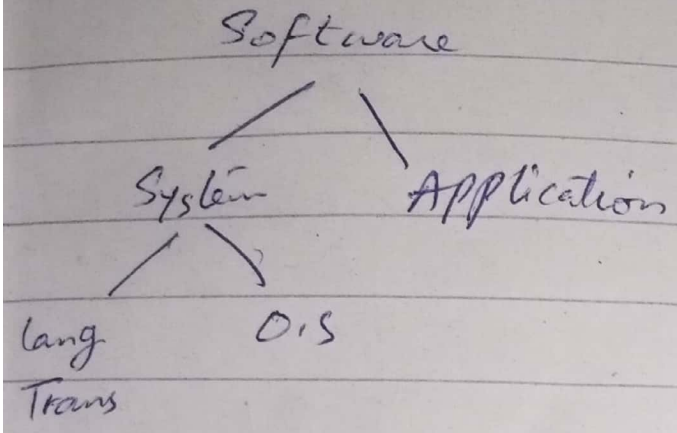
# OPERATING SYSTEM




1. Communication bridge.
(O.S is connect user with hardware)

2. Control program/ ~~title~~ through put.
(one time run many program)

*) Running: one time run one program, Resume: again go same prog

3. Resource allocation.

*) Resource: I/O device, memory, O.S C.PU k

bi resource u
icrle 4.

Utilization time = Execution Time / Burst tim / Service Time
Turn around time

Smallest unit in O.S is "Quantum"
Quantum size "how many quantum"

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- Execution Time decided to O.S.

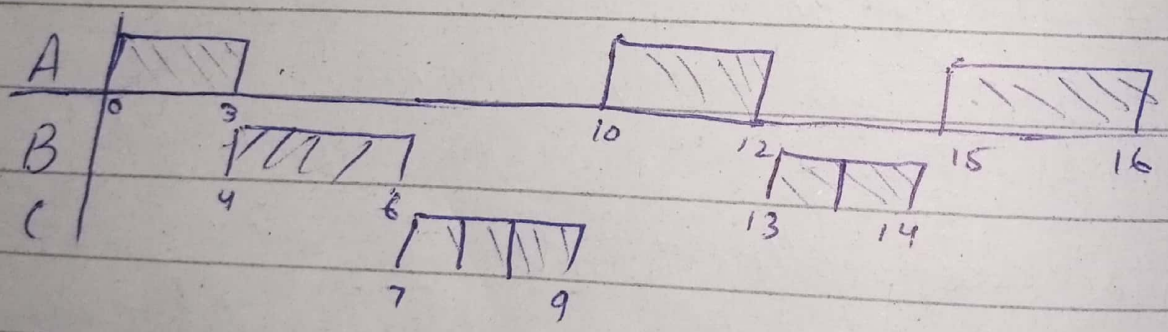
- Time around : Finish time - Arrival tim

T.T

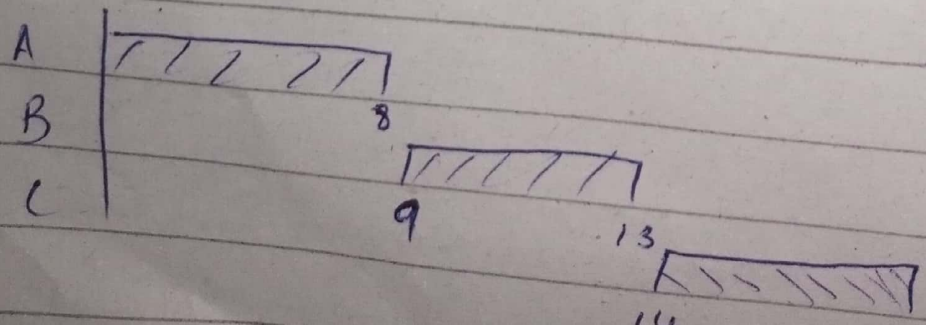
| Averag T.T | | Execution | Arri | End |
|---|---|---|---|---|
| 8/16 = 50% | A | 8 | 0 | 16 |
| 5/13 = 35% | B | 5 | 1 | 14 |
| 3/7 = 42.8% | C | 3 | 2 | 9 |

q = 3

## Round Robbin:-




## Fiist Come Fiist Seive:

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| | E.T | A.T | End time | T.T | A.V % |
|---|---|---|---|---|---|
| A | 8 | 0 | 8 | 8 | 8/8 = 100% |
| B | 5 | 1 | 13 | 12 | 5/12 = 41.6% |
| C | 3 | 2 | 16 | 14 | 3/14 = 21.4% |

$U = (100 + 41.6 + 21.4) \div 3$.

$\boxed{U = 54.3}$

O.S :-

Interact b/w hardware & user

user

↓ ↓ ↓

Application

O.S

Hardware

Q Why do we need O.S.?

A If we want hardware without O.S, we need to write program again & again.

- Through put (many task per unit time) e.g. Linux
- Convinence : easily acquire hardware e.g. Window

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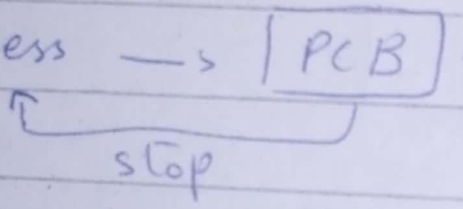
# Process Control Blocks:-

O.S create PCB in every process.

It is data structure and store all process data.

It has (Process ID) of each proce




When process stop/end, PCB life time are delete.

1. Process ID
2. State (Running, Ready, Wait, New, ...
3. Pointer (To point the parent process)
4. Priority
5. Program Counter (which next inst execute)
6. C.P.U register (during execution info in it
7. I/O Information
8. Accounting Info (time limit, execution time

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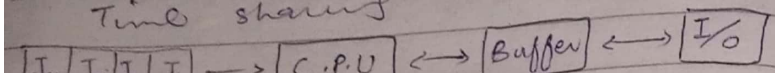
## Batch Processing:- 1960-1970.

Simple B.P (Buffer)
Multi B.P (Spool)
Time sharing




Batch Uni processor

Buffer is temporary storage

Disadvantage:- Idle state.

Multi B.P:-

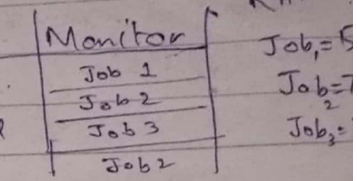
Naturally multi ~~processing~~ programming. In a same batch input gives by $J_1$ and output generate $J_1$ during the processing it takes input $J_2$.

like Printer:-

## Time Sharing:-

Uni processor.

After 0.2 sec watch second job is coming or not. & compare multi job, but which have large memory in RAM.




If 2 Job have same size first run which is arrival first.

## Multi Processor:-

Flynn's arch → e.g. DOS.

SISD (single inst single data). ∴ SI: one pro

SIMD e.g. current O.S: windows, Linux

MISD It is not physically exist. but it is in architecture.

MIMD (Multi inst multi data)

~~O.S~~ current O.S.

Distribution archi ~~shared~~ (MIMD)

It works in big data

multicomp archi → It is Distributed

multi proce (SMP) OR Simitric multi processor → It is share

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# Kernel:-

Kernel
User

Mono Kernel arch (Unix, Linux)
Micro Kernel / Layered arch (Windows.

-> Module:-
Main processor
service
utility
} Resile in kernel.
in Mono kernel.

6 layers:-

It is enchace able.
means any program in hardware automa
in kernel.
It can be communicated.

## 0 Layer (Process Creation)..

Print...
Loop
Control Stor

break in to the process.
It come to the ready queue.
parent child relation. If parent
close all child will be closed.

P=5 Parent
P=5.1 child
P=5.2 child

depends on
piority

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Process
User

## 1. Memory Managment:-

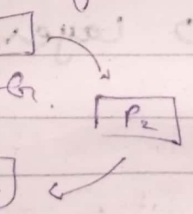
It is like cache or RAM.

## 2. Process Communication:-

IPC (Inter Process Communication)

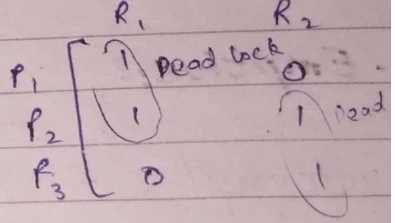
- **Dead lock:-**

When 2 thing (process) have only one resource both process are fight, take who which have high piority & second one in waiting and ~~RAG~~ (~~Resource Allocation Graph~~) both are not executing. after that it take a stavish locks.




- Process communication share our PCB. to find which process should ~~take~~ resources
- It has three types.
  Fully aware to each other
  Partial " " "
  Unaware " " "

- **Fully Aware:-**
  It share fully PC
  It does not have dead lock.
- **Partial Aware:-**
  It share partial
  PCB. It has chance to dead lo
- **Unaware Aware:-**
  It does not share.




## 3. I/O Managment:-

I/O

## 4. User Program:-

## 5. Interface:-

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# Ch#3 Process & Discription

Process: program in execution mode or set of instruction.

It has two types.

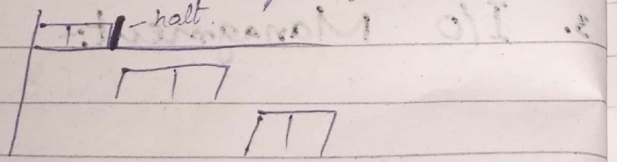
Program → Process → Dependent / Independ → Pre-emp / Non-pre emp

**Dependent:-** program is dependent: e.g. if else condition for loop.

**Independent:-**
e.g. print command.

**Pre-Emptive:-**

If any process halt by interrupt or by force.
It can be on ready queue.



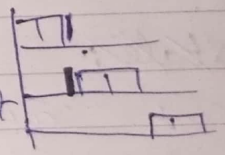

**Non-premptive:-**

Does not halt.

Operating system or Kernel.

## Operating System Do job when It process:

1. Process creation. (reason) login to open new program
   - O.S reason
   - Parent create child
2. Process Termination. It has 14 reas
   1. Compelete process
   2. Dead lock
   3. Starvish
   4. When childs parent finish also finish
   4. Parent request to finish child number
3. Process Block: It has only 1 rea
   Software Interrupt. or If any process ~~dep~~ demand of resource it is in blocked state then in ready q or after block it goes in suspend. multiple to depend on event call
4. Process Resume:-



The second process start is called resume.

5. Communication.

6. **Suspend:-** 1. RAM overload it take hardware some part (virtual memory) behave like temporary memory. or swap

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resource occur = event.

2. It is a time chain. wait for resource

3. Parent suspend to child.

4. O.S reason

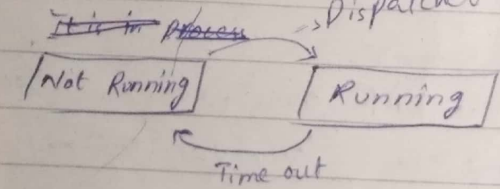
## Logical Views Of Process OR Process Stale Model:-

- 2 stale process model.
- 5 stale process model
- 6 " " "
- 7 " " "

## 2 stale:-

Process switching take more time of O.S.

## 2 stale:-

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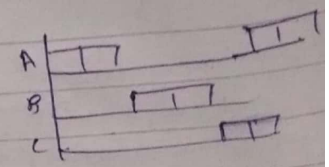
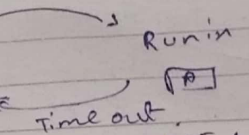
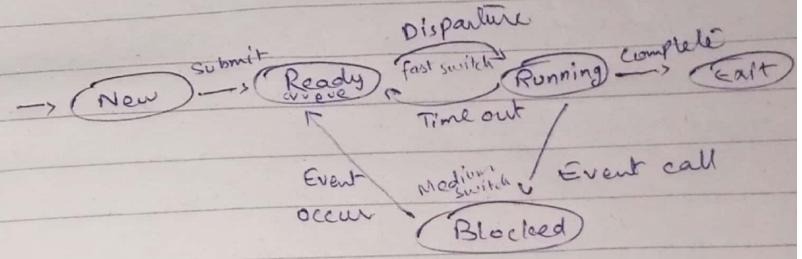


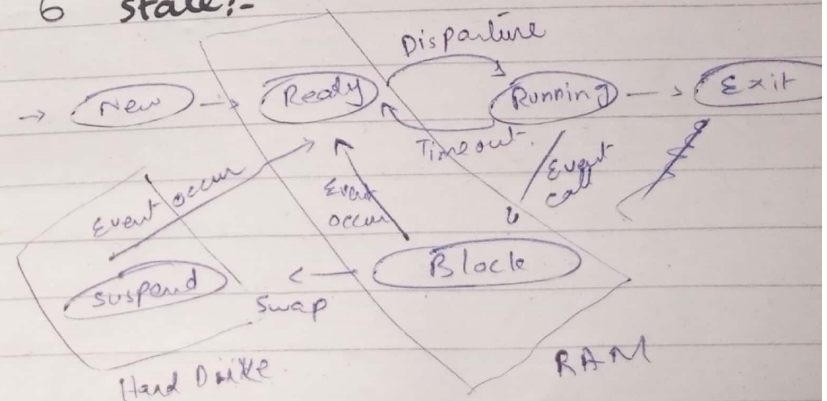




It is not compelete bcz if any process demand any resource so, process not com

## 5 stale:-




## 6 stale:-




If same time event occur in block and suspend. So higher piority is block stale.

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