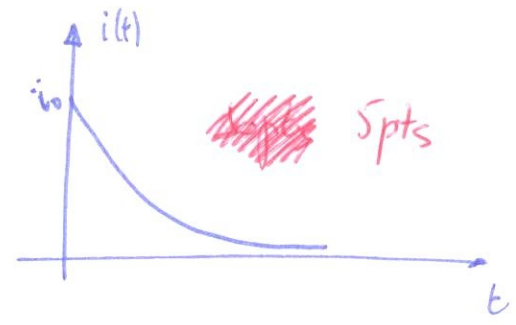
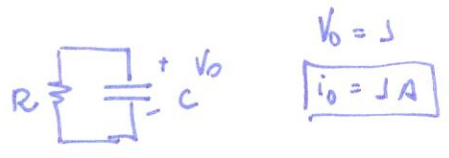
$$0 = R i(t) + \frac{1}{C} \int_{-\infty}^t i(t) dt \rightarrow 0 = R \frac{di(t)}{dt} + \frac{1}{C} i(t) \rightarrow \frac{di(t)}{dt} + \frac{1}{RC} i(t) = 0$$

Supondo $i(t) = e^{\lambda t}$

$$\frac{di(t)}{dt} = \lambda e^{\lambda t} \rightarrow (\lambda + 1/RC) e^{\lambda t} = 0 \rightarrow \lambda + 1/RC = 0 \rightarrow \boxed{\lambda = -1/RC}$$

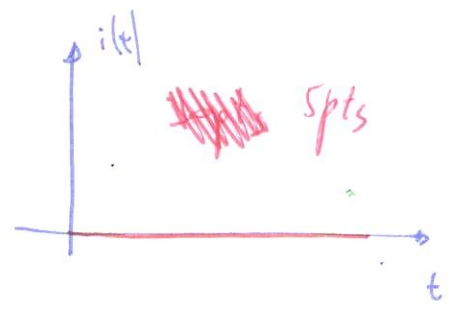
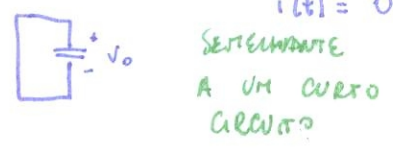
1 - com $R=1, C=1, V_0=1$, temos:

$$\boxed{\lambda = -1} \rightarrow i(t) = i_0 e^{-t}$$



2 - com $R \rightarrow 0, C=1, V_0=2$

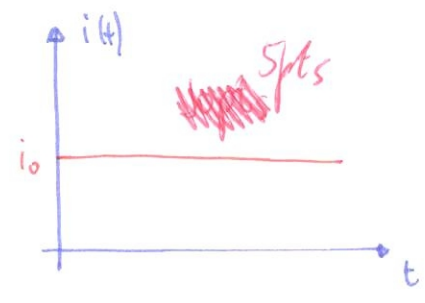
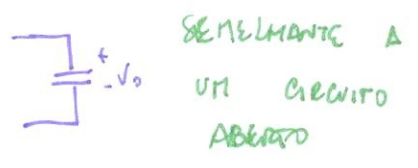
$$\boxed{\lambda = -\infty} \quad i(t) = i_0 e^{-\infty} \quad i(t) = 0$$



A INTERPRETAÇÃO QUE PODE SER FEITA DESSE CIRCUITO É QUE O CAPACITOR SE DESCARREGA INSTANTANEAMENTE, COM UM IMPULSO DE CORRENTE.

3 - com $R \rightarrow +\infty, C=1, V_0=2$

$$\boxed{\lambda = 0} \quad i(t) = i_0 e^{-0} \quad i(t) = i_0$$



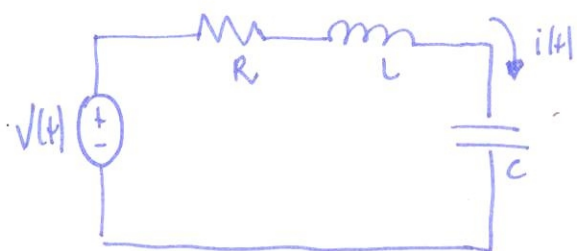
A INTERPRETAÇÃO QUE PODE SER FEITA DESSE CIRCUITO É QUE i_0 É MUITO PEQUENA OU TENDE A ZERO POIS $R \rightarrow +\infty$ É SEMELHANTE A UM CIRCUITO ABERTO

Q2

(b)

(3)

MODELAGEM



$$\frac{\partial^2 i(t)}{\partial t^2} + \frac{R}{L} \frac{\partial i(t)}{\partial t} + \frac{1}{LC} i(t) = 0$$

1- $R=3$, $C=2$, $L=1$, $V_c(0^-)=1$, $i_L(0^-)=1$

$$\frac{\partial^2 i(t)}{\partial t^2} + 3 \frac{\partial i(t)}{\partial t} + \frac{1}{2} i(t) = 0 \rightarrow \lambda_1 = \frac{-3 + \sqrt{7}}{2}$$

$$\lambda_2 = \frac{-3 - \sqrt{7}}{2}$$

$$i(t) = c_1 e^{\left(\frac{-3 + \sqrt{7}}{2}\right)t} + c_2 e^{\left(\frac{-3 - \sqrt{7}}{2}\right)t}$$

$$i(0) = i_L(0) = 1 = c_1 e^0 + c_2 e^0 = c_1 + c_2$$

P/ LKT

$$V(0) = i(0) \cdot R + V_c(0) + L \frac{di(t)}{dt} \Rightarrow 0 = i(0) \cdot R + V_c(0) + L \frac{di(t)}{dt}$$

$$\frac{di(t)}{dt} = -4$$

PARA A DERIVADA DE $i(t)$ $\rightarrow i'(0) = c_1 \left(\frac{-3 + \sqrt{7}}{2}\right) + c_2 \left(\frac{-3 - \sqrt{7}}{2}\right)$

ENTÃO: $c_1 + c_2 = 1$

$$c_1 \left(\frac{-3 + \sqrt{7}}{2}\right) + c_2 \left(\frac{-3 - \sqrt{7}}{2}\right) = -4 \rightarrow c_1 = \frac{1}{2} + \frac{5\sqrt{7}}{14}$$

$$c_2 = \frac{1}{2} - \frac{5\sqrt{7}}{14}$$

$$i(t) = \left(\frac{1}{2} + \frac{5\sqrt{7}}{14}\right) e^{\left(\frac{-3 + \sqrt{7}}{2}\right)t} + \left(\frac{1}{2} - \frac{5\sqrt{7}}{14}\right) e^{\left(\frac{-3 - \sqrt{7}}{2}\right)t}$$

5pts

Q2

(b)

(4)

(2) $R=2, C=2, L=1, V_e(0^-)=1, I_L(0^-)=1$

$$\frac{d^2 i(t)}{dt^2} + 2 \frac{di(t)}{dt} + \frac{1}{2} i(t) = 0 \quad \begin{cases} \lambda_1 = \frac{4+\sqrt{2}}{2} \\ \lambda_2 = \frac{4-\sqrt{2}}{2} \end{cases}$$

$$i(t) = C_1 e^{\left(\frac{4+\sqrt{2}}{2}\right)t} + C_2 e^{\left(\frac{4-\sqrt{2}}{2}\right)t}$$

$$C_1 + C_2 = 1$$

$$\frac{di(t)}{dt} = -3$$

$$V(0) = i(0)R + V_e(0^-) + L \frac{di(t)}{dt}$$

$$i'(0) = C_1 \left(\frac{4+\sqrt{2}}{2}\right) + C_2 \left(\frac{4-\sqrt{2}}{2}\right) \quad \begin{cases} C_1 = \frac{3+5\sqrt{2}}{2} \\ C_2 = \frac{-1-5\sqrt{2}}{2} \end{cases}$$

$$i(t) = \left(\frac{3+5\sqrt{2}}{2}\right) e^{\left(\frac{4+\sqrt{2}}{2}\right)t} + \left(\frac{-1-5\sqrt{2}}{2}\right) e^{\left(\frac{4-\sqrt{2}}{2}\right)t}$$

Spts

(3) $R=1, C=2, L=1, V_e(0^-)=1, I_L(0^-)=1$

$$\frac{d^2 i(t)}{dt^2} + \frac{di(t)}{dt} + \frac{1}{2} i(t) = 0 \quad \begin{cases} \lambda_1 = \frac{1+i}{2} \\ \lambda_2 = \frac{1-i}{2} \end{cases}$$

$$i(t) = C_1 e^{-\frac{1}{2}t} \cos(t/2) + C_2 e^{-\frac{1}{2}t} \sin(t/2)$$

$$\left. \begin{aligned} i(0) = 1 &= C_1 \\ i'(0) = -2 \end{aligned} \right\} C_2 = -3$$

$$i(t) = e^{-\frac{1}{2}t} \cos(t/2) - 3 e^{-\frac{1}{2}t} \sin(t/2)$$

Spts

Q3

a) $h(t) = e^{j\omega_0 t}$

$x(t) = u(t+0.5) - u(t-0.5)$

$y(t) = x(t) * h(t)$

$y(t) = \int_{-\infty}^{+\infty} x(\tau) h(t-\tau) d\tau$

do' ESTÁ DEFINIDA $\tau / -0.5 \leq \tau \leq 0.5$

$y(t) = \int_{-0.5}^{+0.5} x(\tau) h(t-\tau) d\tau \rightarrow y(t) = \int_{-0.5}^{+0.5} e^{j\omega_0(t-\tau)} d\tau$
 $y(t) = e^{j\omega_0 t} \int_{-0.5}^{+0.5} e^{-j\omega_0 \tau} d\tau$

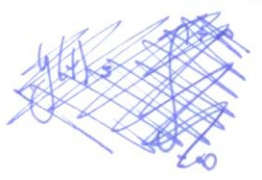
$y(0) = \int_{-0.5}^{+0.5} e^{-j\omega_0 \tau} d\tau = \frac{2}{\omega_0} \sin(\omega_0/2)$

PARA $\omega_0 = 2\pi \omega \sim 2\pi k$
 $\omega/k = 1, 2, 3, \dots$
 jspts

b)

$y(t) = h(t) * x(t) = y(t) = \int_{-\infty}^{+\infty} x(\tau) h(t-\tau) d\tau$

$h(t) = u(t+2) - u(t+1) + \delta(t-3)$



$y(t) = \int_{-2}^{-1} x(t-\tau) d\tau + x(t-3)$

$y(t) = \int_{-2}^{-1} x(\tau) d\tau + x(-3)$

ENT VALORES DE $x(t)$ NECESARIOS

$x(t), -1 \leq t \leq 2$ $x(t), t = -3$
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jspts

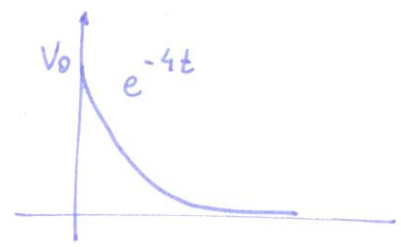
Q4

$$\frac{dy(t)}{dt} + 4y(t) = x(t)$$

RESPOSTA A ENTRADA ZERO:

$$\frac{dy}{dt} + 4y(t) = 0$$

$$\left. \begin{aligned} y(t) &= e^{\lambda t} \\ \frac{dy}{dt} &= \lambda e^{\lambda t} \end{aligned} \right\} \begin{aligned} (\lambda + 4)e^{\lambda t} &= 0 \\ \lambda &= -4 \end{aligned}$$



como $V_0 = 0$ NÃO TEM RESPOSTA A ENTRADA ZERO.

RESPOSTA AO ESTADO ZERO:

SEMELHANTE AO CÁLCULO SUPERIORES QUE $x(t) = e^{(-1+3j)t}$ e $y(t) = k e^{(-1+3j)t}$

$$(-1+3j)k e^{(-1+3j)t} + 4k e^{(-1+3j)t} = e^{(-1+3j)t} \quad \forall t > 0$$

$$(-1+3j)k + 4k = 1$$

$$-k + 3jk + 4k = 1$$

$$3(1+j)k = 1 \rightarrow$$

$$k = \frac{1}{3+j3}$$

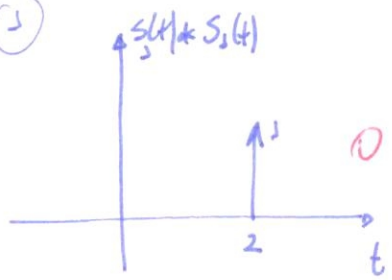
$$k = \frac{3-j3}{18}$$

$$k = \frac{1-j}{6}$$

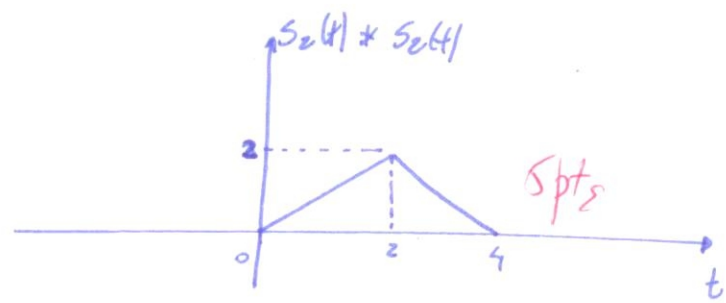
Logo

Q5 -

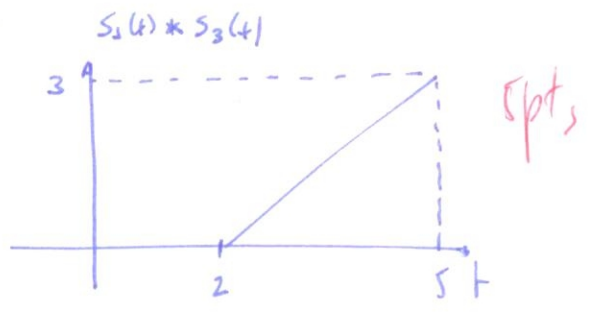
(1)



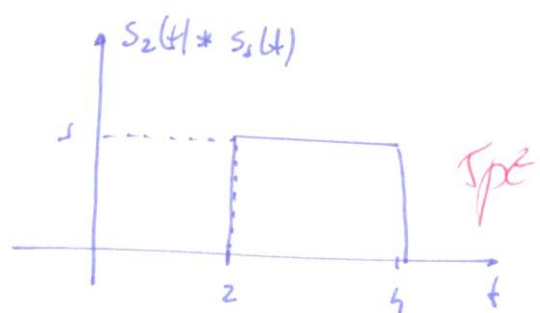
(2)



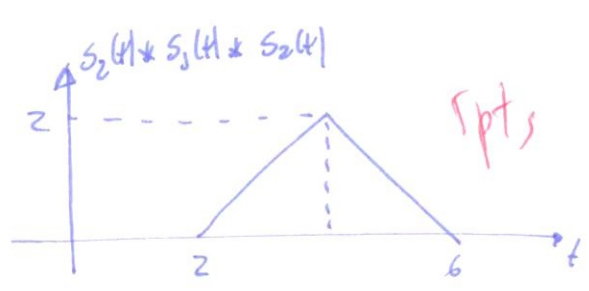
(3)



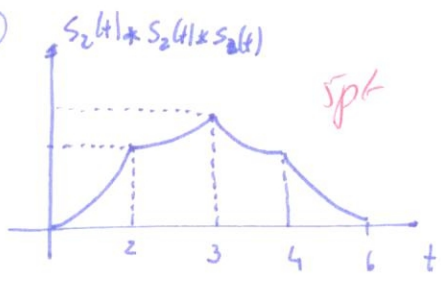
(4)



(5)



(6)



(7)

