

¹ **neonSoilFlux: An R Package for Continuous
2 Sensor-Based Estimation of Soil CO₂ Fluxes**

³ John Zobitz¹ Edward Ayres² Zoey Werbin³ Ridwan Abdi¹
⁴ Natalie Ashburner-Wright⁴ Lillian Brown⁴
⁵ Ryan Frink-Sobierajski⁴ Lajntxiag Lee¹ Dijonë Mehmeti¹
⁶ Christina Tran⁴ Ly Xiong¹ Naupaka Zimmerman^{4,5}

⁷ ¹ Augsburg University, 2211 Riverside Avenue, Minneapolis, MN 55454

⁸ ² National Ecological Observatory Network, Battelle, 1685 38th Street, Suite 100, Boulder,
⁹ CO 80301

¹⁰ ³ Boston University, 5 Cummington Street, Boston, MA 02215

¹¹ ⁴ University of San Francisco, 2130 Fulton Street, San Francisco, CA 94117

¹² ⁵ University of Kansas, 1450 Jayhawk Boulevard, Lawrence, KS 66045

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23 **Conflict of Interest Statements**

24 None of the authors have a financial, personal, or professional conflict of interest related to
25 this work.

26 **Author Contributions**

27 Conceptualization: JZ, NZ; Methodology: EA, JZ, NZ; Software: JZ, NZ, ZW, E A, DM, RA,
28 LX, LL; Validation: JZ, NZ; Formal Analysis: JZ, NZ, DM, RA, LX, LL; Investigation: JZ,
29 NZ, RF-S, CT, NA-W, LB; Resources: JZ, NZ; Data curation: JZ, NZ, DM, LX; Writing
30 – original draft: JZ, NZ; Writing – review and editing: JZ, NZ, ZW, EA, CT, DM, LX,;
31 Visualization: JZ, NZ, DM, RA, LX; Supervision: JZ; NZ; Project Administration: JZ; NZ;
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33 **Data Availability**

34 Anonymous field-collected data, `neonSoilFlux` calculated outputs, and manuscript-generating
35 code for peer review are provided as supplemental files. An anonymous link for peer-review

³⁶ is here: <https://doi.org/10.5281/zenodo.1695117>. This will be made publicly available upon
³⁷ publication.

³⁸ **1 Abstract**

³⁹ Accurate quantification of soil carbon fluxes is essential to reduce uncertainty in estimates of
⁴⁰ the terrestrial carbon sink. However, these fluxes vary over time and across ecosystem types
⁴¹ and so it can be difficult to estimate them accurately across large scales. The flux gradient
⁴² method estimates soil carbon fluxes using co-located measurements of soil CO₂ concentration,
⁴³ soil temperature, soil moisture, and other soil properties. The National Ecological Observatory
⁴⁴ Network (NEON) provides such data across 20 ecoclimatic domains spanning the continental
⁴⁵ U.S., Puerto Rico, Alaska, and Hawai'i. We present an R software package (`neonSoilFlux`)
⁴⁶ that acquires soil environmental data to compute half-hourly soil carbon fluxes for each soil
⁴⁷ replicate plot at a given terrestrial NEON site. To assess the computed fluxes, we visited six
⁴⁸ focal NEON sites and measured soil carbon fluxes using a closed-dynamic chamber approach.
⁴⁹ Outputs from the `neonSoilFlux` showed agreement with measured fluxes (R^2 between mea-
⁵⁰ sured and `neonSoilFlux` outputs ranging from 0.04 to 0.81 depending on calculation method
⁵¹ used); measured outputs generally fell within the range of calculated uncertainties from the
⁵² gradient method. Calculated fluxes from `neonSoilFlux` aggregated to the daily scale exhibited
⁵³ expected site-specific seasonal patterns. While the flux gradient method is broadly effective,
⁵⁴ its accuracy is highly sensitive to site-specific inputs, including the extent to which gap-filling
⁵⁵ techniques are used to interpolate missing sensor data and to estimates of soil diffusivity and
⁵⁶ moisture content. Future refinement and validation of `neonSoilFlux` outputs can contribute
⁵⁷ to existing databases of soil carbon flux measurements, providing near real-time estimates of
⁵⁸ a critical component of the terrestrial carbon cycle.

59 **1.1 Keywords**

60 Soil carbon, carbon dioxide, flux gradient, carbon cycle, field validation, soil respiration, ecosys-
61 tem variability, diffusion

62 **2 Data for peer review**

63 Anonymous field-collected data, `neonSoilFlux` calculated outputs, and manuscript-generating
64 code for peer review are provided as supplemental files. An anonymous link for peer-review
65 is here: <https://doi.org/10.5281/zenodo.1695117>. This will be made publicly available upon
66 publication.

67 **3 Introduction**

68 Soils contain the planet's largest reservoir of terrestrial carbon (Jobbágy & Jackson, 2000). A
69 critical component of this reservoir is soil organic matter, the accumulation of which is influ-
70 enced by biotic factors such as above-ground plant inputs (Jackson et al., 2017). These inputs
71 in turn are influenced by environmental factors such as growing season length, temperature,
72 and moisture (Desai et al., 2022), which also affect the breakdown of soil organic matter and its
73 return to the atmosphere. Across heterogeneous terrestrial landscapes, the interplay between
74 these biotic and abiotic factors influence the size of the soil contribution to the terrestrial
75 carbon sink (Friedlingstein et al., 2025). However, the heterogeneity of these processes across
76 diverse ecosystems in the context of rapid environmental change leads to large uncertainty
77 about the magnitude of this sink in the future, and thus there remains a pressing need to
78 quantify changes in soil carbon pools and fluxes across scales.

79 Ecological observation networks such as the United States' National Ecological Observatory
80 Network (NEON) and others (e.g. the globally-distributed FLUXNET or the European Inte-
81 grated Carbon Observation System) present a significant advancement in the nearly continuous
82 observation of biogeochemical processes at the continental scale. Notably, at 47 terrestrial sites
83 across the continental United States that span 20 ecoclimatic domains, NEON provides half-
84 hourly measurements of soil CO₂ concentration, temperature, and moisture at different vertical
85 depths. Each of these NEON sites also encompasses measurements of the cumulative sum of all
86 ecosystem carbon fluxes in an airshed using the eddy covariance technique (Baldocchi, 2014).
87 Soil observations provided by NEON are on the same timescale and standardized with eddy co-
88 variance measurements from FLUXNET. These types of nearly continuous observational data
89 (NEON and FLUXNET) can be used to reconcile differences between model-derived or data-
90 estimated components of ecosystem carbon flux (Jian et al., 2022; Luo et al., 2011; Phillips et
91 al., 2017; J. Shao et al., 2015; P. Shao et al., 2013; Sihl et al., 2016).

92 Estimated or observed soil carbon fluxes are a key metric for understanding change in soil
93 carbon pools over time (Bond-Lamberty et al., 2024). A soil carbon flux to the atmosphere
94 (F_S , units $\mu\text{mol m}^{-2} \text{ s}^{-1}$), represents the aggregate process of transfer of soil CO₂ to the
95 atmosphere from physical and biological processes (e.g. diffusion and respiration). Soil carbon
96 fluxes can be assumed to encompass soil carbon respiration from autotrophic or heterotrophic
97 sources (Davidson et al., 2006) and modeled with a exponential Q_{10} paradigm (Bond-Lamberty
98 et al., 2004; Chen & Tian, 2005; Hamdi et al., 2013).

99 One common method by which F_S is measured in the field is through the use of soil chambers
100 in a closed, well-mixed system (Norman et al., 1997) with headspace trace gas concentrations
101 measured with an infrared gas analyzer (IRGA). F_S can also be estimated from soil CO₂
102 measurements at different depths in the soil using the flux-gradient method (Maier & Schack-
103 Kirchner, 2014). Closed-chamber IRGA measurements, while being the most common method,

104 require either frequent in-person site visits or expensive and fragile automated systems. The
105 potential of the gradient method is that fluxes can be estimated from continuous data recorded
106 by robust solid-state sensors. The flux-gradient method is an approach that uses conservation
107 of mass to calculate flux at a vertical soil depth z at steady state by applying Fick's law of
108 diffusion. A simplifying assumption for the flux-gradient method is that there is no mass trans-
109 fer in the other spatial dimensions x and y (Maier & Schack-Kirchner, 2014). The diffusivity
110 profile, a key component of this calculation, varies across the soil depth as a function of soil
111 temperature, soil volumetric water content, atmospheric air pressure, and soil bulk density
112 (Millington & Shearer, 1971; Moldrup et al., 1999; Sallam et al., 1984).

113 Databases such as the Soil Respiration Database (SRDB) or the Continuous Soil Respiration
114 Database (COSORE) add to the growing network of resources for making collected observa-
115 tions of soil fluxes available to other researchers (Bond-Lamberty, 2018; Bond-Lamberty et
116 al., 2020; Bond-Lamberty & Thomson, 2010; Jian et al., 2021; Jiang et al., 2024). However,
117 these databases currently encompass primarily direct soil measurements of fluxes (i.e. those
118 using methods like the closed-chamber method described above). Currently, NEON provides
119 all measurements to calculate F_S from Fick's law, but soil flux as a derived data product was
120 descoped from the initial network launch due to budget constraints (Berenbaum et al., 2015).
121 Deriving estimates of F_S using continuous sensor data across NEON sites thus remains a high
122 priority.

123 This study describes an R software package, `neonSoilFlux`, that computes a standardized
124 estimate of F_S at all terrestrial NEON sites using the flux-gradient method. Using direct
125 chamber-based field observations of soil carbon dioxide flux from a subset of terrestrial NEON
126 sites spanning six states, we provide a direct validation of F_S from `neonSoilFlux`.

127 Key objectives of this study are to:

- 128 1. Apply the flux-gradient method to estimate soil CO₂ flux from continuous sensor mea-
129 surements across six NEON sites.
- 130 2. Benchmark estimated soil carbon fluxes against field measurements (e.g., direct chamber
131 measurements of soil flux).
- 132 3. Identify sources of error in the flux-gradient approach across diverse sites in order to
133 guide future work.

134 4 Materials and Methods

135 4.1 Field methods

136 4.1.1 Focal NEON Sites

137 In order to acquire field data to validate model predictions of flux, we selected six terrestrial
138 NEON sites for analysis. We conducted roughly week-long field measurement campaigns at
139 these sites, which span a range of environmental gradients and terrestrial domains (Table 1).
140 SJER, SRER, and WREF were visited during May and June of 2022, and WOOD, KONZ,
141 and UNDE during May and June of 2024.

142 4.1.2 Soil collar placement

143 Either one (2022 sampling campaign) or two (2024 sampling campaign) PVC soil collars (20.1
144 cm inside diameter) were installed in close proximity to the permanent NEON soil sensors at
145 each site (Figure 1). As instruments in the NEON soil sensor arrays can occasionally break
146 down or stop working, the specific soil plot where we made measurements was chosen at each
147 site in consultation with NEON staff to maximize likelihood of quality soil sensor measurements

¹⁴⁸ during the duration of the IRGA measurements. The plot selected at each site (out of the 5 in
¹⁴⁹ each replicate array at each site) are presented in the last column of Table 1. After installation,
¹⁵⁰ collar(s) were left to equilibrate for approximately 24 hours prior to any measurements being
¹⁵¹ taken.

¹⁵² **4.1.3 Infrared gas analyzer measurements of soil CO₂ flux**

¹⁵³ In 2022, we then made measurements of flux on an hourly interval for 8 hours each day.
¹⁵⁴ Measurements were taken from roughly 8 am to 4 pm, with the time interval selected to
¹⁵⁵ capture the majority of the diurnal gradient of soil temperature each day. These measurements
¹⁵⁶ were made using a LI-6800 infrared gas analyzer instrument (LI-COR Environmental, Lincoln,
¹⁵⁷ NE) fitted with a soil chamber attachment (attachment 6800-09). In 2024, we again used the
¹⁵⁸ same LI-6800 instrument, but made half-hourly measurements over an approximately 8 hour
¹⁵⁹ period. In addition, in 2024 we also installed a second collar and used a second instrument, an
¹⁶⁰ LI-870 CO₂ IRGA, connected to an automated robotic chamber (LI-COR chamber 8200-104)
¹⁶¹ controlled by an LI-8250 multiplexer to make automated measurements. The multiplexer was
¹⁶² configured to take half-hourly measurements 24 hours a day for the duration of our sampling
¹⁶³ bout at each site. Each instrument was paired with a soil temperature and moisture probe
¹⁶⁴ (Stevens HydraProbe, Stevens Water, Portland, OR) that was used to make soil temperature
¹⁶⁵ and moisture measurements concurrent with the CO₂ flux measurements. Chamber volumes
¹⁶⁶ were set by measuring collar offsets at each site. System checks were conducted daily for the
¹⁶⁷ LI-6800 and weekly for the LI-8250. Instruments were factory calibrated before each field
¹⁶⁸ season.

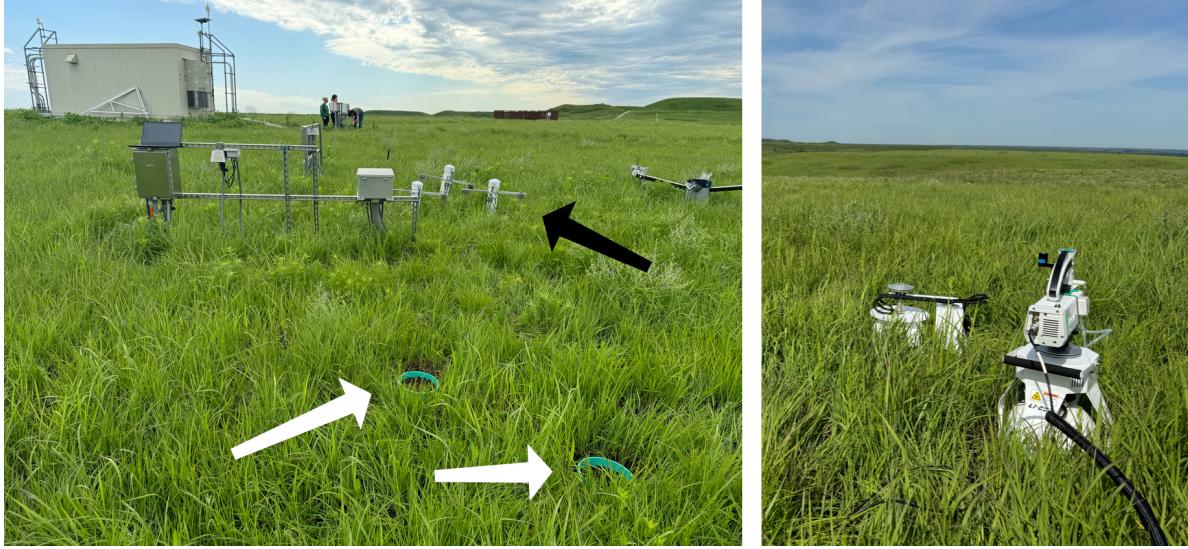


Figure 1: Spatial layout of field sampling using a closed-dynamic chamber setup at a representative NEON site (KONZ). Left image shows collars (white arrows) and permanent soil sensor installation (black arrow) and right image shows the LI-6800 (foreground) and LI-8200-104 (background) instruments placed on the collars.

Table 1: Listing of NEON sites studied for field work and analysis. Site refers to NEON site codes: Santa Rita Experimental Range (SRER), San Joaquin Experimental Range (SJER), Wind River Experimental Forest (WREF), Chase Lake National Wildlife Refuge (WOOD), Konza Prairie Biological Station (KONZ), and the University of Notre Dame Environmental Research Center (UNDE). Location is reported in decimal degrees of latitude and longitude. Other abbreviations include Mean Annual Temperature (MAT); \bar{T}_S : average soil temperature during field measurements; \bar{SWC} : average soil water content during field measurements. Dates refer to field measurement dates for each site. Plot refers to the particular location in the soil sensor array (denoted as HOR by NEON) where field measurements were made.

Site	Location	Ecosystem	MAT	\bar{T}_S	MAP	\bar{SWC}	Dates	Plot
SRER	31.91068, -110.83549	Shrubland	19.3 °C	47.6 °C	346 mm	4.0%	May 29– June 1 2022	004
SJER	37.10878, -119.73228	Oak woodland	16.4 °C	41.7 °C	540 mm	1.2%	June 1–4 2022	005
WREF	45.82049, -121.95191	Evergreen forest	9.2 °C	15.3 °C	2225 mm	27.2%	June 7–9 2022	001
WOOD	47.1282, -99.241334	Restored prairie	4.9 °C	14.9 °C	495 mm	14.9%	June 3–9 2024	001
KONZ	39.100774, -96.563075	Tallgrass prairie	12.4 °C	23.4 °C	870 mm	23.4%	May 29– June 1 2024	001

Table 1: Listing of NEON sites studied for field work and analysis. Site refers to NEON site codes: Santa Rita Experimental Range (SRER), San Joaquin Experimental Range (SJER), Wind River Experimental Forest (WREF), Chase Lake National Wildlife Refuge (WOOD), Konza Prairie Biological Station (KONZ), and the University of Notre Dame Environmental Research Center (UNDE). Location is reported in decimal degrees of latitude and longitude. Other abbreviations include Mean Annual Temperature (MAT); \bar{T}_S : average soil temperature during field measurements; \bar{SWC} : average soil water content during field measurements. Dates refer to field measurement dates for each site. Plot refers to the particular location in the soil sensor array (denoted as HOR by NEON) where field measurements were made.

Site	Location	Ecosystem	MAT	\bar{T}_S	MAP	\bar{SWC}	Dates	Plot
UNDE	46.23391, -89.537254	Deciduous forest	4.3 °C	13.0 °C	802 mm	13.0%	May 22–25 2024	004

169 4.1.4 Post-collection processing of field data

170 We used LI-COR SoilFluxPro software (v 5.3.1) to assess the data after collection and to inform
 171 sampling parameters. We checked appropriateness of dead band and measurement durations
 172 using built-in evaluation tools. Based on this, the deadband period was set for 30-40 seconds,
 173 depending on the site, and the measurement duration was 180 seconds with a 30 second pre-
 174 purge and a 30 second post-purge at most sites, and a 90 second pre- and post-purge at sites
 175 with higher humidity due to recent precipitation events. We also assessed the R^2 of linear and
 176 exponential model fits to measured CO₂ to verify measurement quality.

177 4.2 neonSoilFlux R package

178 We developed an R package called `neonSoilFlux` (Zobitz et al., 2024) to compute half-hourly
 179 soil carbon fluxes and uncertainties from NEON data. The objective of the `neonSoilFlux`
 180 package is a unified workflow (Figure 2) for soil data acquisition and analysis that supplements
 181 the existing `neonUtilities` data acquisition R package (Lunch et al., 2025).

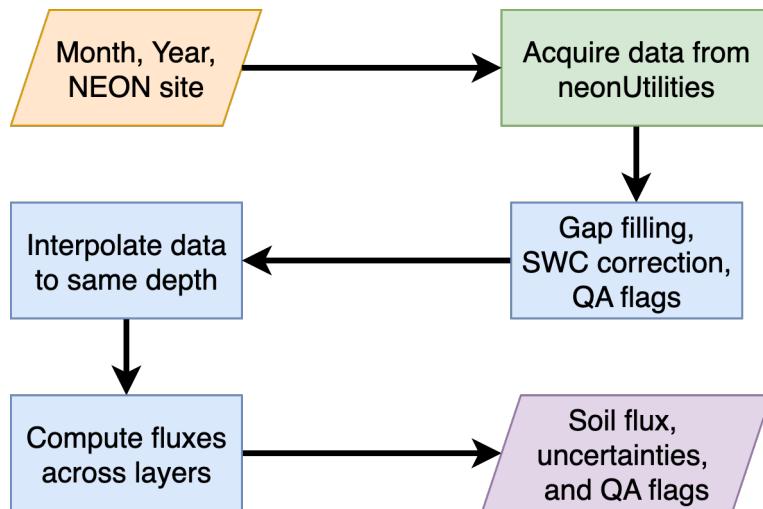


Figure 2: Diagram of `neonSoilFlux` R package. For a given month, year, and NEON site (orange parallelogram), the package acquires all relevant data to compute F_S using the `neonUtilities` R package (green rectangle). Data are gap-filled according to reported QA flags and adjusted for changes in soil water content (SWC) calibration coefficients, then interpolated to the same measurement depth before computing the soil flux, uncertainties, and final QA flags (blue rectangles). The package reports the associated soil flux, uncertainties, and quality assurance (QA) flags for the user (purple parallelogram).

At a given NEON site there are five replicate soil plots, each with measurements of soil CO_2 concentration, soil temperature, and soil moisture at different depths (Figure 3). The `neonSoilFlux` package acquires measured soil CO_2 concentration (NEON, 2024b), soil temperature (NEON, 2024d), soil water content (NEON, 2024e), barometric pressure from the nearby tower (NEON, 2024a), and soil properties (e.g. bulk density) (NEON, 2024c) from a range of different NEON data products. The static soil properties were collected by NEON staff from a nearby soil pit during initial site characterization and are assumed to be constant at each site. A soil flux calculation is computed at each replicate soil plot.

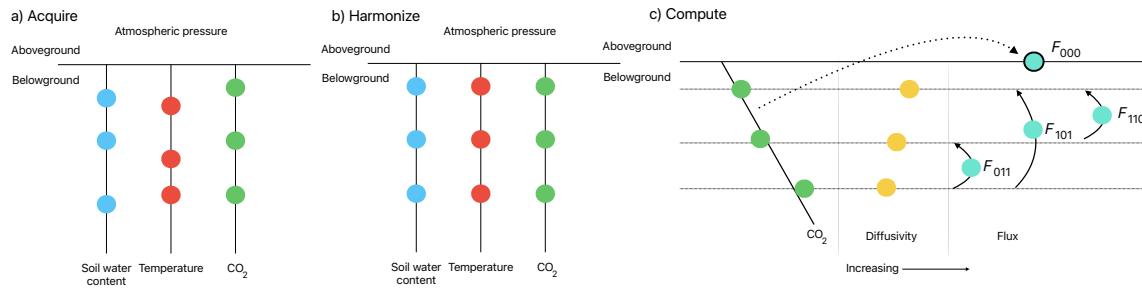


Figure 3: Model diagram of the data workflow for the `neonSoilFlux` R package. a) Acquire: Data are obtained for a given NEON location and horizontal sensor location, which includes soil water content, soil temperature, CO_2 concentration, and atmospheric pressure. All data are screened for quality assurance; if gap-filling of missing data occurs, it is flagged for the user. b) Harmonize: Any belowground data are then harmonized to the same depth as CO_2 concentrations using linear regression. c) Compute: The flux across a given depth is computed via Fick's law, denoted with F_{ijk} , where i , j , or k are either 0 or 1 denoting the layers the flux is computed across ($i = \text{closest to surface}$, $k = \text{deepest}$). F_{000} represents a flux estimate where the gradient dC/dz is the slope of a linear regression of CO_2 with depth.

The workflow to compute a value of F_S with `neonSoilFlux` consists of three primary steps, illustrated in Figure 3. First, NEON data are acquired for a given site and month via the `neonUtilities` R package (yellow parallelogram and green rectangle in Figure 2 and Panel a in Figure 3). Acquired environmental data can be exported to a comma separated value file for additional analysis. Quality assurance (QA) flags are reported as an indicator variable.

195 Since the calibration coefficients on the soil water content sensors have changed over time
196 (NEON, 2024e), raw sensor measurements were back-calculated and soil-specific calibrations
197 were applied following ([ayresValidationRemotelySensed2024?](#)) to generate a consistent
198 time series at each measurement location.

199 The second step is harmonizing the data to compute soil fluxes across soil layers. This step
200 consists of three different actions (blue rectangles in Figure 2 and Panel b in Figure 3). If a
201 given observation by NEON is reported as not passing a quality assurance check, we applied
202 a gap filling method to replace that measurement with its monthly mean at that same depth
203 (Section 4.2.1). Belowground measurements of soil water and soil temperature are then inter-
204 polated to the same depth as soil CO₂ measurements. The diffusivity (Section 4.2.2) and soil
205 flux across different soil layers (Section 4.2.3) are then computed.

206 The third and final step is computing a surface soil flux through extrapolation to the sur-
207 face (purple parallelogram in Figure 2 and Panel c in Figure 3). Uncertainty on a soil flux
208 measurement is computed through quadrature. An aggregate quality assurance (QA) flag
209 for each environmental measurement is also reported, representing if any gap-filled measure-
210 ments were used in the computation of a soil flux. Within the soil flux-gradient method,
211 several different approaches can be used to derive a surface flux (Maier & Schack-Kirchner,
212 2014); the `neonSoilFlux` package reports four different possible values for soil surface flux
213 (Section 4.2.3) for each of two different methods of diffusivity estimation, for a total of eight
214 estimates of flux.

215 4.2.1 Gap-filling routine

216 NEON reports QA flags as binary values for each measurement and half-hourly interval. For
217 a given half-hour, if any input variable (soil CO₂ concentration, soil temperature, or soil

moisture) at depth z is flagged, computation of F_S is not possible. To address this, flagged measurements and their uncertainties were replaced with a bootstrapped monthly mean (\bar{m}) and monthly standard deviation (\bar{s}) (Efron & Tibshirani, 1994).

For each month, depth z , and variable, we computed bootstrapped estimates of \bar{m} and \bar{s} from the vectors of unflagged measurements (\mathbf{m}), reported standard errors (σ), and the 95% confidence interval (ϵ , or expanded uncertainty; Farrance & Frenkel (2012)). We also defined a bias vector $\mathbf{b} = \sqrt{\epsilon^2 - \sigma^2}$, which quantifies the spread of uncertainty in a given period and is incorporated into \bar{m} .

From these, 5000 bootstrap samples were generated for \mathbf{m}, σ , and \mathbf{b} . For each sample (m_k, b_k, σ_k) , we generated a vector \mathbf{n} (length $N = 5000$) by drawing from a normal distribution with mean $m_k + b_k$ and standard deviation σ_k . The sample mean and standard deviation were then computed from \mathbf{n} . The resulting distributions of sample means and sample standard deviations provided the bootstrapped monthly mean (\bar{m}) and standard error (\bar{s}) respectively.

This gap-filling procedure provides a consistent treatment across all data streams. However, alternative approaches may be better suited for longer gaps (e.g., correlations with other NEON measurement levels or soil plots) or for variable-specific conditions. We discuss the effect of gap-filling on our results in Section 6.1.

4.2.2 Soil diffusivity

Soil diffusivity D_a at a given measurement depth is the product of the diffusivity in free air $D_{a,0}$ ($\text{m}^2 \text{ s}^{-1}$) and the tortuosity ξ (no units) (Millington & Shearer, 1971).

We compute $D_{a,0}$ with Equation 1:

$$D_{a,0} = 0.0000147 \cdot \left(\frac{T_i + 273.15}{293.15} \right)^{1.75} \cdot \left(\frac{P}{101.3} \right) \quad (1)$$

240 where T_i is soil temperature ($^{\circ}\text{C}$) at depth i (NEON, 2024d) and P surface barometric pressure
 241 (kPa) (NEON, 2024a).

242 Previous studies by Sallam et al. (1984) and Tang et al. (2003) demonstrated the sensitivity
 243 of modeled F_S depending on the tortuosity model (ξ) used to compute diffusivity. At low
 244 soil water content, the choice of tortuosity model can lead to order-of-magnitude differences
 245 in D_a , which in turn affect modeled F_S . The `neonSoilFlux` package currently includes two
 246 approaches to calculate ξ , representing the range of tortuosity behavior reported in Sallam et
 247 al. (1984).

248 The first approach is the Millington-Quirk model (Millington & Shearer, 1971), in which
 249 tortuosity depends on both porosity and soil water content:

$$\xi = \frac{(\phi - SWC_i)^{10/3}}{\phi^2} \quad (2)$$

250 In Equation 2, SWC is the soil water content at depth i (NEON, 2024e) and ϕ is the porosity,
 251 which in turn is a function of soil physical properties (NEON, 2024c):

$$\phi = \left(1 - \frac{\rho_s}{\rho_m} \right) (1 - f_V) \quad (3)$$

252 In Equation 3, ρ_m is the particle density of mineral soil (2.65 g cm^{-3}), ρ_s the soil bulk density (g
 253 cm^{-3}) excluding coarse fragments greater than 2 mm (NEON, 2024c), and f_V is a site-specific
 254 value that accounts for the proportion of soil fragments between 2-20 mm. Soil fragments

255 greater than 20 mm were not estimated due to limitations in the amount of soil that can be
256 analyzed (NEON, 2024c). We assume that rock fragments contain no internal pores.

257 The Millington-Quirk model assumes ξ is modulated by the amount of fluid saturation in
258 soil pores (Millington & Shearer, 1971). In contrast, the Marshall model (Marshall, 1959)
259 expresses tortuosity as only a function of porosity ($\xi = \phi^{1.5}$), with ϕ defined from Equation
260 3. The Marshall model is independent of soil water content and assumes tortuosity is only
261 governed by soil structure. The `neonSoilFlux` package allows users to choose the tortuosity
262 model most appropriate for site-specific conditions and research goals.

263 **4.2.3 Soil flux computation**

264 We applied Fick's law (Equation 4) to compute the soil flux F_{ij} ($\mu\text{mol m}^{-2} \text{s}^{-1}$) across two
265 soil depths i and j :

$$F_{ij} = -D_a \frac{dC}{dz} \quad (4)$$

266 where D_a is the diffusivity ($\text{m}^2 \text{s}^{-1}$) and $\frac{dC}{dz}$ is the gradient of CO₂ molar concentration
267 ($\mu\text{mol m}^{-3}$, so the gradient has units of $\mu\text{mol m}^{-3} \text{m}^{-1}$). The soil surface flux is theoretically
268 defined by applying Equation 4 to measurements collected at the soil surface and directly
269 below the surface. Measurements of soil temperature, soil water content, and soil CO₂ molar
270 concentration across the soil profile allow for application of Equation 4 across different soil
271 depths. Each site had three measurement layers, so we denote the flux as a three-digit subscript
272 F_{ijk} with indicator variables i , j , and k indicate if a given layer was used (written in order of
273 increasing depth), according to the following:

- F_{000} is a surface flux estimate using the intercept of the linear regression of D_a with depth and the slope from the linear regression of CO₂ with depth (which represents $\frac{dC}{dz}$ in Fick's Law). Tang et al. (2003) used this approach to compute fluxes in an oak-grass savannah.
- F_{110} is a flux estimate across the two shallowest measurement layers.
- F_{011} is a flux estimate across the two deepest measurement layers.
- F_{101} is a flux estimate across the shallowest and deepest measurement layers.

For F_{110} , F_{011} , and F_{101} , the diffusivity used in Fick's Law is always at the deeper measurement layer. When used as a surface flux estimate we assume CO₂ remains constant above this flux depth. Uncertainty in all F_{ijk} values was quantified using quadrature (Taylor, 2022). These computed fluxes could provide the basis for additional soil flux estimates. For example, Tang et al. (2005) estimated surface flux by linearly extrapolating F_{110} and F_{011} to the soil surface.

4.3 Post processing evaluation

Following collection of field measurements and calculation of the soil fluxes from `neonSoilFlux` package, we compared measured F_S based on closed-dynamic chamber measurements with the LI-COR instruments to a given soil flux calculation from `neonSoilFlux` for each site and flux computation method and quantified the relationship statistically (R^2). Finally, for a half-hourly interval we also computed a *post hoc* diffusivity (D_a) using the LI-COR flux along with the CO₂ surface gradient reported by NEON using the measurement levels closest to the surface.

Table 2: Summary of measured soil characteristics and flux results from field measurements across six NEON sites using a LI-COR 6800 (LI-870/8250 measurements omitted to enable direct comparability) via the closed-dynamic chamber method. Numeric values for soil CO₂ flux, soil temperature, and volumetric soil water content (VSWC) are the mean and standard deviation of field measurements at each site.

Site	Flux μmol m ⁻² s ⁻¹	Soil temp °C	VSWC cm ³ cm ⁻³	n
UNDE	2.55 ± 0.26	14.33 ± 0.77	0.33 ± 0.02	61
WOOD	3.02 ± 0.4	16.01 ± 1.54	0.28 ± 0.01	53
WREF	3.62 ± 0.3	15.34 ± 1.76	0.27 ± 0.06	21
KONZ	6.35 ± 0.97	27.28 ± 4.14	0.37 ± 0.01	44
SJER	0.94 ± 0.02	41.68 ± 11.22	0.01 ± 0.01	32
SRER	0.72 ± 0.09	47.64 ± 7.46	0.04 ± 0.01	32

294 5 Results

295 5.1 Concordance between modelled and measured soil CO₂ flux

296 The sites we visited ranged substantially in both their annual average temperature and precip-
 297 itation as well as their biome type (Table 2). These differences also influenced the wide range
 298 of observed flux rates across sites.

299 The timeseries of the measured fluxes from the LI-COR 6800 and 870/8250 were compared
 300 to modeled soil fluxes from the `neonSoilFlux` R package (Figure 4). We also assessed year-
 301 long estimated flux time series and compared those to field measurements made at each site
 302 (Figure 5). Results are reported in local time. Where applicable, sites are displayed from left
 303 to right by increasing soil temperature (Table 1). Positive values of the flux indicate that there
 304 is a flux moving towards the surface. Overall, with the exception of SRER (discussed later) the
 305 computed fluxes determined using a variety of plausible methods spanned the field-measured
 306 fluxes, but the specific flux-gradient method that best approximated field measurements varied
 307 by site.

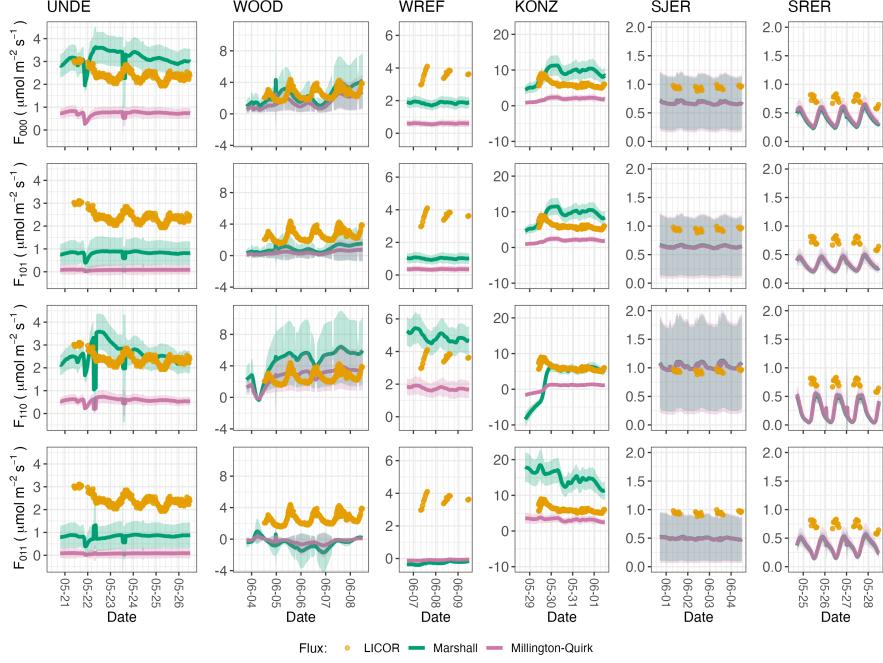


Figure 4: Timeseries of soil surface flux (F_S) from field-measured (yellow lines) and modeled soil fluxes (green or purple lines) by the `neonSoilFlux` R package. Fluxes from the `neonSoilFlux` R package are separated by the diffusivity model used (Millington-Quirk or Marshall, Section 4.2.2). Individual vertical axis labels in the first column represent the measurement levels where the flux-gradient approach is applied (Section 4.2.3). Ribbons for modeled soil fluxes represent ± 1 standard deviation. Results are reported in local time. WREF, SJER, and SRER were sampled in 2022, and UNDE, WOOD, and KONZ were sampled in 2024. Sites (columns) are arranged from left to right in terms of increasing mean annual temperature.

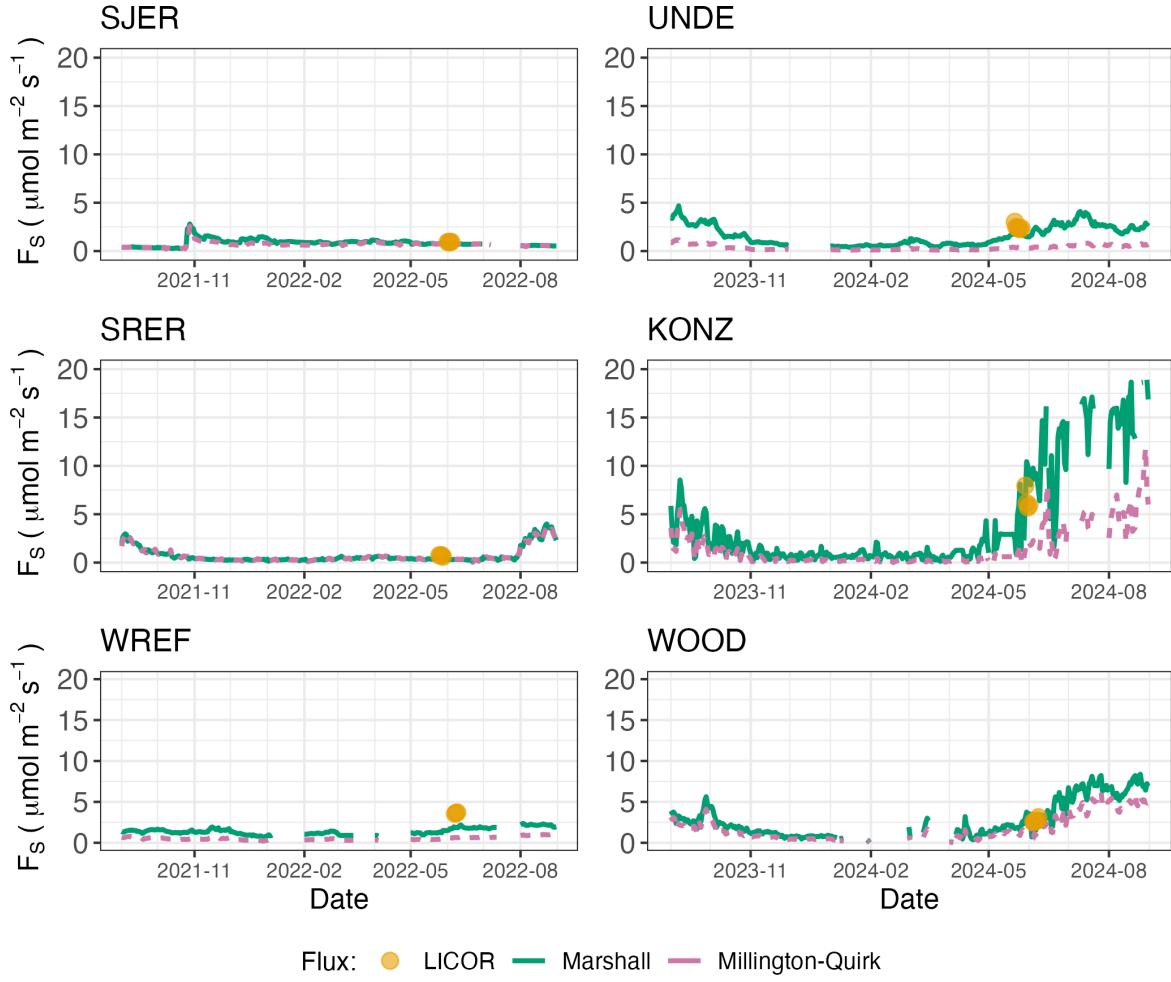


Figure 5: Timeseries of both daily-averaged field F_S (yellow circles) and daily ensemble averaged soil fluxes (average of F_{000} , F_{101} , F_{011} , F_{110} , Section 4.2.3) by the `neonSoilFlux` R package, separated by the diffusivity model used (green or purple lines, Millington-Quirk or Marshall, Section 4.2.2).

308 We calculated a statistical relationship between the various estimates of soil flux computed by
309 `neonSoilFlux` and the field-measured fluxes within daily interval periods. Statistics for these
310 comparisons are reported in Figure 6, which also shows how these fall relative to a 1:1 line.

311 **5.2 Effects of method choice on diffusivity estimates**

312 In four of six field sites, the *post hoc* D_a estimate fell roughly between the two diffusion
313 estimation methods; however this was less the case in the two driest sites, SJER and SRER
314 (Table 1), where the field estimate of diffusivity was either lower or higher than both of the
315 other methods (Figure 7).

316 **6 Discussion**

317 This study presents a unified data science workflow to efficiently process automated measure-
318 ments of belowground soil CO₂ concentrations, soil water content, and soil temperature to
319 infer estimates of soil surface CO₂ effluxes through application of Fick's Law (Equation 4).
320 Our core goals in this study were: (1) to generate estimates of soil flux from continuous soil
321 sensor data at terrestrial NEON sites using the flux-gradient method and then (2) to compare
322 those estimates to field-measured fluxes based on the closed chamber approach at six NEON
323 focal sites. We discuss our progress toward these core goals through (1) an overall evaluation
324 of the flux-gradient approach (and uncertainty calculation) and (2) site-specific evaluation of
325 differences in estimated vs measured fluxes.

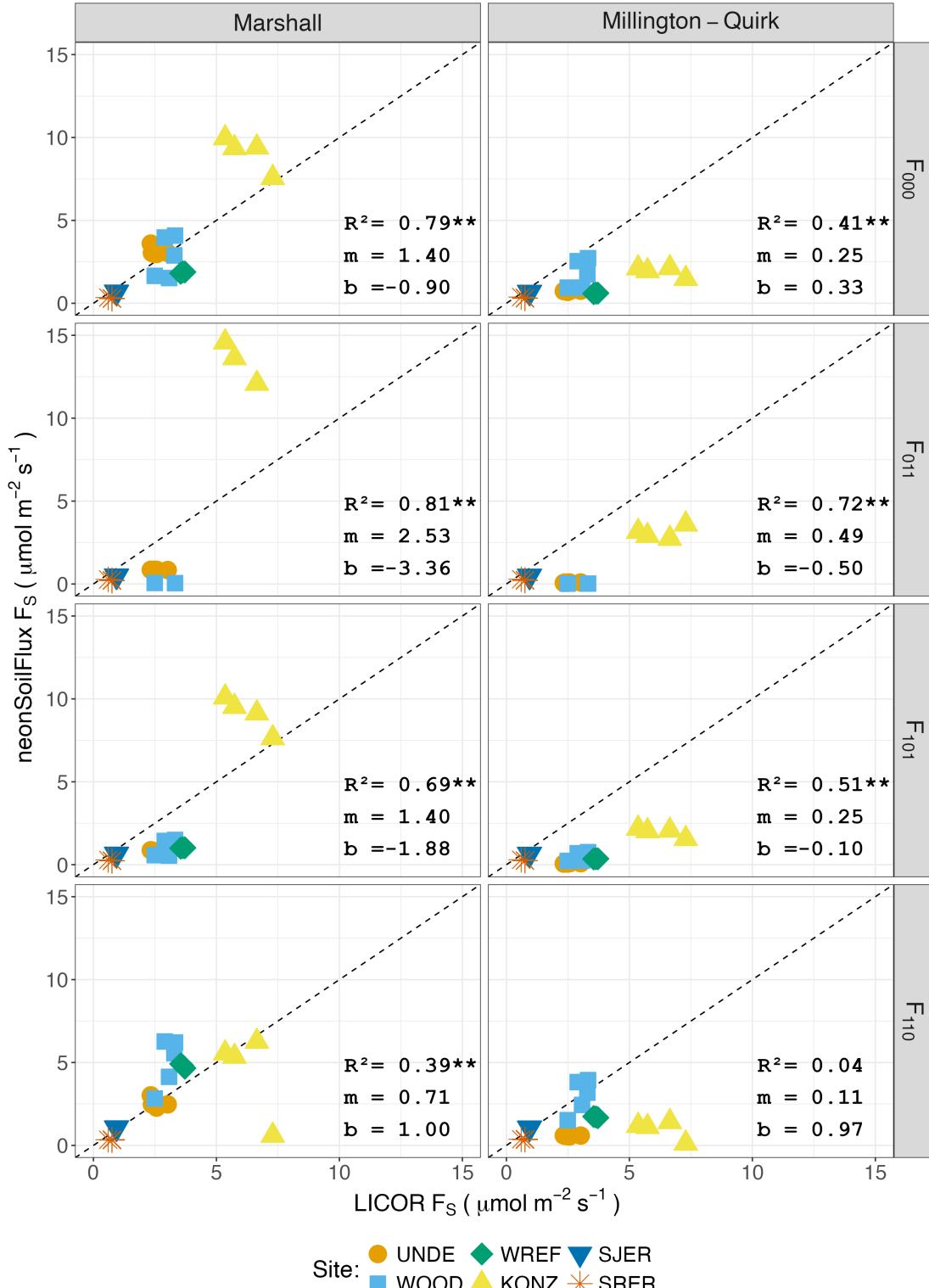


Figure 6: Statistical comparison between measured fluxes at each NEON site with fluxes reported by `neonSoilFlux` with the different flux calculation approaches and diffusivity calculations applied. Points are daily averages and LICOR F_S values are from the 6800 instrument only, for consistency. The dotted line represents a 1:1 relationship, and the reported R^2 quantifies the relationship between field-measured and `neonSoilFlux` estimated fluxes. * = significance at the 5% level, ** = significance at the 1% level. The low-value outlier from KONZ in the F_{110} Marshall plot is an example of the effect of inverted CO₂ gradients causing an estimated flux to be negative, bringing down the daily mean, which later resolved as the soils dried back out.

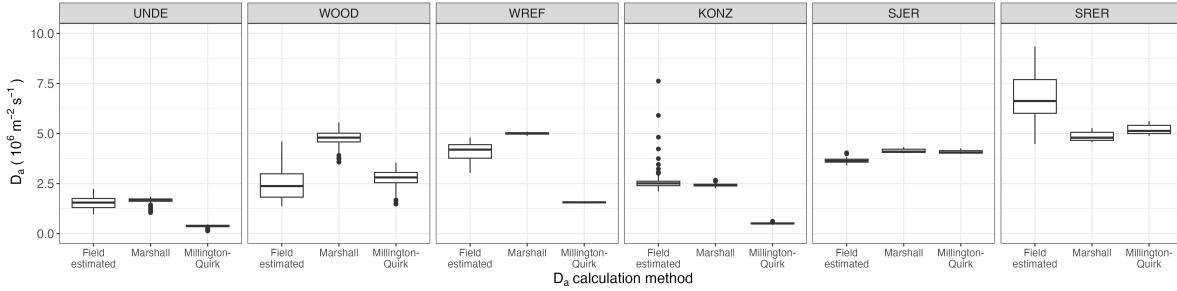


Figure 7: Distribution of diffusivity (D_a) at each study site. Values of D_a were provided by the `neonSoilFlux` package, computed from the Millington-Quirk or Marshall models (Section 4.2.2). A post-hoc estimate of diffusivity (labeled as “Field estimated”) was computed through the field measured flux (Figure 4), divided by the CO_2 gradient from the measurement levels closest to the soil surface, as reported by NEON. We only used F_S measured by the LICOR 6800 at all sites to standardize comparisons.

326 6.1 General evaluation of flux-gradient approach

327 Key assumptions of the flux-gradient approach are that CO_2 concentrations increase through-
 328 out the soil profile such that the highest concentrations are observed in the deepest layers. Ad-
 329 ditionally, field flux measurements should correlate with F_{000} because they represent surface
 330 fluxes. Periods where this gradient condition are not met generally are connected to processes
 331 that occur during soil wetting events, where more shallow soil layers produce higher concentra-
 332 tions of CO_2 due to microbial respiration pulses following rewetting. This effect is likely to be
 333 largest at sites with rich organic soils (e.g. KONZ). Based on this reasoning, in these types of
 334 situations we would *a priori* expect F_{011} (deepest layers) $\leq F_{101} \leq F_{110}$ (shallow layers) \leq
 335 F_{000} (all layers) because the previous flux estimates rely primarily on CO_2 concentrations at
 336 deeper depths, and could miss high concentrations of CO_2 produced in shallower layers.

337 When modeling soil respiration, typically a non-linear response function that also considers soil
 338 type is used (Bouma & Bryla, 2000; Yan et al., 2016, 2018). For the `neonSoilFlux` package,
 339 soil type is connected to the measurement of bulk density, which was characterized at each
 340 NEON site. This bulk density estimate is based on replicate samples collected from the site

341 megapit at a subset of soil horizons, with an estimated uncertainty of $\pm 5\%$ (NEON, 2024c).
342 Coarse fragment estimates also have very large uncertainties, but because the volume fraction
343 tends to be low in surface soils it is unlikely to contribute much additional flux uncertainty.

344 Our results suggest that the most important way to improve reliability of the flux estimate is
345 to reduce the usage of gap-filled data. The current approach to gap filling in `neonSoilFlux`
346 uses monthly mean data to gap fill—this approach decreases the ability of the estimate to be
347 responsive to short-term pulses that occur with rapid weather shifts. Four sites (KONZ, SRER,
348 WREF, and UNDE) had more than 75% of half-hourly periods with no-gap filled measurements
349 (Figure S1, Supplementary Information). Two sites (SJER and WOOD) had more than 75%
350 of half-hourly intervals with just one gap-filled measurement. The large uncertainty evident
351 in Figure 4 for estimates from WOOD and SJER are thus due in part to the gap-filling used
352 in these sites (Figure S1). While we did not need to use gap-filled measurements to compute
353 the flux at WREF, field data collection occurred following a severe rainstorm, with soils at the
354 beginning of the sampling week near their water holding capacity. In general, we recommend
355 that whenever possible, knowledge of local field conditions should influence analysis decisions
356 in addition to any QA filtering protocols in the `neonSoilFlux` package.

357 We recognize that this gap-filling approach may lead to gap-filled values that are quite different
358 from the actual values, such as an underestimate of soil moisture following rain events. Further
359 extensions of the gap filling method could use more sophisticated gap-filling routines, similar to
360 what is used for net ecosystem carbon exchange (Falge et al., 2001; Liu et al., 2023; Mariethoz et
361 al., 2015; Moffat et al., 2007; Zhang et al., 2023). Additionally, since the deepest temperature
362 and soil moisture sensors are located below the deepest CO₂ sensors at NEON sites, it is
363 possible that excluding these deeper layers from consideration prior to analysis would lead to
364 a reduced need for gap filling. Future iterations of the `neonSoilFlux` package may incorporate
365 this as an option. The current gap-filling routine provides a consistent approach that can be

366 applied to each data stream, but further work may explore alternative gap-filling approaches.

367 **6.2 Evaluation of flux-gradient approach at each site**

368 Derived results from the `neonSoilFlux` package have patterns that are broadly consistent with
369 those directly measured in the field (Figure 4 and Figure 5), even though statistical comparisons
370 between the field-measured and `neonSoilFlux` values were quite variable (e.g. R^2 ranging
371 from 0.04 to 0.81; Figure 6). One advantage of the `neonSoilFlux` package is its ability to
372 calculate fluxes across different soil depths (Figure 3), which allows for additional site-specific
373 customization. We believe the package can provide a useful baseline estimate of soil fluxes
374 that can always be complemented through additional field measurements.

375 The six locations studied provide a range of case studies that suggest different considerations
376 may apply to different sites when applying the flux-gradient method. For example, the Santa
377 Rita Experimental Range (SRER) is a desert site characterized by sandy soil, which also was
378 the location of the highest field soil temperatures that we observed (Table 2). At SRER the
379 flux across the top two layers (F_{110}) produced a pattern of soil flux most consistent with the
380 observed field data. The remaining methods F_{101} , F_{011} , or F_{000} are derived from information
381 taken from the deepest layer, which seems to have been decoupled from the surface layers both
382 in terms of temperature and CO₂ concentration. This may be a general circumstance where
383 there are large diurnal temperature extremes that rapidly change during the course of a day
384 and overnight, leading to lags in the timing of when temperature increases propagate down to
385 deeper soil layers.

386 Immediately prior to our visit to Konza Prairie (KONZ), that site that experienced a significant
387 rain event that led to wet soils that gradually dried out over the course of our time there.
388 This pulse of precipitation increased the soil CO₂ concentration at the top layer above the

389 concentrations in lower layers, leading to negative estimated flux values at the start of the
390 field sampling period. In this case it was only when the soil began to return to a baseline level
391 that the assumptions of the flux-gradient method were again met.

392 Both of the previous cases also provide context for the variable statistical comparisons between
393 field-measured soil fluxes and `neonSoilFlux` outputs (Figure 6). When considering systematic
394 deployment of this method across a measurement network, there are a number of independent
395 challenges that require careful consideration. There are clear tradeoffs between (1) accuracy
396 of modeled fluxes (defined here as closeness to field-measured F_S and the uncertainty reduc-
397 tion factor ϵ), (2) precision (which could be defined by the signal to noise ratio), and (3) the
398 choice of the diffusivity model (Section 4.2.2) or flux computation method (Section 4.2.3). A
399 sensitivity analysis (Figure S2, Supplemental Information) found that flux output uncertainty
400 was dominated by measurement uncertainty (T_S , P , SWC , or CO_2) rather than by the dif-
401 fusivity method used to compute soil flux. Notably, the F_{110} method was least sensitive to
402 measurement uncertainty likely because it best aligns with the surface chamber measurement
403 assumptions.

404 Finally, comparing the effects of different diffusivity estimation methods on the match between
405 modeled and measured fluxes (Figure 5) highlights the sensitivity of F_{ijk} to diffusivity. The
406 comparison between diffusivity estimates compared to field estimated diffusivity (Figure 7)
407 demonstrates that site parameters can dictate which measure of diffusivity is most likely to
408 be accurate in a given environmental context. Site-specific differences are largely a reflec-
409 tion of differences in soil moisture across the sites (Table 1), as not all diffusivity estimation
410 methods incorporate soil moisture equivalently. While we here have compares two approaches
411 to calculate diffusivity (the Millington-Quirk and Marshall models), it may be valuable to
412 evaluate other diffusivity models (e.g. the Moldrup model; Moldrup et al. (1999)) as well. Ul-
413 timately the choice of a particular diffusivity model could be determined based on knowledge

⁴¹⁴ of site-specific evaluations or a set of these models could be used to generate a model ensemble
⁴¹⁵ average as a means to trade precision for a more general approach.

⁴¹⁶ **6.3 Recommendations for future method development**

⁴¹⁷ The `neonSoilFlux` package provides several approaches to estimate soil flux using the gradient
⁴¹⁸ method. We believe these approaches enable the software to be used across a range of site-
⁴¹⁹ specific assumptions (Maier & Schack-Kirchner, 2014). We note, however, that this choice
⁴²⁰ can have a determinative approach on the calculated values. Ensemble averaging approaches
⁴²¹ (Elshall et al., 2018; Raftery et al., 2005) may be one way to address this problem if the goal is
⁴²² to calculate fluxes using the same method at a diverse range of different sites. Two other ideas
⁴²³ would be to apply machine learning algorithms (e.g. random forest) to generate a single flux
⁴²⁴ estimate across diverse sites, or using co-located estimates of net ecosystem carbon exchange
⁴²⁵ from eddy-flux towers to further constrain results or to assess soil flux results for plausibility
⁴²⁶ (Phillips et al., 2017).

⁴²⁷ These challenges notwithstanding, the method used here and made available in the
⁴²⁸ `neonSoilFlux` R package has the potential to produce nearly continuous estimates of flux
⁴²⁹ across all terrestrial NEON sites. These estimates are a significant improvement on available
⁴³⁰ approaches to constrain the portion of ecosystem respiration attributable to the soil. This,
⁴³¹ in turn, also aids in our ability to understand the soil contribution to the net ecosystem flux
⁴³² measured at these sites using the co-located eddy flux towers.

⁴³³ **7 Conclusions**

⁴³⁴ We used the R package `neonSoilFlux` to estimate soil CO₂ fluxes with the flux-gradient
⁴³⁵ method using data from buried soil sensors at NEON terrestrial sites. We compared the
⁴³⁶ predicted fluxes to those measured directly using a field-based closed chamber approach. Soil
⁴³⁷ fluxes from `neonSoilFlux` were broadly effective at producing estimates of flux comparable
⁴³⁸ to those measured in the field using a chamber-based technique. However `neonSoilFlux`
⁴³⁹ outputs are quite sensitive to a number of issues, including: missing data (and thus gap-
⁴⁴⁰ filling of input measurement datasets), the selection of soil depths used to best calculate the
⁴⁴¹ gradient (which may vary between sites), and finally the choice of method used for estimating
⁴⁴² soil diffusivity. The flexibility of the `neonSoilFlux` package allows the user to evaluate each
⁴⁴³ of these issues with site-specific knowledge and contexts. Future refinements and subsequent
⁴⁴⁴ validation of `neonSoilFlux` outputs will feed forward into evaluating soil carbon fluxes broader
⁴⁴⁵ spatial scales to enhance understanding of the ways in which soils across diverse ecosystems
⁴⁴⁶ are responding to a changing climate.

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