

Satellite Co-Orbital Engagement Engineering with System Composer

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OUTLINE



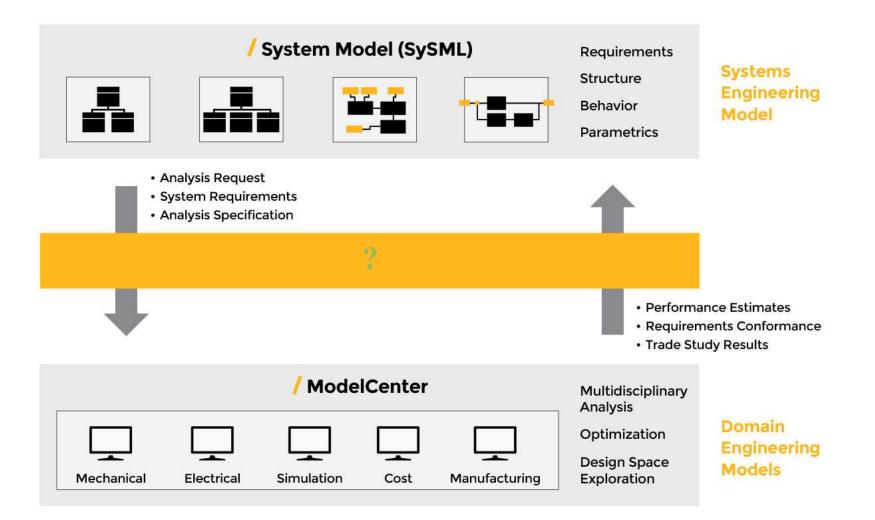
- Background
- Representative Mission to be Modeled
- Mission Modeling Domain
- Integration with Cameo System Modeler
- Integration with MathWorks' System Composer
- Demonstration of Model Execution
- Conclusions



BACKGROUND

CONNECTING SYSTEMS ENGINEERING DOMAIN WITH DOMAIN ENGINEERING MODELS





Authoritative Source of Truth (an integrated set of engineering models)

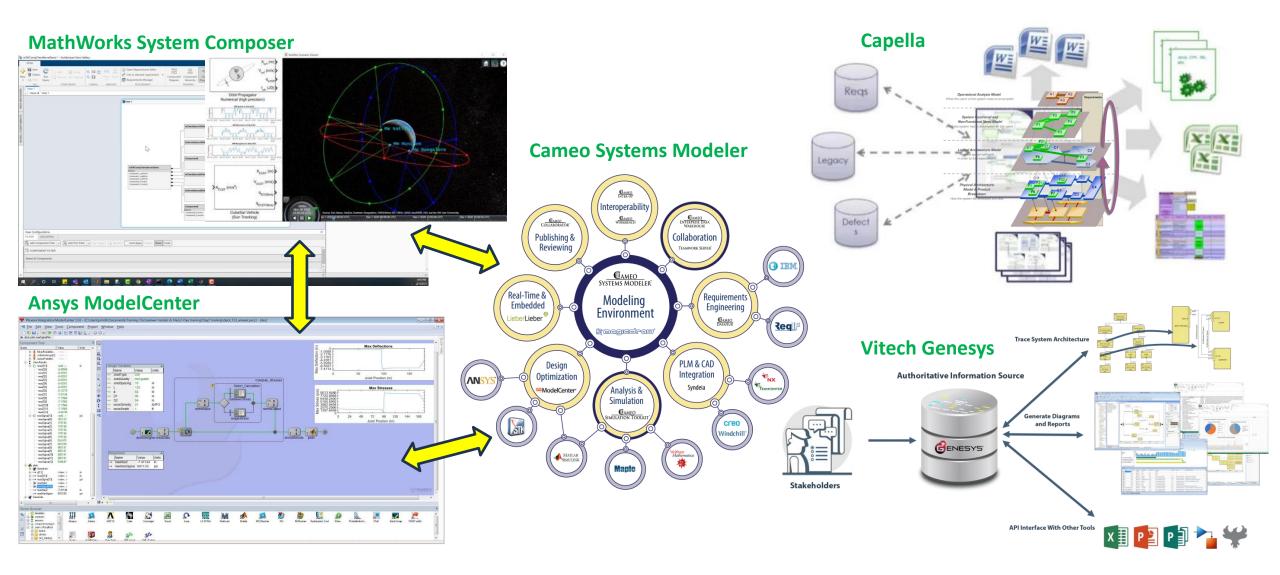
The centerpiece of the digital transformation is the ASoT

The System Model is the glue that ties together disparate models into a single ASoT

The ASoT resides in a digital ecosystem (interconnected infrastructure, environment and methodology)

DIGITAL ECOSYSTEMS ERA

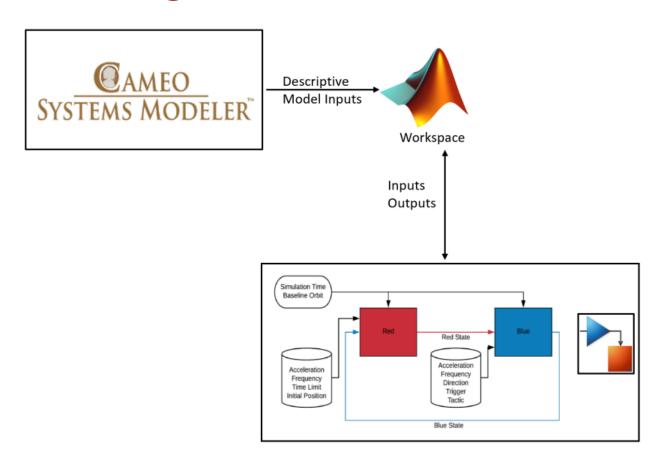




PREVIOUS INTEGRATION ATTEMPTS



- Simulink high-fidelity simulation was integrated with the descriptive model of the spacecraft engagement mission developed in Cameo System Modeler (CSM)
- The value of MBSE approach was clearly demonstrated via
 - enabling enhanced mission analysis
 - facilitating tactics assessments
 - validating operational requirements
 - providing outputs to derive new requirements
- Full integration was not achieved cased by application programming interface incompatibility
 - Incompatible value properties between CSM/Simulink
 - GUI limitations
 - Manual requirements in execution



Rangel, D., Pavalkis, S., and Yakimenko, O. "Incorporation of a High-Fidelity Simulink Model into the Cameo Systems Modeler Environment for a Conceptual Design of Satellite Engagement Missions," Proceedings of the 33rd Annual INCOSE International Symposium (IS2023), Honolulu, HI, July 15-20, 2023.

Hanlon, N., and Yakimenko, O.A., "Hardening Civilian Spacecraft Against Kinetic Attack through Model-Based Systems Engineering," Proceedings of the IEEE Aerospace Conference, Big Sky, MT, March 5-10, 2023.



INTEGRATION WITH MATHWORKS' SYSTEM COMPOSER

MATHWORKS' MBSE TOOLS (R2021A)



System Composer allows users to:

- Create architectures and requirements, allocate between them, and define metadata
- Create custom viewpoints of an architecture model
- Specify and simulate model behaviors using activity diagrams, sequence diagrams, Simulink, Simscape™, and Stateflow®
- Write analyses based on element properties and verify system requirements
- Import and export models using MATLAB® tables, generate reports using Simulink Report Generator™
- Organize System Composer architectural data using Simulink projects, data dictionaries, and model comparison
- Author, simulate, and deploy software architectures and generate code

Requirements Toolbox allows users to:

- Author requirements, import, export, and formalize requirements
- Link requirements to designs, code, and tests, specify relationships, add markup, review traceability to models and code, check consistency
- Requirements-based model verification, interpreting and reporting test results
- Requirements review and comparison, track changes and provide justification, generate reports for sign-off and approval
- Requirements traceability supported by the legacy RMI interface
- Qualify Requirements Toolbox for DO and IEC certification

Simulink Test allows users to:

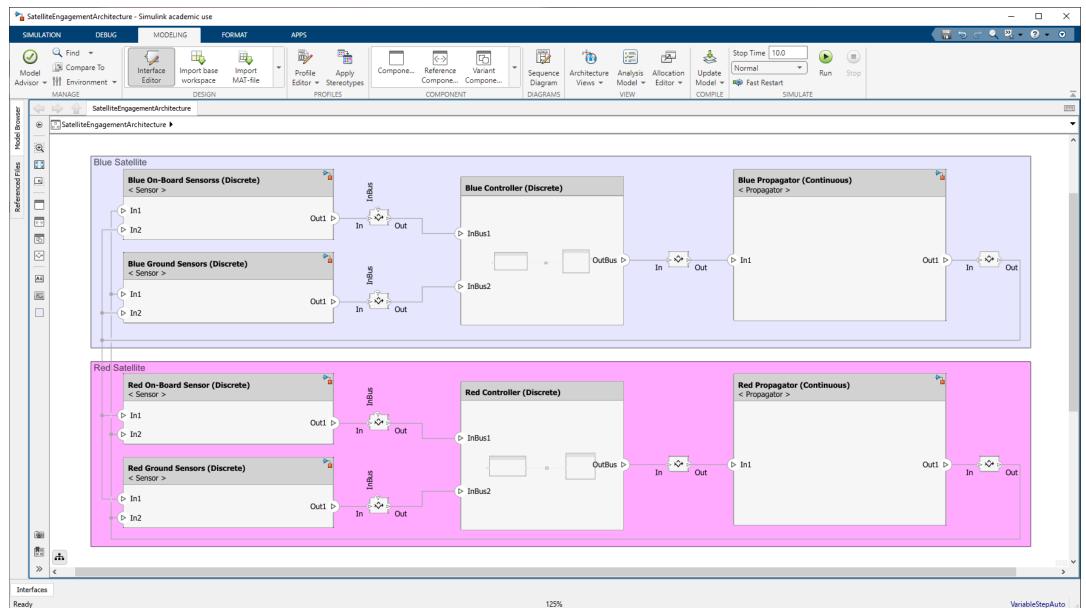
- Create and import data, develop test sequences, log signals, assess simulation and output
- Run tests, view and interpret test results, debug tests, and check test coverage
- Report and archive test specifications and test results, package test files, work with change management systems
- Create and run tests using command-line functions and scripts, set test preferences

- Simplified GUI
- Functions of multiple architecture models: requirements, parametric, and state machine diagram condensed into requirements editor and test manager

MISSION ARCHITECTURE IN SYSTEM COMPOSER

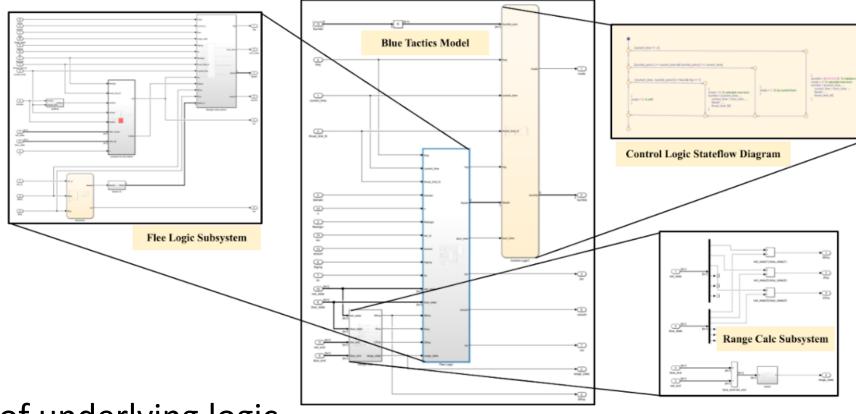
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SIMULINK SUBSYSTEMS AND STATEFLOW DIAGRAMS WITHIN TACTICS COMPONENT



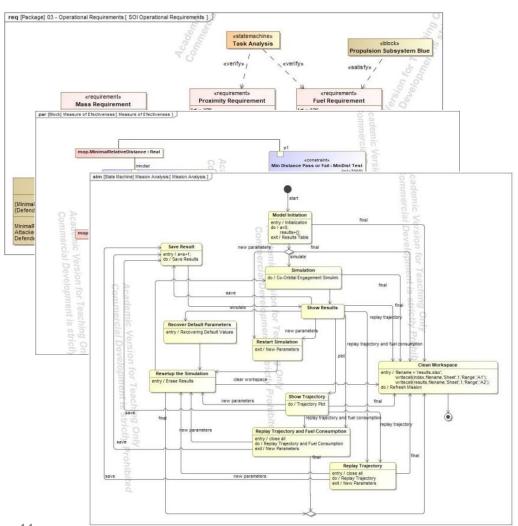


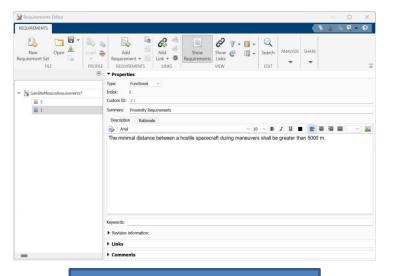
- Visual representation of underlying logic
- Simulation performance improvements
- Requirements traceability and verification
- Increased modularity to adapt to changing requirements and model updates

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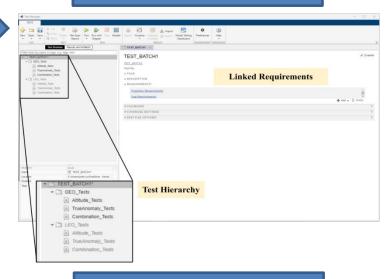
SIMPLIFICATION OF REQUIREMENTS AND ASSESSMENTS GUI







Requirements Editor



Test Manager

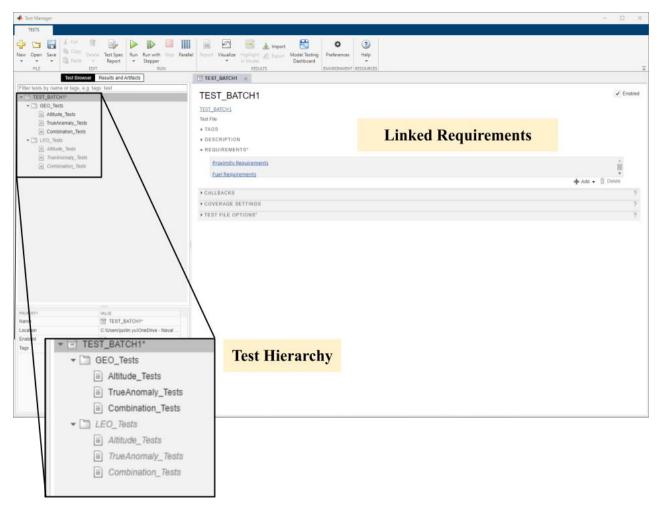
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DEMONSTRATION OF MODEL FEATURES/EXECUTION

TEST MANAGER GUI FOR MANAGING BATCH TESTS





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IN-DEPTH REQUIREMENT VERIFICATION



GEO chaser trajectory starting 10 km below and 0.01° true anomaly behind target

Relative Pos Red wrt Blue Red -----Blue Start Radial In-track Cross-track Range 100 -100 Range (km) -400 -100 -150 3000 2000 1000 -200 20 25 Cross-track (km) In-track (km) Time (hr) Chaser Position in RIC Chaser Velocity in RIC Red Thrust 3000 Radial In-track In-track Cross-track Cross-track -0.05島 1000 -0.1 -1000 -0.215 20 Time (hr) Time (hr) Time (hr) Target Position in RIC Target Velocity in RIC Blue Thrust 3000 Radial -0.05-0.1 10 20 10 15 20 25 Time (hr) Time (hr) Time (hr)

Automatic assessment conducted by Test Manager (proximity requirement)





CONCLUSIONS

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- Successful integration
- Simplified GUI; batch-testing; single source control tool; no value compatibility issues
- Complexity of translating MATLAB into Simulink/Stateflow
- Requirements reader still under construction
- Does not allow not physical signals can't simulate any system