

# A taste of Quasi-Geostrophy

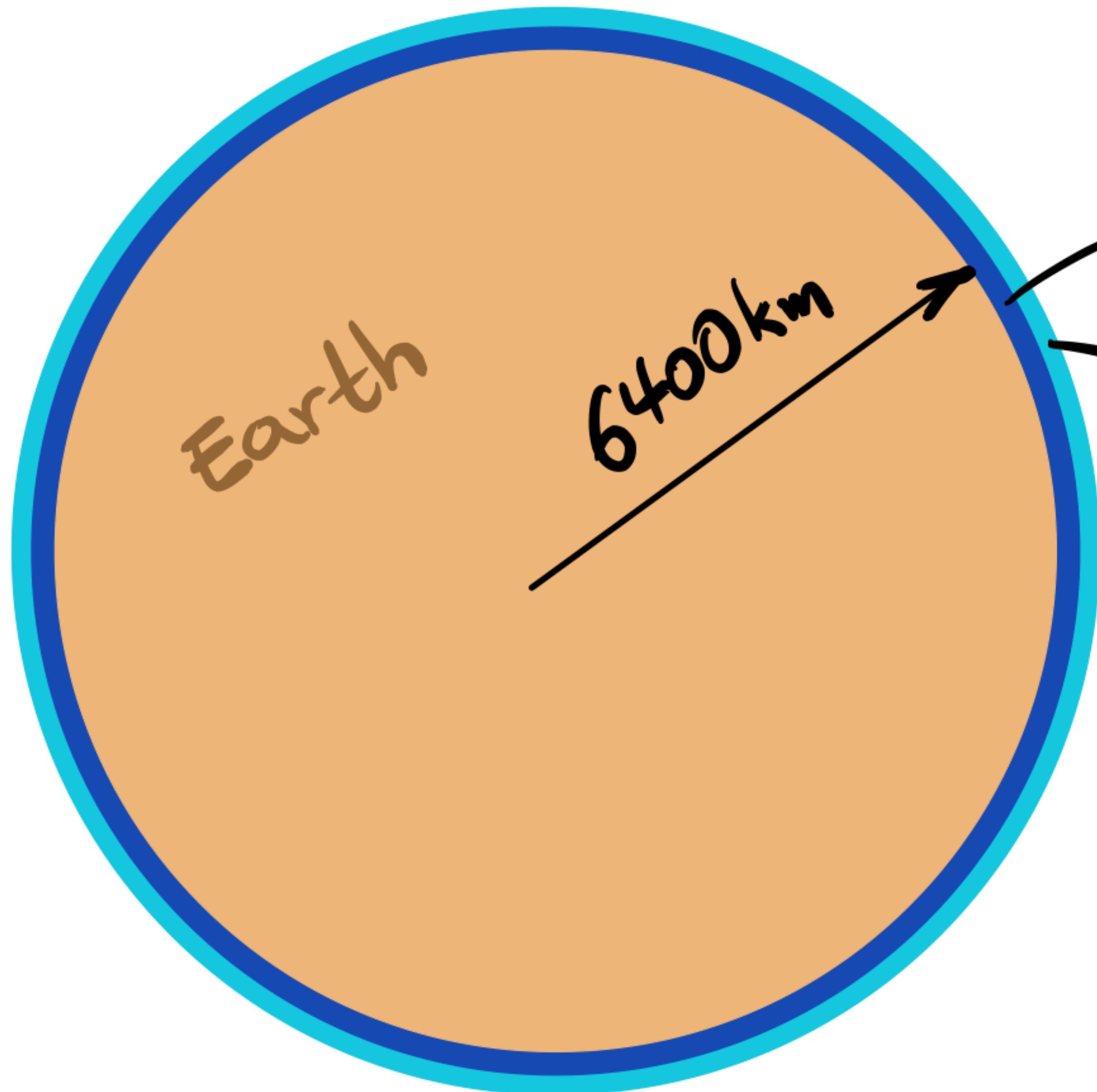


**CLEX Winter School 2020  
Atmosphere & Ocean Dynamics**

(Teaser version via [ZOOM](#))

**Navid Constantinou  
ANU**

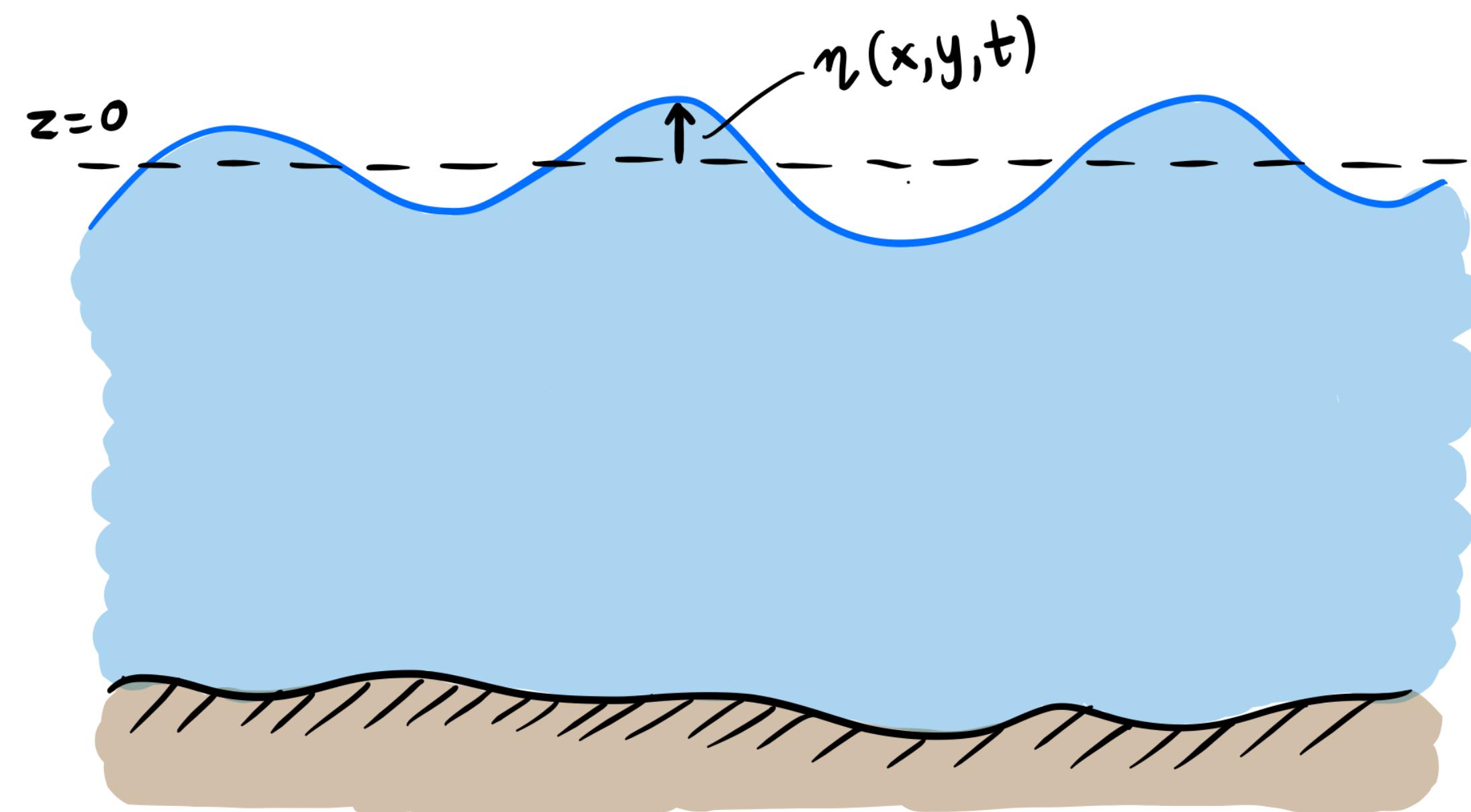
## Shallow-water dynamics



ocean ~4km  
atmosphere ~10 km

ignore stratification;  
take fluid with constant density  $\rho_0$

# Shallow-water dynamics

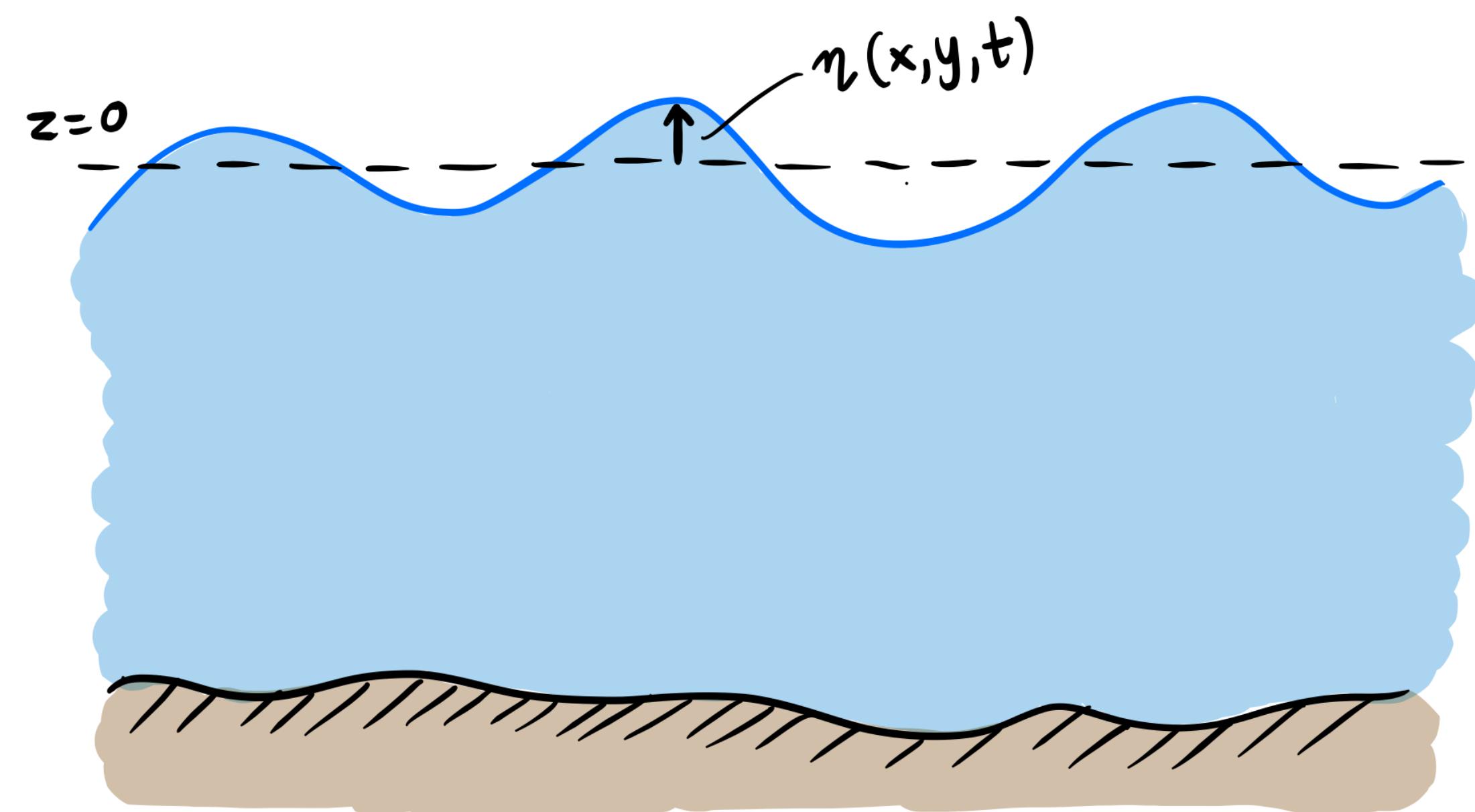


vertical momentum equation

$$\frac{\partial w}{\partial t} + u \frac{\partial w}{\partial x} + v \frac{\partial w}{\partial y} + w \frac{\partial w}{\partial z} = - \frac{1}{\rho_0} \frac{\partial p}{\partial z} - g$$

$\underbrace{\phantom{w}}$  very small       $\underbrace{\phantom{w}}$  very small       $\underbrace{\phantom{w}}$  LARGE       $\underbrace{\phantom{w}}$  LARGE

# Shallow-water dynamics



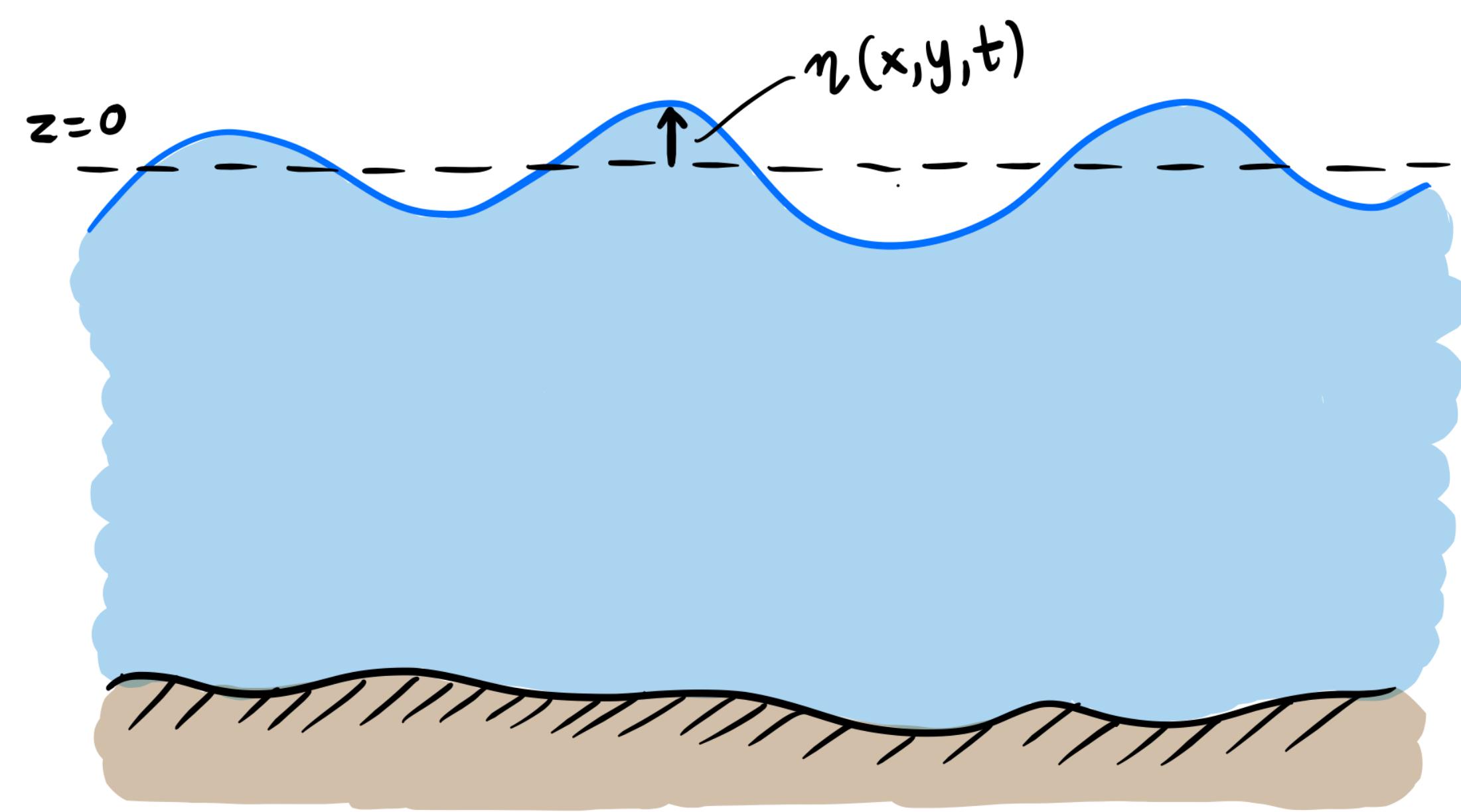
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very small

$$= - \underbrace{\frac{1}{\rho_0} \frac{\partial p}{\partial z}}_{\text{LARGE}} - g \underbrace{\phantom{\frac{1}{\rho_0} \frac{\partial p}{\partial z}}}_{\text{LARGE}}$$

# Shallow-water dynamics



vertical momentum equation

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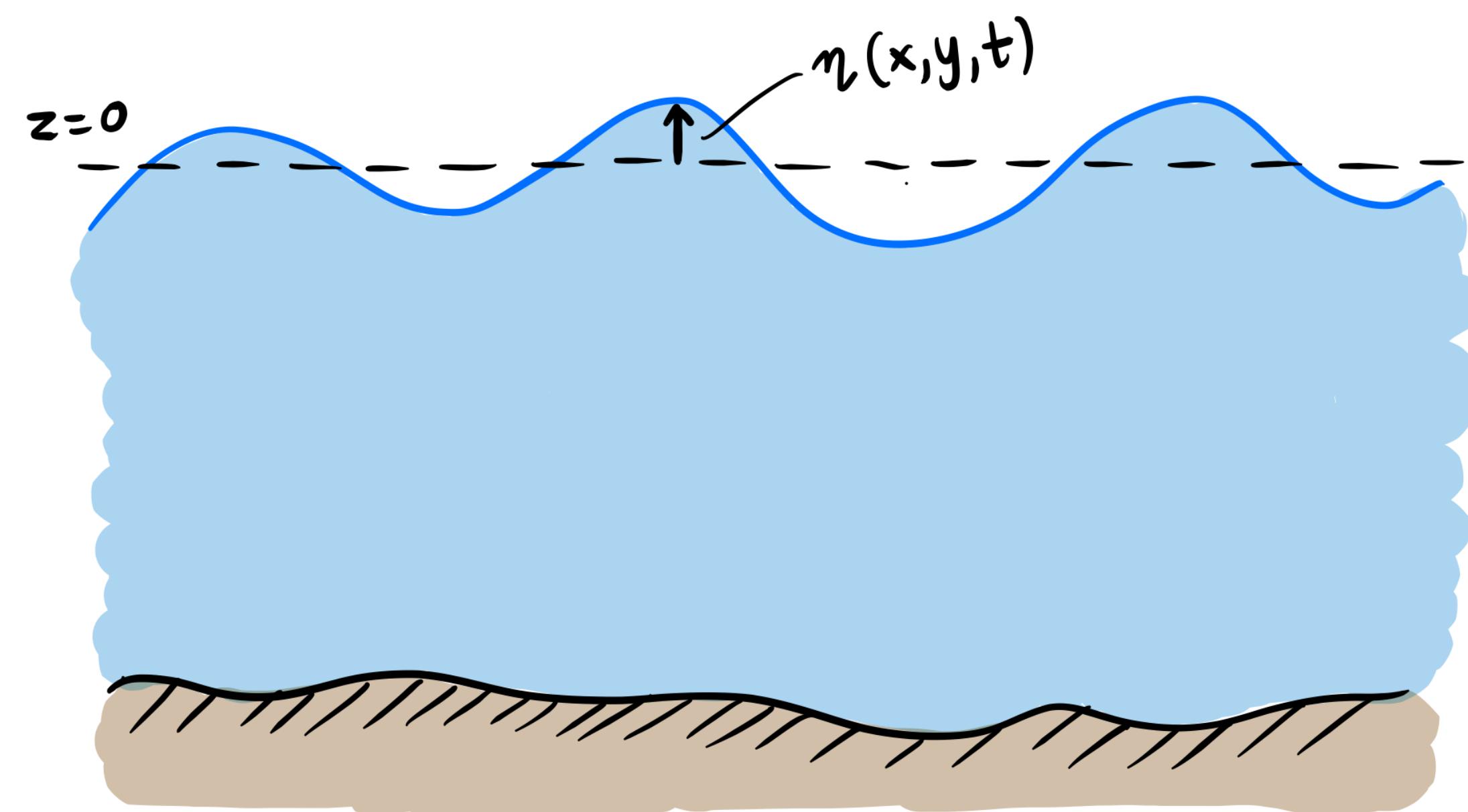
very small

$$= - \underbrace{\frac{1}{\rho_0} \frac{\partial p}{\partial z}}_{\text{LARGE}} - g \underbrace{\phantom{\frac{\partial p}{\partial z}}}_{\text{LARGE}}$$

hydrostatic balance

$$\frac{\partial p}{\partial z} = - \rho_0 g$$

# Shallow-water dynamics



vertical momentum equation

$$\frac{\partial w}{\partial t} + u \frac{\partial w}{\partial x} + v \frac{\partial w}{\partial y} + w \frac{\partial w}{\partial z}$$

very small

$$= - \frac{1}{\rho_0} \frac{\partial p}{\partial z} - g$$

LARGE      LARGE

hydrostatic balance

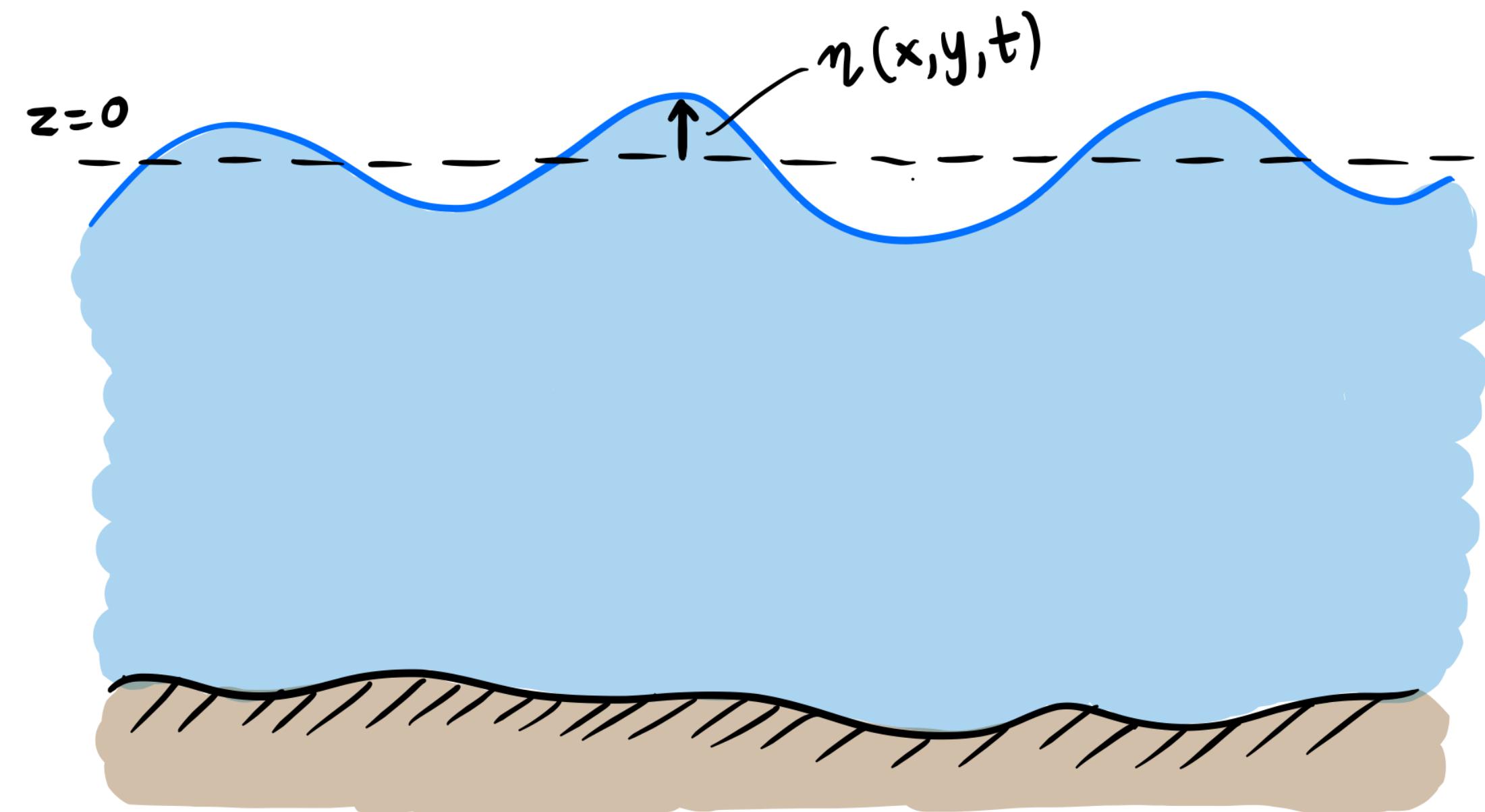
$$\frac{\partial p}{\partial z} = - \rho_0 g$$

$$p(x, y, z = \eta, t) = 1 \text{ atm}$$

$$\left. \begin{array}{l} \\ \\ \end{array} \right\} \Rightarrow p(x, y, z, t) = \rho_0 g(\eta(x, y, t) - z) + 1 \text{ atm}$$

# Shallow-water dynamics

horizontal momentum equations



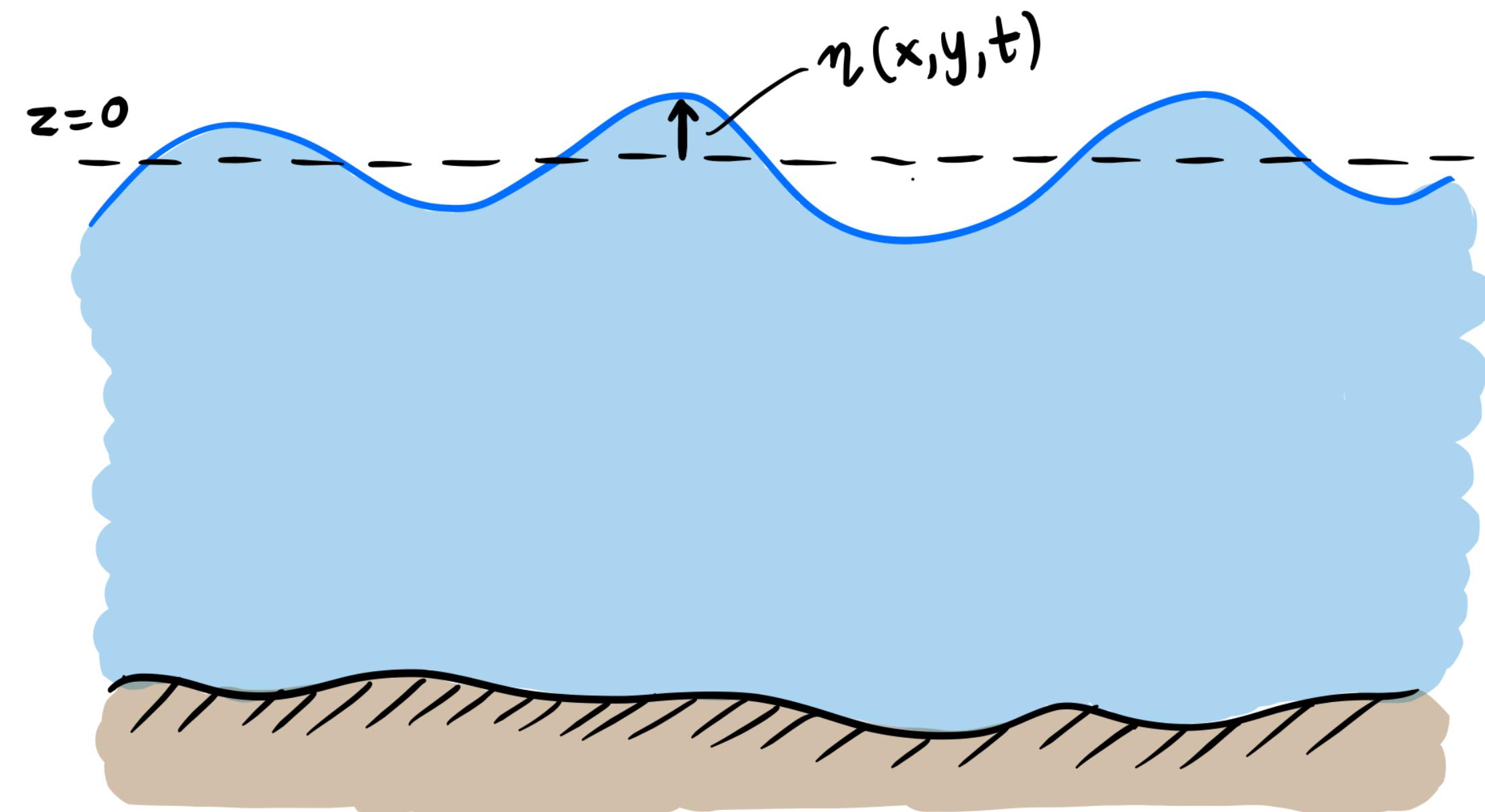
$$\underbrace{\frac{\partial \mathbf{u}}{\partial t} + \mathbf{u} \cdot \nabla \mathbf{u} + f \hat{z} \times \mathbf{u}}_{\frac{D\mathbf{u}}{Dt}} = - \frac{1}{\rho_0} \nabla p$$

$$\mathbf{u} = (u(x, y, t), v(x, y, t))$$

$$\nabla = \frac{\partial}{\partial x} \hat{x} + \frac{\partial}{\partial y} \hat{y}$$

# Shallow-water dynamics

horizontal momentum equations



$$\underbrace{\frac{\partial \mathbf{u}}{\partial t} + \mathbf{u} \cdot \nabla \mathbf{u} + f \hat{z} \times \mathbf{u}}_{\frac{D\mathbf{u}}{Dt}} = - \underbrace{\frac{1}{\rho_0} \nabla p}_{\text{use hydrostatic balance}}$$

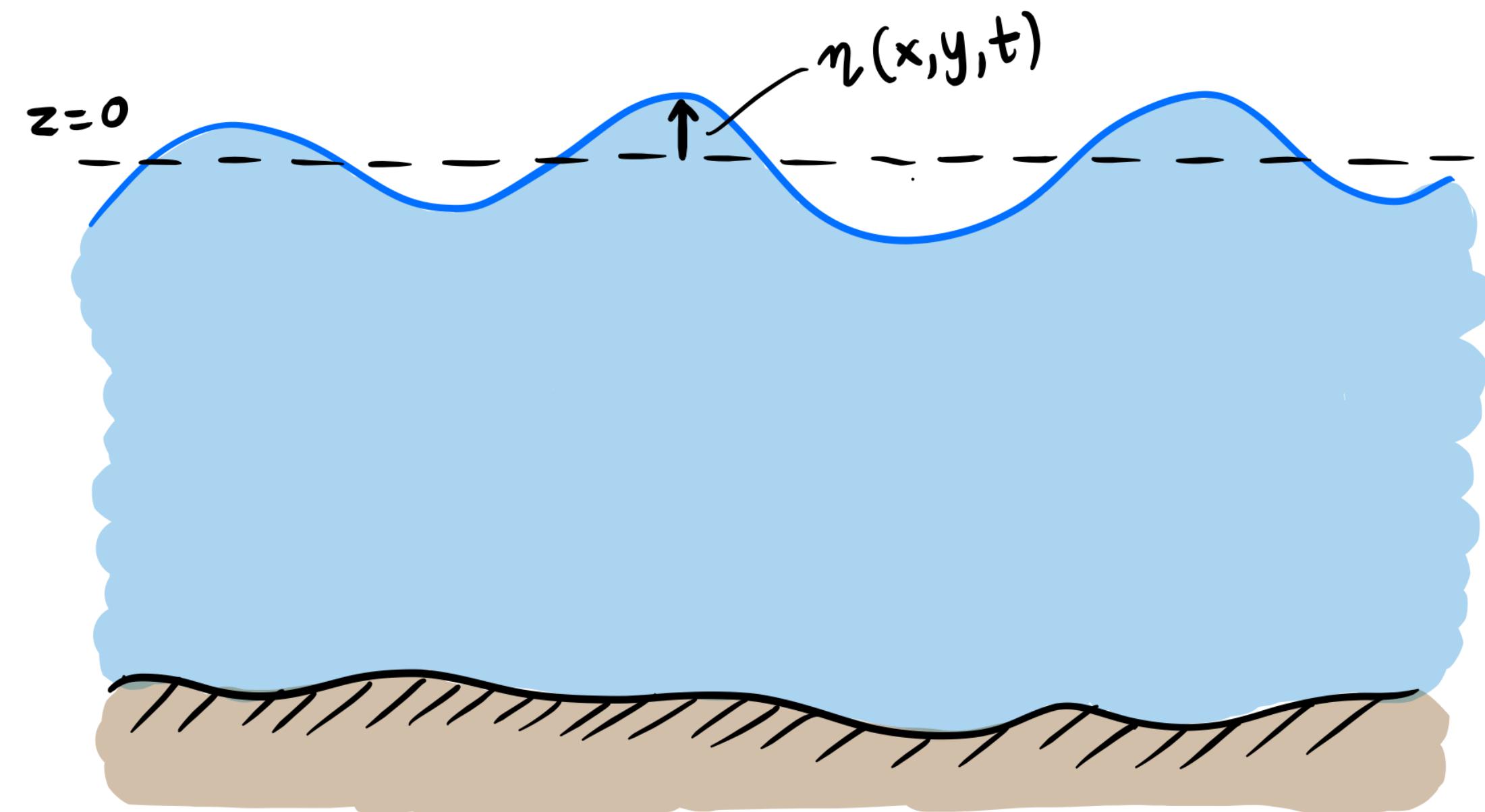
$$p(x, y, z, t) = \rho_0 g (\eta(x, y, t) - z) + p_0$$

$$\mathbf{u} = (u(x, y, t), v(x, y, t))$$

$$\nabla = \frac{\partial}{\partial x} \hat{x} + \frac{\partial}{\partial y} \hat{y}$$

# Shallow-water dynamics

horizontal momentum equations



$$\underbrace{\frac{\partial \mathbf{u}}{\partial t} + \mathbf{u} \cdot \nabla \mathbf{u} + f \hat{z} \times \mathbf{u}}_{\frac{D\mathbf{u}}{Dt}} = - \underbrace{\frac{1}{\rho_0} \nabla p}_{\text{use hydrostatic balance}}$$

$$p(x, y, z, t) = \rho_0 g (\eta(x, y, t) - z) + p_0$$

$$\mathbf{u} = (u(x, y, t), v(x, y, t))$$

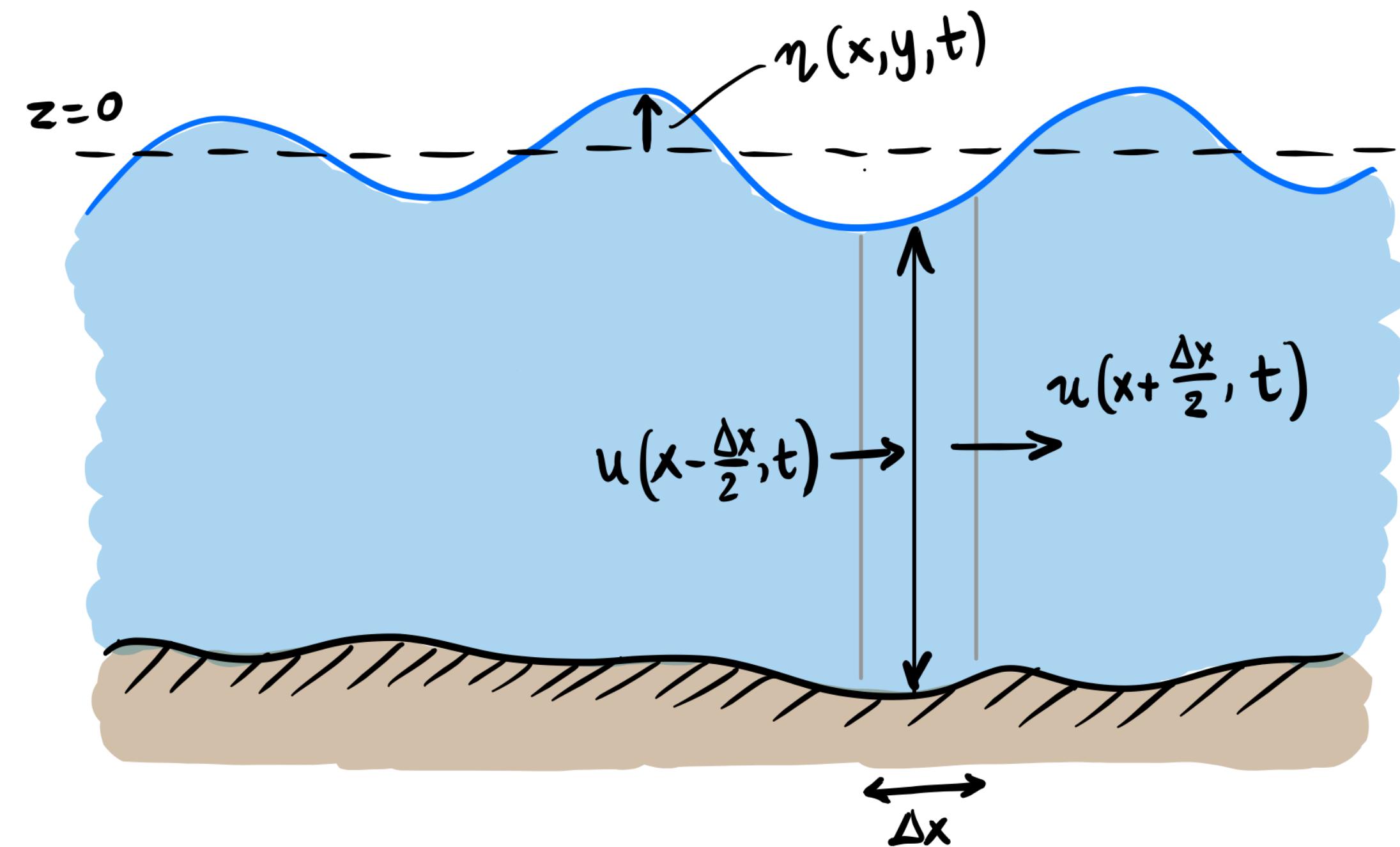
$$\nabla = \frac{\partial}{\partial x} \hat{x} + \frac{\partial}{\partial y} \hat{y}$$

$$\frac{\partial \mathbf{u}}{\partial t} + \mathbf{u} \cdot \nabla \mathbf{u} + f \hat{z} \times \mathbf{u} = - g \nabla \eta$$

# Shallow-water dynamics

mass conservation

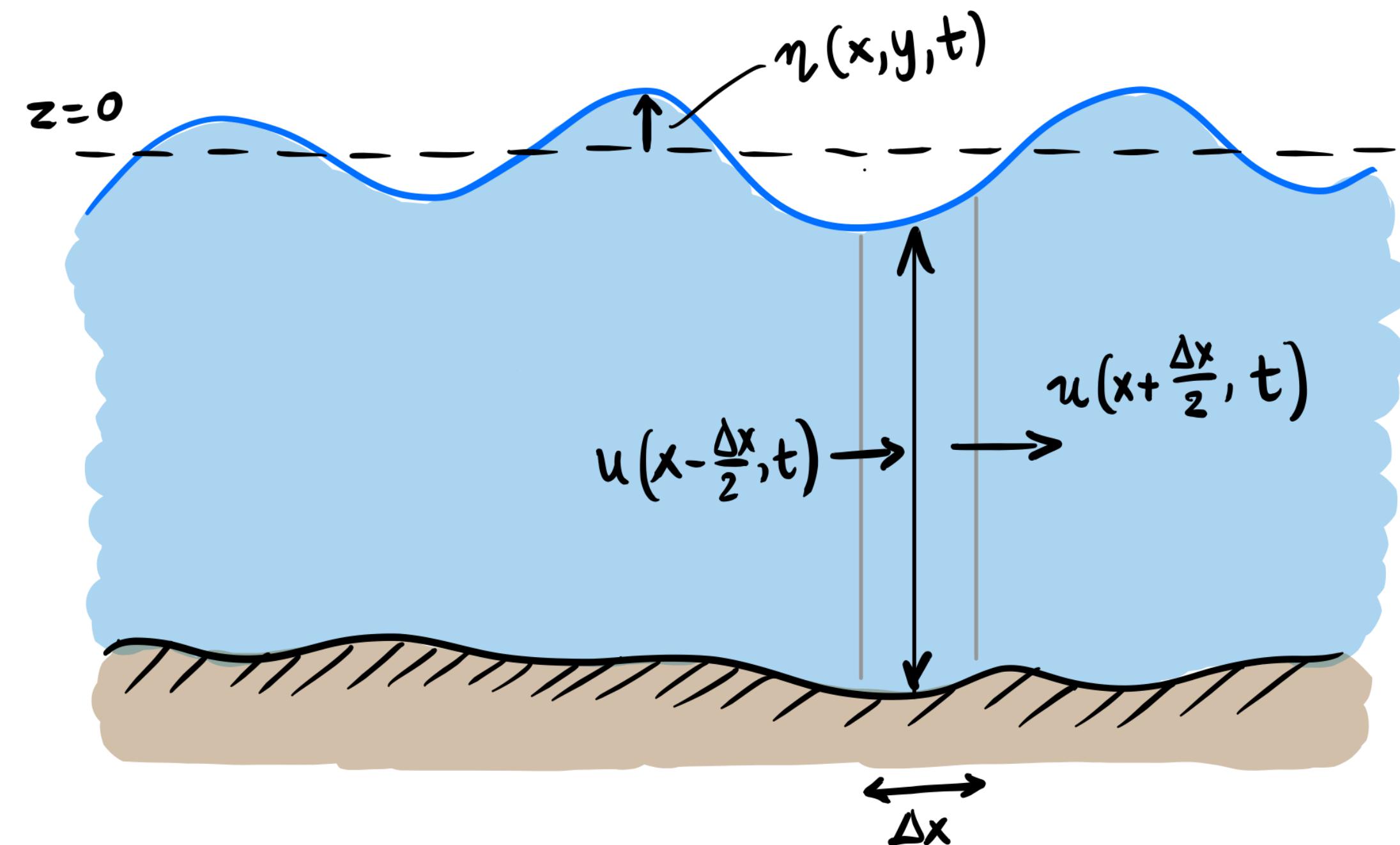
constant density  $\Rightarrow$  volume conservation



# Shallow-water dynamics

mass conservation

constant density  $\Rightarrow$  volume conservation

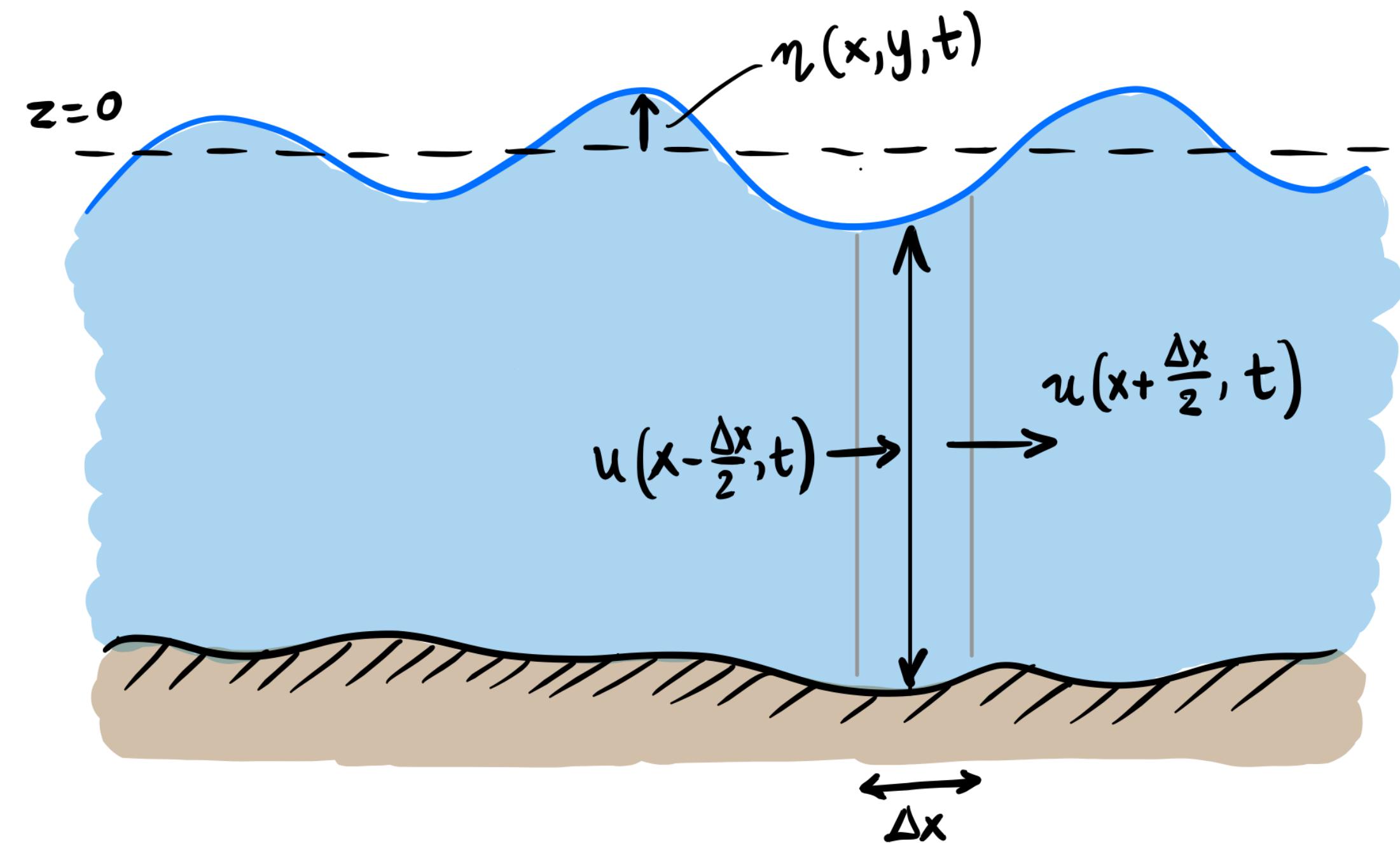


volume of =  $h(x, t) \Delta x$

# Shallow-water dynamics

mass conservation

constant density  $\Rightarrow$  volume conservation

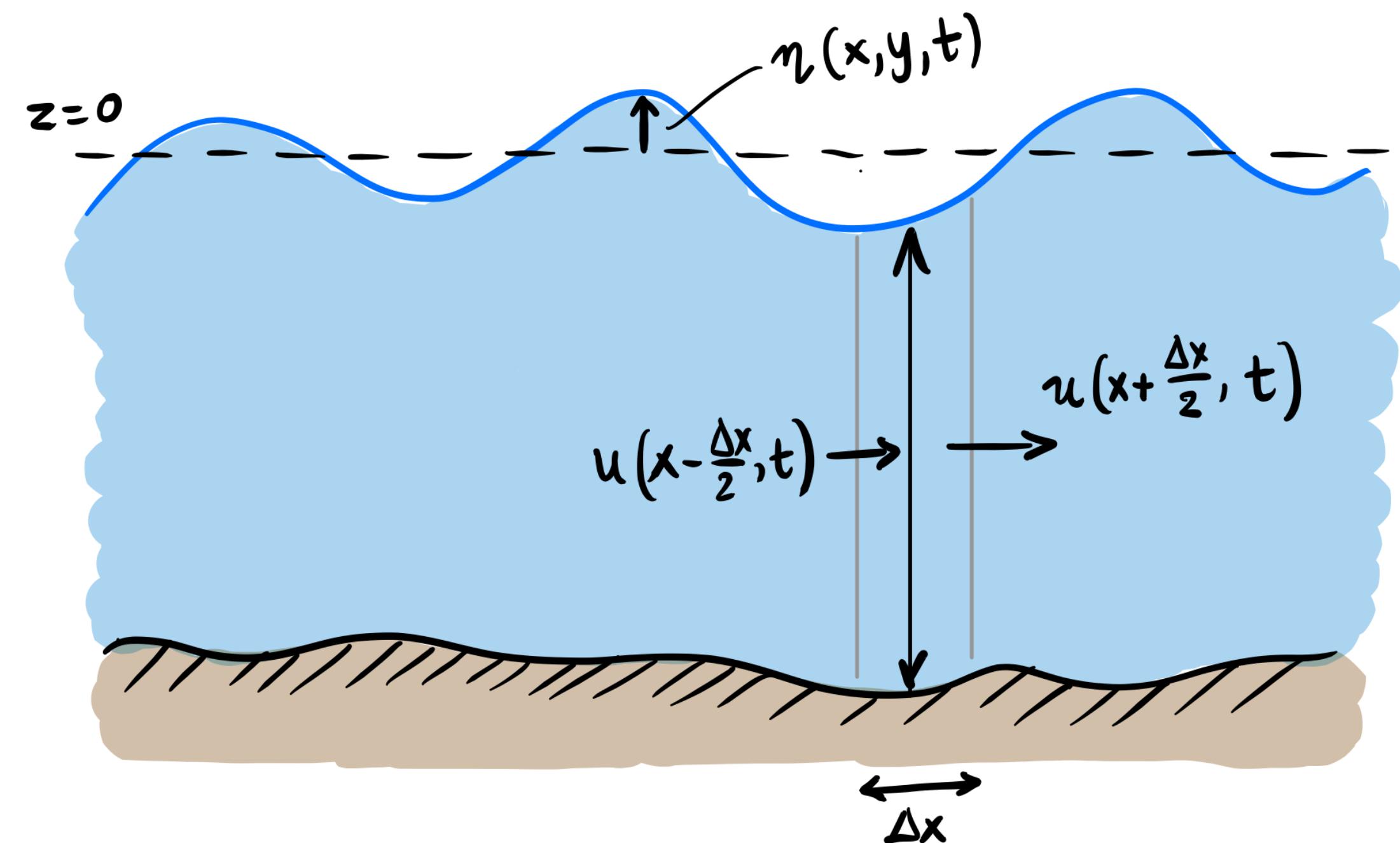


$$\text{volume of } \text{---} = h(x, t) \Delta x$$
$$\text{change of volume } \text{---} = \text{fluid flux into } \text{---} - \text{fluid flux out of } \text{---}$$

# Shallow-water dynamics

mass conservation

constant density  $\Rightarrow$  volume conservation



volume of =  $h(x, t) \Delta x$

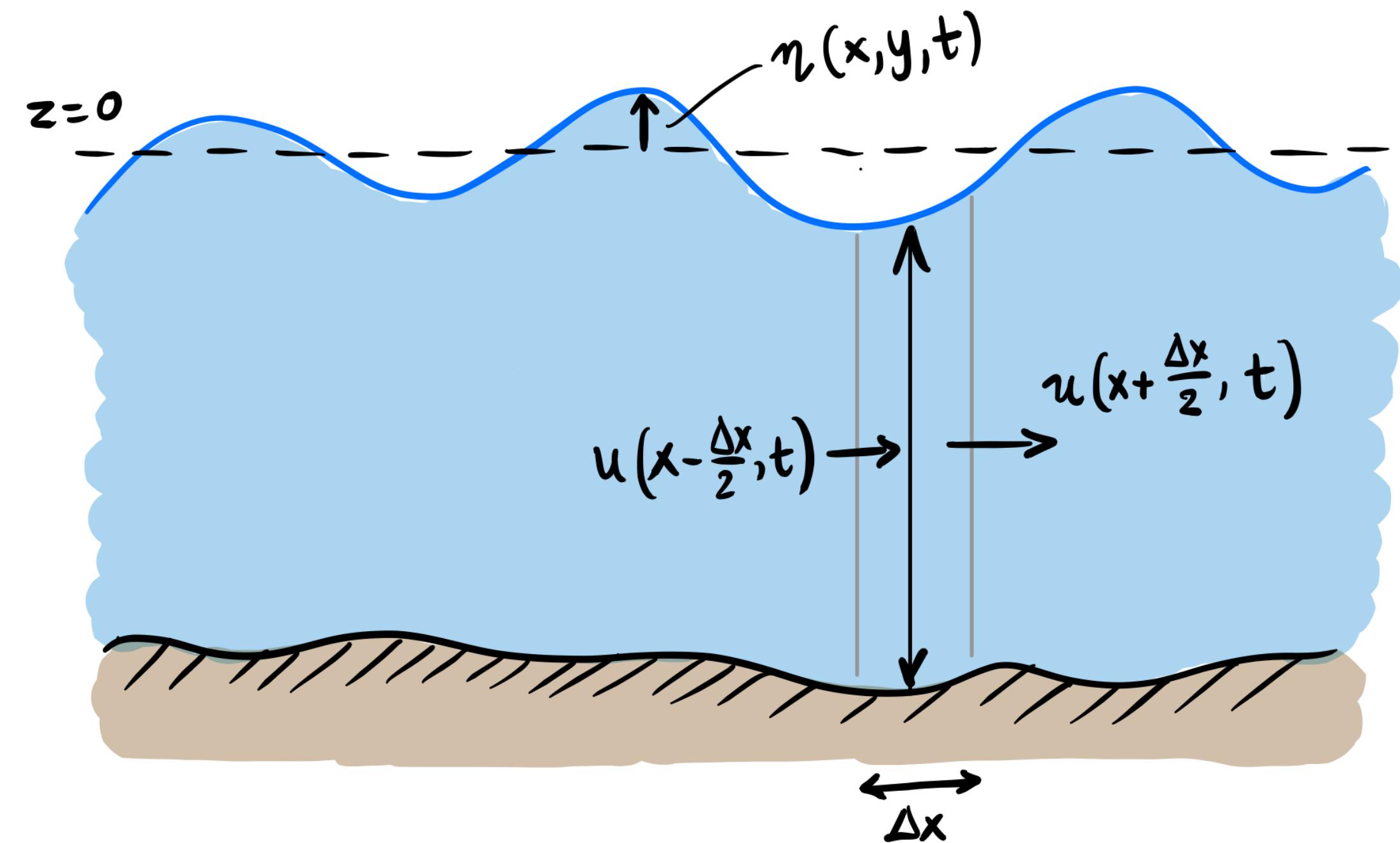
change of volume = fluid flux into - fluid flux out of

$$\Delta x \frac{\partial h(x, t)}{\partial t} = u\left(x - \frac{\Delta x}{2}, t\right) h\left(x - \frac{\Delta x}{2}, t\right) - u\left(x + \frac{\Delta x}{2}, t\right) h\left(x + \frac{\Delta x}{2}, t\right)$$

# Shallow-water dynamics

mass conservation

constant density  $\implies$  volume conservation

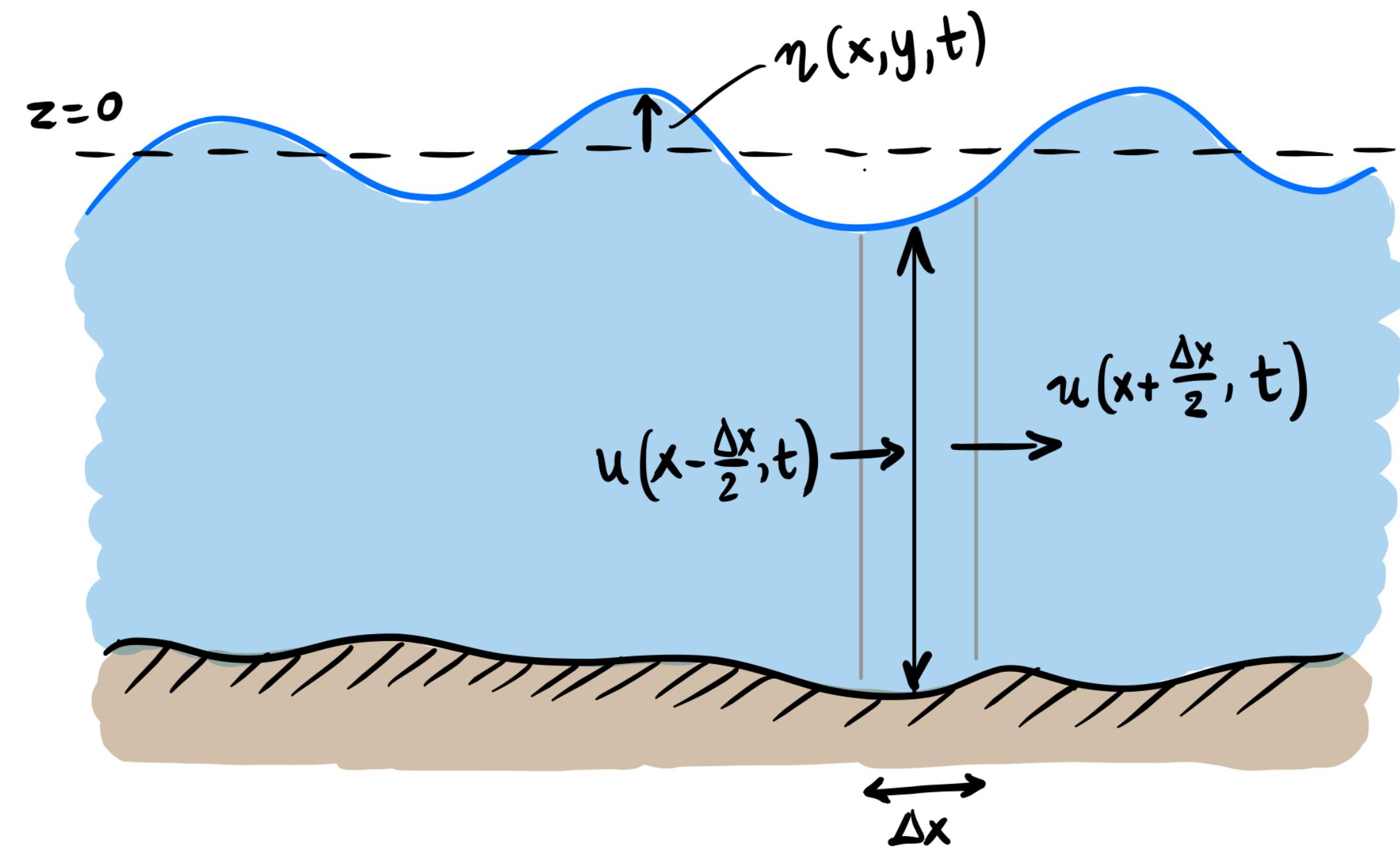


$$\begin{aligned} \text{volume of } \square &= h(x, t) \Delta x \\ \text{change of volume } \square &= \text{fluid flux into } \square - \text{fluid flux out of } \square \\ \Delta x \frac{\partial h(x, t)}{\partial t} &= u\left(x - \frac{\Delta x}{2}, t\right) h\left(x - \frac{\Delta x}{2}, t\right) - u\left(x + \frac{\Delta x}{2}, t\right) h\left(x + \frac{\Delta x}{2}, t\right) \\ &= \Delta x \frac{u\left(x - \frac{\Delta x}{2}, t\right) h\left(x - \frac{\Delta x}{2}, t\right) - u\left(x + \frac{\Delta x}{2}, t\right) h\left(x + \frac{\Delta x}{2}, t\right)}{\Delta x} \end{aligned}$$

# Shallow-water dynamics

mass conservation

constant density  $\implies$  volume conservation

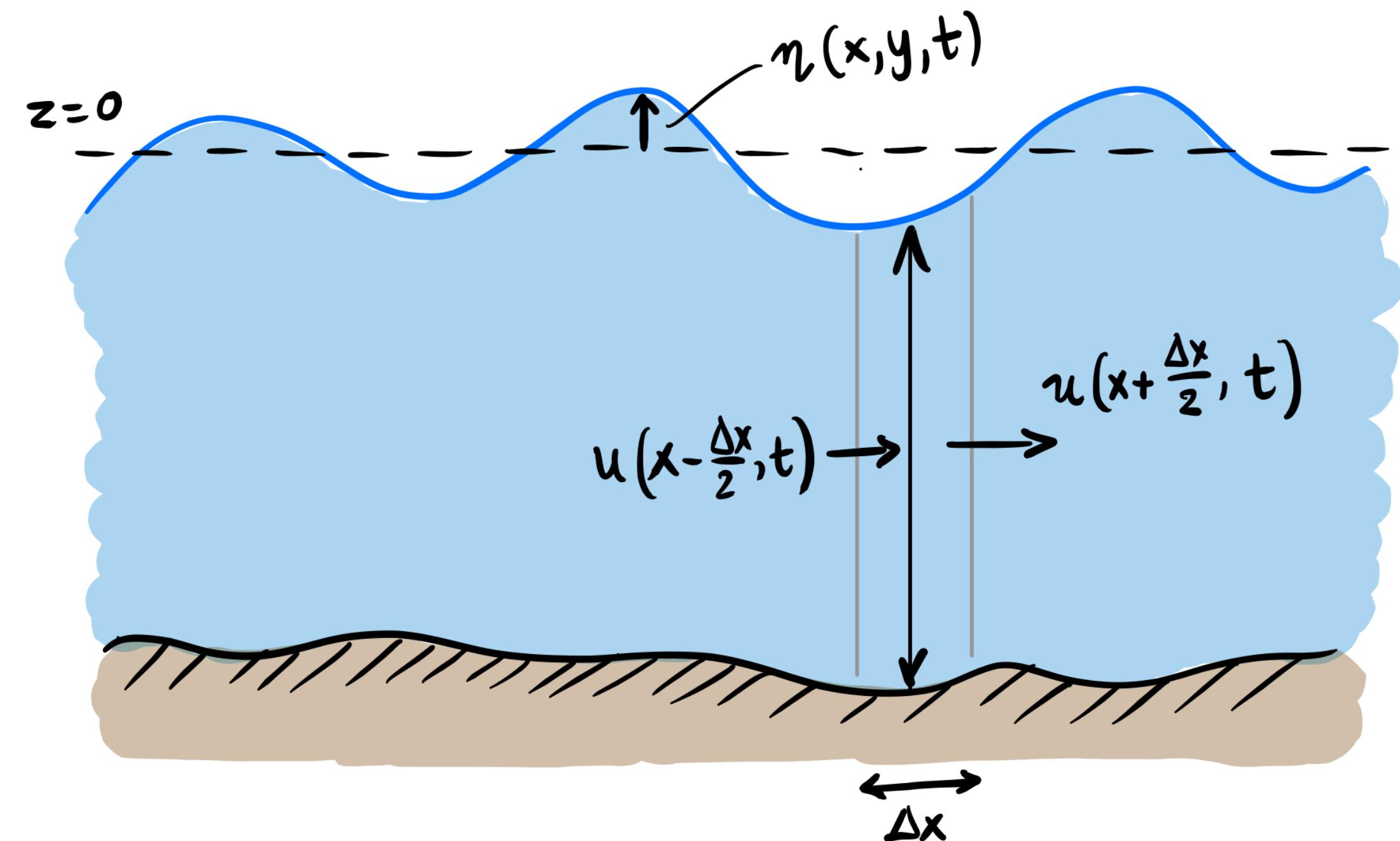


$$\begin{aligned}
 \text{volume of } &= h(x, t) \Delta x \\
 \text{change of volume} &= \text{fluid flux into } - \text{fluid flux out of } \\
 \Delta x \frac{\partial h(x, t)}{\partial t} &= u\left(x - \frac{\Delta x}{2}, t\right) h\left(x - \frac{\Delta x}{2}, t\right) - u\left(x + \frac{\Delta x}{2}, t\right) h\left(x + \frac{\Delta x}{2}, t\right) \\
 &= \Delta x \frac{u\left(x - \frac{\Delta x}{2}, t\right) h\left(x - \frac{\Delta x}{2}, t\right) - u\left(x + \frac{\Delta x}{2}, t\right) h\left(x + \frac{\Delta x}{2}, t\right)}{\Delta x} \\
 &\approx - \Delta x \frac{\partial}{\partial x} [h(x, t) u(x, t)]
 \end{aligned}$$

# Shallow-water dynamics

mass conservation

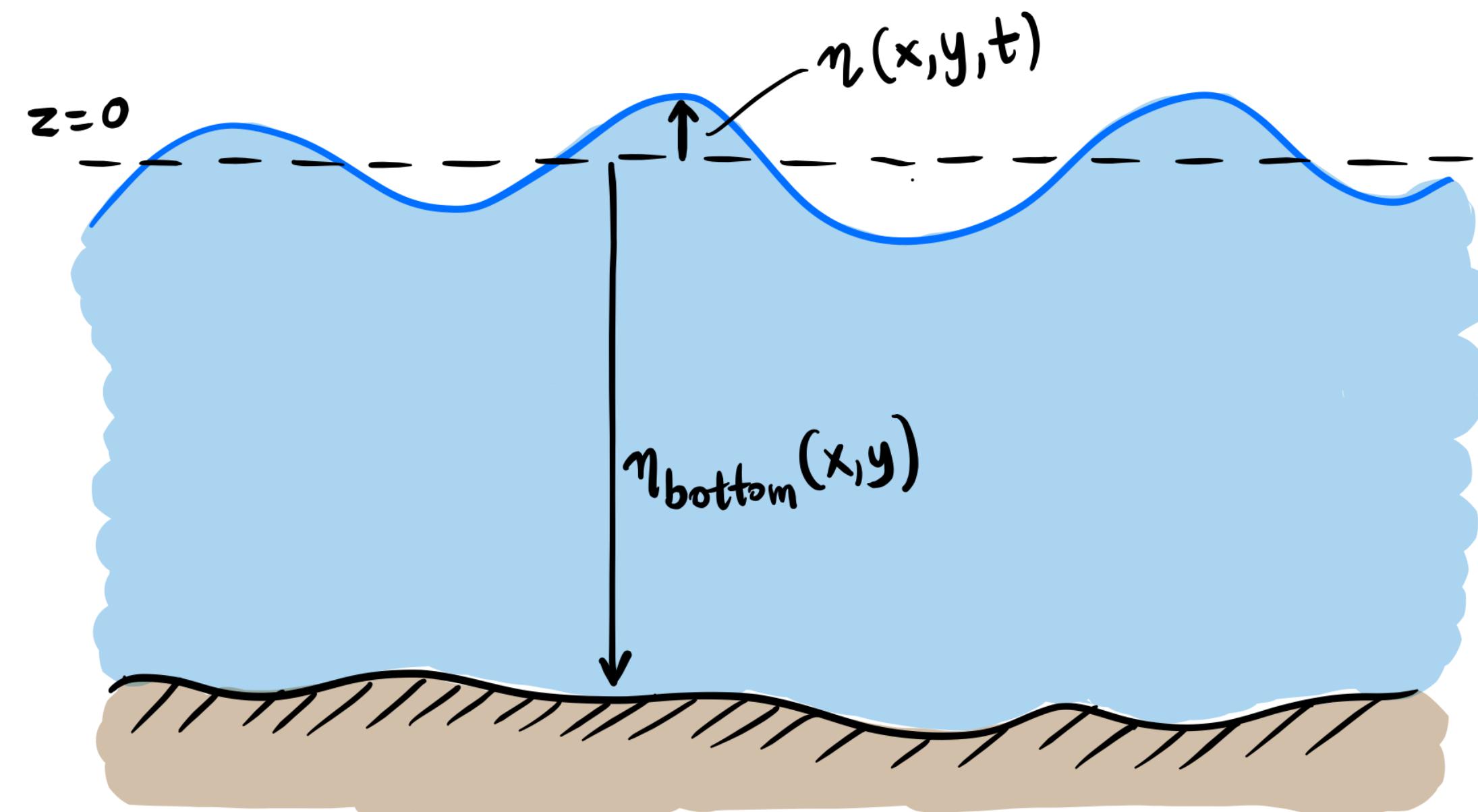
constant density  $\Rightarrow$  volume conservation



$$\begin{aligned} \text{volume of } &= h(x, t) \Delta x \\ \text{change of volume} &= \text{fluid flux into } - \text{fluid flux out of } \\ \Delta x \frac{\partial h(x, t)}{\partial t} &= u\left(x - \frac{\Delta x}{2}, t\right) h\left(x - \frac{\Delta x}{2}, t\right) - u\left(x + \frac{\Delta x}{2}, t\right) h\left(x + \frac{\Delta x}{2}, t\right) \\ &= \Delta x \frac{u\left(x - \frac{\Delta x}{2}, t\right) h\left(x - \frac{\Delta x}{2}, t\right) - u\left(x + \frac{\Delta x}{2}, t\right) h\left(x + \frac{\Delta x}{2}, t\right)}{\Delta x} \\ &\approx - \Delta x \frac{\partial}{\partial x} [h(x, t) u(x, t)] \end{aligned}$$

$$\frac{\partial h}{\partial t} + \nabla \cdot (uh) = 0$$

# Shallow-water dynamics



$$\frac{\partial \mathbf{u}}{\partial t} + \mathbf{u} \cdot \nabla \mathbf{u} + f \hat{z} \times \mathbf{u} = -g \nabla \eta$$

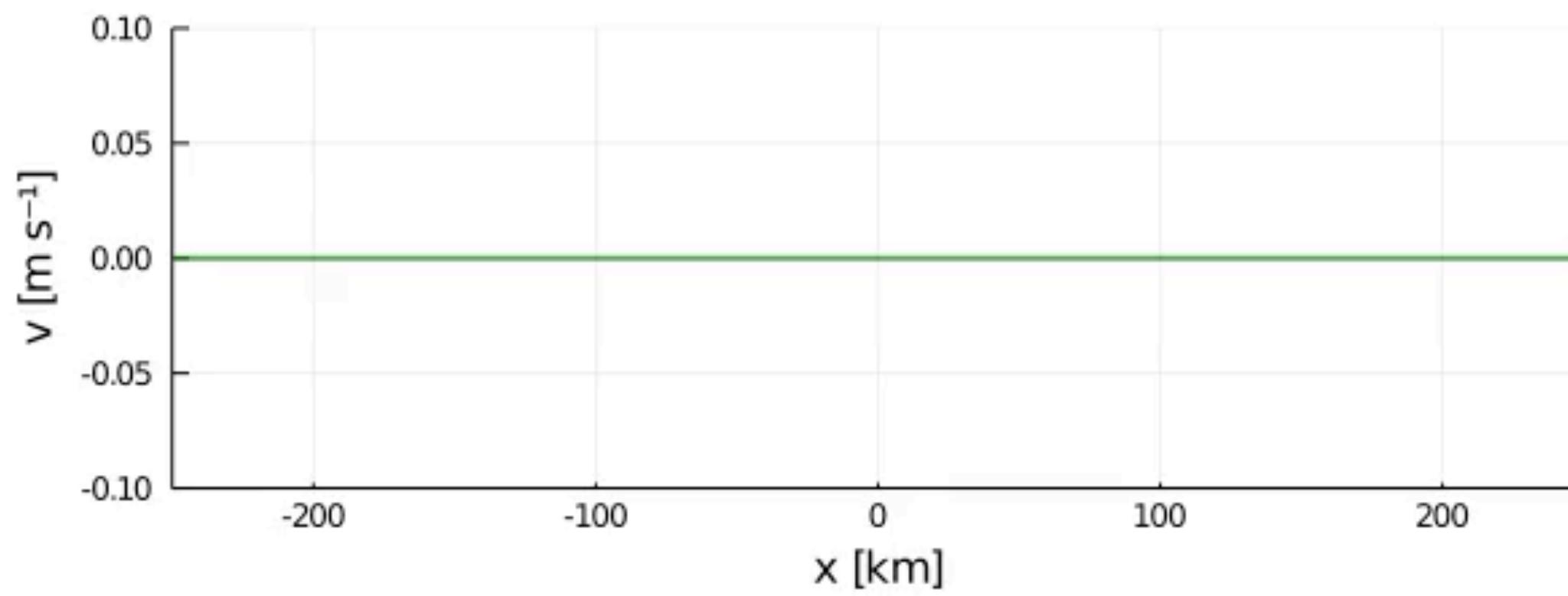
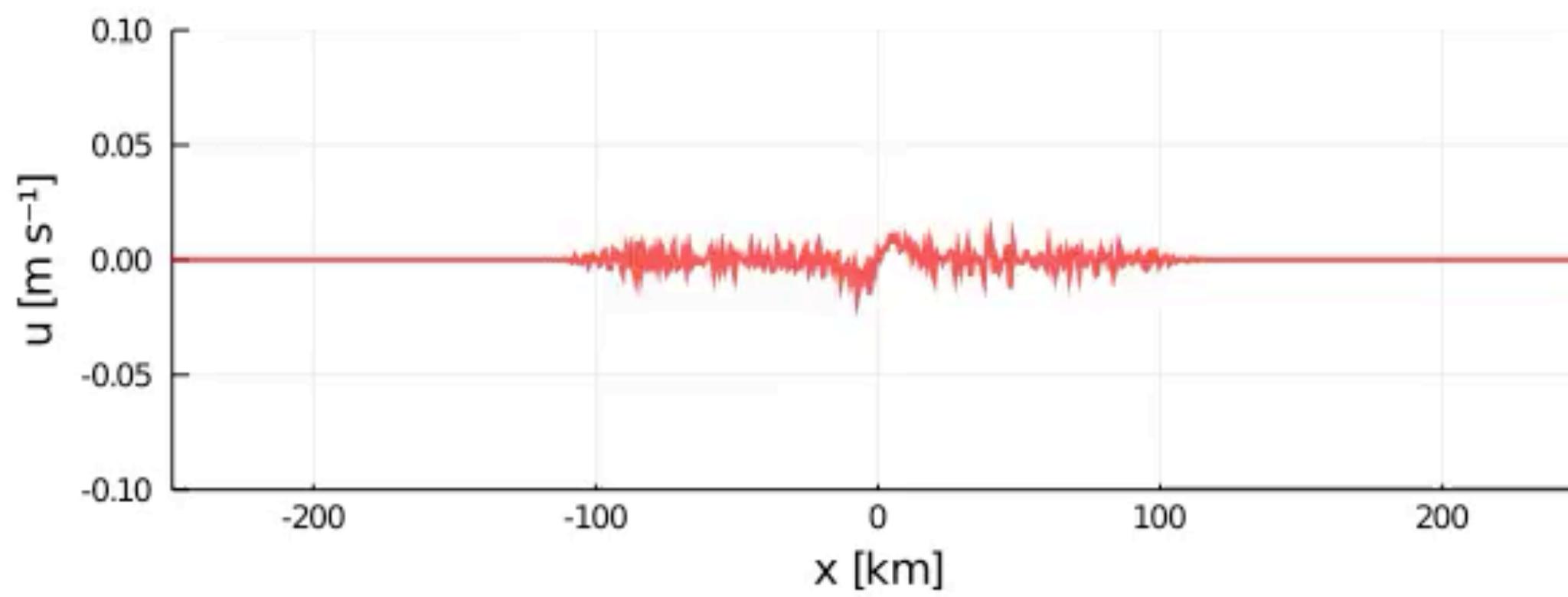
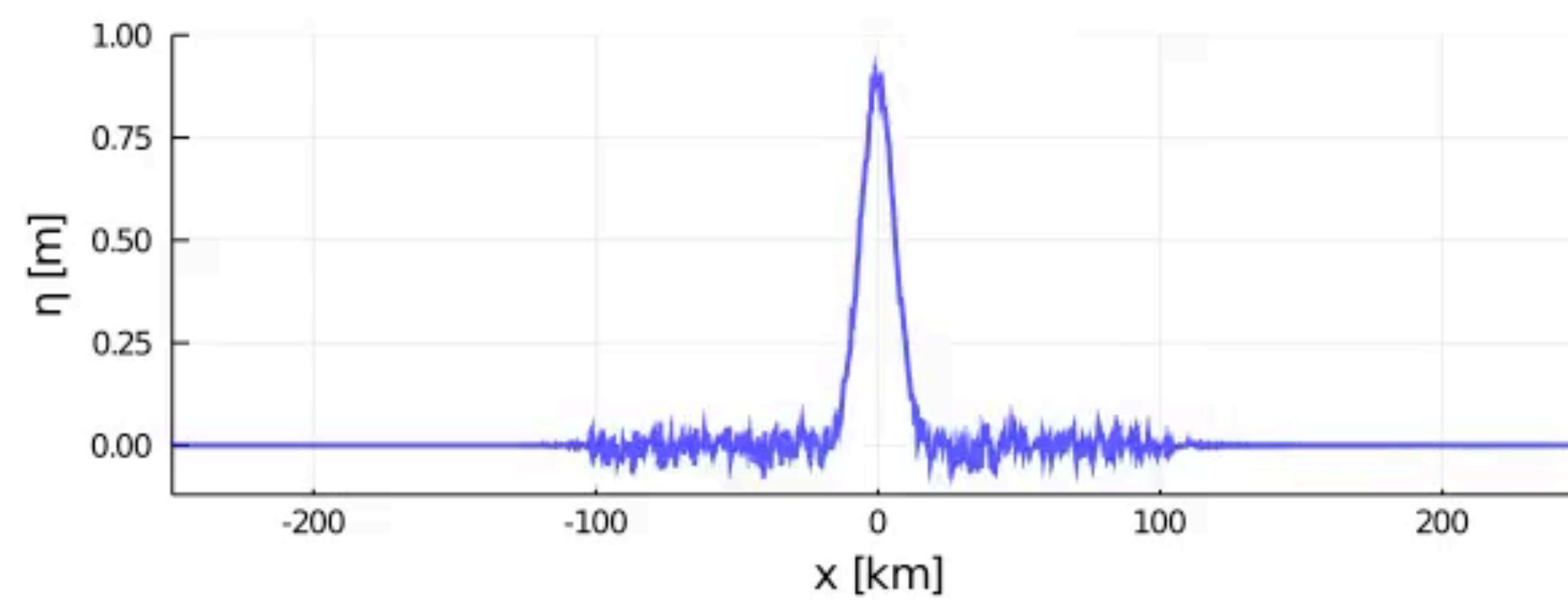
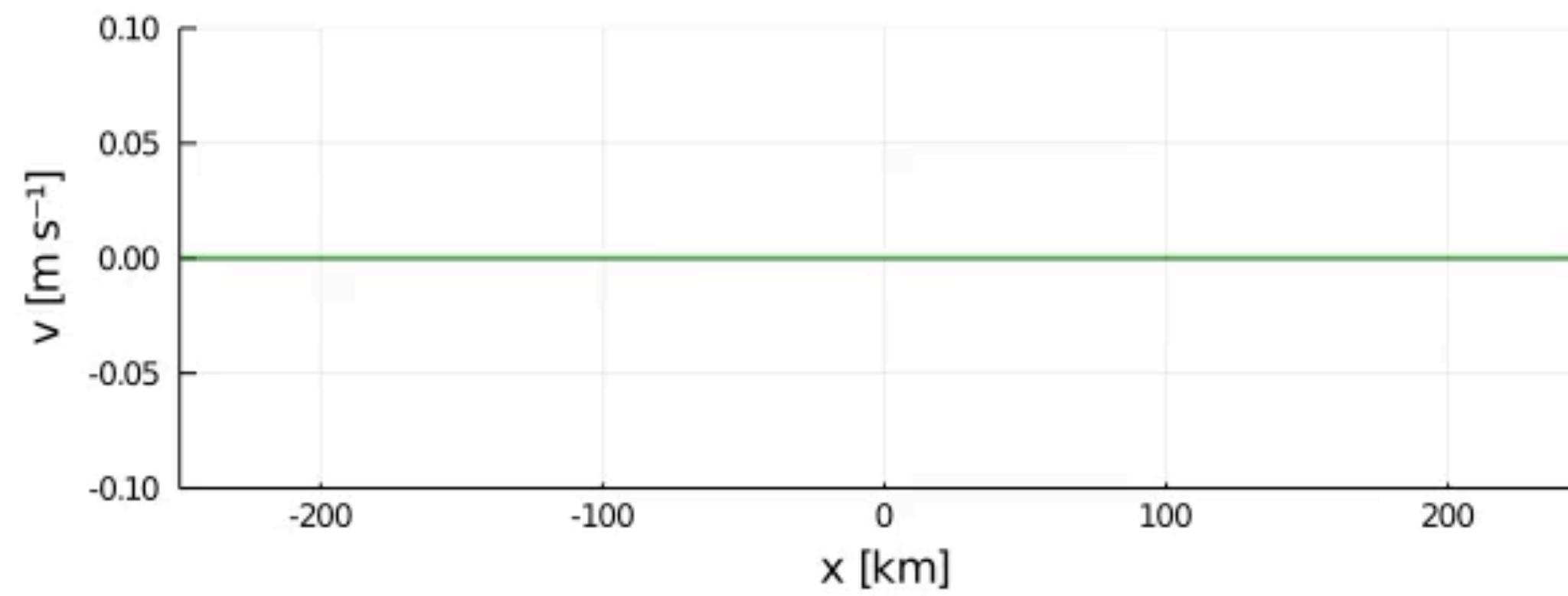
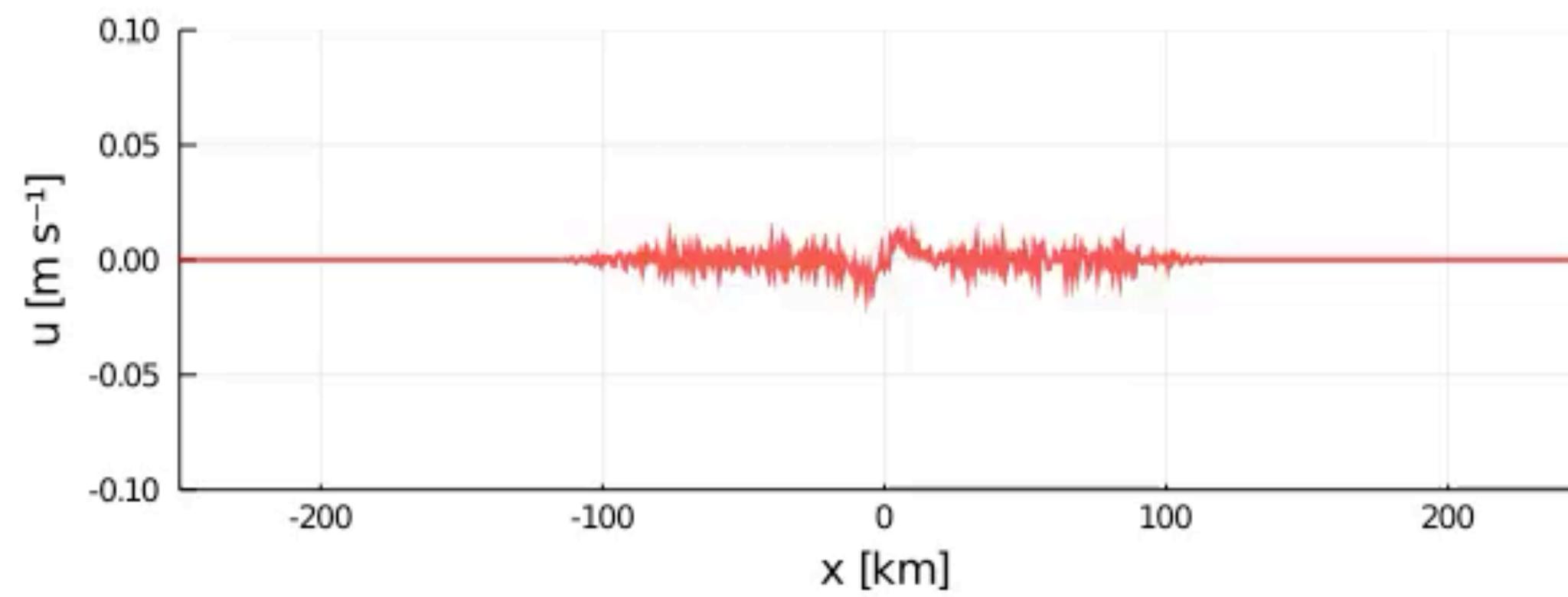
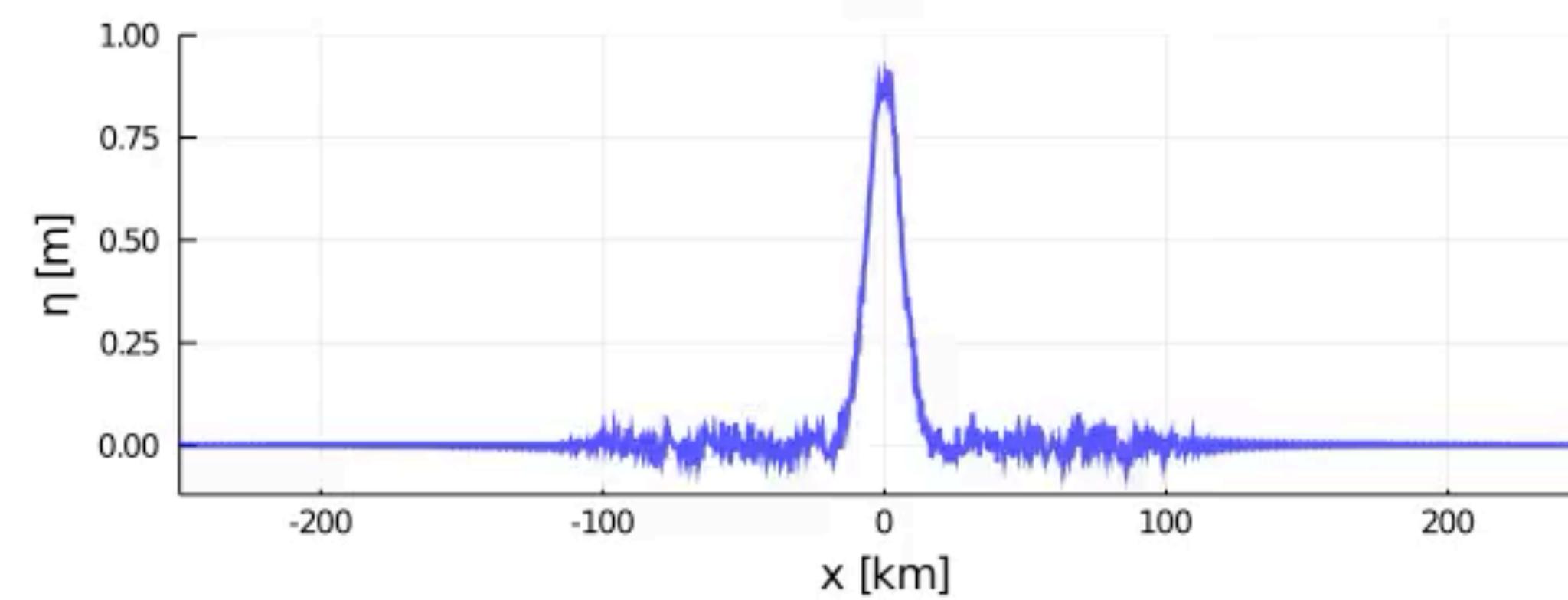
$$\frac{\partial h}{\partial t} + \nabla \cdot (\mathbf{u} h) = 0$$

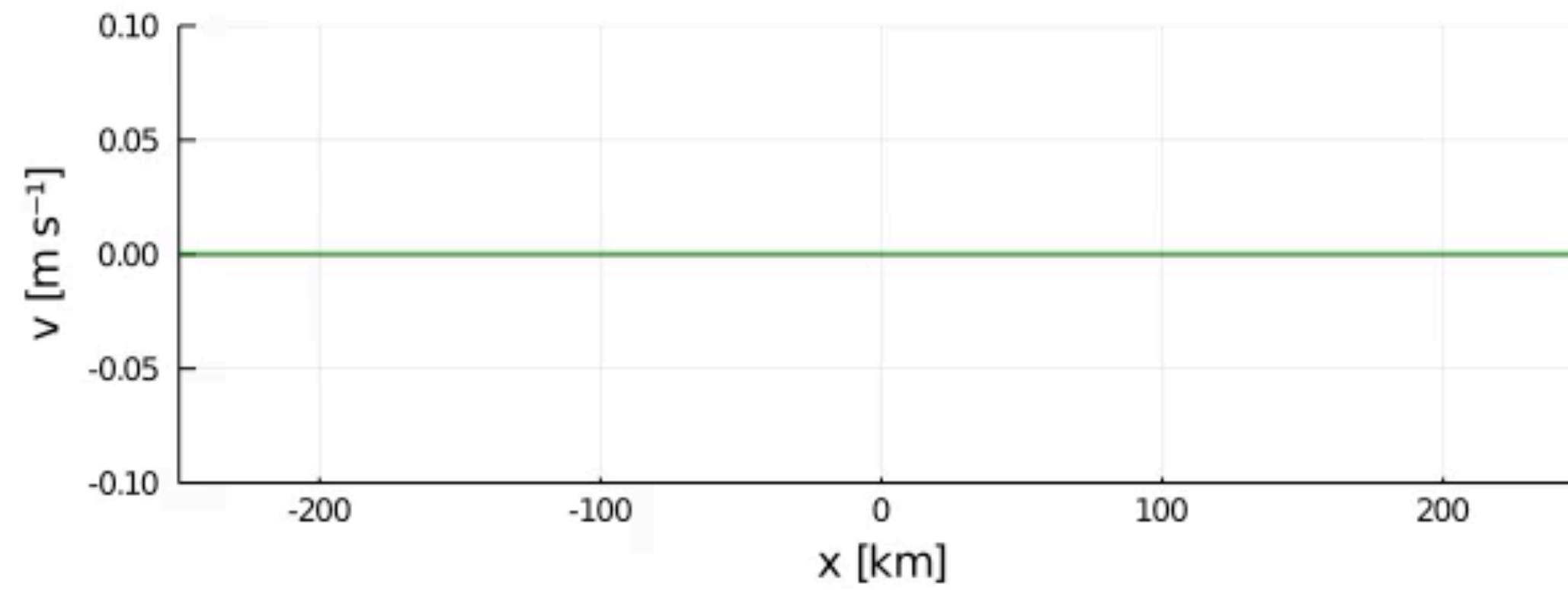
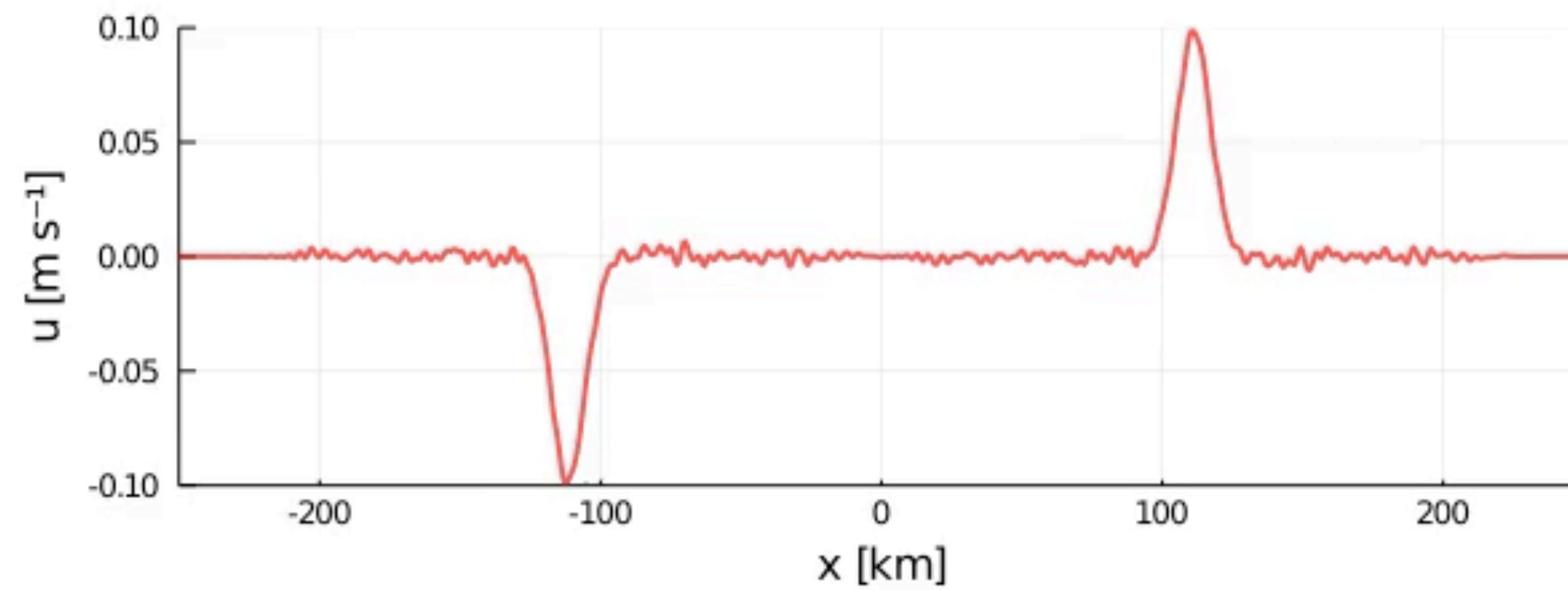
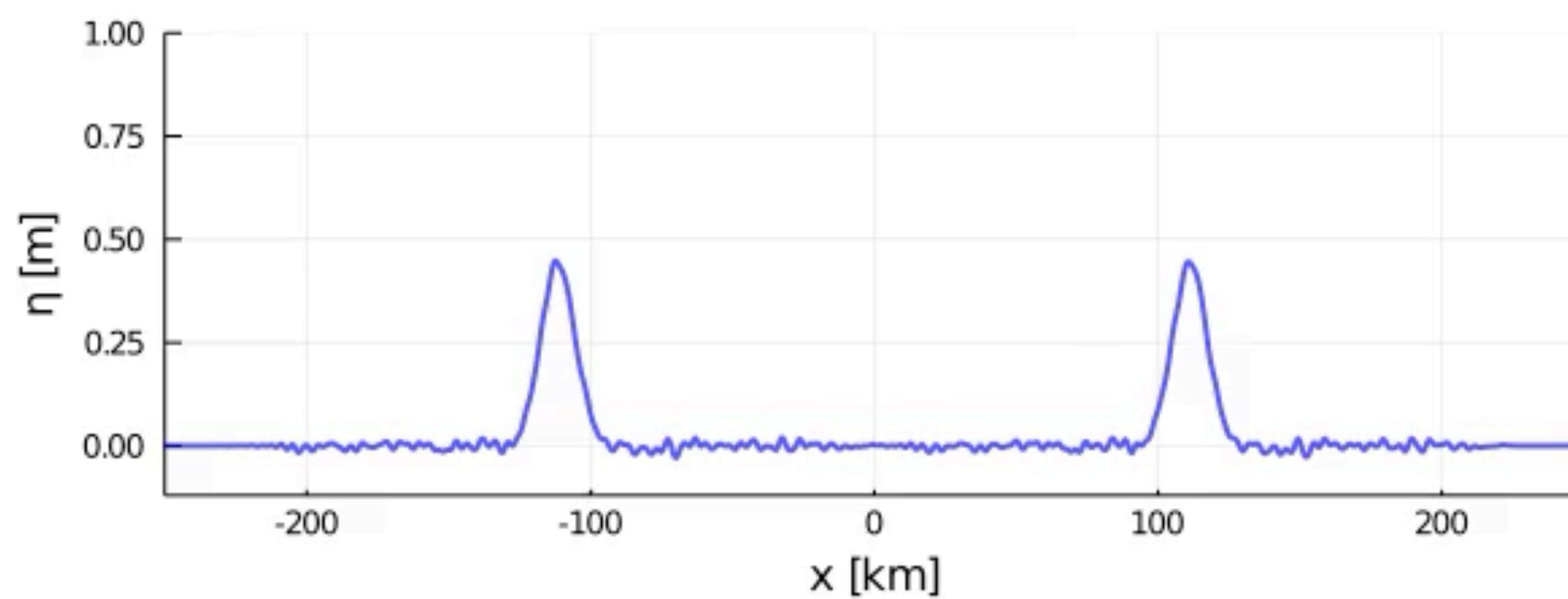
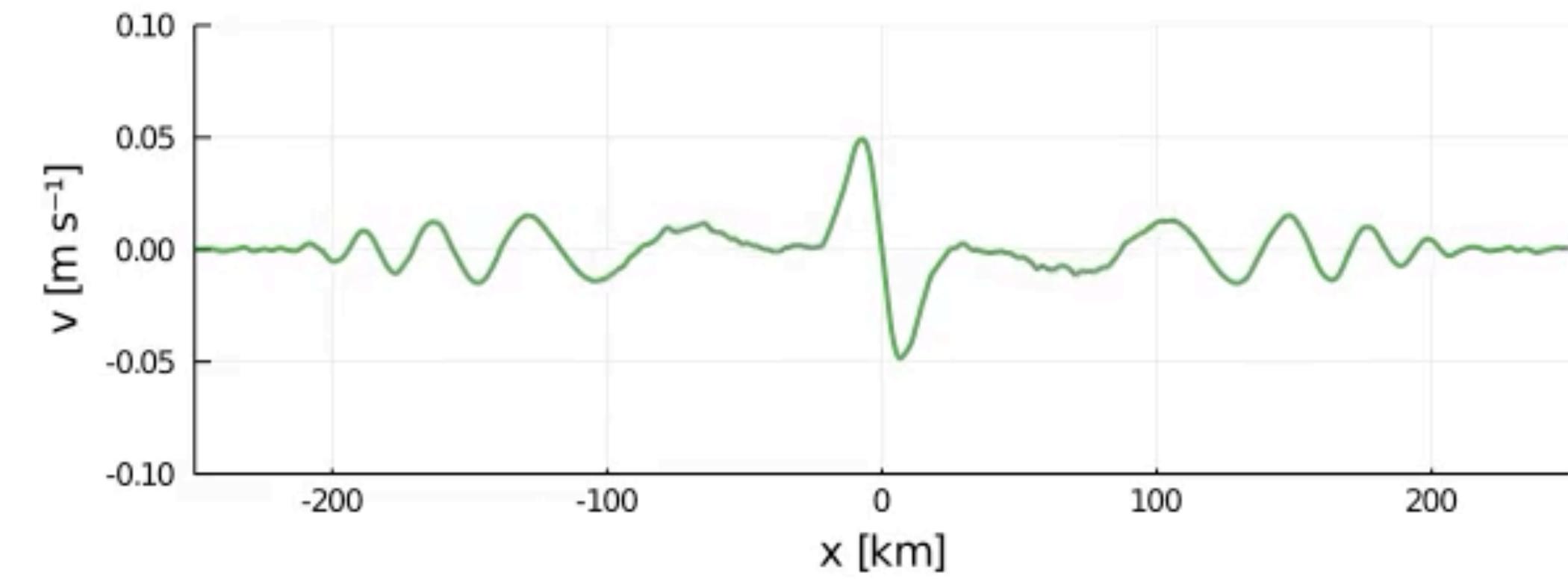
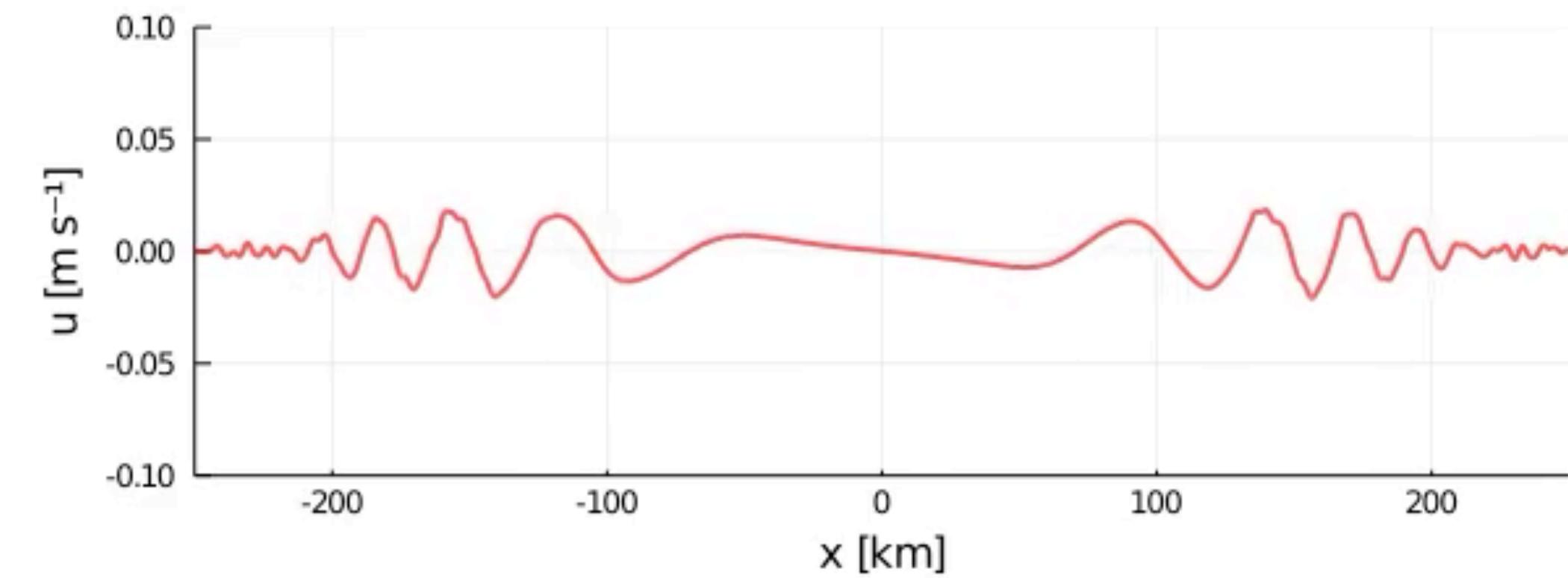
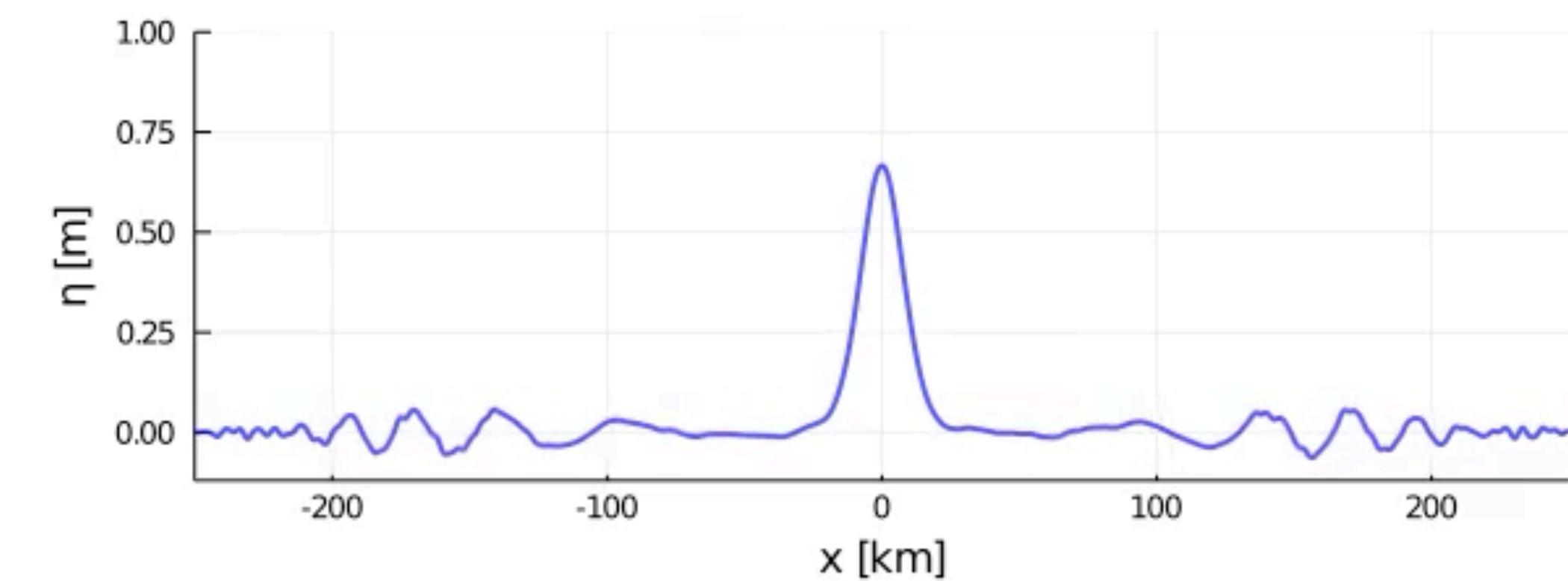
$$h(x, y, t) = \eta(x, y, t) - \eta_{\text{bottom}}(x, y)$$

$$\mathbf{u} = (u(x, y, t), v(x, y, t))$$

$$\nabla = \frac{\partial}{\partial x} \hat{x} + \frac{\partial}{\partial y} \hat{y}$$

admit wave solutions  
(waves that “live” on the fluid’s surface)

$f = 0$ non-rotating  
 $t = 0.0 \text{ min}$  $\sqrt{gH} = 160 \text{ km h}^{-1}$ rotating  
 $t = 0.0 \text{ min}$  $f = 10^{-2} \text{ s}^{-1}$

$f = 0$ non-rotating  
 $t = 41.7$  min $\sqrt{gH} = 160 \text{ km h}^{-1}$ rotating  
 $t = 89.0$  min $f = 10^{-2} \text{ s}^{-1}$

# Rotating shallow-water dynamics

horizontal  
momentum eqs

$$\frac{\partial \mathbf{u}}{\partial t} + \mathbf{u} \cdot \nabla \mathbf{u} + f \hat{\mathbf{z}} \times \mathbf{u} = -g \nabla \eta$$

after the dust settles...

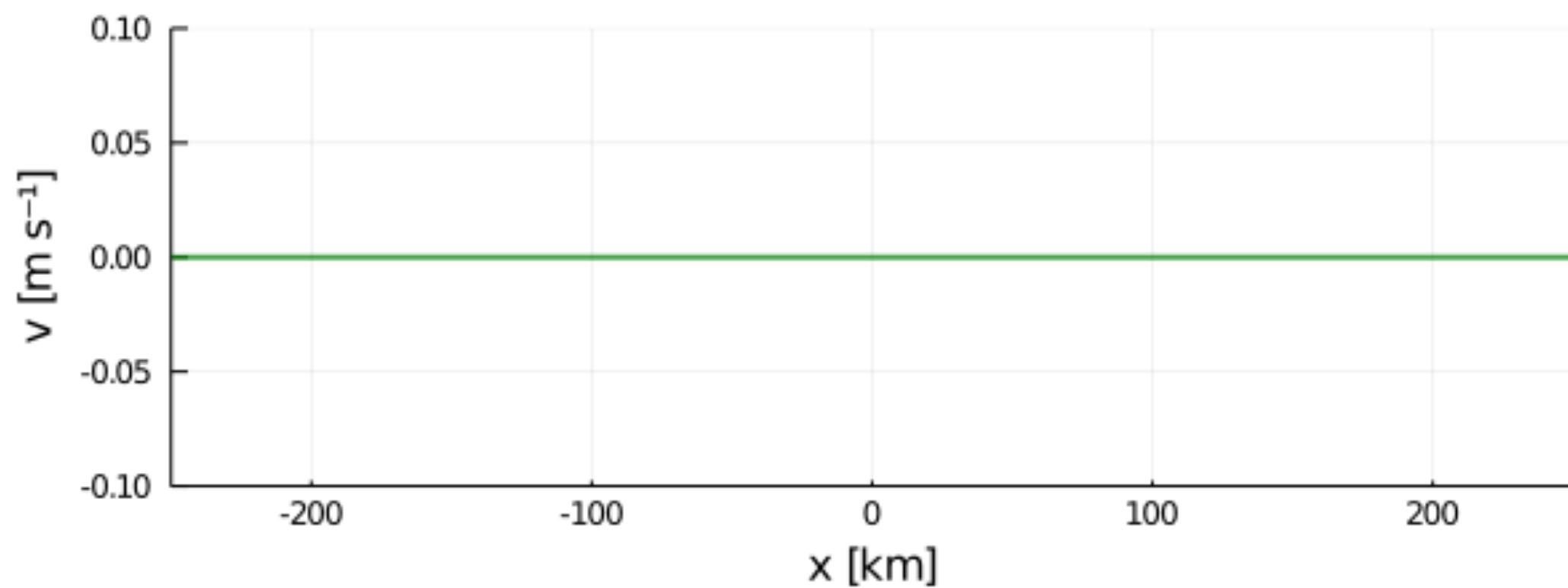
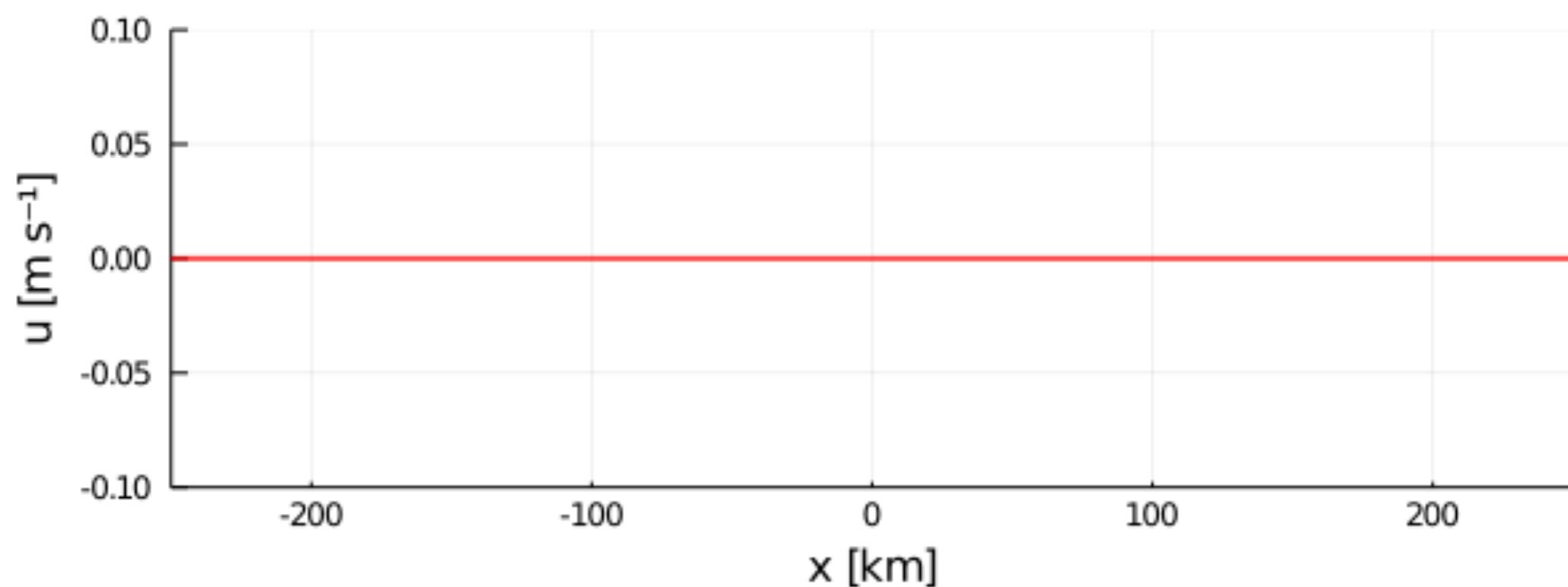
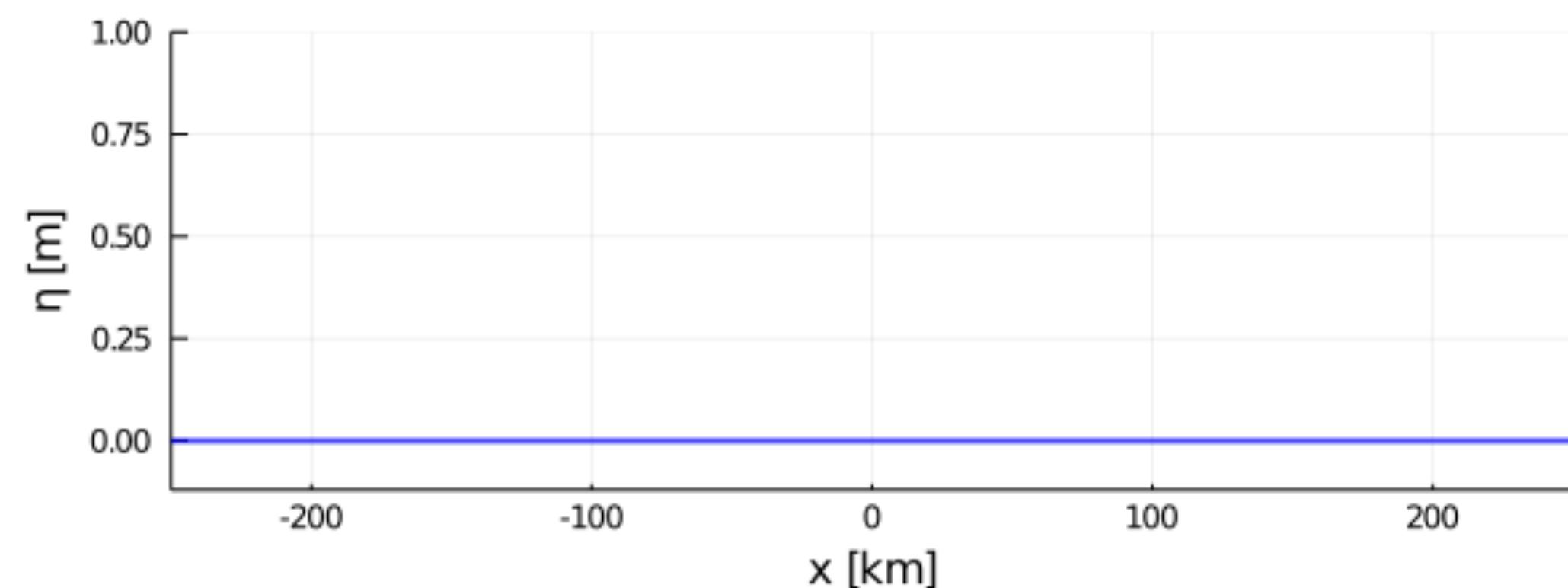
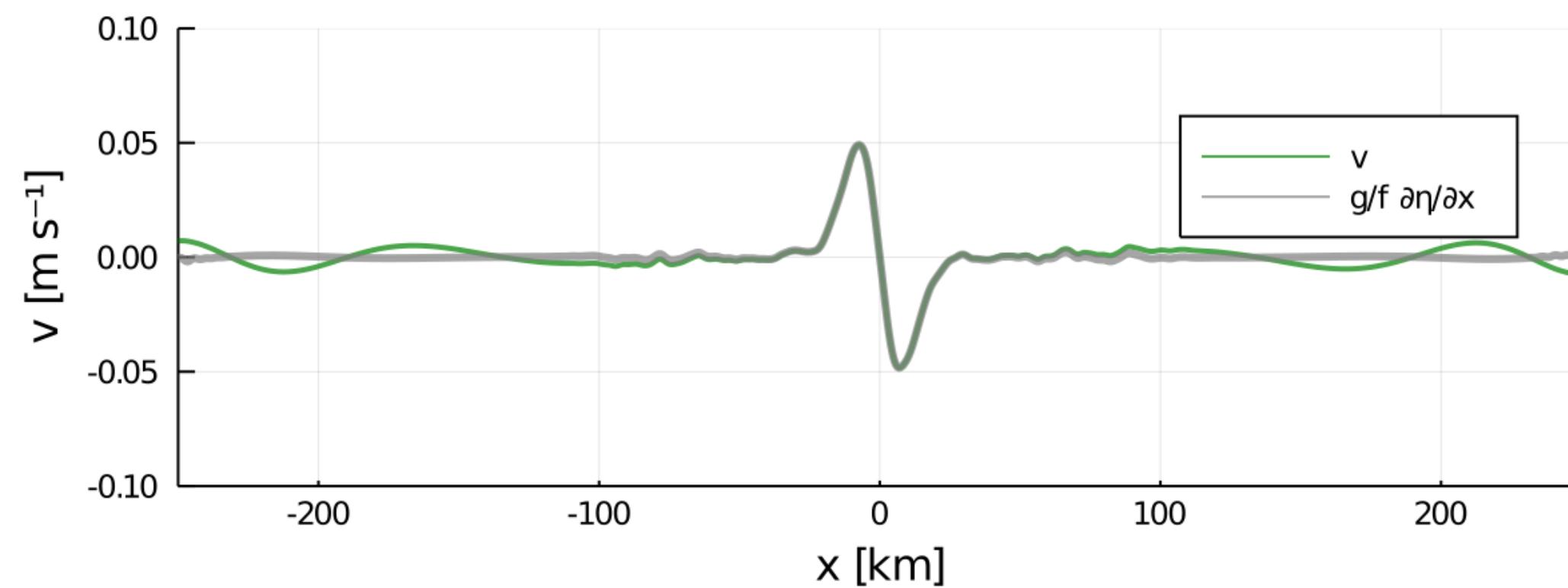
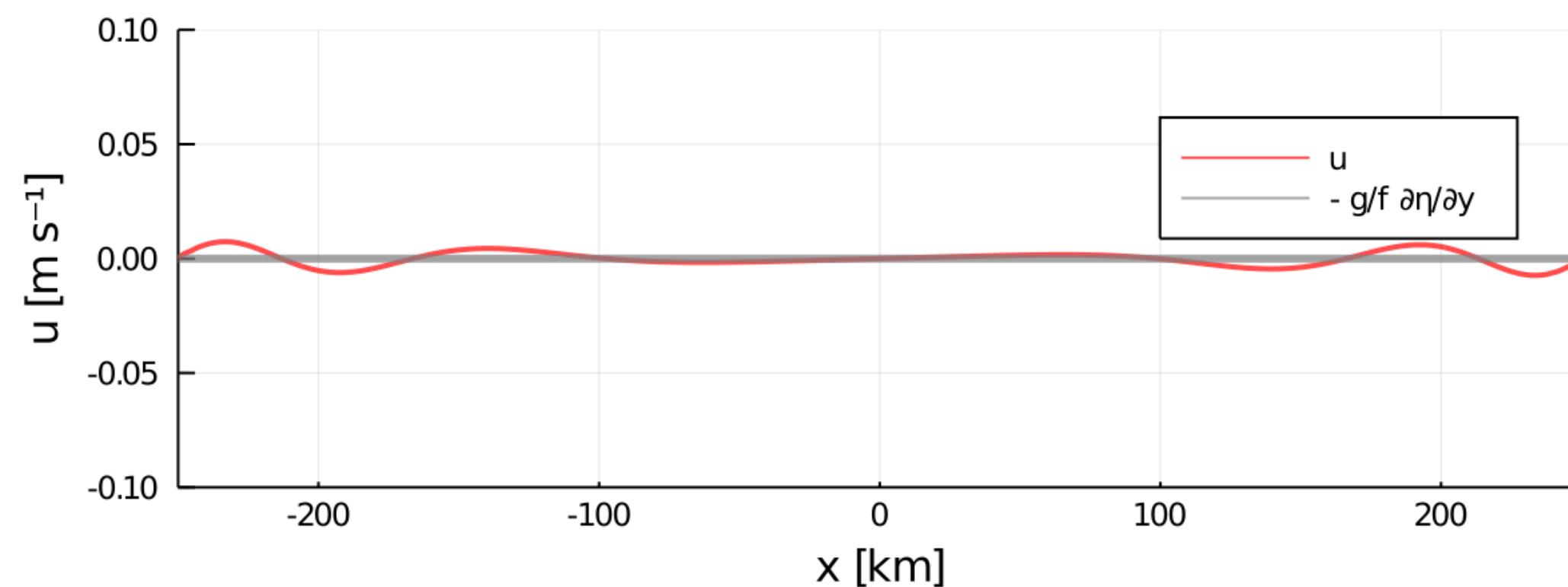
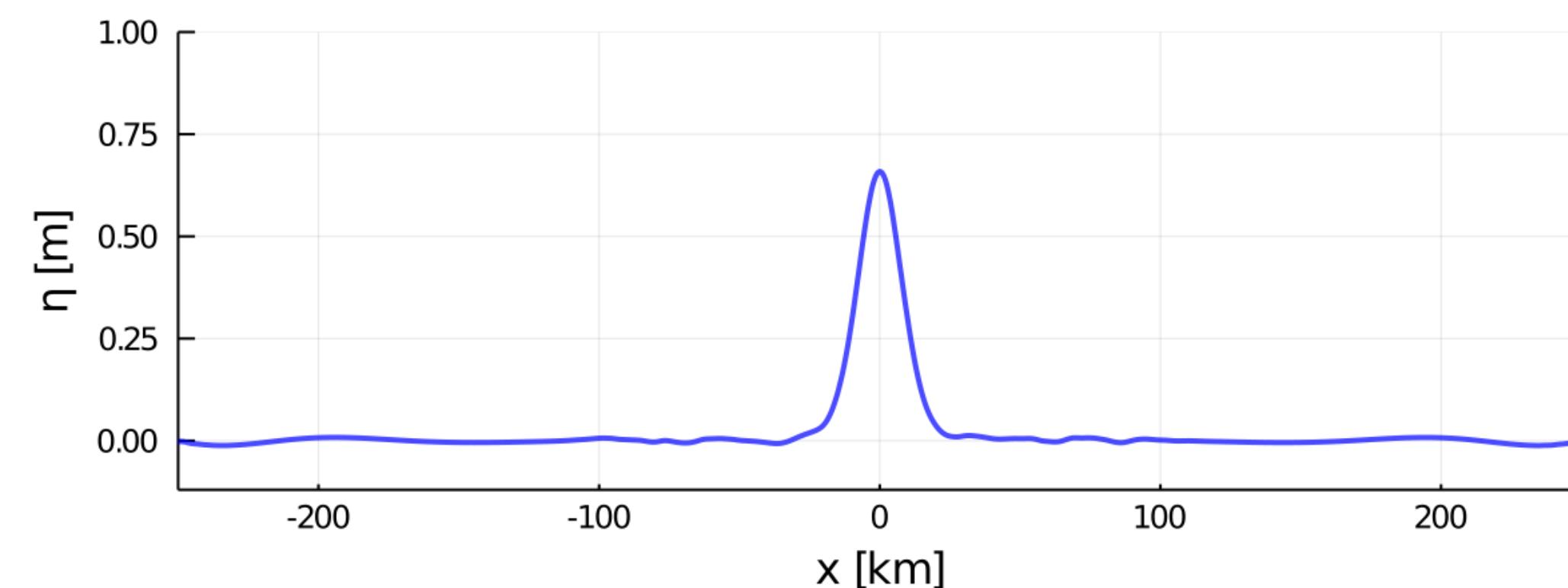
$$f \hat{\mathbf{z}} \times \mathbf{u} \approx -g \nabla \eta$$

Coriolis  $\approx$  pressure  
gradient

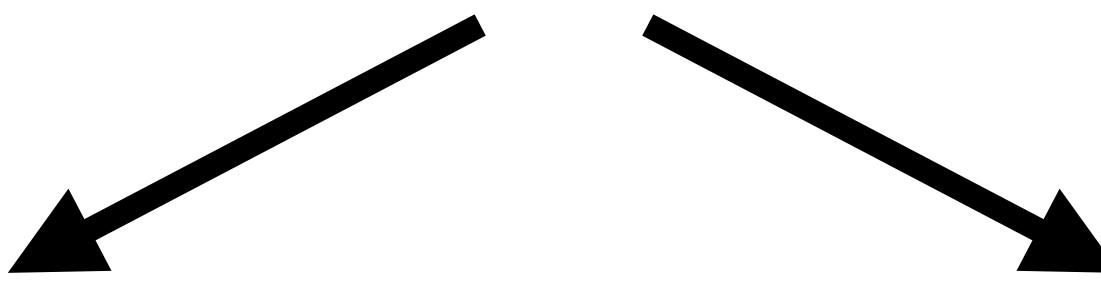
geostrophic balance

$$u_{\text{geostrophic}} = -\frac{g}{f} \frac{\partial \eta}{\partial y}$$

$$v_{\text{geostrophic}} = +\frac{g}{f} \frac{\partial \eta}{\partial x}$$

$f = 0$ non-rotating  
 $t = 200.0 \text{ min}$ rotating  
 $t = 250.0 \text{ min}$  $f = 10^{-2} \text{ s}^{-1}$ 

## Rotating shallow-water dynamics



Slow motions  
approximately in  
geostrophic balance

~ days (atmos)/weeks (ocean)

“weather”

Fast-travelling motions

~ hours

“noise”

$$u_{\text{geostrophic}} = - \frac{\partial}{\partial y} \left( \frac{p}{\rho f} \right)$$

$$v_{\text{geostrophic}} = + \frac{\partial}{\partial x} \left( \frac{p}{\rho f} \right)$$

# Flows in Geostrophic Balance

$$u_{\text{geostrophic}} = - \frac{\partial}{\partial y} \left( \frac{p}{\rho f} \right)$$

$$v_{\text{geostrophic}} = + \frac{\partial}{\partial x} \left( \frac{p}{\rho f} \right)$$

Evolve much slower than gravity waves

# Flows in Geostrophic Balance

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$$v_{\text{geostrophic}} = + \frac{\partial}{\partial x} \left( \frac{p}{\rho f} \right)$$

Evolve much slower than gravity waves

Incompressible:  $\frac{\partial}{\partial x} u_{\text{geostrophic}} + \frac{\partial}{\partial y} v_{\text{geostrophic}} = 0$

# Flows in Geostrophic Balance

$$u_{\text{geostrophic}} = - \frac{\partial}{\partial y} \left( \frac{p}{\rho f} \right)$$

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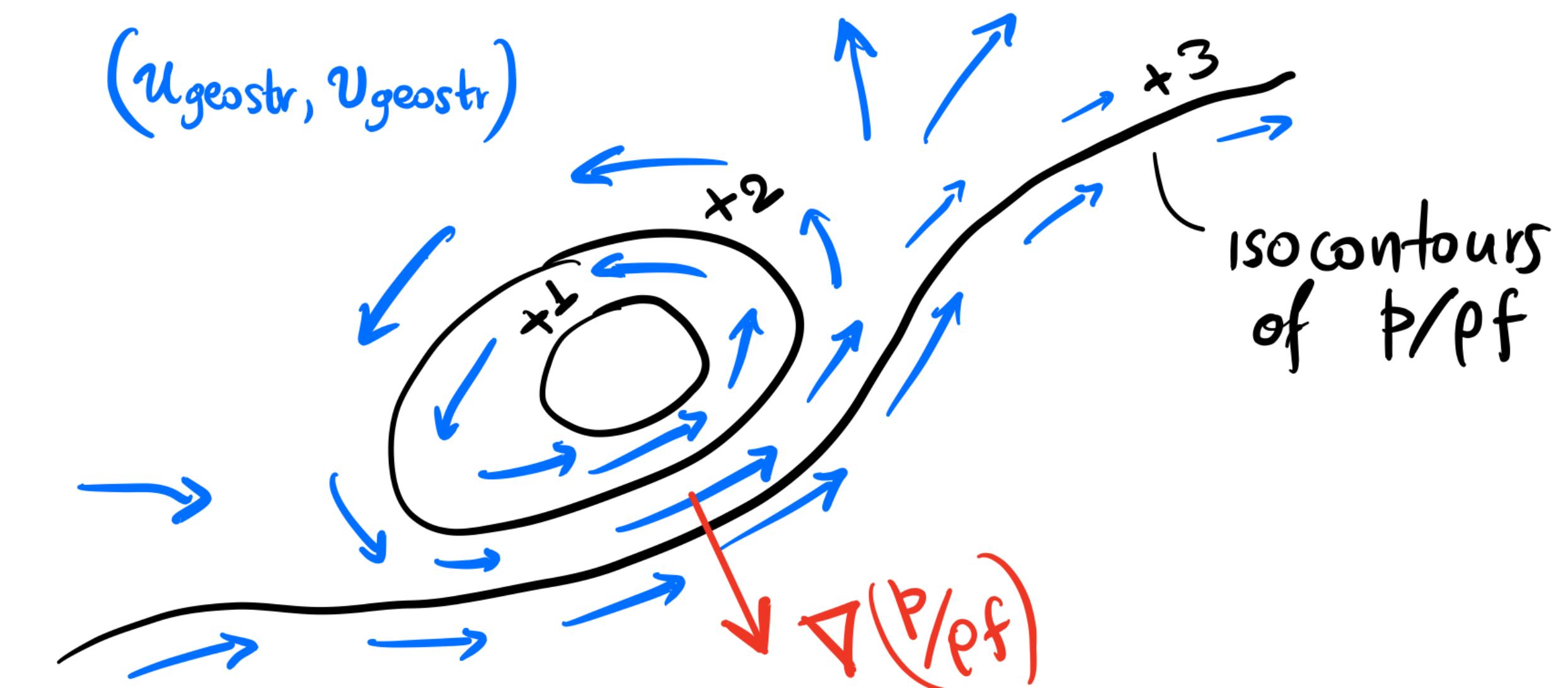
Evolve much slower than gravity waves

Incompressible:

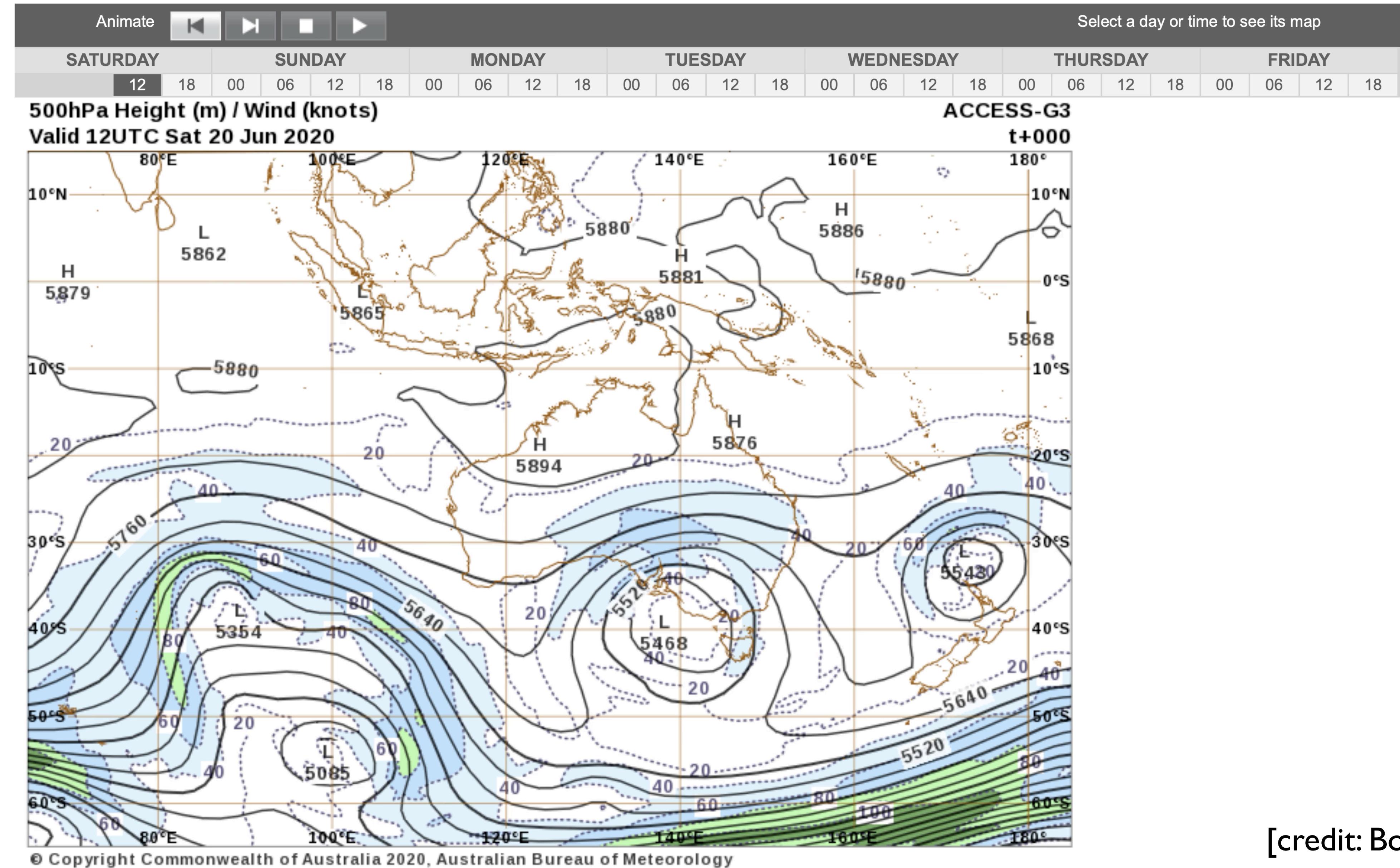
$$\frac{\partial}{\partial x} u_{\text{geostrophic}} + \frac{\partial}{\partial y} v_{\text{geostrophic}} = 0$$

Flow follows contours  
of constant  $p/\rho f$

$$\nabla \left( \frac{p}{\rho f} \right) \cdot u_{\text{geostrophic}} = 0$$



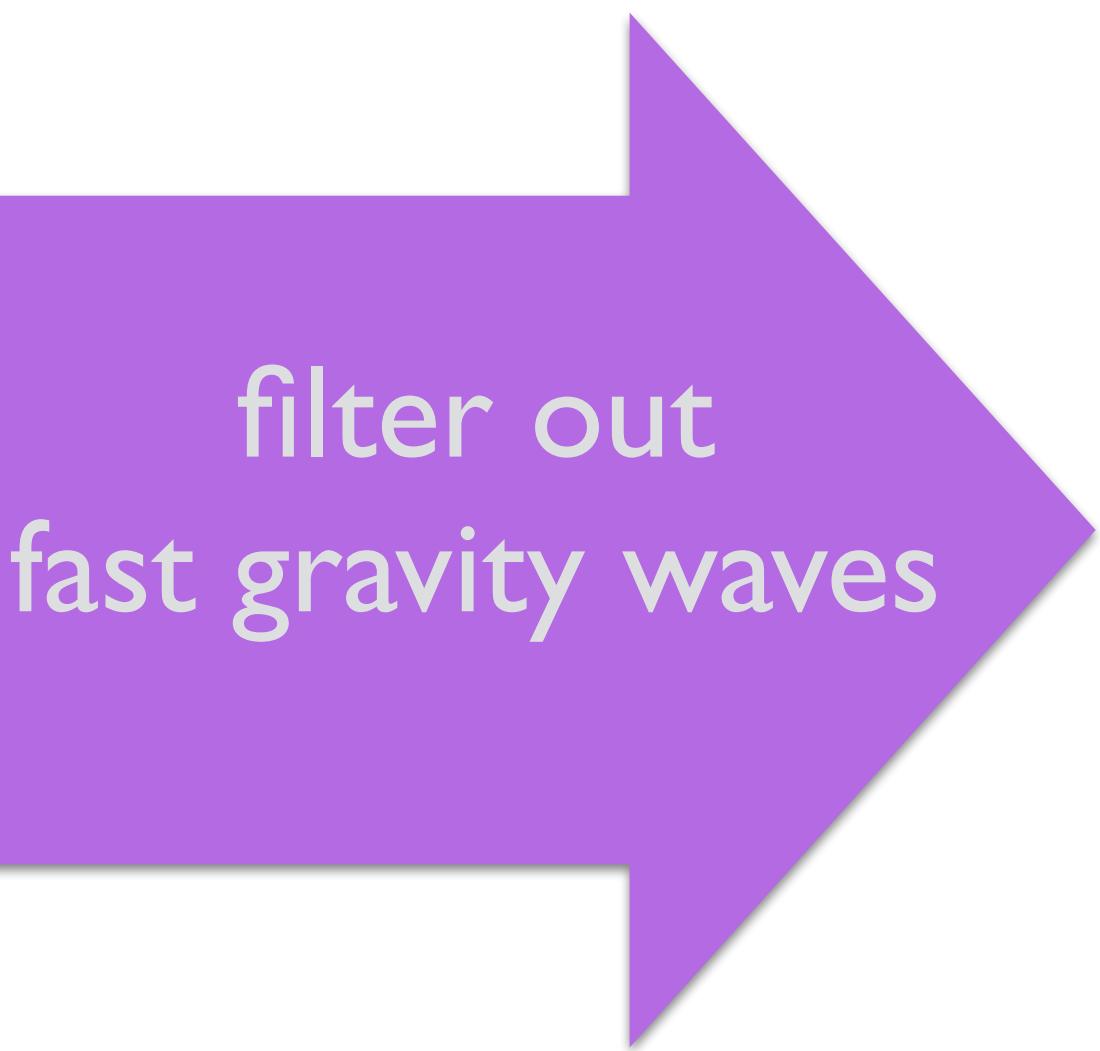
# Weather maps are all about Quasi-Geostrophy



What if  
we don't care about “noise” (=gravity waves)  
and we just want to know  
how the “weather” (almost geostrophically balanced flow)  
evolves?

Rotating  
shallow-water  
dynamics

$$\frac{\partial}{\partial t} \begin{pmatrix} u \\ v \\ \eta \end{pmatrix} = \dots$$



Quasi-Geostrophic  
dynamics

$$\frac{\partial}{\partial t} p = \dots$$

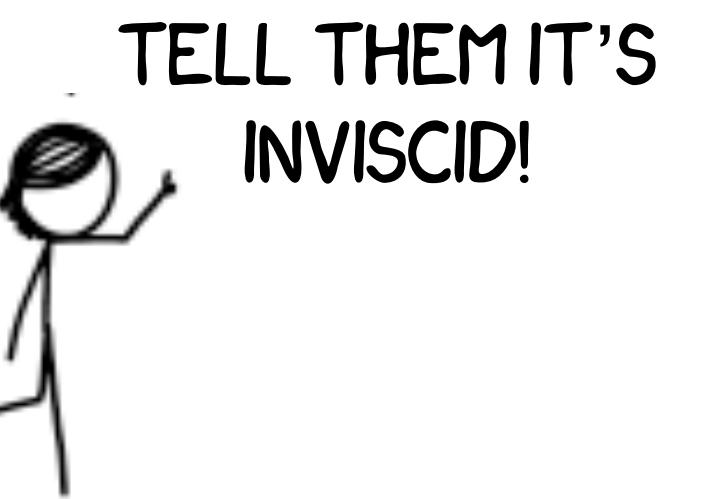
One variable suffices  
to obtain the flow

Let's change pace.

How does QG dynamics relates  
to 2D turbulence?

(Incompressible 2D flow = Quasi-Geostrophy **without** rotation)

# Incompressible 2D flow



$$\frac{\partial \mathbf{u}}{\partial t} + \mathbf{u} \cdot \nabla \mathbf{u} = -\frac{1}{\rho_0} \nabla p$$

$$\mathbf{u} = (u(x, y, t), v(x, y, t))$$

$$p(x, y, t)$$

$$\nabla \cdot \mathbf{u} = 0$$

# Incompressible 2D flow

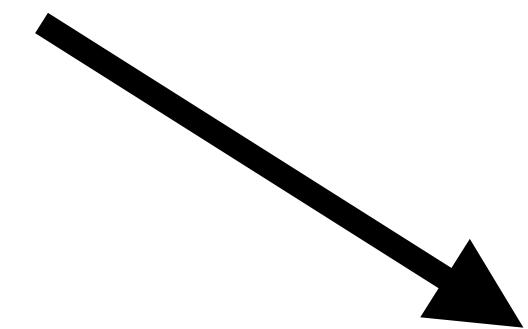


$$\frac{\partial \mathbf{u}}{\partial t} + \mathbf{u} \cdot \nabla \mathbf{u} = -\frac{1}{\rho_0} \nabla p$$

$$\mathbf{u} = (u(x, y, t), v(x, y, t))$$

$$p(x, y, t)$$

$$\nabla \cdot \mathbf{u} = 0$$



$$(u, v) = (-\partial_y \psi, \partial_x \psi)$$

vorticity       $(\nabla \times \mathbf{u}) \cdot \hat{z} = \nabla^2 \psi$

# Incompressible 2D flow



$$\frac{\partial \mathbf{u}}{\partial t} + \mathbf{u} \cdot \nabla \mathbf{u} = -\frac{1}{\rho_0} \nabla p$$

$$\nabla \cdot \mathbf{u} = 0$$

$$(\mathbf{u}, v) = (-\partial_y \psi, \partial_x \psi)$$

vorticity

$$(\nabla \times \mathbf{u}) \cdot \hat{z} = \nabla^2 \psi$$

$$\mathbf{u} = (u(x, y, t), v(x, y, t))$$

$$p(x, y, t)$$

*take the curl*  $\nabla \times$

incompressible 2D flow

$$\left( \frac{\partial}{\partial t} + \mathbf{u} \cdot \nabla \right) \nabla^2 \psi = 0$$

$$(\mathbf{u}, v) = (-\partial_y \psi, \partial_x \psi)$$

# Incompressible 2D flow = Quasi-Geostrophy **on f-plane**

Incompressible 2D flow

$$\left( \frac{\partial}{\partial t} + \mathbf{u} \cdot \nabla \right) \nabla^2 \psi = 0$$

$$(\mathbf{u}, v) = (-\partial_y \psi, \partial_x \psi)$$

QG **without** rotation

$$\left( \frac{\partial}{\partial t} + \mathbf{u} \cdot \nabla \right) \nabla^2 \left( \frac{p}{\varrho_0 f} \right) = 0$$

$$(\mathbf{u}, v) = \left( -\frac{\partial}{\partial y} \left( \frac{p}{\varrho_0 f} \right), \frac{\partial}{\partial x} \left( \frac{p}{\varrho_0 f} \right) \right)$$

Note similarity with  
passive tracer equation

$$\left( \frac{\partial}{\partial t} + \mathbf{u} \cdot \nabla \right) \theta = 0$$

**f-plane**

$$f = f_0 = \text{const.}$$

(Flat Earth)

**β-plane**

$$f = f_0 + \beta y$$

(Spherical Earth)

# Incompressible 2D flow = Quasi-Geostrophy **on f-plane**

$$\left( \frac{\partial}{\partial t} + \mathbf{u} \cdot \nabla \right) \nabla^2 \psi = 0$$

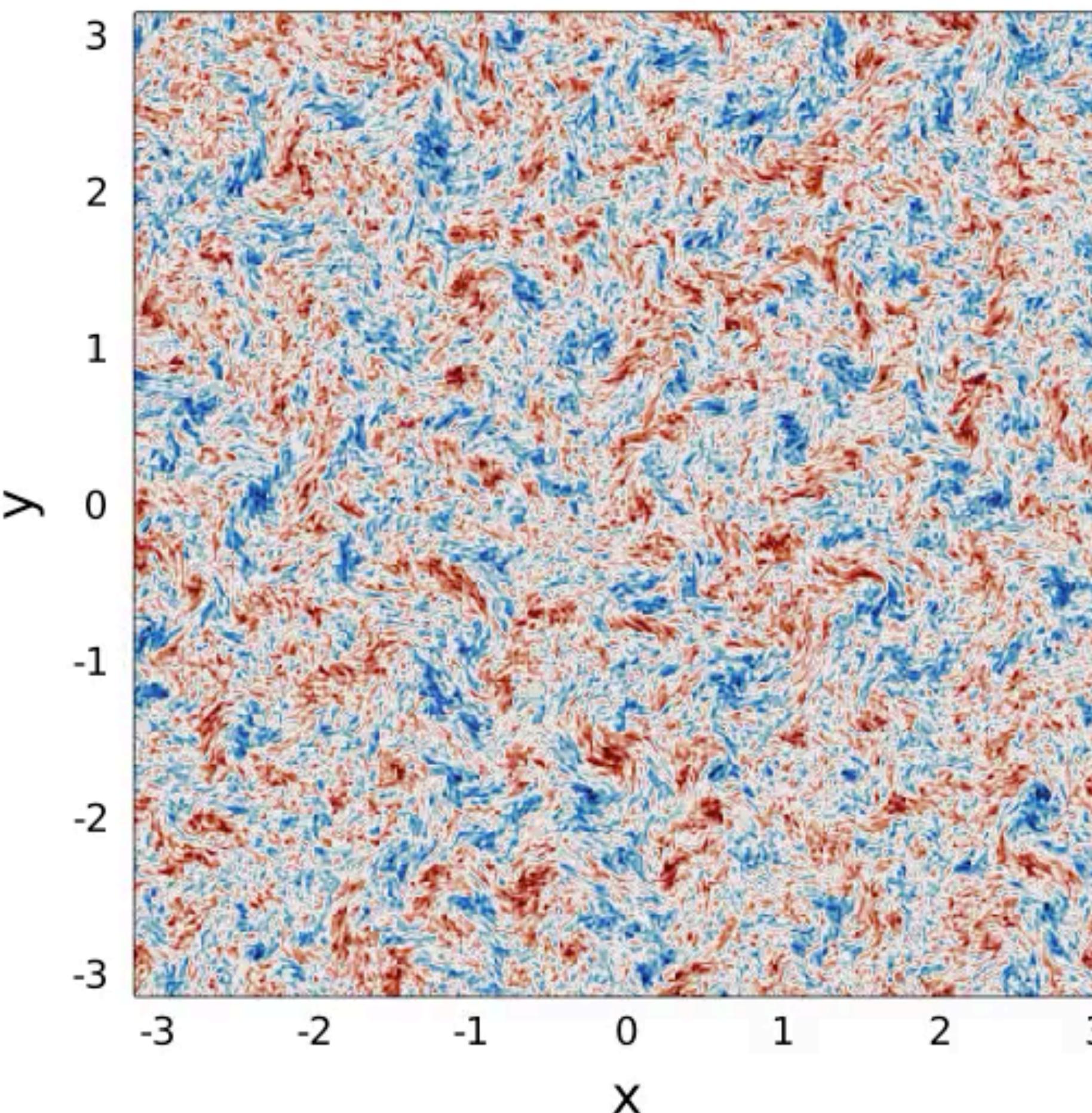
$$(\mathbf{u}, v) = (-\partial_y \psi, \partial_x \psi)$$

Note similarity with  
passive tracer equation

$$\left( \frac{\partial}{\partial t} + \mathbf{u} \cdot \nabla \right) \theta = 0$$

$$(\nabla \times \mathbf{u}) \cdot \hat{z} = \nabla^2 \psi$$

vorticity, t=0.00



[simulation using [GeophysicFlows.jl](#)]

# Incompressible 2D flow = Quasi-Geostrophy **on f-plane**

$$\left( \frac{\partial}{\partial t} + \mathbf{u} \cdot \nabla \right) \nabla^2 \psi = 0$$

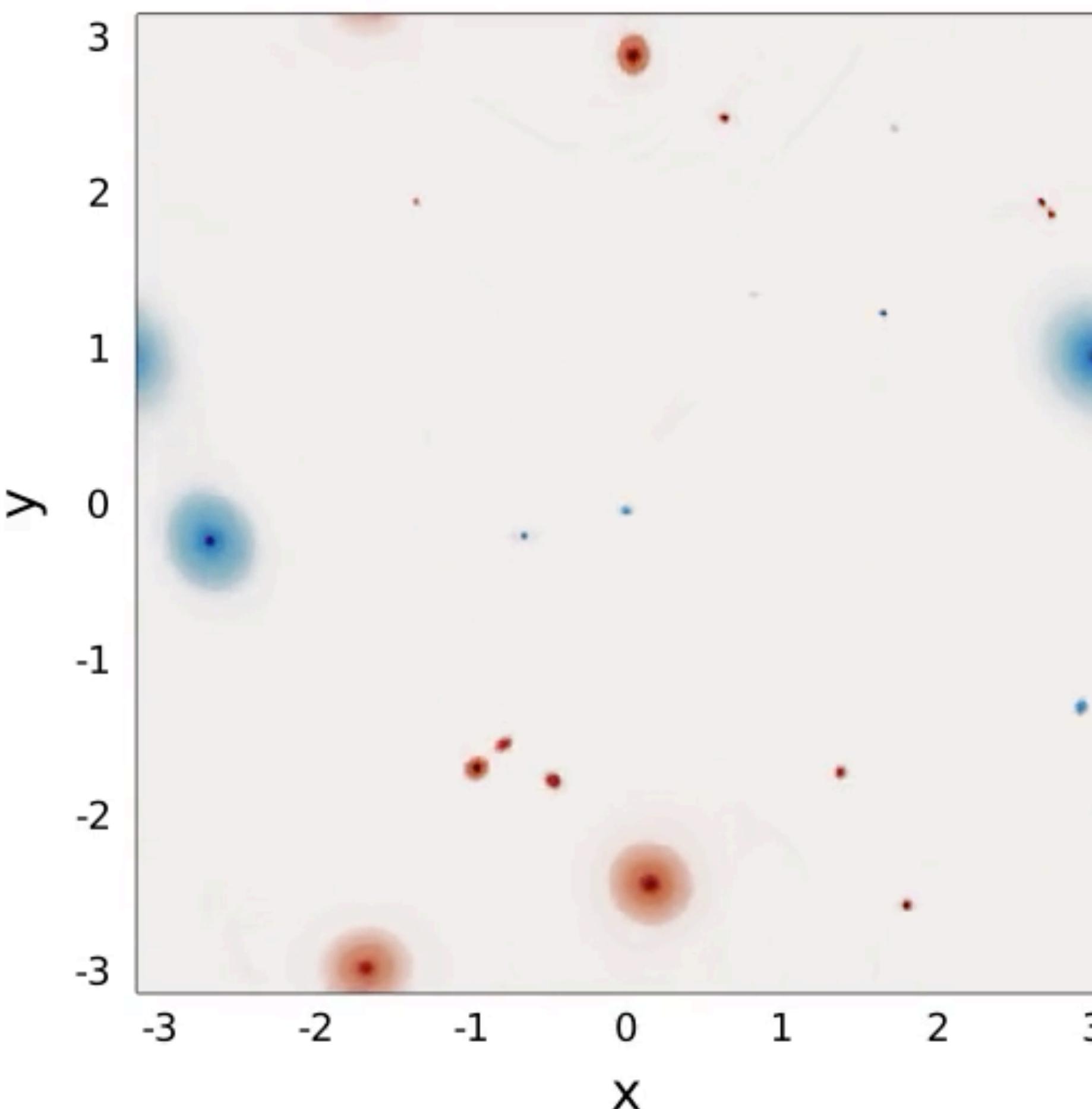
$$(\mathbf{u}, v) = (-\partial_y \psi, \partial_x \psi)$$

Note similarity with  
passive tracer equation

$$\left( \frac{\partial}{\partial t} + \mathbf{u} \cdot \nabla \right) \theta = 0$$

$$(\nabla \times \mathbf{u}) \cdot \hat{\mathbf{z}} = \nabla^2 \psi$$

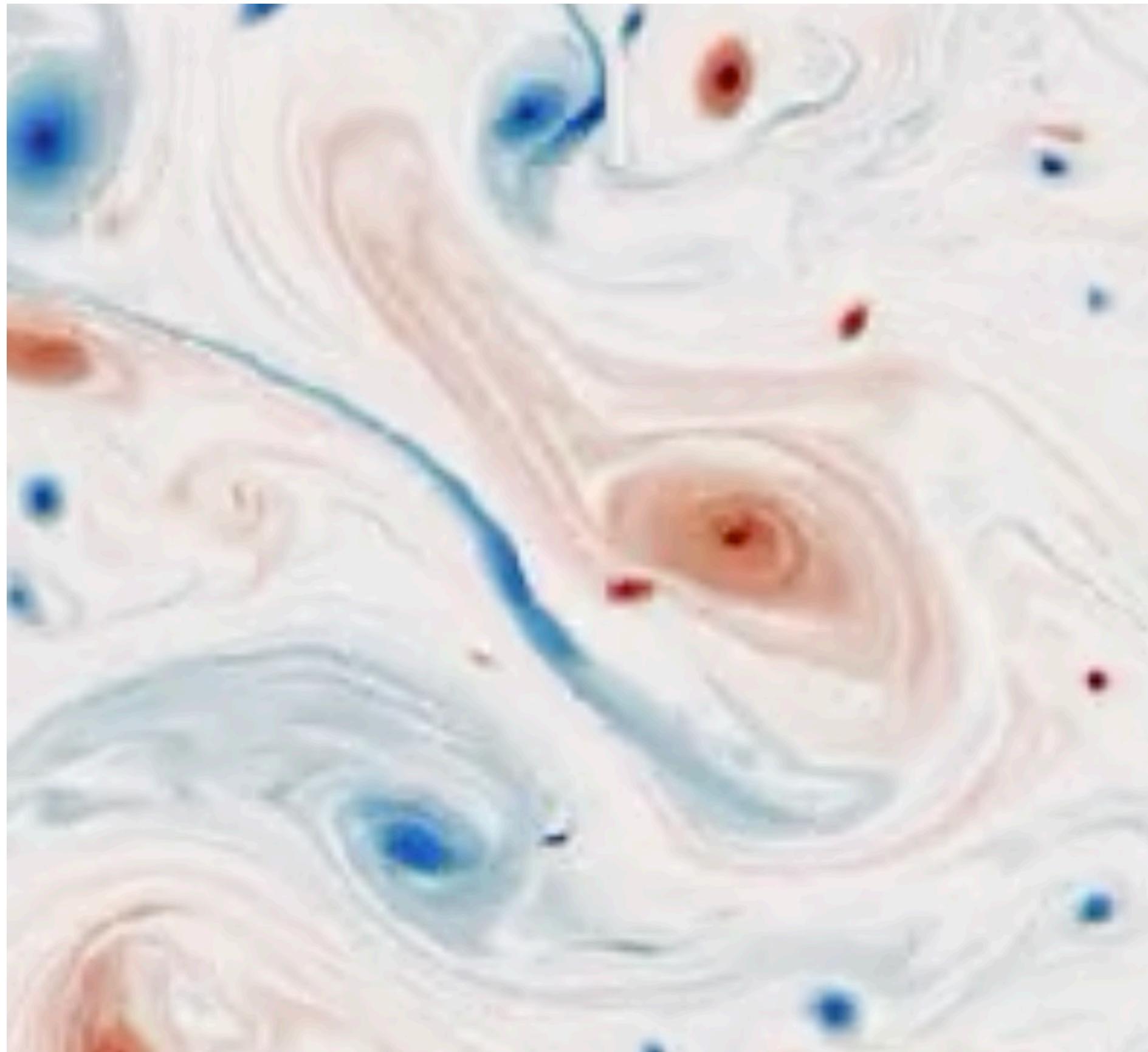
vorticity, t=140.00



[simulation using [GeophysicFlows.jl](#)]

Rotating 3D fluids *resemble* 2D turbulence

2D turbulence **without rotation**



[simulation using [GeophysicFlows.jl](#)]

3D fluid in **rotating** tank



[MIT Weather in Tank]

# Quasi-Geostrophy with Earth's curvature ( $\beta$ -plane)

$$\left( \frac{\partial}{\partial t} + \mathbf{u} \cdot \nabla \right) \underbrace{\left( \nabla^2 \psi + f \right)}_{\text{PV}} = 0$$

$$(\mathbf{u}, v) = (-\partial_y \psi, \partial_x \psi) , \quad \psi = \frac{p}{\rho_0 f}$$

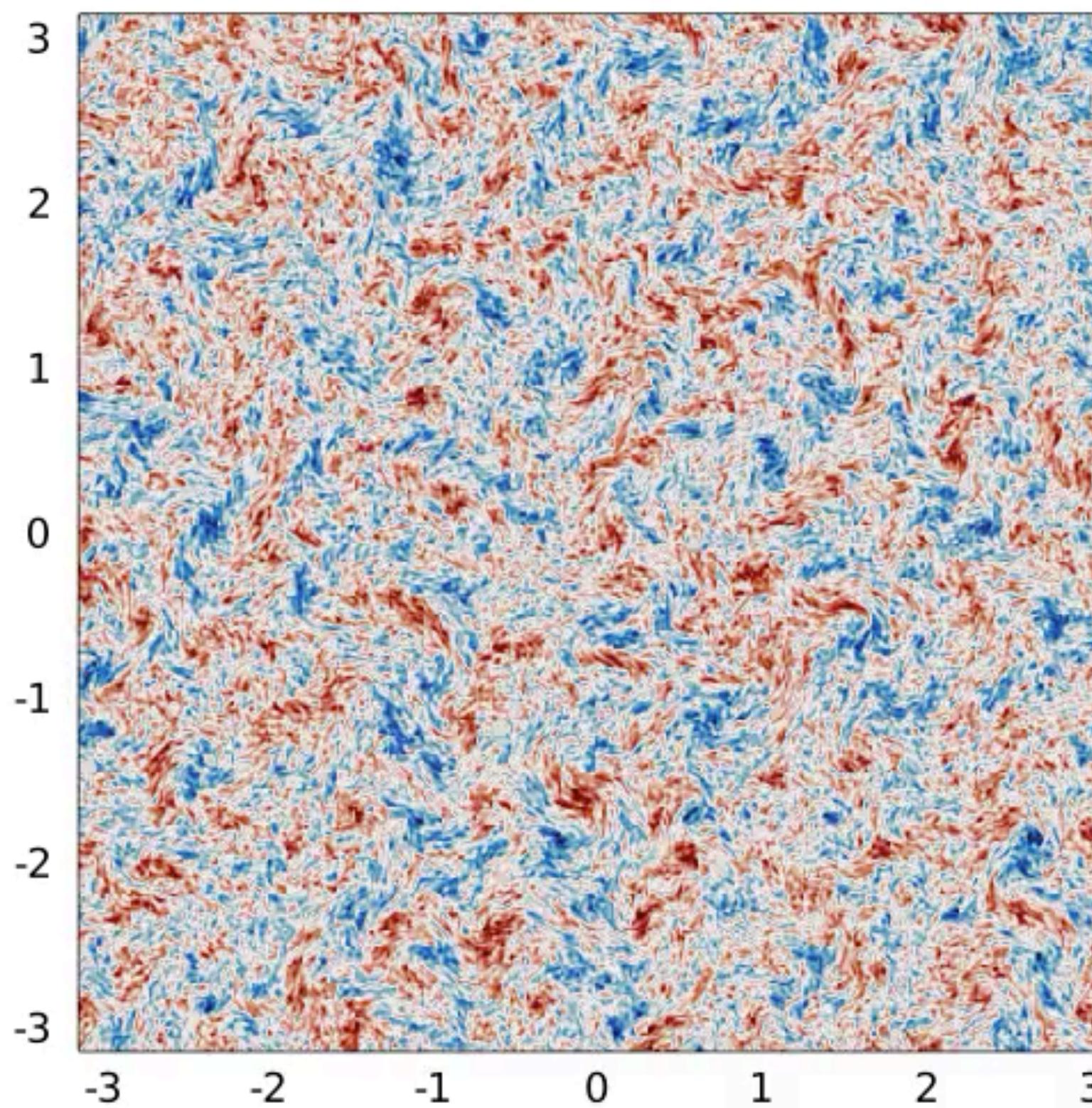
What's materially conserved is the Potential Vorticity (PV)

# Quasi-Geostrophy with Earth's curvature ( $\beta$ -plane)

non-rotating

$$\nabla^2 \psi$$

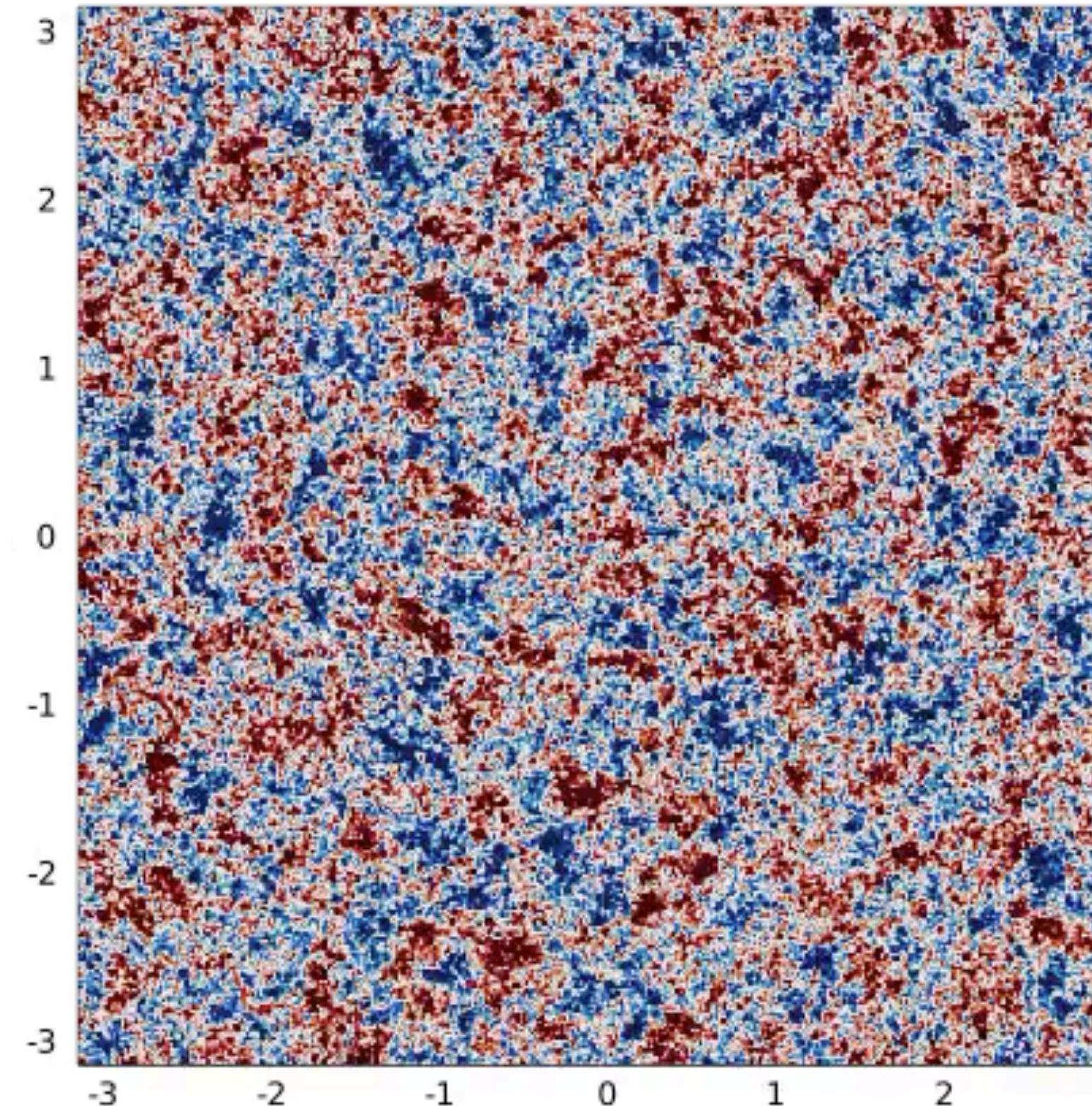
vorticity,  $t=0.00$



$$f = 0$$

$$\nabla^2 \psi$$

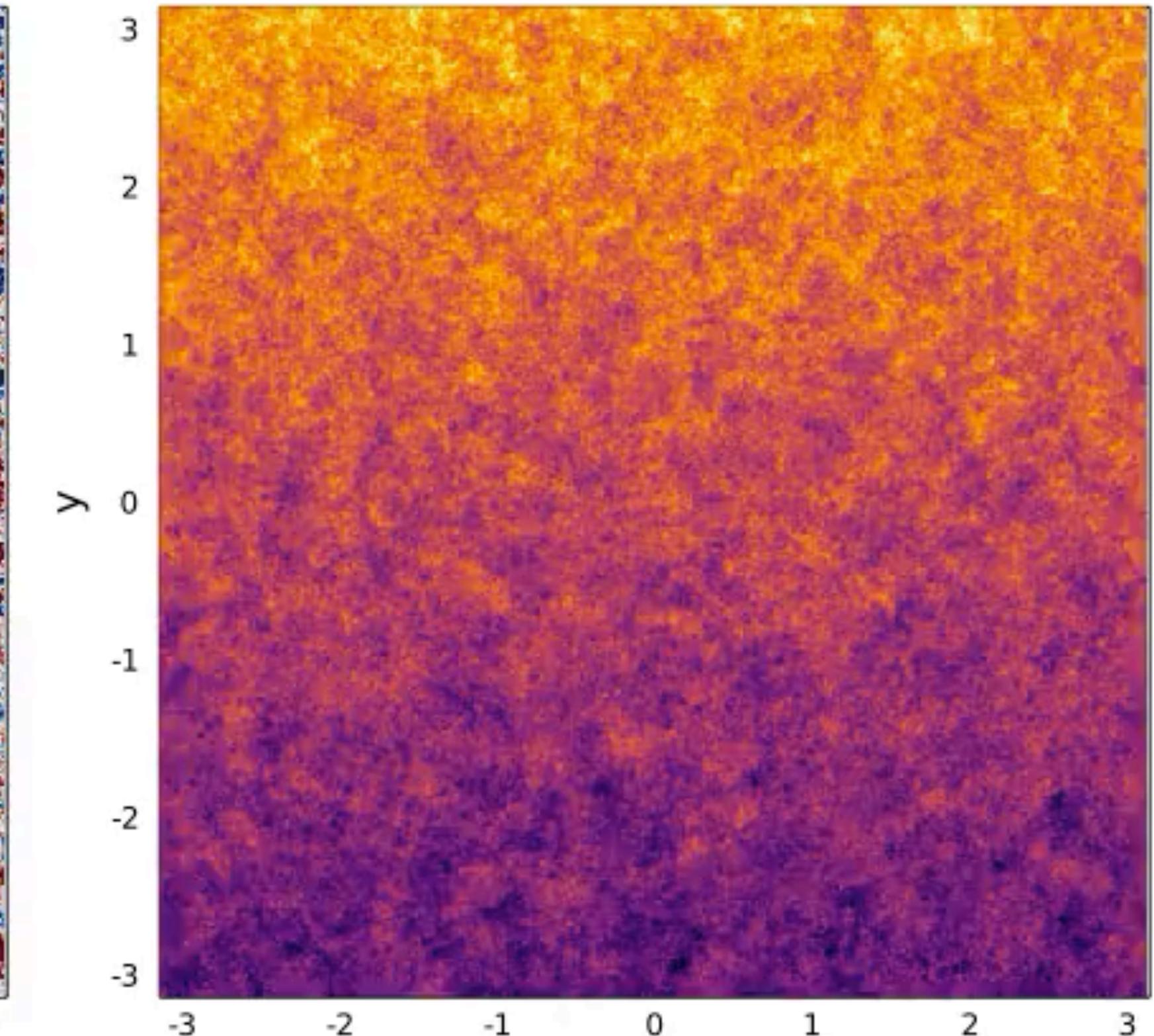
vorticity,  $t=0.00$



rotating

$$\nabla^2 \psi + f$$

PV,  $t=0.00$



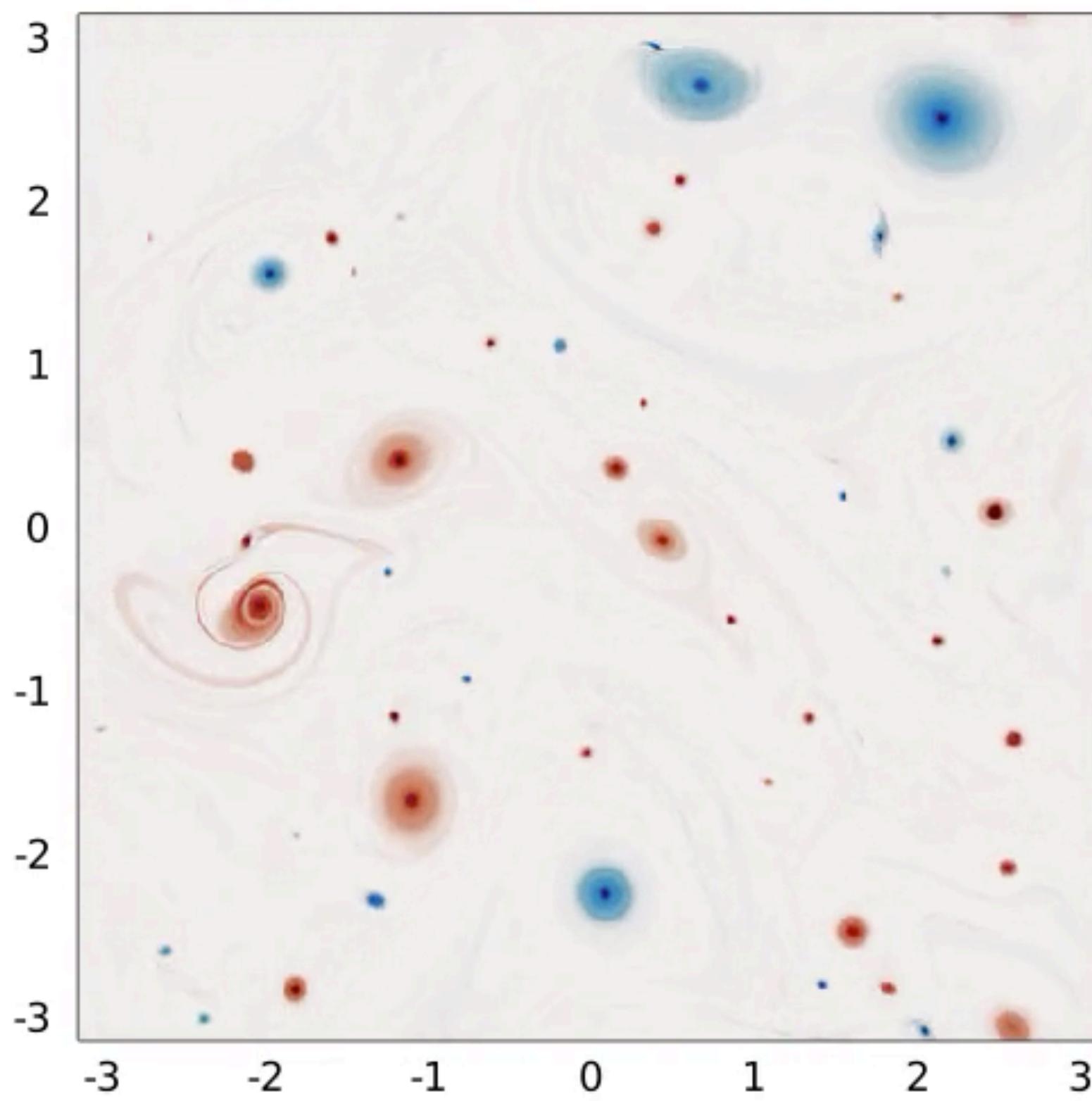
$$f = f_0 + \beta y$$

[simulations using [GeophysicFlows.jl](#)]

# Quasi-Geostrophy with Earth's curvature ( $\beta$ -plane)

non-rotating

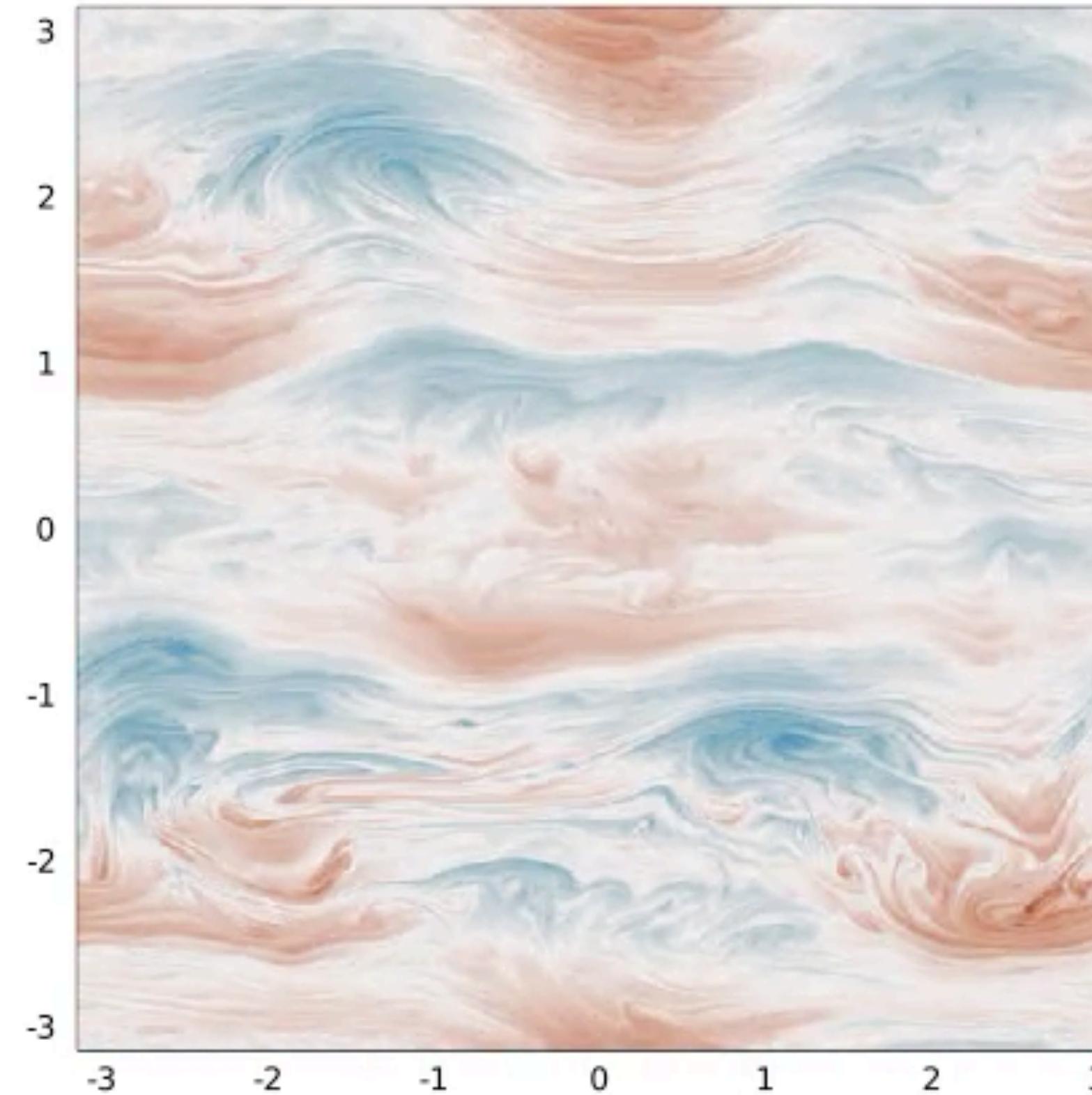
$\nabla^2 \psi$   
vorticity, t=45.00



$$f = 0$$

rotating

$\nabla^2 \psi$   
vorticity, t=45.00



$$f = f_0 + \beta y$$

[simulations using [GeophysicFlows.jl](#)]

# Atmosphere & Ocean Dynamics

## CLE~~X~~ School 2021 (?)

X = {Winter, Summer, Autum, Spring, Xmas, Easter, ...}

THE FOLLOWING **PREVIEW** HAS BEEN APPROVED FOR  
**ALL AUDIENCES**  
BY THE MOTION PICTURE ASSOCIATION OF ~~AMERICA~~<sup>ARC</sup>, INC.

Jupyter notebooks for reproducing animations can be found at:

[github.com/navidcy/CLExWinterSchool2020](https://github.com/navidcy/CLExWinterSchool2020)