

# Nathan Lambert

✉ [nathan@natolambert.com](mailto:nathan@natolambert.com) • 🌐 [natolambert.com](https://natolambert.com) • in [natolambert](https://natolambert.com)  
🐦 [natolambert](https://twitter.com/natolambert) • 🌐 [natolambert](https://natolambert.com) • Last updated on October 15, 2025

I research **data-driven decision making**, including progressing **reinforcement learning** algorithms, applying them to real-world problems such as **large language models** and **robotics**, and planning for the **societal implications** therein.

## Education

**Ph.D. in Electrical Engineering and Computer Science**, University of California, Berkeley (4.0/4.0) 2017 – 2022  
*Synergy of Prediction and Control in Model-based Reinforcement Learning*  
Advisors: [Kristofer S.J. Pister](#), [Roberto Calandra](#)  
Committee: [Sergey Levine](#), [Claire Tomlin](#)

**B.S. in Electrical and Computer Engineering**, Cornell University (4.0/4.0) 2013 – 2017

## Industry Experience

**Allen Institute for AI**, Seattle, WA | Research Scientist 2023 – cont.  
**HuggingFace**, Remote | Research Scientist and RLHF Team Lead 2022 – 2023  
**DeepMind**, London (*Virtual*) | Research Intern (Host: [Martin Riedmiller](#)) 2021  
**Facebook AI**, Menlo Park | Research Intern and Student Researcher (Host: [Roberto Calandra](#)) 2019 – 2020  
**Tesla**, Palo Alto Test Engineering Intern 2015

## Honors & Awards

Ai2 The Cat Herder 2024  
ACL Best Resource Paper Award (Dolma) 2024  
ACL Best Theme Paper Award (OLMo) 2024  
GeekWire Innovation of the year (OLMo) 2024  
Reward Reports - Auditing AI Mozilla Technology Fund Cohort 2023  
Best Oral Presentation; Berkeley Sensor and Actuator Sensor Spring Review 2022  
Best Student Paper Finalist; IEEE Symposium on Multi-Robot and Multi-Agent Systems 2021  
Berkeley EECS Demetri Angelakos Memorial Achievement Award 2021  
Heart to Humanity Eternal (H2H8) Pioneer 2021  
NDSEG Graduate Research Fellowship Program Top 200 2018  
NSF Graduate Research Fellowship Program Honorable Mention 2017, 2018  
Berkeley EECS Department Fellowship 2017  
Eight undergraduate scholarships 2013 – 2017  
Cornell Rowing Charles E. Courtney Award, Tau Beta Pi Scholarship, Southeastern New England Defense Industry Alliance STEM Scholarship  
2016, 2017, Cornell Athletics 400 Club Induction, Beta Pi Induction, Eta Kappa Nu Induction, American Society of Engineering Education  
SMART Scholar Award

## Publications [Google Scholar: 7.5k+ citations and an h-index of 34, Semantic Scholar ]

Representative publications that I am a primary author on are highlighted.

2025.....

1. [RewardBench: Evaluating Reward Models for Language Modeling](#) [code]  
[Nathan Lambert](#), [Valentina Pyatkin](#), [Jacob Morrison](#), [LJ Miranda](#), [Bill Yuchen Lin](#), [Khyathi Chandu](#),  
[Nouha Dziri](#), [Sachin Kumar](#), [Tom Zick](#), [Yejin Choi](#), [Noah A. Smith](#), and [Hannaneh Hajishirzi](#)  
NAACL 2025

2. [2 OLMo 2 Furious \[code\]](#)  
Team OLMo, Pete Walsh, [Luca Soldaini](#), Dirk Groeneveld, [Kyle Lo](#), Shane Arora, Akshita Bhagia, [Yuling Gu](#), [Shengyi Huang](#), Matt Jordan, [Nathan Lambert](#), Dustin Schwenk, Oyvind Tafjord, Taira Anderson, David Atkinson, [Faeze Brahman](#), [Christopher Clark](#), [Pradeep Dasigi](#), [Nouha Dziri](#), Michal Guerquin, [Hamish Ivison](#), Pang Wei Koh, Jiacheng Liu, Saumya Malik, William Merrill, [Lester James V. Miranda](#), [Jacob Morrison](#), Tyler Murray, Crystal Nam, [Valentina Pyatkin](#), Aman Rangapur, Michael Schmitz, Sam Skjonsberg, David Wadden, Christopher Wilhelm, Michael Wilson, Luke Zettlemoyer, [Ali Farhadi](#), [Noah A. Smith](#), and [Hannaneh Hajishirzi](#)  
arXiv Preprint 2024
3. [Tülu 3: Pushing Frontiers in Open Language Model Post-Training \[code\]](#)  
[Nathan Lambert](#), Jacob Morrison, Valentina Pyatkin, Shengyi Huang, Hamish Ivison, Faeze Brahman, Lester James V. Miranda, Alisa Liu, Nouha Dziri, Shane Lyu, Yuling Gu, Saumya Malik, Victoria Graf, Jena D. Hwang, Jiangjiang Yang, Ronan Le Bras, Oyvind Tafjord, Chris Wilhelm, [Luca Soldaini](#), [Noah A. Smith](#), Yizhong Wang, Pradeep Dasigi, and Hannaneh Hajishirzi  
Technical Report 2024
4. [Molmo and pixmo: Open weights and open data for state-of-the-art multimodal models \[code\]](#)  
Matt Deitke, Christopher Clark, Sangho Lee, Rohun Tripathi, Yue Yang, Jae Sung Park, Mohammadreza Salehi, Niklas Muennighoff, [Kyle Lo](#), [Luca Soldaini](#), Jiasen Lu, Taira Anderson, Erin Bransom, Kiana Ehsani, Huong Ngo, YenSung Chen, Ajay Patel, Mark Yatskar, Christopher Callison-Burch, Andrew Head, Rose Hendrix, Favyen Bastani, Eli VanderBilt, [Nathan Lambert](#), Yvonne Chou, Arnavi Chheda, Jenna Sparks, Sam Skjonsberg, Michael Schmitz, Aaron Sarnat, Byron Bischoff, Pete Walsh, Christopher Newell, Piper Wolters, Tanmay Gupta, Kuo-Hao Zeng, Jon Borchardt, Dirk Groeneveld, Jennifer Dumas, Crystal Nam, Sophie Lebrecht, Caitlin Marie Wittliff, Carissa Schoenick, Oscar Michel, Ranjay Krishna, Luca Weihs, [Noah A. Smith](#), [Hanna Hajishirzi](#), Ross Girshick, [Ali Farhadi](#), and Aniruddha Kembhavi  
arXiv Preprint 2024
5. [M-RewardBench: Evaluating Reward Models in Multilingual Settings \[code\]](#)  
Srishti Gureja, Lester James V Miranda, Shayekh Bin Islam, Rishabh Maheshwary, Drishti Sharma, Gusti Winata, [Nathan Lambert](#), Sebastian Ruder, Sara Hooker, and Marzieh Fadaee  
arXiv Preprint 2024
6. [OLMoE: Open Mixture-of-Experts Language Models \[code\]](#)  
Niklas Muennighoff, [Luca Soldaini](#), Dirk Groeneveld, [Kyle Lo](#), Jacob Daniel Morrison, Sewon Min, Weijia Shi, Pete Walsh, Oyvind Tafjord, [Nathan Lambert](#), [Yuling Gu](#), Shane Arora, Akshita Bhagia, Dustin Schwenk, David Wadden, Alexander Wettig, Binyuan Hui, Tim Dettmers, Douwe Kiela, [Ali Farhadi](#), [Noah A. Smith](#), Pang Wei Koh, Amanpreet Singh, and [Hanna Hajishirzi](#)  
arXiv Preprint 2024
7. [Towards a Framework for Openness in Foundation Models: Proceedings from the Columbia Convening on Openness in Artificial Intelligence](#)  
Adrien Basdevant, Camille François, Victor Storch, Kevin Bankston, Ayah Bdeir, Brian Behlendorf, Merouane Debbah, Sayash Kapoor, Yann LeCun, Mark Surman, Helen King-Turvey, [Nathan Lambert](#), Stefano Maffulli, Nik Marda, Govind Shivkumar, and Justine Tunney  
Workshop Proceedings 2024
8. [Unpacking DPO and PPO: Disentangling Best Practices for Learning from Preference Feedback \[code\]](#)  
[Hamish Ivison](#), Yizhong Wang, Jiacheng Liu, Zeqiu Wu, [Valentina Pyatkin](#), [Nathan Lambert](#), [Noah A. Smith](#), Yejin Choi, and [Hannaneh Hajishirzi](#)  
NeurIPS 2024
9. [Wildguard: Open one-stop moderation tools for safety risks, jailbreaks, and refusals of llms \[code\]](#)  
Seungju Han, Kavel Rao, Allyson Ettinger, Liwei Jiang, Bill Yuchen Lin, [Nathan Lambert](#), Yejin Choi, and [Nouha Dziri](#)  
NeurIPS Dataset and Benchmarks 2024
10. [Self-directed synthetic dialogues and revisions technical report](#)  
[Nathan Lambert](#), Hailey Schoelkopf, Aaron Gokaslan, [Luca Soldaini](#), [Valentina Pyatkin](#), and Louis Castricato  
Technical Report 2024

11. [Dolma: an Open Corpus of Three Trillion Tokens for Language Model Pretraining Research](#) [code]  
Luca Soldaini, Rodney Kinney, Akshita Bhagia, Dustin Schwenk, David Atkinson, Russell Authur, Ben Bogin, Khyathi Chandu, Jennifer Dumas, Yanai Elazar, Valentin Hofmann, Ananya Harsh Jha, Sachin Kumar, Li Lucy, Xinxu Lyu, **Nathan Lambert**, Ian Magnusson, [Jacob Morrison](#), Niklas Muennighoff, Aakanksha Naik, Crystal Nam, Matthew E. Peters, Abhilasha Ravichander, Kyle Richardson, Zejiang Shen, Emma Strubell, Nishant Subramani, Oyvind Tafjord, Pete Walsh, Luke Zettlemoyer, [Noah A. Smith](#), [Hannaneh Hajishirzi](#), Iz Beltagy, Dirk Groeneveld, Jesse Dodge, and [Kyle Lo](#)  
ACL 2024 (Best Paper Award)
12. [OLMo: Accelerating the Science of Language Models](#) [code]  
Dirk Groeneveld, Iz Beltagy, Pete Walsh, Akshita Bhagia, Rodney Kinney, Oyvind Tafjord, Ananya Harsh Jha, [Hamish Ivison](#), Ian Magnusson, [Yizhong Wang](#), Shane Arora, David Atkinson, Russell Authur, Khyathi Raghavi Chandu, Arman Cohan, Jennifer Dumas, Yanai Elazar, [Yuling Gu](#), Jack Hessel, Tushar Khot, William Merrill, [Jacob Morrison](#), Niklas Muennighoff, Aakanksha Naik, Crystal Nam, Matthew E. Peters, [Valentina Pyatkin](#), Abhilasha Ravichander, Dustin Schwenk, Saurabh Shah, Will Smith, Emma Strubell, Nishant Subramani, Mitchell Wortsman, [Pradeep Dasigi](#), **Nathan Lambert**, Kyle Richardson, Luke Zettlemoyer, Jesse Dodge, [Kyle Lo](#), [Luca Soldaini](#), [Noah A. Smith](#), and [Hannaneh Hajishirzi](#)  
ACL 2024 (Best Paper Award)
13. [A Survey on Data Selection for Language Models](#)  
Alon Albalak, Yanai Elazar, Sang Michael Xie, Shayne Longpre, **Nathan Lambert**, Xinyi Wang, Niklas Muennighoff, Bairu Hou, Liangming Pan, Haewon Jeong, Colin Raffel, Shiyu Chang, Tatsunori Hashimoto, and William Yang Wang  
TMLR 2024
14. [Social Choice Should Guide AI Alignment in Dealing with Diverse Human Feedback](#)  
Vincent Conitzer, Rachel Freedman, Jobst Heitzig, Wesley H. Holliday, Bob M. Jacobs, **Nathan Lambert**, Milan Mossé, Eric Pacuit, [Stuart Russell](#), Hailey Schoelkopf, Emanuel Tewelde, and William S. Zwicker  
ICML Position Paper 2024
15. [D2PO: Discriminator-Guided DPO with Response Evaluation Models](#)  
Prasann Singhal, **Nathan Lambert**, Scott Niekum, Tanya Goyal, and Greg Durrett  
COLM 2024
16. [Zephyr: Direct Distillation of LM Alignment](#) [code]  
Lewis Tunstall, Edward Beeching, **Nathan Lambert**, Nazneen Rajani, Kashif Rasul, Younes Belkada, [Shengyi Huang](#), Leandro von Werra, Clémentine Fourrier, Nathan Habib, Nathan Sarrazin, Omar Sanseviero, Alexander M. Rush, and Thomas Wolf  
COLM 2024
17. [A Unified View on Solving Objective Mismatch in Model-Based Reinforcement Learning](#)  
Ran Wei, **Nathan Lambert**, Anthony McDonald, Alfredo Garcia, and [Roberto Calandra](#)  
Transactions on Machine Learning Research 2024
18. [BLISS: Interplanetary Exploration with Swarms of Low-Cost Spacecraft](#)  
Alexander N Alvara, [Lydia Lee](#), Emmanuel Sin, **Nathan Lambert**, Andrew J Westphal, and [Kristofer SJ Pister](#)  
Acta Astronautica 2024

## 2023

19. [Camels in a Changing Climate: Enhancing LM Adaptation with Tulu 2](#) [code]  
[Hamish Ivison](#), [Yizhong Wang](#), [Valentina Pyatkin](#), **Nathan Lambert**, Matthew Peters, [Pradeep Dasigi](#), Joel Jang, David Wadden, [Noah A. Smith](#), Iz Beltagy, and [Hannaneh Hajishirzi](#)  
arXiv Preprint 2023
20. [The Alignment Ceiling: Objective Mismatch in Reinforcement Learning from Human Feedback](#)  
**Nathan Lambert** and [Roberto Calandra](#)  
arXiv Preprint 2023
21. [Entangled Preferences: The History and Risks of Reinforcement Learning and Human Feedback](#)  
**Nathan Lambert**, Thomas Krendl Gilbert, and Tom Zick  
arXiv Preprint 2023

22. *Confidence-Building Measures for Artificial Intelligence: Workshop Proceedings*  
Sarah Shoker, Andrew Reddie, Sarah Barrington, Miles Brundage, Husanjot Chahal, Michael Depp, Bill Drexel, Ritwik Gupta, Marina Favaro, Jake Hecla, Alan Hickey, Margarita Konaev, Kirthi Kumar, **Nathan Lambert**, Andrew Lohn, Cullen O’Keefe, Nazneen Rajani, Michael Sellitto, Robert Trager, Leah Walker, Alexa Wehsener, and Jessica Young  
arXiv Preprint 2023
23. *Reward Reports for Reinforcement Learning* [code]  
Thomas Gilbert, Sarah Dean, **Nathan Lambert**, Tom Zick, and Aaron Snoswell  
AAAI/ACM Conference on AI, Ethics, and Society 2023

## 2022

24. *Measuring Data*  
Margaret Mitchell, Alexandra Sasha Luccioni, **Nathan Lambert**, Marissa Gerchick, Angelina McMillan-Major, Ezinwanne Ozoani, Nazneen Rajani, Tristan Thrush, Yacine Jernite, and Douwe Kiela  
arXiv Preprint 2022
25. *Choices, Risks, and Reward Reports: Charting Public Policy for Reinforcement Learning Systems*  
Thomas Gilbert, Sarah Dean, Tom Zick, and **Nathan Lambert**  
Center for Long-Term Cybersecurity Whitepaper Series 2022
26. *Investigating Compounding Prediction Errors in One-step Dynamics Models* [code]  
**Nathan Lambert**, Roberto Calandra, and Kristofer Pister  
arXiv Preprint 2022
27. *Understanding the Challenges of Exploration for Offline Reinforcement Learning*  
**Nathan Lambert**, Markus Wulfmeier, Arunkumar Byravan, Michael Bloesch, William Whitney, Vibhavari Dasagi, Tim Hertweck, and Martin Riedmiller  
arXiv Preprint 2022

## 2021

28. *MBRL-Lib: A Modular Library for Model-based Reinforcement Learning* [code]  
Luis Pineda, Brandon Amos, Amy Zhang, **Nathan Lambert**, and Roberto Calandra  
arXiv Preprint 2021
29. *BotNet: A Simulator for Studying the Effects of Accurate Communication Models on High-agent-count Multi-agent Control* [code]  
Mark Selden, Felipe Campos, Jason Zhou, **Nathan Lambert**, Daniel Drew, and Kristofer Pister  
Symposium on Multi-Agent and Multi-Robot Systems 2021 (Best Student Paper Finalist)
30. *Axes for Sociotechnical Inquiry in AI Research*  
Sarah Dean, Thomas Krendl Gilbert, **Nathan Lambert**, and Tom Zick  
Transactions on Technology and Society (TTS) 2021 (Authors arranged alphabetically)
31. *On the Importance of Hyperparameter Optimization for Model-based Reinforcement Learning*  
Baohe Zhang, Raghu Rajan, Luis Pineda, **Nathan Lambert**, André Biedenkapp, Kurtland Chua, Frank Hutter, and Roberto Calandra  
International Conference on Artificial Intelligence and Statistics (AISTATS) 2021
32. *Learning Accurate Long-term Dynamics for Model-based Reinforcement Learning* [code]  
**Nathan Lambert**, Albert Wilcox, Howard Zhang, Kristofer SJ Pister, and Roberto Calandra  
International Conference on Decision and Control (CDC) 2021
33. *Nonholonomic Yaw Control of an Underactuated Flying Robot With Model-Based Reinforcement Learning*  
**Nathan Lambert**, Craig Schindler, Daniel Drew, and Kristofer Pister  
Robotics and Automation Letters (RAL) 2021

## 2020

34. *Objective Mismatch in Model-based Reinforcement Learning*  
**Nathan Lambert**, Brandon Amos, Omry Yadan, and Roberto Calandra  
Conference on Learning for Decision and Control (L4DC) 2020

35. [AI Development for the Public Interest: From Abstraction Traps to Sociotechnical Risks](#)  
McKane Andrus, Sarah Dean, Thomas Gilbert, **Nathan Lambert**, and Tom Zick  
International Symposium on Technology and Society (ISTATS) 2020 (Authors arranged alphabetically)
36. [Learning for Microrobot Exploration: Model-based Locomotion, Robust Navigation, and Low-Power Deep Classification](#)  
**Nathan Lambert**, Fahran Toddywala, Brian Liao, Eric Zhu, Lydia Lee, and Kristofer Pister  
International Conference on Manipulation, Automation and Robotics at Small Scales (MARSS) 2020
37. [Learning Generalizable Locomotion Skills with Hierarchical Reinforcement Learning](#)  
Tianyu Li, **Nathan Lambert**, Roberto Calandra, Akshara Rai, and Franziska Meier  
International Conference on Robotics and Automation (ICRA) 2020

## 2019

38. [Low-Level Control of a Quadrotor With Deep Model-Based Reinforcement Learning](#) [code]  
**Nathan Lambert**, Daniel Drew, Joseph Yaconelli, Sergey Levine, Roberto Calandra, and Kristofer Pister  
Robotics and Automation Letters (RAL) 2019

## 2018

39. [Toward Controlled Flight of the Ionocraft: A Flying Microrobot Using Electrohydrodynamic Thrust With Onboard Sensing and No Moving Parts](#)  
Daniel S Drew, **Nathan Lambert**, Craig B Schindler, and Kristofer Pister  
Robotics and Automation Letters (RAL) 2018

## 2017

40. [Enhanced lithium niobate pyroelectric ionizer for chip-scale ion mobility-based gas sensing](#)  
K. B. Vinayakumar, V. Gund, **Nathan Lambert**, S. Lodha, and A. Lal  
Sensors 2017

## Repositories

<a href="#">allenai/awesome-open-source-lms</a> ★346   <i>A curated list of open-source language models</i>	2024
<a href="#">allenai/reward-bench</a> ★641   <i>The first evaluation tool for reward models</i>	2024
<a href="#">allenai/open-instruct</a> ★3.3k   <i>Post-training language models</i>	2023
<a href="#">natolambert/blogcaster</a> ★207   <i>AI tools for multimodal blogging</i>	2023
<a href="#">huggingface/alignment-handbook</a> ★5.4k   <i>RLHF model lessons and recipes</i>	2023
<a href="#">huggingface/trl</a> ★15.9k   <i>Lean library for RLHF</i>	2023
<a href="#">huggingface/simulate</a> ★190   <i>Tool for building embodied AI environments</i>	2022
<a href="#">huggingface/diffusers</a> ★31.3k   <i>Diffusion models library</i>	2022
<a href="#">facebookresearch/mbri-lib</a> ★1k   <i>Model-based reinforcement learning library</i>	2021
<a href="#">natolambert/dynamicslearn</a> ★57   <i>Model-based RL for mixed sim. and real</i>	2020

## Machine Learning Artifacts

Key – M: Model, D: Dataset, S: Space

<a href="#">allenai/OLMo-2-1124-13B-Instruct</a> ★45   M   <i>Round 2!</i>	2024
<a href="#">allenai/Llama-3.1-Tulu-3-8B</a> ★172   M   <i>Our SOTA post-training on Llama 3.1</i>	2024
<a href="#">allenai/tulu-3-sft-mixture</a> ★178   D   <i>Our new SFT dataset</i>	2024
<a href="#">allenai/OLMoE-1B-7B-0924-Instruct</a> ★92   M   <i>Open-source MoE model</i>	2024
<a href="#">allenai/tulu-2.5-preference-data</a> ★19   D   <i>Collection of preference datasets</i>	2024
<a href="#">allenai/reward-bench</a> ★401   S   <i>Benchmark for reward modeling</i>	2024
<a href="#">allenai/OLMo-7B-Instruct</a> ★53   M   <i>A truly open-source chat model</i>	2024
<a href="#">allenai/OLMo-7B</a> ★647   M   <i>Our first open-source language model</i>	2024
<a href="#">allenai/tulu-2-dpo-70b</a> ★157   M   <i>First model scaling DPO</i>	2023
<a href="#">HuggingFaceH4/zephyr-7b-beta</a> ★1.7k+   M   <i>Small and powerful chat model v2</i>	2023
<a href="#">HuggingFaceH4/zephyr-7b-alpha</a> ★1.1k+   M   <i>Small and powerful chat model</i>	2023
<a href="#">HuggingFaceH4/starchat-playground</a> ★n/a   S   <i>Playground for coding assistant models</i>	2023
<a href="#">HuggingFaceH4/starchat-alpha</a> ★232   M   <i>Coding assistant language model</i>	2023
<a href="#">HuggingFaceH4/open-llm-leaderboard</a> ★13.6k+   S   <i>Leaderboard for open instruction-tuned LLMs</i>	2023
<a href="#">HuggingFaceH4/stack-exchange-preferences</a> ★133   D   <i>Preference dataset for RLHF</i>	2023

## Invited Talks

---

### 2025

---

1. An unexpected RL renaissance – Minds and Machines Seminar, Seattle ([slides](#), [recording](#))

### 2024

---

2. (Tutorial) Language Modeling – Neural Information Processing Systems ([slides](#), [recording](#))
3. How to approach post-training for AI applications – [Infer AI Engineer Vancouver](#) ([slides](#), [recording](#))
4. The state of reasoning – [Latent Space @ NeurIPS](#) ([slides](#), [recording](#))
5. Tülu 3 Preview – [Princeton AI Alignment and Safety Seminar \(PASS\)](#) ([slides](#), [recording](#))
6. RewardBench, Evaluating Reward Models for Language Modeling – Deep Learning Classics and Trends ([slides](#))
7. RewardBench – Anthropic Societal Impacts Team

### 2023

---

8. History and Risks of RLHF – Workshop of Social Choice for AI Ethics and Safety
9. History and Risks of RLHF – Workshop on Sociotechnical AI Safety ([slides](#))
10. Bridging RLHF from LLMs back to control – [CoRL LangRob Workshop](#) ([slides](#), [recording](#))
11. Objective Mismatch in Reinforcement Learning from Human Feedback – [Deep Learning Classics and Trends](#) ([Slides Available](#), [Recording Available](#))
12. (Tutorial) Reinforcement Learning from Human Feedback – International Conference on Machine Learning ([Slides Available](#), [Recording Available](#))
13. (Tutorial) Steering language models with reinforcement learning from human feedback and constitutional AI – ACM Conference on Fairness, Accountability, and Transparency ([Slides Available](#))
14. Reinforcement Learning from Human Feedback; Open and Academic Progress – UCL Dark Lab ([Recording Available](#), [Slides](#))
15. Reinforcement Learning from Human Feedback; Pathways to Open Reproduction of ChatGPT – Microsoft Data Science Gems

### 2022

---

16. Reward Reports for Reinforcement Learning – [ICML Workshop on Responsible Decision Making in Dynamic Environments](#) ([Recording Available](#), [Slides](#))
17. Synthesizing Robotic Controllers with Model-based Reinforcement Learning – Lead The Future
18. Planning through Exploration and Exploitation in Model-based Reinforcement Learning – University of Pennsylvania – Perception, Action, and Learning Group ([Recording Available](#), [Slides](#))
19. (Job Talk) Legible Reinforcement Learning via Dynamics Models – Microsoft Research ([Slides](#))
20. The Challenges of Exploration for Offline Reinforcement Learning – DeepMind Robotics All Hands
21. (Job Talk) Synergy of Prediction and Control in Model-based Reinforcement Learning – Amazon Robotics & AI ([Slides](#))

### 2021

---

22. (Job Talk) Control-oriented Predictions in Model-based Reinforcement Learning – Cruise AI
23. Improving Model Predictive Control in Model-based Reinforcement Learning – [Cornell Robotics Seminar](#) ([Recording Available](#), [Slides](#))

### 2020

---

24. Model Learning for Low-level Control in Robotics – [UC Berkeley Semiautonomous Seminar](#) ([Recording Available](#), [Slides](#))

### 2019

---

25. – [UC Berkeley Semiautonomous Seminar](#)

## Mentorship

---

[Saumya Malik](#) (Ai2 Pre-Doctoral Researcher '25)  
[Jacob Morrison](#) (Ai2 Pre-Doctoral Researcher '25)  
[Mark Selden](#) (UC Berkeley BS '22)

2024  
2024  
2020



<a href="#">Albert Wilcox</a> (UC Berkeley BS '22, Ph.D. student at Georgia Tech)	2019
<a href="#">Jason Zhou</a> (UC Berkeley BS, MS '21 to <a href="#">Matician</a> )	2019
<a href="#">Felipe Campos</a> (UC Berkeley BS '20 to <a href="#">Armstrong Robotics</a> )	2018
<a href="#">Howard Zhang</a> (UC Berkeley BS, MS'21 to UCLA PhD)	2018

## Peer Review

Empirical Methods in Natural Language Processing, Demo Track	2024
Transactions on Machine Learning Research (TMLR)	2024
Conference on Machine Learning (ICML) (count is 1 unless labelled)	2020, 2022 (3), 2023, 2024 (3)
Conference on Neural Information Processing Systems (NeurIPs)	2022 (2), 2023, 2024
Conference on Learning Representations (ICLR) (*Outstanding Reviewer)	2021* (3), 2022 (3)
Conference on Robot Learning (CORL)	2020
Conference on Robotics and Automation (ICRA)	2020, 2021, 2022 (2)
Conference on Intelligent Robots and Systems (IROS)	2021, 2022 (2)
Robotics - Science and Systems (RSS)	2022
Conference on Decision and Control (CDC)	2021
Robotics and Automation Letters (RA-L)	2019, 2020, 2022
Transactions on Cybernetics	2019, 2020

## Professional Activities

Associate Editor (AE), Conference on Intelligent Robots and Systems (IROS)	2023
<a href="#">Farama Foundation Board of Technical Advisors</a>	2022 – 2024
<a href="#">NeurIPs Workshop on Robot Learning Organizer</a>	2021, 2022
<a href="#">Member of Well-Being in Machine Learning</a>	2021 – 2024
<a href="#">RLDM Workshop on Building Accountable and Transparent RL Organizer</a>	2022
Berkeley AI Research Audio & Video Team	2021 – 2022
<a href="#">Machine Learning Collective Office Hours</a>	2021 – cont.
<a href="#">Tapia Panel on Student Mental Health Organizer</a>	2021
<a href="#">Founder of UC Berkeley EECS Equal Access to Application Assistance (EAAA) Program</a>	2020 – 2022
Wellness Coordinator for UC Berkeley Electrical Engineering Graduate Student Assembly (EEGSA)	2020 – 2022
Bay Area Teachers in Schools	2017

## Policy Engagement

<a href="#">Partnership on AI Partner Forum, Panel on AI Agents</a>	2024
<a href="#">Columbia Convening on Openness and AI</a>	2024
NAIRR Panel at AI Expo for National Competitiveness	2024
<a href="#">IAS AI Policy and Governance Working Group</a>	2024

## Teaching

NLP with Deep Learning (Stanford University CS224N), Guest Lecture, Life after DPO ( <a href="#">slides</a> , <a href="#">course</a> )	Sp2024
Transformers United (Stanford University CS25N), Guest Lecture, hi story of open alignment ( <a href="#">slides</a> , <a href="#">recording</a> )	Sp2024
Policy Challenges of AI (Harvard University), Guest lecture on open-source AI ( <a href="#">slides</a> , <a href="#">course</a> )	Sp2024
Machine Learning from Human Preferences (Stanford University CS329H), Guest lecture on RLHF ( <a href="#">slides</a> , <a href="#">course</a> )	Fa2023
AI History (Seoul National University, School of Law), Guest lecture on RL History ( <a href="#">course</a> )	Fa2023
HuggingFace Deep RL Course (RLHF, from 0 to ChatGPT), Online (>160k views) ( <a href="#">watch</a> )	Win.2022
Introduction to Artificial Intelligence (UCB CS188), TA	Su2020, Fa2020
Introduction to Artificial Intelligence (UCB CS188), Instructor <i>lectured to 800+ students</i>	Sp2020
Designing Information Devices and Systems II (UCB EE16B), TA	Fa2019
Integrated Micro Sensors and Actuators (Cornell ECE4320), Grader	Sp2017
Mathematics of Signal and System Analysis (Cornell ECE 3250), TA	Fa2016

## Extracurriculars

---

The Retort AI Podcast	2023 – cont.
Interconnects AI Blog	2020 – cont.
Cornell Varsity Lightweight Rowing	2013 – 2017
Novice Rowing Coach	2017 – 2018
Graduates for Engaged and Extended Scholarship in Computing and Engineering President	2021 – 2022