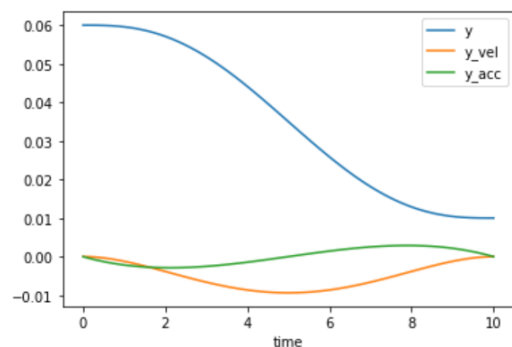# Introduction to Robotics

Assignment 6-7

Secret Code: DEV

Plots of question 1:
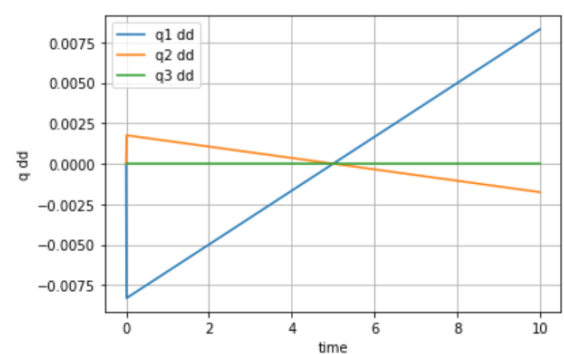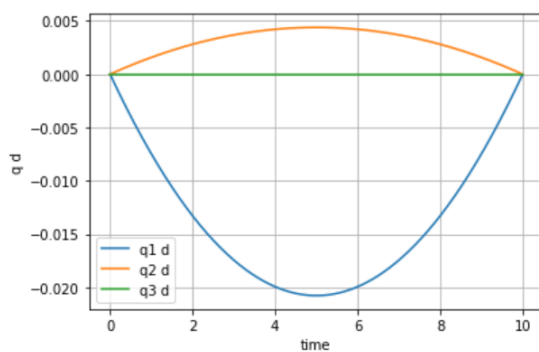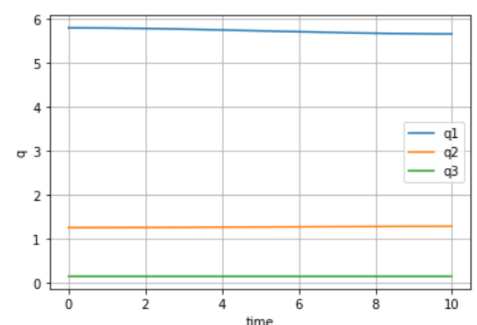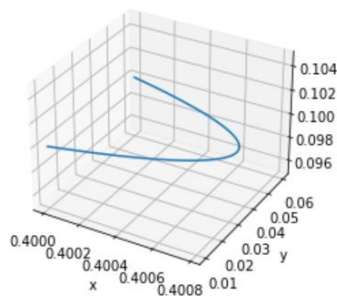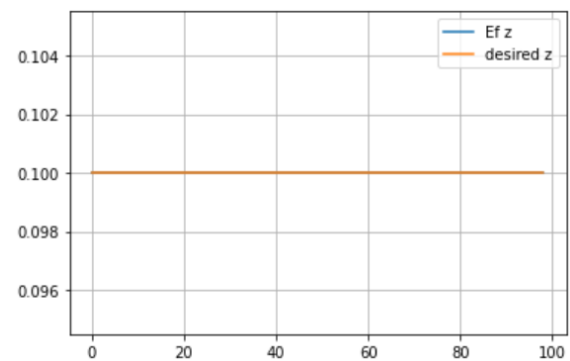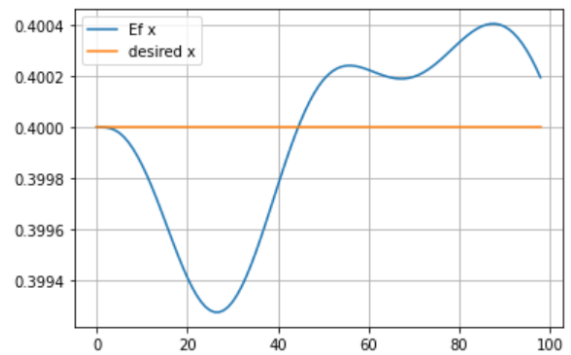

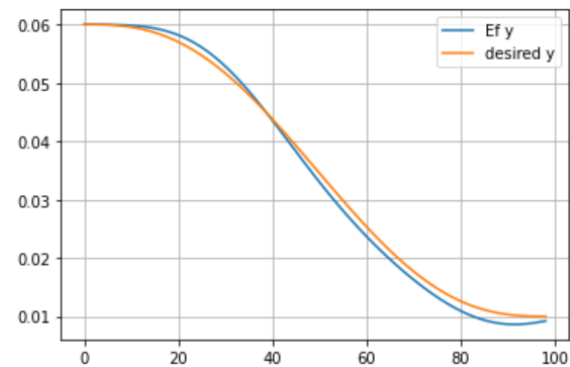Trajectory using Cubic Interpolation in Task-Space
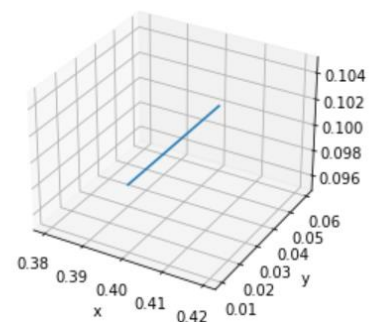
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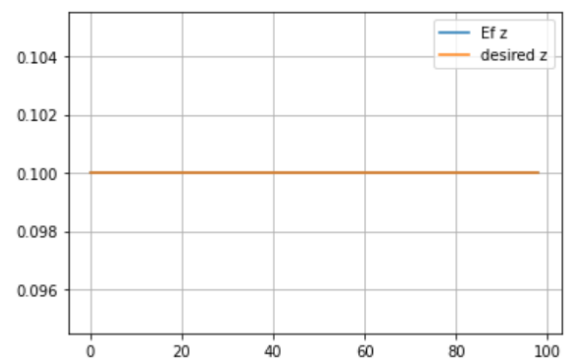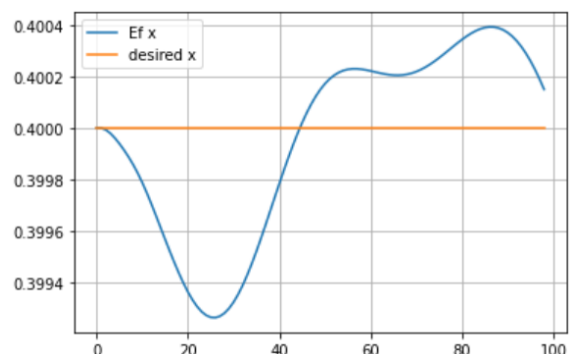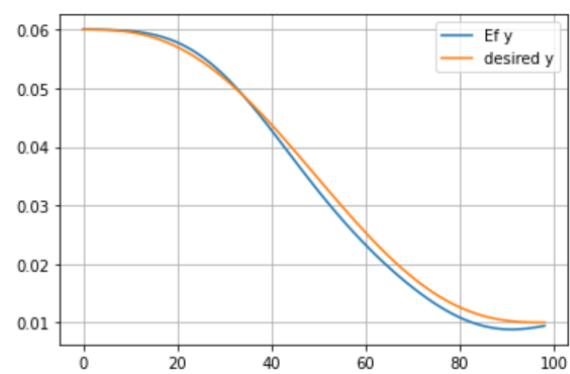
Trajectory using Cubic Interpolation in Joint-Space

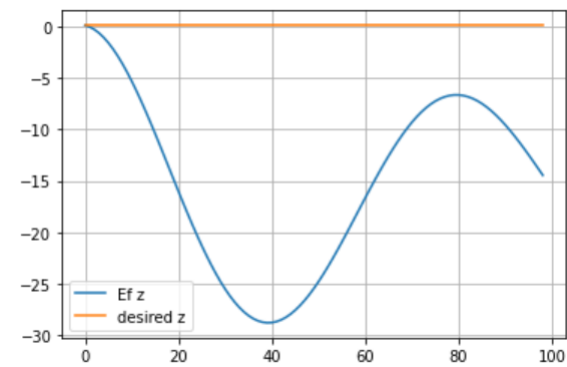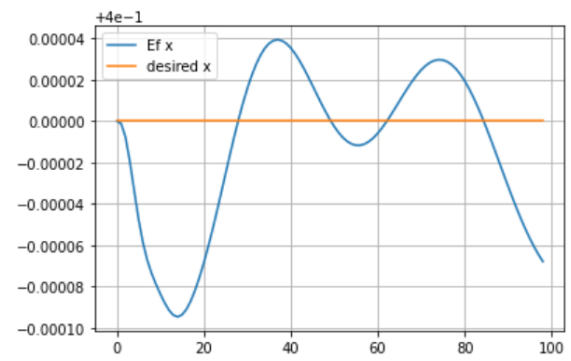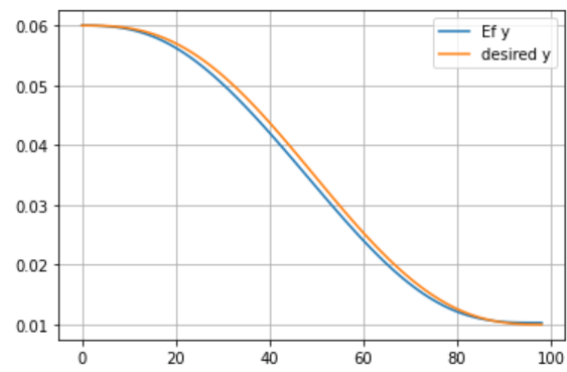# Plots for question 3:
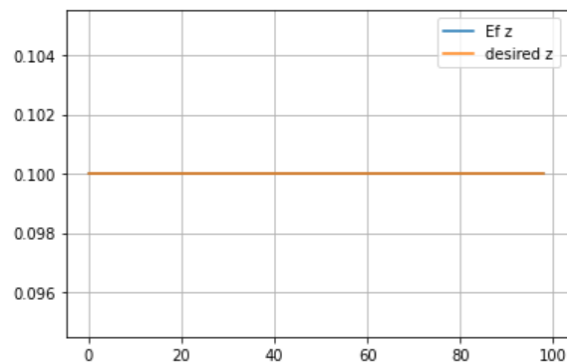
Gains: [1,0.3], [0.65,0.1], [0.6,1]

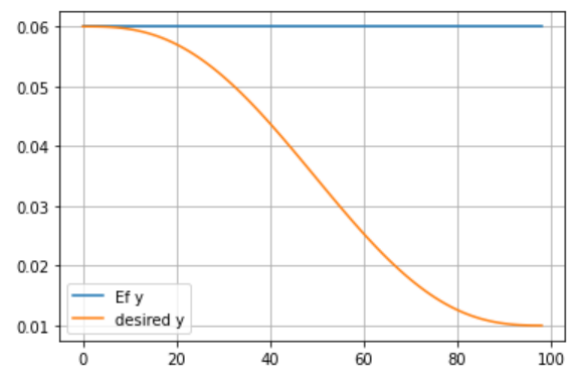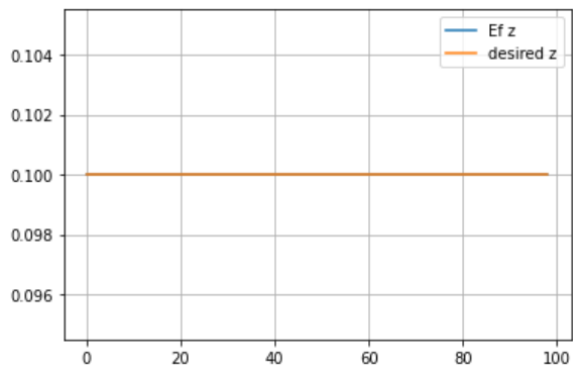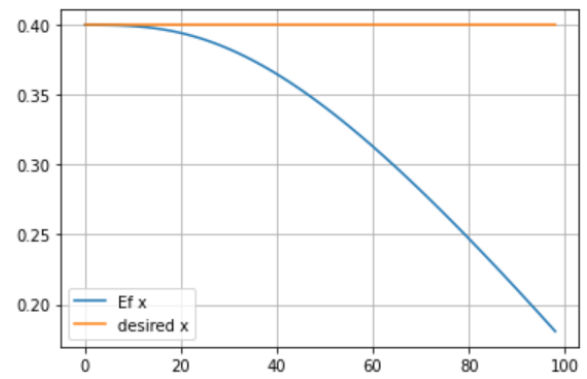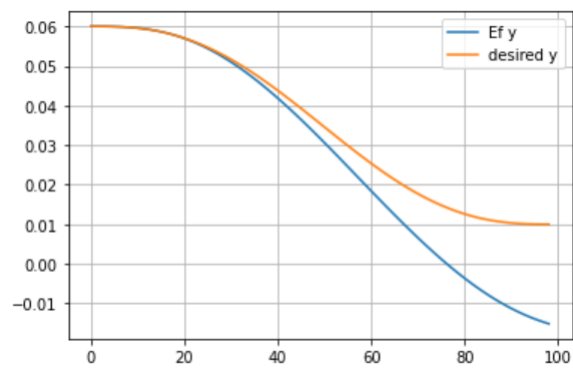3.a

3.b

Plots for question 3:

3.c

Gains: [0,0], [0,0], [0,0]

3.a

3.b

3.c