Royal Military College of Canada
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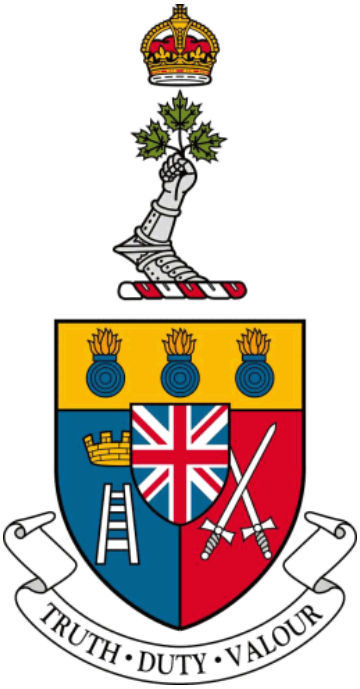

DID-03 - Statement of Requirements

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September 14, 2018

Contents

1 Introduction **2**
- 1.1 Document Purpose . . . 2
- 1.2 Background . . . 2
- 1.3 Aim . . . 2
- 1.4 Scope . . . 2

2 Requirement Definition Activities **3**
- 2.1 Information . . . 3
  - 2.1.1 Meetings with Dr. Givigi . . . 3
- 2.2 How References Were Used . . . 3
  - 2.2.1 First Reference . . . 3
  - 2.2.2 Another Reference . . . 3

3 Product Requirements **4**
- 3.1 Functional Requirements (FR) . . . 4
  - 3.1.1 FR-01: First Thing To Do . . . 4
  - 3.1.2 FR-02: Second Thing To Do . . . 4
- 3.2 Performance Requirements (PR) . . . 4
  - 3.2.1 PR-01 . . . 4
- 3.3 Interface Requirements (IR) . . . 4
  - 3.3.1 IR-01 . . . 4
- 3.4 Simulation Requirements (SimR) . . . 4
  - 3.4.1 SimR-01 . . . 4
- 3.5 Implementation Requirements (ImpR) . . . 4
  - 3.5.1 ImpR-01 . . . 4
  - 3.5.2 ImpR-02: Turtlebot Robot Operating System . . . 4
- 3.6 Schedule Restrictions (SR) . . . 4
  - 3.6.1 SchR-01: First Prototype . . . 4

4 Risk Assessment **5**
- 4.1 Risks . . . 5
- 4.2 Likelihood . . . 5
- 4.3 Impact . . . 5

5 Conclusion **6**
- 5.1 Summary . . . 6
- 5.2 Link to Preliminary Design Specification . . . 6

Part 1

Introduction

1.1 Document Purpose

1.2 Background

1.3 Aim

1.4 Scope

Part 2

Requirement Definition Activities

2.1 Information

2.1.1 Meetings with Dr. Givigi

2.2 How References Were Used

2.2.1 First Reference

2.2.2 Another Reference

Part 3

Product Requirements

3.1 Functional Requirements (FR)

3.1.1 FR-01: First Thing To Do

3.1.2 FR-02: Second Thing To Do

3.2 Performance Requirements (PR)

3.2.1 PR-01

3.3 Interface Requirements (IR)

3.3.1 IR-01

3.4 Simulation Requirements (SimR)

3.4.1 SimR-01

3.5 Implementation Requirements (ImpR)

3.5.1 ImpR-01

3.5.2 ImpR-02: Turtlebot Robot Operating System

The simplest obstacle avoidance algorithm must be implemented on a Turtlebot using the Robot Operating System

3.6 Schedule Restrictions (SR)

3.6.1 SchR-01: First Prototype

The first functional prototype shall be available for Beta testing no later than November 1st

Part 4

Risk Assessment

4.1 Risks

4.2 Likelihood

4.3 Impact

Part 5

Conclusion

5.1 Summary

5.2 Link to Preliminary Design Specification

References