Nathan Lambert

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 ✓ Last updated on October 16, 2025

I research data-driven decision making, including progressing reinforcement learning algorithms, applying them to real-world problems such as large language models and robotics, and planning for the societal implications therein.

Education

Ph.D. in Electrical Engineering and Computer Science, University of California, Berkeley (4.0/4.0) 2017 – 2022

Synergy of Prediction and Control in Model-based Reinforcement Learning

Advisors: Kristofer S.J. Pister, Roberto Calandra Committee: Sergey Levine, Claire Tomlin

B.S. in Electrical and Computer Engineering, Cornell University (4.0/4.0)

2013 - 2017

Industry Experience

Allen Institute for AI, Seattle, WA Research Scientist	2023 - cont.
HuggingFace, Remote Research Scientist and RLHF Team Lead	2022 - 2023
DeepMind, London (Virtual) Research Intern (Host: Martin Riedmiller)	2021
Facebook AI, Menlo Park Research Intern and Student Researcher (Host: Roberto Calandra)	2019 - 2020
Tesla, Palo Alto Test Engineering Intern	2015

Honors & Awards

CVPR Best Paper Honorable Mention (Molmo & Pixmo)	2025
Best Reasoning & RL Talk, AI Engineer World's Fair	2025
Ai2 The Cat Herder	2024
ACL Best Resource Paper Award (Dolma)	2024
ACL Best Theme Paper Award (OLMo)	2024
GeekWire Innovation of the year (OLMo)	2024
Reward Reports - Auditing Al Mozilla Technology Fund Cohort	2023
Best Oral Presentation; Berkeley Sensor and Actuator Sensor Spring Review	2022
Best Student Paper Finalist; IEEE Symposium on Multi-Robot and Multi-Agent Systems	2021
Berkeley EECS Demetri Angelakos Memorial Achievement Award	2021
Heart to Humanity Eternal (H2H8) Pioneer	2021
NDSEG Graduate Research Fellowship Program Top 200	2018
NSF Graduate Research Fellowship Program Honorable Mention	2017, 2018
Berkeley EECS Department Fellowship	2017
Eight undergraduate scholarships	2013 – 2017

Cornell Rowing Charles E. Courtney Award, Tau Beta Pi Scholarship, Southeastern New England Defense Industry Alliance STEM Scholarship 2016, 2017, Cornell Athletics 400 Club Induction, Beta Pi Induction, Eta Kappu Nu Induction, American Society of Engineering Education SMART Scholar Award

Publications [Google Scholar: 7.5k+ citations and an h-index of 34, Semantic Scholar]

Representative publications that I am a primary author on are highlighted.

2025

- 1. Spurious Rewards: Rethinking Training Signals in RLVR
 - Rulin Shao, Shuyue Stella Li, Rui Xin, Scott Geng, Yiping Wang, Sewoong Oh, Simon Shaolei Du, Nathan Lambert, Sewon Min, Ranjay Krishna, Yulia Tsvetkov, Hannaneh Hajishirzi, Pang Wei Koh, and Luke Zettlemoyer arXiv Preprint 2025
- RewardBench 2: Advancing Reward Model Evaluation
 Saumya Malik, Valentina Pyatkin, Sander Land, Jacob Morrison, Noah A Smith, Hannaneh Hajishirzi, and Nathan Lambert
 arXiv Preprint 2025

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- 3. Reinforcement Learning from Human Feedback
 Nathan Lambert
 Book 2025
- 4. RewardBench: Evaluating Reward Models for Language Modeling [code]

 Nathan Lambert, Valentina Pyatkin, Jacob Morrison, LJ Miranda, Bill Yuchen Lin, Khyathi Chandu, Nouha Dziri, Sachin Kumar, Tom Zick, Yejin Choi, Noah A. Smith, and Hannaneh Hajishirzi NAACL 2025

2024

- 5. 2 OLMo 2 Furious [code]
 - Team OLMo, Pete Walsh, Luca Soldaini, Dirk Groeneveld, Kyle Lo, Shane Arora, Akshita Bhagia, Yuling Gu, Shengyi Huang, Matt Jordan, Nathan Lambert, Dustin Schwenk, Oyvind Tafjord, Taira Anderson, David Atkinson, Faeze Brahman, Christopher Clark, Pradeep Dasigi, Nouha Dziri, Michal Guerquin, Hamish Ivison, Pang Wei Koh, Jiacheng Liu, Saumya Malik, William Merrill, Lester James V. Miranda, Jacob Morrison, Tyler Murray, Crystal Nam, Valentina Pyatkin, Aman Rangapur, Michael Schmitz, Sam Skjonsberg, David Wadden, Christopher Wilhelm, Michael Wilson, Luke Zettlemoyer, Ali Farhadi, Noah A. Smith, and Hannaneh Hajishirzi arXiv Preprint 2024
- 6. Tülu 3: Pushing Frontiers in Open Language Model Post-Training [code]

 Nathan Lambert, Jacob Morrison, Valentina Pyatkin, Shengyi Huang, Hamish Ivison, Faeze Brahman,
 Lester James V. Miranda, Alisa Liu, Nouha Dziri, Shane Lyu, Yuling Gu, Saumya Malik, Victoria Graf,
 Jena D. Hwang, Jiangjiang Yang, Ronan Le Bras, Oyvind Tafjord, Chris Wilhelm, Luca Soldaini, Noah A. Smith,
 Yizhong Wang, Pradeep Dasigi, and Hannaneh Hajishirzi
 Technical Report 2024
- 7. Molmo and pixmo: Open weights and open data for state-of-the-art multimodal models [code] Matt Deitke, Christopher Clark, Sangho Lee, Rohun Tripathi, Yue Yang, Jae Sung Park, Mohammadreza Salehi, Niklas Muennighoff, Kyle Lo, Luca Soldaini, Jiasen Lu, Taira Anderson, Erin Bransom, Kiana Ehsani, Huong Ngo, YenSung Chen, Ajay Patel, Mark Yatskar, Christopher Callison-Burch, Andrew Head, Rose Hendrix, Favyen Bastani, Eli VanderBilt, Nathan Lambert, Yvonne Chou, Arnavi Chheda, Jenna Sparks, Sam Skjonsberg, Michael Schmitz, Aaron Sarnat, Byron Bischoff, Pete Walsh, Christopher Newell, Piper Wolters, Tanmay Gupta, Kuo-Hao Zeng, Jon Borchardt, Dirk Groeneveld, Jennifer Dumas, Crystal Nam, Sophie Lebrecht, Caitlin Marie Wittlif, Carissa Schoenick, Oscar Michel, Ranjay Krishna, Luca Weihs, Noah A. Smith, Hanna Hajishirzi, Ross Girshick, Ali Farhadi, and Aniruddha Kembhavi arXiv Preprint 2024
- 8. M-RewardBench: Evaluating Reward Models in Multilingual Settings [code]
 Srishti Gureja, Lester James V Miranda, Shayekh Bin Islam, Rishabh Maheshwary, Drishti Sharma,
 Gusti Winata, Nathan Lambert, Sebastian Ruder, Sara Hooker, and Marzieh Fadaee
 arXiv Preprint 2024
- 9. OLMoE: Open Mixture-of-Experts Language Models [code]
 Niklas Muennighoff, Luca Soldaini, Dirk Groeneveld, Kyle Lo, Jacob Daniel Morrison, Sewon Min, Weijia Shi,
 Pete Walsh, Oyvind Tafjord, Nathan Lambert, Yuling Gu, Shane Arora, Akshita Bhagia, Dustin Schwenk,
 David Wadden, Alexander Wettig, Binyuan Hui, Tim Dettmers, Douwe Kiela, Ali Farhadi, Noah A. Smith,
 Pang Wei Koh, Amanpreet Singh, and Hanna Hajishirzi
 arXiv Preprint 2024
- 10. Towards a Framework for Openness in Foundation Models: Proceedings from the Columbia Convening on Openness in Artificial Intelligence
 - Adrien Basdevant, Camille François, Victor Storchan, Kevin Bankston, Ayah Bdeir, Brian Behlendorf, Merouane Debbah, Sayash Kapoor, Yann LeCun, Mark Surman, Helen King-Turvey, **Nathan Lambert**, Stefano Maffulli, Nik Marda, Govind Shivkumar, and Justine Tunney Workshop Proceedings 2024
- Unpacking DPO and PPO: Disentangling Best Practices for Learning from Preference Feedback [code]
 Hamish Ivison, Yizhong Wang, Jiacheng Liu, Zeqiu Wu, Valentina Pyatkin, Nathan Lambert, Noah A Smith,
 Yejin Choi, and Hannaneh Hajishirzi
 NeurIPS 2024

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12. Wildguard: Open one-stop moderation tools for safety risks, jailbreaks, and refusals of Ilms [code]
Seungju Han, Kavel Rao, Allyson Ettinger, Liwei Jiang, Bill Yuchen Lin, Nathan Lambert, Yejin Choi, and Nouha Dziri

NeurIPS Dataset and Benchmarks 2024

- Self-directed synthetic dialogues and revisions technical report
 Nathan Lambert, Hailey Schoelkopf, Aaron Gokaslan, Luca Soldaini, Valentina Pyatkin, and Louis Castricato
 Technical Report 2024
- 14. Dolma: an Open Corpus of Three Trillion Tokens for Language Model Pretraining Research [code] Luca Soldaini, Rodney Kinney, Akshita Bhagia, Dustin Schwenk, David Atkinson, Russell Authur, Ben Bogin, Khyathi Chandu, Jennifer Dumas, Yanai Elazar, Valentin Hofmann, Ananya Harsh Jha, Sachin Kumar, Li Lucy, Xinxi Lyu, Nathan Lambert, Ian Magnusson, Jacob Morrison, Niklas Muennighoff, Aakanksha Naik, Crystal Nam, Matthew E. Peters, Abhilasha Ravichander, Kyle Richardson, Zejiang Shen, Emma Strubell, Nishant Subramani, Oyvind Tafjord, Pete Walsh, Luke Zettlemoyer, Noah A. Smith, Hannaneh Hajishirzi, Iz Beltagy, Dirk Groeneveld, Jesse Dodge, and Kyle Lo ACL 2024 (Best Paper Award)
- 15. OLMo: Accelerating the Science of Language Models [code]

Dirk Groeneveld, Iz Beltagy, Pete Walsh, Akshita Bhagia, Rodney Kinney, Oyvind Tafjord, Ananya Harsh Jha, Hamish Ivison, Ian Magnusson, Yizhong Wang, Shane Arora, David Atkinson, Russell Authur, Khyathi Raghavi Chandu, Arman Cohan, Jennifer Dumas, Yanai Elazar, Yuling Gu, Jack Hessel, Tushar Khot, William Merrill, Jacob Morrison, Niklas Muennighoff, Aakanksha Naik, Crystal Nam, Matthew E. Peters, Valentina Pyatkin, Abhilasha Ravichander, Dustin Schwenk, Saurabh Shah, Will Smith, Emma Strubell, Nishant Subramani, Mitchell Wortsman, Pradeep Dasigi, Nathan Lambert, Kyle Richardson, Luke Zettlemoyer, Jesse Dodge, Kyle Lo, Luca Soldaini, Noah A. Smith, and Hannaneh Hajishirzi ACL 2024 (Best Paper Award)

16. A Survey on Data Selection for Language Models

Alon Albalak, Yanai Elazar, Sang Michael Xie, Shayne Longpre, **Nathan Lambert**, Xinyi Wang, Niklas Muennighoff, Bairu Hou, Liangming Pan, Haewon Jeong, Colin Raffel, Shiyu Chang, Tatsunori Hashimoto, and William Yang Wang TMLR 2024

- 17. Social Choice Should Guide Al Alignment in Dealing with Diverse Human Feedback
 - Vincent Conitzer, Rachel Freedman, Jobst Heitzig, Wesley H. Holliday, Bob M. Jacobs, **Nathan Lambert**, Milan Mossé, Eric Pacuit, Stuart Russell, Hailey Schoelkopf, Emanuel Tewolde, and William S. Zwicker ICML Position Paper 2024
- D2PO: Discriminator-Guided DPO with Response Evaluation Models
 Prasann Singhal, Nathan Lambert, Scott Niekum, Tanya Goyal, and Greg Durrett
 COLM 2024
- 19. Zephyr: Direct Distillation of LM Alignment [code]

Lewis Tunstall, Edward Beeching, Nathan Lambert, Nazneen Rajani, Kashif Rasul, Younes Belkada, Shengyi Huang, Leandro von Werra, Clémentine Fourrier, Nathan Habib, Nathan Sarrazin, Omar Sanseviero, Alexander M. Rush, and Thomas Wolf COLM 2024

- A Unified View on Solving Objective Mismatch in Model-Based Reinforcement Learning
 Ran Wei, Nathan Lambert, Anthony McDonald, Alfredo Garcia, and Roberto Calandra
 Transactions on Machine Learning Research 2024
- 21. BLISS: Interplanetary Exploration with Swarms of Low-Cost Spacecraft
 Alexander N Alvara, Lydia Lee, Emmanuel Sin, Nathan Lambert, Andrew J Westphal, and Kristofer SJ Pister
 Acta Astraunica 2024

2023

22. Camels in a Changing Climate: Enhancing LM Adaptation with Tulu 2 [code]
Hamish Ivison, Yizhong Wang, Valentina Pyatkin, Nathan Lambert, Matthew Peters, Pradeep Dasigi,
Joel Jang, David Wadden, Noah A. Smith, Iz Beltagy, and Hannaneh Hajishirzi
arXiv Preprint 2023

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- The Alignment Ceiling: Objective Mismatch in Reinforcement Learning from Human Feedback Nathan Lambert and Roberto Calandra arXiv Preprint 2023
- 24. Entangled Preferences: The History and Risks of Reinforcement Learning and Human Feedback Nathan Lambert, Thomas Krendl Gilbert, and Tom Zick arXiv Preprint 2023
- 25. Confidence-Building Measures for Artificial Intelligence: Workshop Proceedings

Sarah Shoker, Andrew Reddie, Sarah Barrington, Miles Brundage, Husanjot Chahal, Michael Depp, Bill Drexel, Ritwik Gupta, Marina Favaro, Jake Hecla, Alan Hickey, Margarita Konaev, Kirthi Kumar, Nathan Lambert, Andrew Lohn, Cullen O'Keefe, Nazneen Rajani, Michael Sellitto, Robert Trager, Leah Walker, Alexa Wehsener, and Jessica Young arXiv Preprint 2023

Reward Reports for Reinforcement Learning [code]
 Thomas Gilbert, Sarah Dean, Nathan Lambert, Tom Zick, and Aaron Snoswell AAAI/ACM Conference on AI, Ethics, and Society 2023

2022.....

27. Measuring Data

Margaret Mitchell, Alexandra Sasha Luccioni, Nathan Lambert, Marissa Gerchick, Angelina McMillan-Major, Ezinwanne Ozoani, Nazneen Rajani, Tristan Thrush, Yacine Jernite, and Douwe Kiela arXiv Preprint 2022

- 28. Choices, Risks, and Reward Reports: Charting Public Policy for Reinforcement Learning Systems
 Thomas Gilbert, Sarah Dean, Tom Zick, and Nathan Lambert
 Center for Long-Term Cybersecurity Whitepaper Series 2022
- 29. Investigating Compounding Prediction Errors in One-step Dynamics Models [code] Nathan Lambert, Roberto Calandra, and Kristofer Pister arXiv Preprint 2022
- 30. Understanding the Challenges of Exploration for Offline Reinforcement Learning
 Nathan Lambert, Markus Wulfmeier, Arunkumar Byravan, Michael Bloesch, William Whitney,
 Vibhavari Dasagi, Tim Hertweck, and Martin Riedmiller
 arXiv Preprint 2022

2021

- 31. MBRL-Lib: A Modular Library for Model-based Reinforcement Learning [code] Luis Pineda, Brandon Amos, Amy Zhang, Nathan Lambert, and Roberto Calandra arXiv Preprint 2021
- 32. BotNet: A Simulator for Studying the Effects of Accurate Communication Models on High-agent-count Multi-agent Control [code]

Mark Selden, Felipe Campos, Jason Zhou, Nathan Lambert, Daniel Drew, and Kristofer Pister Symposium on Multi-Agent and Multi-Robot Systems 2021 (Best Student Paper Finalist)

- 33. Axes for Sociotechnical Inquiry in Al Research
 Sarah Dean, Thomas Krendl Gilbert, Nathan Lambert, and Tom Zick
 Transactions on Technology and Society (TTS) 2021 (Authors arranged alphabetically)
- 34. On the Importance of Hyperparameter Optimization for Model-based Reinforcement Learning Baohe Zhang, Raghu Rajan, Luis Pineda, Nathan Lambert, André Biedenkapp, Kurtland Chua, Frank Hutter, and Roberto Calandra International Conference on Artificial Intelligence and Statistics (AISTATS) 2021
- 35. Learning Accurate Long-term Dynamics for Model-based Reinforcement Learning [code]

 Nathan Lambert, Albert Wilcox, Howard Zhang, Kristofer SJ Pister, and Roberto Calandra
 International Conference on Decision and Control (CDC) 2021
- 36. Nonholonomic Yaw Control of an Underactuated Flying Robot With Model-Based Reinforcement Learning Nathan Lambert, Craig Schindler, Daniel Drew, and Kristofer Pister Robotics and Automation Letters (RAL) 2021

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202	0	
	Objective Mismatch in Model-based Reinforcement Learning Nathan Lambert, Brandon Amos, Omry Yadan, and Roberto Calandra Conference on Learning for Decision and Control (L4DC) 2020	
38.	Al Development for the Public Interest: From Abstraction Traps to Sociotechnical Risks McKane Andrus, Sarah Dean, Thomas Gilbert, Nathan Lambert, and Tom Zick International Symposium on Technology and Society (ISTATS) 2020 (Authors arranged alphabetical	ılly)
39.	Learning for Microrobot Exploration: Model-based Locomotion, Robust Navigation, and Low-Power Classification	Deep
	Nathan Lambert, Fahran Toddywala, Brian Liao, Eric Zhu, Lydia Lee, and Kristofer Pister International Conference on Manipulation, Automation and Robotics at Small Scales (MARSS) 202	0
40.	Learning Generalizable Locomotion Skills with HierarchicalReinforcement Learning Tianyu Li, Nathan Lambert, Roberto Calandra, Akshara Rai, and Franziska Meier International Conference on Robotics and Automation (ICRA) 2020	
201	9	
41.	Low-Level Control of a Quadrotor With Deep Model-Based Reinforcement Learning [code] Nathan Lambert, Daniel Drew, Joseph Yaconelli, Sergey Levine, Roberto Calandra, and Kristofer Robotics and Automation Letters (RAL) 2019	Pister
201	8	
42.	Toward Controlled Flight of the Ionocraft: A Flying Microrobot Using Electrohydrodynamic Thrust V Sensing and No Moving Parts Daniel S Drew, Nathan Lambert, Craig B Schindler, and Kristofer Pister Robotics and Automation Letters (RAL) 2018	Vith Onboard
201	7	
43.	Enhanced lithium niobate pyroelectric ionizer for chip-scale ion mobility-based gas sensing K. B. Vinayakumar, V. Gund, Nathan Lambert, S. Lodha, and A. Lal Sensors 2017	
Re	positories	
	lambert/rlhf-book ★1.3k Book on RLHF	2025
	ai/awesome-open-source-lms ★346 A curated list of open-source language models	2024
	ai/reward-bench ★641 The first evaluation tool for reward models ai/open-instruct ★3.3k Post-training language models	2024 2023
	lambert/blogcaster ★207 AI tools for multimodal blogging	2023
	singface/alignment-handbook ★5.4k RLHF model lessons and recipes	2023
	singface/trl ★15.9k Lean library for RLHF	2023
	singface/simulate ★190 Tool for building embodied AI environments	2022
	gingface/diffusers ★31.3k Diffusion models library pookresearch/mbrl-lib ★1k Model-based reinforcement learning library	2022 2021
	lambert/dynamicslearn ★57 Model-based RL for mixed sim. and real	2020
Ma	nchine Learning Artifacts	

Key — M: Model, D: Dataset, S: Space	
allenai/OLMo-2-1124-13B-Instruct ★ 45 M Round 2!	2024
allenai/Llama-3.1-Tulu-3-8B ★ 172 M Our SOTA post-training on Llama 3.1	2024
allenai/tulu-3-sft-mixture ★ 178 D Our new SFT dataset	2024
allenai/OLMoE-1B-7B-0924-Instruct ★ 92 M Open-source MoE model	2024
allenai/tulu-2.5-preference-data ★ 19 D Collection of preference datasets	2024
allenai/reward-bench ★ 401 S Benchmark for reward modeling	2024
allenai/OLMo-7B-Instruct ★ 53 M A truly open-source chat model	2024
allenai/OLMo-7B ★ 647 M Our first open-source language model	2024
allenai/tulu-2-dpo-70b ★ 157 M First model scaling DPO	2023

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HuggingFaceH4/zephyr-7b-beta ★ 1.7k+ M Small and powerful chat model v2	2023
HuggingFaceH4/zephyr-7b-alpha ★ 1.1k+ M Small and powerful chat model	2023
HuggingFaceH4/starchat-playground [deleted] S Playground for coding assistant models (removed)	2023
HuggingFaceH4/starchat-alpha ★ 232 M Coding assistant language model	2023
HuggingFaceH4/open-Ilm-leaderboard ★ 13.6k+ S Leaderboard for open instruction-tuned LLMs	2023
HuggingFaceH4/stack-exchange-preferences ★ 133 D Preference dataset for RLHF	2023

Invited Talks

2025

- 1. Open Models in 2025 The Curve (slides)
- 2. Building a thinking Olmo Conference on Language Modeling (COLM), ScalR Workshop (slides)
- 3. Reasoning; What comes next? VentureBeat Transform
- 4. The art of a good (reasoning) model Enterprise AI Agent Summit, Seattle WA (slides, recording)
- 5. A taxonomy for next-generation reasoning models AI Engineer World's Fair (slides, recording)
- 6. Experiments with Reinforcement Learning with Verifiable Rewards USC Information Sciences Institute (slides, recording)
- 7. The RL Era of Language Models UC Santa Cruz, Silicon Valley Extension (slides, recording)
- 8. An unexpected RL renaissance Minds and Machines Seminar, Seattle (slides, recording)

2024

- 9. (Tutorial) Language Modeling Neural Information Processing Systems (slides, recording)
- 10. How to approach post-training for Al applications Infer Al Engineer Vancouver (slides, recording)
- 11. The state of reasoning Latent Space @ NeurIPS (slides, recording)
- 12. Tülu 3 Preview Princeton Al Alignment and Safety Seminar (PASS) (slides, recording)
- 13. RewardBench, Evaluating Reward Models for Language Modeling Deep Learning Classics and Trends (slides)
- 14. RewardBench Anthropic Societal Impacts Team

2023.

- 15. History and Risks of RLHF Workshop of Social Choice for AI Ethics and Safety
- 16. History and Risks of RLHF Workshop on Sociotechnical Al Safety $\,$ (slides)
- 17. Bridging RLHF from LLMs back to control CoRL LangRob Workshop (slides, recording)
- 18. Objective Mismatch in Reinforcement Learning from Human Feedback Deep Learning Classics and Trends (Slides Available, Recording Available)
- 19. (Tutorial) Reinforcement Learning from Human Feedback International Conference on Machine Learning (Slides Available, Recording Available)
- 20. (Tutorial) Steering language models with reinforcement learning from human feedback and constitutional AI ACM Conference on Fairness, Accountability, and Transparency (Slides Available)
- 21. Reinforcement Learning from Human Feedback; Open and Academic Progress UCL Dark Lab (Recording Available, Slides)
- 22. Reinforcement Learning from Human Feedback; Pathways to Open Reproduction of ChatGPT Microsoft Data Science Gems

2022

- 23. Reward Reports for Reinforcement Learning ICML Workshop on Responsible Decision Making in Dynamic Environments (Recording Available, Slides)
- 24. Synthesizing Robotic Controllers with Model-based Reinforcement Learning Lead The Future
- 25. Planning through Exploration and Exploitation in Model-based Reinforcement Learning University of Pennsylvania Perception, Action, and Learning Group (Recording Available, Slides)
- 26. (Job Talk) Legible Reinforcement Learning via Dynamics Models Microsoft Research (Slides)
- 27. The Challenges of Exploration for Offline Reinforcement Learning DeepMind Robotics All Hands
- 28. (Job Talk) Synergy of Prediction and Control in Model-based Reinforcement Learning Amazon Robotics & AI (Slides)

2021

29. (Job Talk) Control-oriented Predictions in Model-based Reinforcement Learning - Cruise AI

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30. Improving Model Predictive Control in Model-based Reinforcement Learning – Cornel Available, Slides)	I Robotics Seminar (Recording
2020	
31. Model Learning for Low-level Control in Robotics – UC Berkeley Semiautonomous Sem	inar (Recording Available, Slides)
2019	
32. – UC Berkeley Semiautonomous Seminar	
Mentorship	
Daniel Marta (Thesis Committee Member) Saumya Malik (Ai2 Pre-Doctoral Researcher '25) Jacob Morrison (Ai2 Pre-Doctoral Researcher '25) Mark Selden (UC Berkeley BS '22) Albert Wilcox (UC Berkeley BS '22, Ph.D. student at Georgia Tech) Jason Zhou (UC Berkeley BS, MS '21 to Matician) Felipe Campos (UC Berkeley BS '20 to Armstrong Robotics) Howard Zhang (UC Berkeley BS, MS'21 to UCLA PhD)	2025 2024 2024 2020 2019 2019 2018 2018
Peer Review	
	2025 (1) 2024 2024 2024 2020, 2022 (3), 2023, 2024 (3) 2022 (2), 2023, 2024, 2025 (3) 2020 2020, 2021, 2022 (2) 2021, 2022 (2) 2022 2021 2019, 2020, 2022 2019, 2020
Professional Activities	
Area Chair (AC), Conference on Language Modeling (COLM) Associate Editor (AE), Conference on Intelligent Robots and Systems (IROS) Farama Foundation Board of Technical Advisors NeurlPs Workshop on Robot Learning Organizer Member of Well-Being in Machine Learning RLDM Workshop on Building Accountable and Transparent RL Organizer Berkeley AI Research Audio & Video Team Machine Learning Collective Office Hours Tapia Panel on Student Mental Health Organizor Founder of UC Berkeley EECS Equal Access to Application Assistance (EAAA) Program Wellness Coordinator for UC Berkeley Electrical Engineering Graduate Student Assembly Bay Area Teachers in Schools	
Policy Engagement	
Partnership on Al Partner Forum, Panel on Al Agents Columbia Convening on Openness and Al	2024 2024

Teaching

Advances and Challenges in Language Models, Reasoning, and Al Agents (U.W. CSE599H), Guest Lecture, Ai	ı introduc-
tion to post-training (slides, course)	Sp2025
NLP with Deep Learning (Stanford University CS224N), Guest Lecture, Life after DPO (slides, course, recording	s) Sp2024
Transformers United (Stanford University CS25N), Guest Lecture, hi story of open alignment (slides, recording	s) Sp2024
Policy Challenges of AI (Harvard University), Guest lecture on open-source AI (slides, course)	Sp2024
Machine Learning from Human Preferences (Stanford University CS329H), Guest lecture on RLHF (slides, cours	e) Fa2023
Al History (Seoul National University, School of Law), Guest lecture on RL History (course)	Fa2023
HuggingFace Deep RL Course (RLHF, from 0 to ChatGPT), Online (>160k views) (watch)	Win.2022
Introduction to Artificial Intelligence (UCB CS188), TA Su202	0, Fa2020
Introduction to Artificial Intelligence (UCB CS188), Instructor lectured to 800+ students	Sp2020
Designing Information Devices and Systems II (UCB EE16B), TA	Fa2019
Integrated Micro Sensors and Actuators (Cornell ECE4320), Grader	Sp2017
Mathematics of Signal and System Analysis (Cornell ECE 3250), TA	Fa2016

Extracurriculars

The Retort Al Podcast	2023 - cont.
Interconnects Al Blog	2020 - cont.
Cornell Varsity Lightweight Rowing	2013 - 2017
Novice Rowing Coach	2017 - 2018
Graduates for Engaged and Extended Scholarship in Computing and Engineering President	2021 - 2022

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