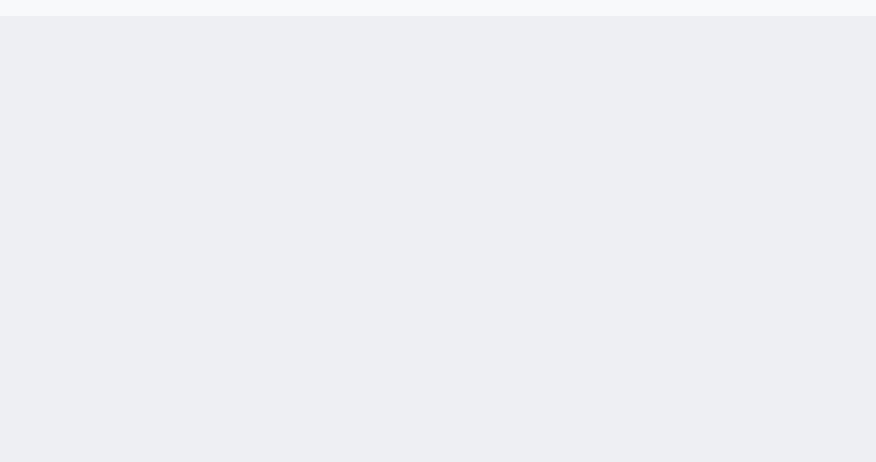


Select Robot ▾

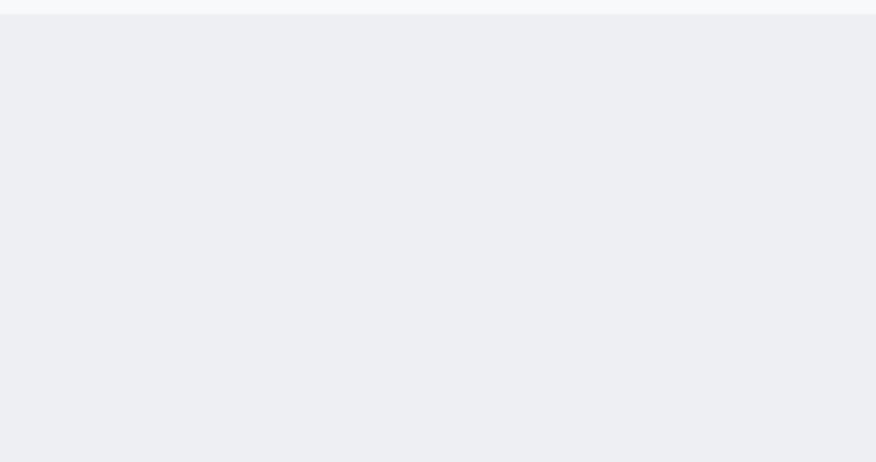
- SCARA QUANTUM
- ABB TEXSONICS
- Grid

Teach Point



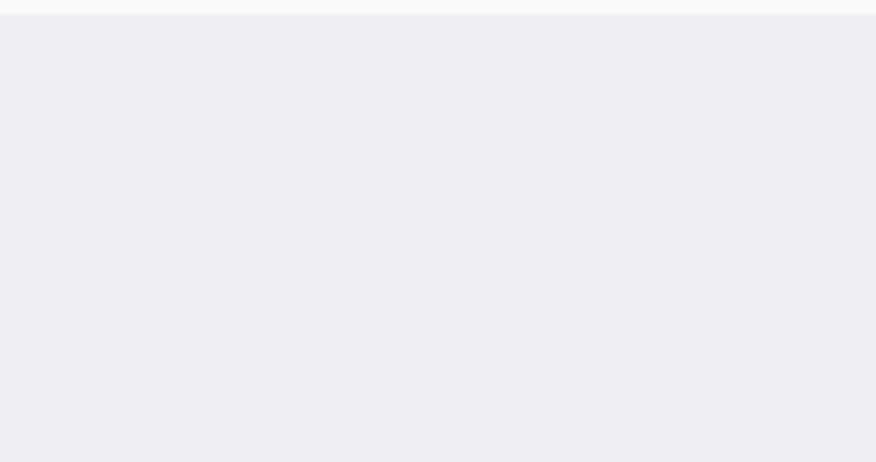
Insert Clear Save Load

Robot Program



Load Clear

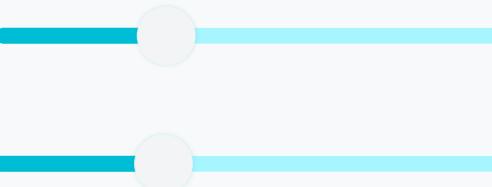
Programming Window



Move P0 P1 Insert

Object Position

Object ▾



Settings

Simulation Real

Jog Cartesian

Input Parameters

Displacement



Speed



Operation

HOME **START**

PAUSE **STOP**

