Response time reduction in make-to-order and assemble-to-order supply chain design

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Make-to-order and assemble-to-order systems are successful business strategies in managing responsive supply chains, characterized by high product variety, highly variable customer demand and short product life cycles. These systems usually spell long customer response times due to congestion. Motivated by the strategic importance of response time reduction, this paper presents models for designing make-to-order and assemble-to-order supply chains under Poisson customer demand arrivals and general service time distributions. The make-to-order supply chain design model seeks to simultaneously determine the location and the capacity of distribution centers (DCs) and allocate stochastic customer demand to DCs by minimizing response time in addition to the fixed cost of opening DCs and equipping them with sufficient assembly capacity and the variable cost of serving customers. The problem is setup as a network of spatially distributed M/G/1 queues, modeled as a non-linear mixed-integer program, and linearized using a simple transformation and a piecewise linear approximation. An exact solution approach is presented that is based on the cutting plane method. Then, the problem of designing a two-echelon assemble-to-order supply chain comprising of plants and DCs serving a set of customers is considered. A Lagrangean heuristic is proposed that exploits the echelon structure of the problem and uses the solution methodology for the make-to-order problem. Computational results and managerial insights are provided. It is empirically shown that substantial reduction in response times can be achieved with minimal increase in total costs in the design of responsive supply chains. Furthermore, a supply chain configuration that considers congestion is proposed and its effect on the response time can be very different from the traditional configuration that ignores congestion.

Keywords: Response time, make to order, assemble to order, supply chain design, cutting plane method, Lagrangean relaxation

1. Introduction

Make-to-Order (MTO) systems are successful business strategies to manage responsive supply chains that are characterized by high product variety, highly variable customer demand and short product life cycles. Because of mass customization and competition on product variety, many firms adopt an MTO strategy to offer a variety of products and deal with product proliferation. Dell's manufacturing and distribution of Personal Computers (PCs) is an excellent example of an MTO supply chain (Margretta, 1998; Dell, 2000). Dell typically offers several lines of product, with each allowing at least dozens of "features" from which customers can select when placing an order—different combinations of CPU, hard drive, memory and other peripherals. In Dell's supply chain, multiple components are procured

and kept in inventory at various assembly facilities, from which they are assembled into a wide variety of finished products in response to customer orders. Whereas each of these components takes a substantial lead time to manufacture, the time to assemble all these components into a PC is low, provided there is sufficient assembly capacity and the components are available. In traditional Make-To-Stock (MTS) supply chains, the customer orders are met from stocks of an inventory of finished products that are kept at various points of the network. This is done to reduce the delay in fulfilling customer orders, increase sales and avoid stockouts. However, the problems associated with holding inventory of finished products may outweigh the benefits, especially when those products become obsolete as technology advances or fashion changes. While an MTO strategy eliminates finished goods inventories and reduces a firm's exposure to the risk of obsolescence, it usually spells long customer response time (Gupta and Benjaafar, 2004).

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In order to reconcile the dual needs of a quick response time and high product variety, many firms such as General Electric, American Standard, Compag, IBM, BMW and National Bicycle use a hybrid strategy (i.e., mix of MTO and MTS) called the Assemble-To-Order (ATO) strategy, in which a subassembly, or a number of common subassemblies used in several products, are assembled and placed in inventory until an order is received for the finished product (Song and Zipkin, 2003). This allows the firm to customize the orders by having the product ready using the MTO strategy, while taking advantage of the economies of scale using the MTS strategy. Also, investment in the semi-finished product inventory is smaller compared to the option of maintaining a similar amount of finished goods inventory. Furthermore, demand pooling benefits can be realized. Although, maintaining a semi-finished product inventory in ATO systems lowers the customer response time as compared to a pure MTO system, it can be further reduced by minimizing congestion at the point of differentiation. Naturally, the response time to deliver the product is critical and forms the basis for competition. Consumers' willingness to pay a premium for a shorter response time provides further incentives for firms to reduce response time in MTO and ATO supply chains.

Although various integrated models of supply chain design have been proposed in recent years to support lead time reduction, these models have continued to be largely guided by more traditional concerns of efficiency and cost in MTS settings, where the primary focus is on minimizing the fixed cost of facility location and the variable transportation cost under fairly stable and deterministic customer demand settings. This approach is personified by the work of Dogan and Goetschalckx (1999), Vidal and Goetschalckx (2000), Teo and Shu (2004), Shen (2005), Eskigun et al. (2005) and Elhedhli and Gzara (2008). For example, Vidal and Goetschalckx (2000) present a model that captures the effect of change in transportation lead time and demand on the optimal configuration of the global supply chain network, assuming that the demand is deterministic. Eskigun et al. (2005) incorporate delivery lead time and the choice of transportation mode in the design of a supply chain under a deterministic demand setting. These models tend to ignore congestion at the facilities and its effect on response time. Their solutions prescribe locating facilities whose capacity utilization is very high, resulting in an excessively long response time when subjected to variability in service times and randomness in customer orders. Reviews by Vidal and Goetschalckx (1997), Erengüç et al. (1999) and Sarmiento and Nagi (1999) also point out that most of the existing supply chain design models do not consider measures of customer service such as response time in making location/allocation decisions. Also, refer to the recent review by Klose and Drexl (2005). This is not surprising given the complexity of the model and the interplay of locational and queueing aspects of the problem. To the best of our knowledge, Huang et al. (2005) is one of the first to model the effect of congestion in the design of distribution networks. They model capacity using the mean and variance of the Distribution Centers (DCs) as continuous variables, whereas our model considers capacity as a set of discrete options with known means and variances. They propose solution procedures based on outer approximation and Lagrangean relaxation, and tested on small instances of the problem.

Another growing body of literature that is related to our work and accounts for congestion and its effect on response time in strategic planning is models for facility location with immobile servers, stochastic demand and congestion (such as location of emergency medical facilities, fire stations, telecommunication network design, automated teller machines or internet mirror site location). For an extensive review, refer to Berman and Krass (2002). Due to the complexity of the underlying problem, most papers in this area make very strong assumptions: (i) either the number or capacity of the facilities (or both) are assumed to be fixed; (ii) the facilities are assumed to be identical; (iii) the demand arrival process is assumed to be Poisson; and (iv) the service process is usually assumed to be exponential (see, Amiri (1997), Marianov and Serra (2002), Wang et al. (2003) and Elhedhli (2006) and references therein). Despite that, most of the techniques proposed to date to solve these problems, with the exception of Elhedhli (2006), are either approximate or heuristic based. Our work is also similar in spirit to models for capacity planning with congestion effects, for which only heuristic solution procedures have been reported; see Rajagopalan and Yu (2001) and references therein.

The objective of this paper is to model the effect of congestion on the response time and analyze the tradeoff among response time costs, facility location and capacity acquisition costs, and outbound transportation costs in the design of supply chain networks. More specifically, we present a model to determine the configuration of an MTO supply chain, where the emphasis is on minimizing the customer response time through the acquisition of sufficient assembly capacity and the optimal allocation of workload to the assembly facilities (DCs) under stochastic customer demand settings. The DCs are modeled as spatially distributed queues with Poission arrivals and general service times to capture the dynamics of the response time. The model is formulated as a non-linear Mixed-Integer Programming (MIP) problem and is linearized using piecewise linear functions. We present a cutting plane algorithm that provides the optimal solution to the problem. Furthermore, we present a Lagrangean relaxation heuristic procedure for solving large-scale instances of such integrated models. Then, we present a model for the two-echelon ATO supply chain design problem, where a set of plants and DCs are to be established to distribute various finished products to a set of customers with stochastic demand. DCs act as assembly facilities, where semi-finished products, procured from plants are held in inventories, from which they are assembled into a wide variety of finished products in

response to customer demands. We propose a Lagrangean relaxation heuristic that exploits the echelon structure of the problem and uses the solution methodology proposed above for the MTO problem. Explicit consideration of congestion effects and their impact on response time in making location, capacity and allocation decisions in supply chains distinguishes this work from most other supply chain design models.

The rest of the paper is organized as follows. Section 2 provides a non-linear MIP formulation of the MTO supply chain design problem, a piecewise linearization and an exact solution approach based on the cutting plane method. The simplifications resulting from assuming exponentially distributed service times (M/M/1 case) and deterministic service times (M/D/1 case) are also explicitly described. In Section 3, we present the formulation of the two-echelon ATO supply chain design problem and a Lagrangean heuristic. Computational results and managerial insights are reported in Section 4. Finally, Section 5 concludes with some directions for future research.

2. MTO supply chain design

Consider the problem of designing an MTO supply chain, where a set of DCs are to be established and equipped with sufficient capacity to serve a set of customers. Sufficient capacity here implies being able to obtain service without waiting for an excessively long time after the order is placed. The DCs maintain inventory of multiple components and facilitate the assembly and shipment of a wide variety of finished products in a timely fashion without carrying expensive finished-goods inventory and incurring a long response time. Response time refers to the interval between the placing of an order and receipt of the ordered product. In MTO supply chains, because a customer order triggers the assembly of finished product from components, the response time consists of the assembly lead time and the delivery lead time. The delivery time between individual DCs and customers is relatively constant compared to the order fulfilment time at DCs in such settings. Moreover, it can further be reduced (using alternative transportation modes or expedited delivery services) to respond quickly to customer orders on a short-term basis. However, the assembly lead time is highly dependent on the DC capacity and the allocated workload and is difficult to change (on a short-term basis) once the DC is established.

2.1. Model formulation

We consider the setting depicted in Fig. 1. We assume that the demand for each product from each customer is independent and occurs according to a Poisson process. Once the demand for a product is realized at the customers' end, the order is placed at the DCs. DCs will act as assembly facil-

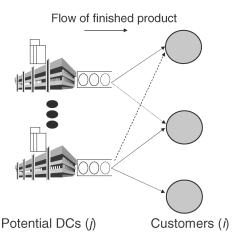


Fig. 1. An MTO supply chain network.

ities and the customers' orders arriving at the DCs are met on a First-Come First-Serve (FCFS) basis. We assume that each DC operates as a single flexible-capacity server with infinite buffers to accommodate customer orders waiting for service.

Under these assumptions, the MTO supply chain is modeled as a network of independent M/G/1 queues in which the DCs are treated as servers with service rates proportional to their capacity levels, where the capacity levels are discrete. We also assume that there is an unlimited supply of components and their inventory holding costs at the DCs are insignificant. Hence, the model formulated below simultaneously determines the location and capacity of DCs and the assignment of customer to DCs by minimizing the response time costs in addition to the fixed location and capacity acquisition costs, the assembly and transportation costs from DCs to customers. Besides capacity restrictions (steady-state conditions) at the DCs, and the demand requirements, there are constraints which ensure that at most one capacity level is selected at the DCs. To model this problem, we define the following notation.

Indices and parameters:

 $i = \text{index for customers}, i = 1, 2, \dots, I;$

i = index for potential DCs, j = 1, 2, ..., J;

k = index for potential capacity level at DCs, k = index

 $1, 2, \ldots, K;$

 f_{jk} = fixed cost of opening DC j and acquiring capacity level k (\$/period);

 c_{ij} = unit cost of serving customer *i* from DC *j* (\$/unit);

t = mean response time cost per unit time per customer(\$/period/customer);

 λ_i = mean demand rate for the product from customer i (units/period);

 μ_{jk} = mean *service rate* at DC *j*, if it is allocated capacity level *k* (units/period);

 σ_{jk}^2 = variance of *service times* at DC *j*, if it is allocated capacity level *k*.

Decision variables:

 x_{ij} = fraction of customer i's demand served by DC j (0 \leq

$$y_{jk} = \begin{bmatrix} x_{ij} \le 1 \\ 1, & \text{if DC } j \text{ is opened and capacity level } k \\ & \text{is acquired} \\ 0, & \text{otherwise.} \end{bmatrix}$$

Let the demand for the product at customer location i be an independent random variable that follows a Poisson process with mean λ_i . If x_{ij} is the fraction of customer i's demand served by DC j, then the aggregate demand arrival rate at DC j is also a random variable that follows a Poisson process with mean $\lambda_j = \sum_{i=1}^{I} \lambda_i x_{ij}$, due to the superposition of Poisson processes. If the service times at each DC follow a general distribution and each DC is modeled as an M/G/1 queue, then the mean service rate of DC j, if it is allocated capacity level k, is given by $\mu_j = \sum_{k=1}^K \mu_{jk} y_{jk}$ and the variance in service times is $\sigma_j^2 = \sum_{k=1}^K \sigma_{jk}^2 y_{jk}$. This service rate reflects the server capacity or essentially the number of MTO products a DC can assemble and ship in a given time period. Let τ_i represent the mean service time at DC j ($\tau_j = 1/\mu_j$), ρ_j be the utilization of DC j ($\rho_j = \lambda_j/\mu_j$) and CV_j^2 be the squared coefficient of variation of service times $(CV_i^2 = \sigma_i^2/\tau_i^2)$. Under steady-state conditions $(\lambda_i < \mu_i)$ and FCFS queuing discipline, the expected average waiting time (including the service time) at DC j is given by the Pollaczek–Khintchine (PK) formula:

$$E[W_j(M/G/1)] = \left(\frac{1 + CV_j^2}{2}\right) \frac{\tau_j \rho_j}{1 - \rho_j} + \tau_j$$
$$= \left(\frac{1 + CV_j^2}{2}\right) \frac{\lambda_j}{\mu_i(\mu_i - \lambda_i)} + \frac{1}{\mu_i} \quad \forall j,$$

and the expected total waiting time for DC j is obtained by multiplying the waiting time at DC j by the expected demand as

$$\left(\frac{1+CV_j^2}{2}\right)\frac{\lambda_j^2}{\mu_i(\mu_i-\lambda_i)}+\frac{\lambda_j}{\mu_i}\qquad\forall j.$$

The expected *total* waiting time for the entire system is given by

$$E[W(M/G/1)] = \sum_{j=1}^{J} \left[\left(\frac{1 + CV_j^2}{2} \right) \frac{\lambda_j^2}{\mu_j(\mu_j - \lambda_j)} + \frac{\lambda_j}{\mu_j} \right],$$

and can be written as:

$$\frac{1}{2}\sum_{i=1}^{J}\left[\left(1+CV_{j}^{2}\right)\frac{\lambda_{j}}{\mu_{j}-\lambda_{j}}+\left(1-CV_{j}^{2}\right)\frac{\lambda_{j}}{\mu_{j}}\right].$$

This is equivalent to

$$\frac{1}{2} \sum_{j=1}^{J} \left[\left(1 + \sum_{k=1}^{K} CV_{jk}^{2} y_{jk} \right) \frac{\sum_{i=1}^{I} \lambda_{i} x_{ij}}{\sum_{k=1}^{K} \mu_{jk} y_{jk} - \sum_{i=1}^{I} \lambda_{i} x_{ij}} + \left(1 - \sum_{k=1}^{K} CV_{jk}^{2} y_{jk} \right) \frac{\sum_{i=1}^{I} \lambda_{i} x_{ij}}{\sum_{k=1}^{K} \mu_{ik} y_{ik}} \right]. \tag{1}$$

The resulting non-linear MIP formulation is

$$(P_{N}): \min \sum_{j=1}^{J} \sum_{k=1}^{K} f_{jk} y_{jk} + \sum_{i=1}^{I} \sum_{j=1}^{J} c_{ij} \lambda_{i} x_{ij} + t E[W(M/G/1)],$$
(2)

subject to

$$\sum_{i=1}^{I} \lambda_i x_{ij} \le \sum_{k=1}^{K} \mu_{jk} y_{jk} \qquad \forall j, \tag{3}$$

$$\sum_{k=1}^{K} y_{jk} \le 1 \qquad \forall j, \tag{4}$$

$$\sum_{j=1}^{J} x_{ij} = 1 \qquad \forall i, \tag{5}$$

$$0 \le x_{ij} \le 1, \quad y_{jk} \in \{0, 1\} \qquad \forall i, j, k.$$
 (6)

The first term in the objective function (2) represents the fixed cost (amortized over the planning period) of locating DCs and equipping them with adequate assembly capacity. The second term accounts for the variable cost of assembly and shipment of products from DCs to customers. The third term is the expected total response time cost or the lost sales due to excessive response times between DCs and customers. The expected total response time cost is expressed as a product of average response time cost per unit time that one of its customers spends in the system and expected total waiting time in the system. In this paper, for simplicity and tractability reasons, we assume that the cost of the response time is linearly proportional to the waiting time. However, the model can be extended to other cost functions such as a piecewise linear function or a cost function proportional to max $\{0, E[W(M/G/1)] - W_0\}$, where W_0 is the maximum tolerated waiting time for a customer. Moreover, the average response time cost t may vary from customer to customer (t_{ii}) if desired, but we assume for simplicity that it is the same across customers. It can be interpreted as a penalty function that reflects the true cost of not fulfilling customer orders in the committed lead time. In practice, determining the values of average response time cost can be challenging, however, one can rely on techniques outlined in Rao et al. (2000). To accurately reflect lost sales due to unacceptable response time, Rao et al. (2000) surveyed Caterpillar dealers to determine the percent of customers who would renege if a product was not available immediately, after 2 weeks, and after 4 weeks. A lower bound on the response time cost can be provided by the inventory holding costs (Eskigun et al., 2005). Furthermore, the problems can be solved iteratively with different values of t to obtain a trade-off curve from which decision makers may choose a solution based on their preference between location and capacity acquisition cost, transportation cost, and response time costs.

Constraints (3) ensure that the steady-state conditions $(\lambda_i \le \mu_i)$ at the DCs are met. Constraint set (4) ensures that at most one capacity level is selected at a DC, whereas constraint set (5) ensures that the total demand is met.

Constraints (6) are non-negativity and binary restrictions. The formulation can easily handle single-sourcing requirements by imposing binary restrictions on x_{ij} . This would restrict the assignment of customer i's demand to one and only one DC i.

The non-linearity in (P_N) arises due to the expression of the total waiting time at the DCs, E[W(M/G/1)]. It can be shown that E[W(M/G/1)] is convex in aggregate arrival rate λ_j , for a fixed value of μ_j and convex in service rate μ_j , for a fixed value of λ_j , where $\lambda_j = \sum_{i=1}^I \lambda_i x_{ij}$ and $\mu_j = \sum_{k=1}^K \mu_{jk} y_{jk}$. Intuitively, one would expect that the waiting time increases with increasing marginal returns as the arrival rate increases and decreases with decreasing marginal returns as the service rate increases. In the next section, we deal with the non-linearity due to the expression of the total average waiting time using a linearization based on a simple transformation and a piecewise linear approximation. We also present an exact solution procedure based on the cutting plane algorithm. Our cutting plane algorithm is similar to the outer-approximation algorithm (Duran and Grossman, 1986).

2.2. Linearization and cutting plane method

In order to linearize Equation (1), let us define non-negative auxiliary variables R_i , such that:

$$R_j = \frac{\lambda_j}{\lambda_j - \mu_j} = \frac{\sum_{i=1}^I \lambda_i x_{ij}}{\sum_{k=1}^K \mu_{jk} y_{jk} - \sum_{i=1}^I \lambda_i x_{ij}} \quad \forall j$$

which implies that

$$\sum_{i=1}^{I} \lambda_i x_{ij} = \frac{R_j}{1 + R_j} \sum_{k=1}^{K} \mu_{jk} y_{jk}$$

$$= \rho_j \sum_{k=1}^{K} \mu_{jk} y_{jk} = \sum_{k=1}^{K} \mu_{jk} z_{jk}$$
(7)

where

$$z_{jk} = \begin{cases} 0 & \text{if } y_{jk} = 0\\ \rho_i & \text{if } y_{ik} = 1 \end{cases} \quad \forall j, k$$
 (8)

and $\rho_i = R_i/(1 + R_i)$ is the server (DC) utilization.

Since there is at most one k' with $y_{jk'} = 1$ while $y_{jk} = 0$ for all other $k \neq k'$, the expression $z_{jk} = \rho_j y_{jk}$ can be ensured by adding the following constraints:

$$z_{jk} \le y_{jk} \qquad \forall j, k,$$

$$\sum_{k=1}^{K} z_{jk} = \rho_j \qquad \forall j.$$

The function $\rho_j = R_j/(1 + R_j)$ is concave. Given a set of points R_j^h indexed by H, ρ_j can be approximated by an infinite set of piecewise linear functions that are tangent to ρ_j at points R_j^h (as shown in Fig. 2) that is

$$\rho_{j} = \min_{h \in H} \left\{ \frac{1}{(1 + R_{i}^{h})^{2}} R_{j} + \frac{(R_{j}^{h})^{2}}{(1 + R_{i}^{h})^{2}} \right\} \qquad \forall j$$

or

$$\rho_j \le \frac{1}{(1+R_i^h)^2} R_j + \frac{(R_j^h)^2}{(1+R_i^h)^2} \quad \forall j, h \in H.$$

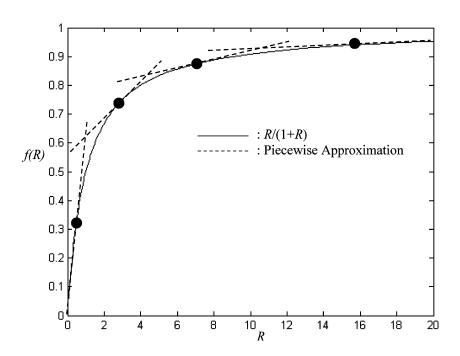


Fig. 2. A piecewise linear approximation of $R_i/(1+R_i)$.

The expression for E[W(M/G/1)] reduces to

$$E[W(M/G/1)] = \frac{1}{2} \sum_{j=1}^{J} \left\{ \left(1 + \sum_{k=1}^{K} CV_{jk}^{2} y_{jk} \right) R_{j} + \left(1 - \sum_{k=1}^{K} CV_{jk}^{2} y_{jk} \right) \rho_{j} \right\}$$
$$= \frac{1}{2} \sum_{j=1}^{J} \left(R_{j} + \sum_{k=1}^{K} CV_{jk}^{2} w_{jk} + \rho_{j} - \sum_{k=1}^{K} CV_{jk}^{2} z_{jk} \right)$$

where

$$w_{jk} = \begin{cases} 0 & \text{if} \quad y_{jk} = 0 \\ R_j & \text{if} \quad y_{jk} = 1 \end{cases} \text{ and } z_{jk} = \begin{cases} 0 & \text{if} \quad y_{jk} = 0 \\ \rho_j & \text{if} \quad y_{jk} = 1 \end{cases} \quad \forall j, k.$$

Similarly, because there exists at most one k' with $y_{jk'} = 1$ while $y_{jk} = 0$ for all other $k \neq k'$, the expression $w_{jk} = R_j y_{jk}$ can be ensured by adding the following constraints:

$$w_{jk} \le M y_{jk}$$
 $\forall j, k$
 $\sum_{k=1}^{K} w_{jk} = R_j$ $\forall j,$

where *M* is the usual Big-M. The resulting linear MIP formulation is

$$(P_{L(H)}): \min \sum_{j=1}^{J} \sum_{k=1}^{K} f_{jk} y_{jk} + \sum_{i=1}^{I} \sum_{j=1}^{J} c_{ij} \lambda_{i} x_{ij} + \frac{t}{2} \sum_{i=1}^{J} \left\{ R_{j} + \rho_{j} + \sum_{k=1}^{K} C V_{jk}^{2} (w_{jk} - z_{jk}) \right\}, \quad (9)$$

subject to

$$\sum_{i=1}^{I} \lambda_i x_{ij} - \sum_{k=1}^{K} \mu_{jk} z_{jk} = 0 \qquad \forall j,$$
 (10)

$$\sum_{k=1}^{K} y_{jk} \le 1 \qquad \forall j, \tag{11}$$

$$\sum_{i=1}^{J} x_{ij} = 1 \qquad \forall i, \tag{12}$$

$$z_{jk} - y_{jk} \le 0 \qquad \forall j, k, \tag{13}$$

$$\rho_j - \frac{1}{\left(1 + R_i^h\right)^2} R_j \le \frac{\left(R_j^h\right)^2}{\left(1 + R_i^h\right)^2} \qquad \forall j, h \in H,$$
(14)

$$\rho_j - \sum_{k=1}^K z_{jk} = 0 \qquad \forall j, \tag{15}$$

$$w_{jk} - My_{jk} \le 0 \qquad \forall j, k, \tag{16}$$

$$\sum_{k=1}^{K} w_{jk} - R_j = 0 \qquad \forall j, \tag{17}$$

$$y_{jk} \in \{0, 1\}; \ 0 \le x_{ij}, z_{jk} \le 1; \ \rho_j, R_j, w_{jk} \ge 0; \ \forall i, j, k.$$

The steady-state conditions $(\lambda_j < \mu_j)$ translate into capacity constraints, and are enforced by the constraints (10) and (13) and forced to "<" by the term R_i in the objective.

 $(P_{L(H)})$ is a minimization problem, at least one of the constraints in Equation (14) will be binding. This implies that

$$\rho_j = \min_{h \in H} \left[\frac{1}{\left(1 + R_j^h\right)^2} R_j + \frac{\left(R_j^h\right)^2}{\left(1 + R_j^h\right)^2} \right] \quad \forall j \text{ when } y_{jk} = 1.$$

In order to deal with the infinite number of constraints (14) in the linear MIP model $(P_{L(H)})$, we use a cutting plane algorithm, described as follows. For an initial and finite set of points $(R_j^h)_{\bar{H}\subset H}$, $(P_{L(\bar{H})})$ is a relaxation of the full problem $(P_{L(H)})$, hence a lower bound to $(P_{L(H)})$ or (P_N) is provided by the optimal objective function value $v((P_{L(\bar{H})}))$, where

$$v((\mathbf{P}_{\mathbf{L}(\bar{H})})) = \sum_{j=1}^{J} \sum_{k=1}^{K} f_{jk} \bar{y}_{jk} + \sum_{i=1}^{I} \sum_{j=1}^{J} c_{ij} \lambda_{i} \bar{x}_{ij} + \frac{t}{2} \sum_{i=1}^{J} \left\{ \bar{R}_{j} + \bar{\rho}_{j} + \sum_{k=1}^{K} CV_{jk}^{2} (\bar{w}_{jk} - \bar{z}_{jk}) \right\},$$

where $(\bar{x}, \bar{y}, \bar{R}, \bar{\rho}, \bar{w}, \bar{z})$ is the solution of $(P_{L(\bar{H})})$. Furthermore, (\bar{x}, \bar{y}) is feasible to (P_N) and hence:

$$\begin{split} &\sum_{j=1}^{J} \sum_{k=1}^{K} f_{jk} \overline{y}_{jk} + \sum_{i=1}^{I} \sum_{j=1}^{J} c_{ij} \lambda_{i} \overline{x}_{ij} \\ &+ \frac{t}{2} \sum_{j=1}^{J} \left[\left(1 + \sum_{k=1}^{K} C V_{jk}^{2} \overline{y}_{jk} \right) \frac{\sum_{i=1}^{I} \lambda_{i} \overline{x}_{ij}}{\sum_{k=1}^{K} \mu_{jk} \overline{y}_{jk} - \sum_{i=1}^{I} \lambda_{i} \overline{x}_{ij}} \right. \\ &+ \left(1 - \sum_{k=1}^{K} C V_{jk}^{2} \overline{y}_{jk} \right) \frac{\sum_{i=1}^{I} \lambda_{i} \overline{x}_{ij}}{\sum_{k=1}^{K} \mu_{jk} \overline{y}_{jk}} \end{split}$$

provides an upper bound to $(P_{L(\bar{H})})$ and (P_N) . If the best known upper bound coincides with the lower bound at a given iteration, then the optimal solution is obtained and the algorithm is terminated. If not, a new set of cuts (14) are generated using (\bar{R}_j) and appended to $(P_{L(\bar{H})})$ and the procedure is repeated. The computational performance of the algorithm is reported in Section 4.

2.3. Special cases

In this section, we examine two special cases that are commonly looked at in the literature.

2.3.1. Systems with exponential service times (M/M/1 case)

The exponential processing and assembly time is a reasonable assumption in cases where there is high variability in setup times and processing times, e.g., in semiconductor wafer fabrication (Kim and Tang, 1997). Also, this is more reasonable than deterministic processing and assembly times for MTO products with very high product variety

and varying batch sizes. For exponentially distributed service times at the DCs, the total expected waiting time for the entire system is given by

$$E[W(M/M/1)] = \sum_{j=1}^{J} \frac{\lambda_j}{\mu_j - \lambda_j}$$

$$= \sum_{j=1}^{J} \left(\frac{\sum_{i=1}^{I} \lambda_i x_{ij}}{\sum_{k=1}^{K} \mu_{jk} y_{jk} - \sum_{i=1}^{I} \lambda_i x_{ij}} \right) = \sum_{j=1}^{J} R_j.$$

The resulting linear MIP model is

$$(\mathbf{P}_{\mathrm{L}(H)}^{M/M/1}): \min \sum_{j=1}^{J} \sum_{k=1}^{K} f_{jk} y_{jk} + \sum_{i=1}^{I} \sum_{j=1}^{J} c_{ij} \lambda_i x_{ij} + t \sum_{j=1}^{J} R_j$$
(19)

subject to Equations (10) to (15),

$$y_{jk} \in \{0, 1\}; \quad 0 \le x_{ij}, z_{jk} \le 1; \quad \rho_j, R_j \ge 0 \quad \forall i, j, k.$$

The model is structurally identical to the service system design model presented in Amiri (1997) and Elhedhli (2006).

2.3.2. Systems with deterministic service times (M/D/1 case)

In many cases, the processing/assembly of finished products at the DCs often involves repeated steps without much variation (Kim and Tang, 1997). This is particularly true for MTO products with limited options and batch size of one such as Dell's PCs. For deterministic service times, the expected waiting time for the entire system is given by

$$E[W(M/D/1)] = \frac{1}{2} \sum_{j=1}^{J} \left(\frac{\lambda_j}{\mu_j - \lambda_j} + \frac{\lambda_j}{\mu_j} \right) = \frac{1}{2} \sum_{j=1}^{J} (R_j + \rho_j).$$

The resulting linear MIP model is as follows:

$$\left(P_{L(H)}^{M/D/1}\right) : \min \sum_{j=1}^{J} \sum_{k=1}^{K} f_{jk} y_{jk}
+ \sum_{i=1}^{I} \sum_{j=1}^{J} c_{ij} \lambda_i x_{ij} + \frac{t}{2} \sum_{j=1}^{J} (R_j + \rho_j),$$
(20)

subject to Equations (10) to (15),

$$y_{jk} \in \{0, 1\}; \quad 0 \le x_{ij}, z_{jk} \le 1; \quad \rho_j, R_j \ge 0 \quad \forall i, j, k.$$

The cutting plane algorithm described above can be used to solve these models to optimality. Alternatively, one can rely on the Lagrangean heuristics. Some computational results are provided in Section 4.

3. ATO supply chain design

In this section, we consider the design of an ATO supply chain, where we seek to locate a set of plants and DCs to distribute a product with a non-trivial bill of materials to Flow of semi-finished products (n) Flow of finished product

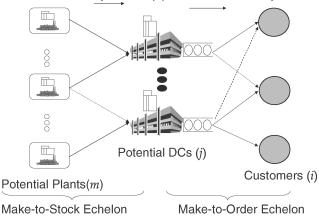


Fig. 3. An ATO supply chain network.

a set of customers with stochastic demand. The DCs will act as intermediate facilities between the plants and the customers and facilitate the shipment of products between the two echelons, as shown in Fig. 3.

The semi-finished products are produced at the plants and shipped to the DCs. Once the demand is realized at the customers' end, the order is placed to the DC and the final product is assembled and the demand is met. Hence, the supply chain network is a combination of the MTS echelon (plant-DC echelon) and the MTO echelon (DC-customer echelon). The problem environment is characterized by a stochastic customer demand that has to be satisfied from a set of DCs and where sufficient capacity has to be acquired in order to avoid long response times. To model this problem, we define the following additional notation.

m = index for potential plants, m = 1, 2, ..., M;

= index for semi-finished products, n = 1, 2, ..., N;

 g_m = fixed cost of opening a plant at location m (\$/period):

 P_m = maximum available capacity of plant m (units);

 c'_{jmm} = unit production and transportation cost for semifinished product *n* from plant *m* to DC *j*;

 η_n = number of units of semi-finished product *n* required to make one unit of finished product;

 u_m = decision variable that equals one, if plant m is opened; zero, otherwise;

 v_{jmn} = number of units of semi-finished product n produced from plant m and shipped to DC j.

Under the assumption that the demand at customer i is an independent random variable that follows a Poisson process with mean λ_i and the service time at each DC follows a general distribution, each DC is modeled as an M/G/1 queue, whose mean service rate, if it is allocated capacity level k, is given by $\mu_j = \sum_{k=1}^K \mu_{jk} y_{jk}$ and the variance in service times is given by $\sigma_j^2 = \sum_{k=1}^K \sigma_{jk}^2 y_{jk}$. Under steady-state conditions $(\lambda_j < \mu_j)$ and FCFS queuing discipline, the

total average waiting time for the entire system (service plus queuing time) is given by Equation (1). The resulting nonlinear MIP formulation that simultaneously determines the location and capacity of plants and DCs, the shipment levels from plants to DCs, and allocation of customers to DCs by minimizing response time costs in addition to fixed facility location and capacity acquisition costs, production and transportation costs between echelons is as follows:

$$(P_{ATO}) : \min \sum_{m=1}^{M} g_{m} u_{m} + \sum_{j=1}^{J} \sum_{k=1}^{K} f_{jk} y_{jk} + \sum_{j=1}^{J} \sum_{m=1}^{M} \sum_{n=1}^{N} c'_{jmn} v_{jmn}$$

$$+ \sum_{i=1}^{I} \sum_{j=1}^{J} c_{ij} \lambda_{i} x_{ij} + \frac{t}{2} \sum_{j=1}^{J} \left(1 + \sum_{k=1}^{K} C V_{jk}^{2} y_{jk} \right)$$

$$\times \frac{\sum_{i=1}^{I} \lambda_{i} x_{ij}}{\sum_{k=1}^{K} \mu_{jk} y_{jk} - \sum_{i=1}^{I} \lambda_{i} x_{ij}}$$

$$+ \frac{t}{2} \sum_{j=1}^{J} \left(1 - \sum_{k=1}^{K} C V_{jk}^{2} y_{jk} \right) \frac{\sum_{i=1}^{I} \lambda_{i} x_{ij}}{\sum_{k=1}^{K} \mu_{jk} y_{jk}}, \quad (21)$$

subject to

$$\sum_{i=1}^{J} \sum_{n=1}^{N} v_{jmn} \le P_m u_m \qquad \forall m, \tag{22}$$

$$\sum_{m=1}^{M} v_{jmn} = \sum_{i=1}^{I} \eta_n \lambda_i x_{ij} \qquad \forall j, n,$$
(23)

$$\sum_{i=1}^{I} \lambda_i x_{ij} \le \sum_{k=1}^{K} \mu_{jk} y_{jk} \qquad \forall j, \tag{24}$$

$$\sum_{k=1}^{K} y_{jk} \le 1 \qquad \forall j, \tag{25}$$

$$\sum_{i=1}^{J} x_{ij} = 1 \qquad \forall i, \tag{26}$$

$$0 \le x_{ij} \le 1, \quad y_{jk}, u_m \in \{0, 1\}, \quad v_{jmn} \ge 0$$

 $\forall i, j, k, m, n.$ (27)

The objective function (21) consists of the fixed cost of opening plants, the fixed cost of locating DCs and equipping DCs with the required capacity level, the variable cost of producing and procuring semi-finished product, the variable cost of serving customers from DCs and the total waiting time costs at the DCs. Constraints (22) are capacity restrictions on the opened plants and permit the use of opened plants only. Constraints (23) are commodity flow conservation equations at the DCs. Constraints (24) ensure that the steady-state conditions at the DCs are met. Constraints (25) ensure that at most one capacity level is selected at a DC whereas constraints (26) ensure that the total demand is met. Constraints (27) are non-negativity and binary constraints.

3.1. Lagrangean relaxation

There are number of ways in which the model can be relaxed in Lagrangean fashion (see Klose and Drexl (2005) and reference therein). In this paper, we exploit the echelon structure of the ATO supply chain using Lagrangean relaxation to decompose the model into two subproblems. Note that in (P_{ATO}), constraints (22) relate to the MTS echelon, and constraints (24) to (26) relate to the MTO echelon, whereas constraints (23) are the flow conservation constraints that link the two echelons. Upon relaxing the flow conservation constraints (23) with dual multipliers β_{jn} , the problem decomposes into two subproblems:

(SP_{MTS}):
$$\min \sum_{m=1}^{M} g_m u_m + \sum_{j=1}^{J} \sum_{m=1}^{M} \sum_{n=1}^{N} (c'_{jmn} - \beta_{jn}) v_{jmn}$$
, (28)

subject to

$$\sum_{j=1}^{J} \sum_{n=1}^{N} v_{jmn} \le P_m u_m \qquad \forall m, \tag{29}$$

$$u_m \in \{0, 1\}, \quad v_{jmn} \ge 0 \qquad \forall j, m, n.$$
 (30)

(SP_{MTO}): min
$$\sum_{j=1}^{J} \sum_{k=1}^{K} f_{jk} y_{jk} + \sum_{i=1}^{I} \sum_{j=1}^{J} \sum_{n=1}^{N} (c_{ij} + \eta_n \beta_{jn}) \lambda_i x_{ij}$$

$$+\frac{t}{2} \sum_{j=1}^{J} \left(1 + \sum_{k=1}^{K} C V_{jk}^{2} y_{jk} \right) \frac{\sum_{i=1}^{I} \lambda_{i} x_{ij}}{\sum_{k=1}^{K} \mu_{jk} y_{jk} - \sum_{i=1}^{I} \lambda_{i} x_{ij}}$$

$$+ \frac{t}{2} \sum_{i=1}^{J} \left(1 - \sum_{k=1}^{K} C V_{jk}^{2} y_{jk} \right) \frac{\sum_{i=1}^{I} \lambda_{i} x_{ij}}{\sum_{k=1}^{K} \lambda_{i} x_{ij}},$$
 (31)

subject to

$$\sum_{i=1}^{I} \lambda_i x_{ij} \le \sum_{k=1}^{K} \mu_{jk} y_{jk}, \tag{32}$$

$$\sum_{j=1}^{J} x_{ij} = 1 \qquad \forall i, \tag{33}$$

$$\sum_{k=1}^{K} y_{jk} \le 1 \qquad \forall j, \tag{34}$$

$$0 \le x_{ij} \le 1, \quad y_{ik} \in \{0, 1\} \qquad \forall i, j, k.$$
 (35)

Subproblem (SP_{MTS}) is a linear MIP model that determines the location of plants and the flow of semi-finished products into the DCs, whereas the subproblem (SP_{MTO}) is a non-linear MIP model that provides the location and capacity level of DCs and the allocation of customers to DCs. Note that the subproblem (SP_{MTO}) is the MTO supply chain design model presented in the previous section and hence we use the proposed cutting plane algorithm to solve it.

From model (P_{ATO}), we can derive some valid constraints. For example, consider the following set of

constraints:

$$\sum_{m=1}^{M} P_m u_m \ge \sum_{i=1}^{I} \lambda_i, \tag{36}$$

$$\sum_{m=1}^{M} v_{jmn} \le \eta_n \Big(\max_k \mu_{jk} \Big) \qquad \forall j, n, \tag{37}$$

$$\sum_{i=1}^{J} \sum_{m=1}^{M} v_{jmn} \ge \eta_n \sum_{i=1}^{I} \lambda_i \qquad \forall n.$$
 (38)

Constraints (36) are aggregate capacity constraints for the MTS echelon. Constraints (37) are derived from Equations (23) and (24) and constraints (38) follow from Equations (23) and (26). Constraints (37) imply that the total flow of semi-finished products through a DC should not exceed the DC's maximum throughput capacity, whereas constraints (38) ensure that the flow of every semi-finished product from plants to DC is at least equal to the bill of materials multiplied by the demand of that product from all the customers. These constraints are redundant in the original MIP formulation, but they improve the quality of the subproblem solutions in terms of the feasibility to the original problem upon relaxing the flow conservation constraints. This results in better heuristic solutions. Therefore, we add these set of constraints to (SP_{MTS}) as follows:

(SP_{MTS}):
$$\min \sum_{m=1}^{M} g_m u_m + \sum_{j=1}^{J} \sum_{m=1}^{M} \sum_{n=1}^{N} (c'_{jmn} - \beta_{jn}) v_{jmn},$$
(39)

subject to

$$\sum_{i=1}^{J} \sum_{n=1}^{N} v_{jmn} \le P_m u_m \qquad \forall m, \tag{40}$$

$$\sum_{m=1}^{M} P_m u_m \ge \sum_{i=1}^{I} \lambda_i,\tag{41}$$

$$\sum_{k=1}^{M} v_{jmn} \le \eta_n \Big(\max_{k} \mu_{jk} \Big) \qquad \forall j, n, \qquad (42)$$

$$\sum_{j=1}^{J} \sum_{m=1}^{M} v_{jmn} \ge \eta_n \sum_{i=1}^{I} \lambda_i \qquad \forall n, \tag{43}$$

$$u_m \in \{0, 1\}, \quad v_{imn} \ge 0 \qquad \forall j, m, n.$$
 (44)

3.1.1. The lower bound

The Lagrangean lower bound is given by the solution of the Lagrangean dual problem, $\max_{\beta}[v(SP_{MTS}) + v(SP_{MTO})]$ which is equivalent to

$$\max_{\beta} \left\{ \min_{h \in I_{u,v}} \sum_{m=1}^{M} g_m u_m^h + \sum_{j=1}^{J} \sum_{m=1}^{M} \sum_{n=1}^{N} (c'_{jmn} - \beta_{jn}) v_{jmn}^h + \min_{h \in I_{x,y}} \sum_{j=1}^{J} \sum_{k=1}^{K} f_{jk} v_{jk}^h + \sum_{i=1}^{I} \sum_{j=1}^{J} \sum_{n=1}^{N} (c_{ij} + \eta_n \beta_{jn}) \lambda_i x_{ij}^h \right\}$$

$$+ \frac{t}{2} \sum_{j=1}^{J} \left(1 + \sum_{k=1}^{K} CV_{jk}^{2} y_{jk}^{h} \right) \frac{\sum_{i=1}^{I} \lambda_{i} x_{ij}^{h}}{\sum_{k=1}^{K} \mu_{jk} y_{jk}^{h} - \sum_{i=1}^{I} \lambda_{i} x_{ij}^{h}}$$

$$+ \frac{t}{2} \sum_{j=1}^{J} \left(1 - \sum_{k=1}^{K} CV_{jk}^{2} y_{jk}^{h} \right) \frac{\sum_{i=1}^{I} \lambda_{i} x_{ij}}{\sum_{k=1}^{K} \mu_{jk} y_{jk}} \right\}.$$

Thus can be explicitly written as

(MP):
$$\max_{\beta} \theta_1 + \theta_2$$
,

subject to

$$\begin{split} \theta_{1} + \sum_{j=1}^{J} \sum_{m=1}^{M} \sum_{n=1}^{N} v_{jmn}^{h} \beta_{jn} &\leq \sum_{m=1}^{M} g_{m} u_{m}^{h} \\ + \sum_{j=1}^{J} \sum_{m=1}^{M} \sum_{n=1}^{N} c'_{jmn} v_{jmn}^{h} \ h \in I_{u,v}, \\ \theta_{2} - \sum_{i=1}^{I} \sum_{j=1}^{J} \sum_{n=1}^{N} \left(\eta_{n} \lambda_{i} x_{ij}^{h} \right) \beta_{jn} &\leq \sum_{j=1}^{J} \sum_{k=1}^{K} f_{jk} y_{jk}^{h} \\ + \sum_{i=1}^{I} \sum_{j=1}^{J} c_{ij} \lambda_{i} x_{ij}^{h} \\ + \frac{t}{2} \sum_{j=1}^{J} \left(1 + \sum_{k=1}^{K} C V_{jk}^{2} y_{jk}^{h} \right) \frac{\sum_{i=1}^{I} \lambda_{i} x_{ij}^{h}}{\sum_{k=1}^{K} \mu_{jk} y_{jk}^{h} - \sum_{i=1}^{I} \lambda_{i} x_{ij}^{h}} \\ + \frac{t}{2} \sum_{j=1}^{J} \left(1 - \sum_{k=1}^{K} C V_{jk}^{2} y_{jk}^{h} \right) \frac{\sum_{i=1}^{I} \lambda_{i} x_{ij}}{\sum_{k=1}^{K} \mu_{jk} y_{jk}} \quad h \in I_{x,y}, \end{split}$$

where $I_{u,v}$ is the index set of feasible points of the set:

 $\{(u_m, v_{jmn}): \text{ Equations (40) to (43)}; u_m \in \{0, 1\}; v_{jmn} \ge 0, \forall j, m, n\},$

and $I_{x,y}$ is the index set of feasible points of the set:

 $\{(x_{ij}, y_{jk}): \text{ Equations } (32) \text{ to } (34); x_{ij} \ge 0; y_{jk} \in \{0, 1\}, \forall i, j, k\}.$

We use Kelley's cutting plane method, in which the point $\bar{\beta}$ is the solution of the relaxed master problem (RMP), defined on subsets $\bar{I}_{u,v} \subset I_{u,v}$ and $\bar{I}_{x,y} \subset I_{x,y}$ (Kelley, 1960). This $\bar{\beta}$ from (RMP) is used to solve the subproblems (SP_{MTS}) and (SP_{MTO}), and generate two cuts of the form:

$$\theta_{1} + \sum_{j=1}^{J} \sum_{m=1}^{M} \sum_{n=1}^{N} v_{jmn}^{\bar{i}} \beta_{jn} \leq \sum_{m=1}^{M} g_{m} u_{m}^{\bar{i}} + \sum_{j=1}^{J} \sum_{m=1}^{M} \sum_{n=1}^{N} c'_{jmn} v_{jmn}^{\bar{i}},$$

$$(45)$$

$$\theta_{2} - \sum_{i=1}^{I} \sum_{j=1}^{J} \sum_{n=1}^{N} (\eta_{n} \lambda_{i} x_{ij}^{\bar{i}'}) \beta_{jn} \leq \sum_{j=1}^{J} \sum_{k=1}^{K} f_{jk} y_{jk}^{\bar{i}'}$$

$$+ \sum_{i=1}^{I} \sum_{j=1}^{J} c_{ij} \lambda_{i} x_{ij}^{\bar{i}'} + \frac{t}{2} \sum_{j=1}^{J} \left(1 + \sum_{k=1}^{K} C V_{jk}^{2} y_{jk}^{\bar{i}'} \right)$$

$$\times \frac{\sum_{i=1}^{I} \lambda_{i} x_{ij}^{\bar{i}'}}{\sum_{k=1}^{K} \mu_{jk} y_{jk}^{\bar{i}'} - \sum_{i=1}^{I} \lambda_{i} x_{ij}^{\bar{i}'}} + \frac{t}{2} \sum_{j=1}^{J} \left(1 - \sum_{k=1}^{K} C V_{jk}^{2} y_{jk}^{\bar{i}'} \right)$$

$$\times \frac{\sum_{i=1}^{I} \lambda_{i} x_{ij}^{\bar{i}'}}{\sum_{k=1}^{K} \mu_{jk} y_{ik}^{\bar{i}'}}.$$

$$(46)$$

The index sets $\bar{I}_{u,v}$ and $\bar{I}_{x,y}$ are updated as $\bar{I}_{u,v} \cup \{\bar{i}'\}$ and $\bar{I}_{x,y} \cup \{\bar{i}'\}$, respectively, as the algorithm proceeds through the iterations.

3.1.2. The heuristic: finding a feasible solution

The first subproblem (SP_{MTS}) provides the location of plants (u_m) and the flow of semi-finished products into the DCs (v_{jmn}) , whereas the second subproblem (SP_{MTO}) provides the location and the capacity decisions of the DCs (y_{jk}) , the assignment of customers to DCs (x_{ij}) . Note that the link between the two subproblems is the flow balance of products in and out of DCs. Hence, a feasible solution to problem (P_{ATO}) can be constructed by solving (SP_{MTS}) with the additional set of constraints $\sum_{m=1}^{M} v_{jmn} = \sum_{i=1}^{I} \eta_n \lambda_i \overline{\chi}_{ij}$, where $\overline{\chi}_{ij}$ is obtained from the solution of (SP_{MTO}). The overall procedure is shown in Fig. 4. Computational results are provided next.

4. Computational results and insights

In this section, we report our computational experiences with the proposed solution methodologies and present some insights. All the proposed solution procedures were coded in C and the MIP problems were solved using ILOG CPLEX 10.1 (using the Callable Library) on a Sun Blade 2500 workstation with 1.6-GHz UltraSPARC IIIi processors. In the implementation of the iterative cutting plane algorithm and after the solution of the relaxed MIP, we use the procedure CPXaddrows() to append the cuts generated and exploit warm starting.

4.1. Test problems

The test problems are derived from the 2000 census data consisting of 150 largest cities in the continental United States (see Daskin (2004)). We generate nine sets of test problems by setting the number of customers (I) to the 50, 100 and 150 largest cities, and the potential DC locations (J) to the five, ten and 20 most populated cities. The mean customer demand rates λ_i are obtained by dividing the population of those cities by 10^3 . The unit transportation costs c_{ij} are obtained by dividing the great-circle distance between the customer i and the potential DC location j by 100. The service rate of DC j equipped with capacity level k, is set to $\mu_{jk} = \beta_k \sum_i \lambda_i$ (where $\beta_k = 0.15$, 0.20, 0.45 for I = 50; $\beta_k = 0.10$, 0.20, 0.30 for I = 100; $\beta_k = 0.10$, 0.15, 0.20, 0.30, 0.45 for I = 150). The fixed costs, f_{jk} are set to $100 \times \sqrt{\mu_{ik}}$ to

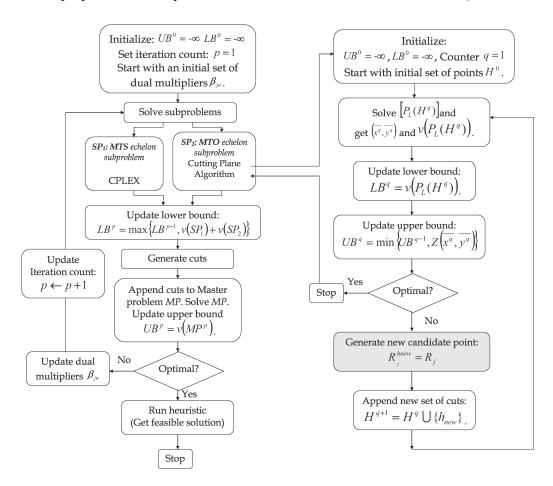


Fig. 4. Solution procedure for two-echelon ATO supply chain design.

reflect economies of scale. For the M/M/1 case, the variance of service times σ_{jk}^2 are set to the mean service rates, μ_{jk} whereas for the M/G/1, the σ_{jk}^2 is obtained by setting coefficient of variation (CV) to 1.5. The average response time cost t is set to $\theta \times (\sum_i \sum_j (\lambda_i c_{ij})/(I \times J))$, where θ is the response time cost multiplier and $\lambda_i c_{ij}$ denotes the total production and transportation cost associated with the order from the ith customer served by the jth DC. In order to explore the sensitivity of the solution to different levels of response time costs, the multiplier θ is tested for 0.1, 1, 5, 10, 50, 100 and 200 (higher value of θ models the situation in which losing a customer order due to high expected waiting time is extremely costly). For the ATO supply chains, the instances are generated by setting the capacities of plants to: $P_m = U[0.1, 0.5] \times \sum_{i=1}^{J} \lambda_i$ whereas their fixed cost are set to: $g_m = U[1000, 2000] \times \sqrt{(P_m)}$. In order to compare the performance of the cutting plane method and the Lagrangean heuristic for different values of the ratio of plant capacities to total demand (r), the instances are generated by setting the capacities of plants to: $P_m = (r \times \sum_{i=1}^{I} \lambda_i)/M$ and the fixed costs to: $g_m = U[100, 110] \times \sqrt{(P_m)}$. The production coefficients (bill of materials) η_n were randomly generated in the range U[1, 5] and rounded up to the nearest integer value.

4.2. An illustrative case study

Using the first set of test problems (where I = 50, J = 5 and K = 3), we illustrate that the MTO supply chain configuration that considers congestion and its effect on response time can be different from the configuration that ignores congestion. Furthermore, we show empirically that substantial reduction in response times can be achieved with minimal increase in total costs in the design of responsive supply chains.

The first set of test problems consists of 50 customers, five potential DC locations (j = 1, New York, NY; j = 2, Los Angeles, CA; j = 3, Chicago, IL; j = 4, Houston, TX; j = 5, Philadelphia, PA) that can be equipped with three capacity levels (k = 1, small; k = 2, medium; k = 3, large). The problem is solved to optimality (with a gap of 10^{-6}) using the cutting plane algorithm. Table 1 summarizes the results for different values of the response time cost by setting θ to 0, 0.1, 1, 10, 100 and 1000 under four different cases: M/G/1 case with CV = 1.5, M/M/1 case, M/G/1 case with CV = 0.5, and M/D/1 case. The table shows the total objective function value (TC), fixed cost (FC), variable cost (VC), total response time cost (RC), total expected waiting time (E(W)), average DC utilization $(\bar{\rho})$, DCs opened and their capacity levels (Open DCs (y_{ik})), expected waiting time at the DCs (W_i) , DC utilization (ρ_i) , the number of cuts generated (CUT), the number of iterations required (ITR) and the CPU time in seconds (CPU(s)) under different scenarios. The supply chain network configuration for two extreme values of response time cost ($\theta = 0$ versus $\theta = 1000$) are shown in Fig. 5. Figure 6(a) shows the effect of changing response time cost on the total expected waiting time (E(W)), and Fig. 6(b) shows the effect of changing the total expected waiting time E(W) on the sum of the fixed and transportation costs. The observations are as follows.

- Figure 5 shows that the supply chain configuration that ignores congestion opens four DCs (medium size DCs in New York, Los Angeles and Chicago and a small DC in Houston) whereas the configuration that considers congestion opens five DCs, all with capacity level 3. Also, there is substantial reallocation of customer demand among the DCs in order to balance the workload to reduce the DC utilization and overall response time in the system. Hence, the supply chain configuration that considers congestion and its effect on response time can be different from the traditional configuration that ignores congestion. However, we observe that at very high values of θ, the configurations (location, capacity and demand allocations) are not significantly different among the M/G/1, M/M/1 and M/D/1 cases.
- 2. As we see from Table 1, even with very small values of average response time cost, $t = 0.1 \times \text{mean}_{i,i}(\lambda_i c_{ij})$ or $t = 1 \times \text{mean}_{i,i}(\lambda_i c_{ii})$, substantial improvement in the total expected waiting time (E[W]) can be achieved over t = 0. For example, for the M/G/1 case (CV =1.5), E[W] decreases from 77.41 units to 48.37 units for $\theta = 0.1$ and 1 respectively. This is due to the even distribution of demand among DCs. Figure 6(a) also shows that the substantial reduction in response time can be achieved with a small value of the response time costs. This is because, as we increase the magnitude of the response time cost, DCs with higher capacity are used and/or the number of DCs opened increases, average DC utilization decreases, thereby reducing congestion and improving average response time. From Fig. 6(b), we see that the left portion of the curves are quite flat, indicating that substantial improvement (decrease) in response time can be achieved with a small increase in fixed and transportation costs.
- 3. As the response time cost becomes dominant compared to other cost components, DCs with higher capacity levels are opened, and average DC utilization decreases, thereby improving (decreasing) the response time. For example, in Table 1, in the M/G/1 case (CV=1.5), for $\theta=1$, four medium size DCs are opened, whereas for $\theta=1000$, five large size DCs are opened. The average DC utilization decreases from 0.83 to 0.44 and the expected waiting time decreases from 48.37 to 5.44.
- 4. As we increase the magnitude of the response time cost, the transportation cost decreases initially and then increases. For example, in Table 1, in the M/G/1 case (CV = 1.5), for $\theta = 0$, TC = 103, 577; for $\theta = 1$, TC = 101, 849; and for $\theta = 1000$, TC = 106, 029. This is due to the reallocation of customer demand among DCs in an attempt to reduce the total expected waiting time.

Table 1. Comparison of the MTO supply chain network configurations for M/G/1, M/M/1 and M/D/1 cases: an illustrative example

		M/G/1 (CV = 1.5)	M/M/1 ($CV = 1$)	M/G/1 (CV = 0.5)	M/D/1 (CV = 0)
$\theta = 0$	TC	146, 965	146, 965	146, 965	146, 965
	FC	43, 388	43, 388	43, 388	43, 388
	VC	103, 577	103, 577	103, 577	103, 577
	RC	0	0	0	0
	E(W)	∞	∞	∞	∞
	$ar{ ho}$	0.96	0.96	0.96	0.96
	Open DCs	1(2), 2(2), 3(2), 4(1)	1(2), 2(2), 3(2), 4(1)	1(2), 2(2), 3(2), 4(1)	1(2), 2(2), 3(2), 4(1)
	W_j	$[138.79, \infty, 5.27, \infty]$			
	$ ho_j$	[0.99, 1.00, 0.84, 1.00]	[0.99, 1.00, 0.84, 1.00]	[0.99, 1.00, 0.84, 1.00]	[0.99, 1.00, 0.84, 1.00]
	ČUT	0	0	0	0
	ITR	1	1	1	1
	CPU(s)	0.14	0.14	0.14	0.14
$\theta = 0.1$	TC	148, 567	148, 333	148, 042	146, 724
	FC	46, 816	43, 388	43, 388	43, 388
	VC	101, 494	104, 235	104, 093	104, 033
	RC	257	710	560	503
	E(W)	77.41	214.05	169.00	152.40
	$\bar{\rho}$	0.83	0.96	0.96	0.96
	Open DCs	1(2), 2(2), 3(2), 4(2)	1(2), 2(2), 3(2), 4(1)	1(2), 2(2), 3(2), 4(1)	1(2), 2(2), 3(2), 4(1)
	W_j	[10.09, 33.51, 2.49, 2.83]	[33.93, 98.34, 7.24, 74.55]	[42.56, 124.89, 6.66, 94.06]	[48.12, 139.37, 6.43, 107.05]
		[0.99, 0.97, 0.71, 0.74]	[0.97, 0.99, 0.88, 0.99]	[0.98, 0.99, 0.87, 0.99]	[0.98, 0.99, 0.87, 0.99]
	$ ho_j \ ext{CUT}$	4	20	20	20
	ITR	2	6	6	6
	CPU(s)	0.35	0.88	1.69	0.9
$\theta = 1$	TC			149, 286	149, 139
$\theta = 1$	FC	150, 269	149, 683	,	,
		46, 816	46, 816	46, 816	46, 816
	VC	101, 849	101, 744	101, 649	101, 609
	RC	1604	1,124	822	714
	E(W)	48.37	33.9	24.79	21.55
	$\bar{\rho}$	0.83	0.83	0.83	0.83
	Open DCs	1(2), 2(2), 3(2), 4(2)	1(2), 2(2), 3(2), 4(2)	1(2), 2(2), 3(2), 4(2)	1(2), 2(2), 3(2), 4(2)
	W_j	[10.09, 15.08, 2.49, 3.39]	[10.09, 18.11, 2.49, 3.21]	[10.09, 22.02, 2.49, 3.06]	[10.09, 24.19, 2.49, 3.00]
	$ ho_j$	[0.91, 0.94, 0.71, 0.77]	[0.91, 0.95, 0.71, 0.76]	[0.91, 0.96, 0.71, 0.75]	[0.91, 0.96, 0.71, 0.75]
	CUT	4	8	16	12
	ITR	2	3	5	4
	CPU(s)	0.33	0.41	0.91	0.45
$\theta = 10$	TC	157, 274	155, 674	154, 324	153, 874
	FC	52, 078	49, 447	49, 447	49, 447
	VC	101, 407	101, 640	101, 638	101, 616
	RC	3789	4,587	3,240	2811
	E(W)	11.43	13.84	9.77	8.48
	$ar{ ho}$	0.67	0.75	0.75	0.75
	Open DCs	1(3), 2(3), 3(2), 4(2)	1(2), 2(3), 3(2), 4(2)	1(2), 2(3), 3(2), 4(2)	1(2), 2(3), 3(2), 4(2)
	W_{j}	[1.75, 2.27, 2.10, 1.94]	[6.63, 2.27, 2.54, 2.39]	[6.63, 2.27, 2.58, 2.36]	[6.78, 2.27, 2.65, 2.28]
	$ ho_j$	[0.64, 0.69, 0.68, 0.66]	[0.87, 0.69, 0.72, 0.71]	[0.87, 0.69, 0.72, 0.70]	[0.87, 0.69, 0.73, 0.69]
	CUT	12	12	8	12
	ITR	4	4	3	4
	CPU(s)	0.65	0.62	0.49	0.60
$\theta = 100$	TC	182, 451	176, 255	172, 486	170, 940
	FC	57, 340	57, 340	57, 340	54, 709
	VC	101, 987	101, 494	101, 494	101, 557
	RC	23, 124	17, 421	13, 650	14, 675
	E(W)	6.98	5.26	4.12	4.43
	$ar{ ho}$	0.56	0.56	0.56	0.61
	Open DCs	1(3), 2(3), 3(3), 4(3)	1(3), 2(3), 3(3), 4(3)	1(3), 2(3), 3(3), 4(3)	1(3), 2(3), 3(3), 4(2)
	W_{i}	[1.45, 1.68, 0.96, 1.05]	[1.54, 1.84, 0.91, 0.97]	[1.54, 1.84, 0.91, 0.97]	[1.75, 2.15, 1.00, 1.54]
	$ ho_j$	[0.59, 0.63, 0.49, 0.51]	[0.61, 0.65, 0.48, 0.49]	[0.61, 0.65, 0.48, 0.49]	[0.64, 0.68, 0.50, 0.61]
	CUT	16	4	4	16
		5	2	2	5
	111				
	ITR CPU(s)	0.77	0.26	0.35	0.93

Table 1. Comparison of the MTO supply chain network configurations for M/G/1, M/M/1 and M/D/1 cases: an illustrative example (*Continued*)

		M/G/1 (CV = 1.5)	M/M/1 ($CV = 1$)	$M/G/1 \ (CV = 0.5)$	M/D/1 ($CV = 0$)
$\theta = 1000$	TC	358, 156	316, 316	289, 863	280, 873
	FC	71, 675	71, 675	71, 675	71, 675
	VC	106, 029	102, 974	99, 683	99, 460
	RC	180, 453	141, 666	118, 506	109, 738
	E(W)	5.44	4.27	3.57	3.31
	$ar{ ho}$	0.44	0.44	0.44	0.44
	Open DCs	1(3), 2(3), 3(3), 4(3), 5(3)	1(3), 2(3), 3(3), 4(3), 5(3)	1(3), 2(3), 3(3), 4(3), 5(3)	1(3), 2(3), 3(3), 4(3), 5(3)
	W_i	[0.64, 1.39, 0.78, 0.84, 0.55]	[0.66, 1.51, 0.77, 0.83, 0.50]		
	$ ho_i$	[0.39, 0.58, 0.44, 0.46, 0.35]	[0.40, 0.60, 0.44, 0.45, 0.34]	[0.40, 0.63, 0.43, 0.46, 0.30]	[0.42, 0.63, 0.43, 0.46, 0.29]
	ČUT	35	35	25	10
	ITR	8	8	6	3
	CPU(s)	1.66	1.45	1.2	0.39

4.3. Performance of the cutting plane method for MTO supply chain design

Table 2 displays the performance of the cutting plane method for MTO supply chain design problems under M/G/1 (CV = 1.5), M/M/1 (CV = 1.0) and M/D/1

(CV=0) cases for varying problem sizes. The columns marked FC, VC and RC represent the fixed costs, the variable production and transportation, and the response time costs respectively, expressed as a percentage of total costs (TC). The columns marked E(W) are the total average waiting time in the system, $\overline{\rho}$ is the average DC utilization and

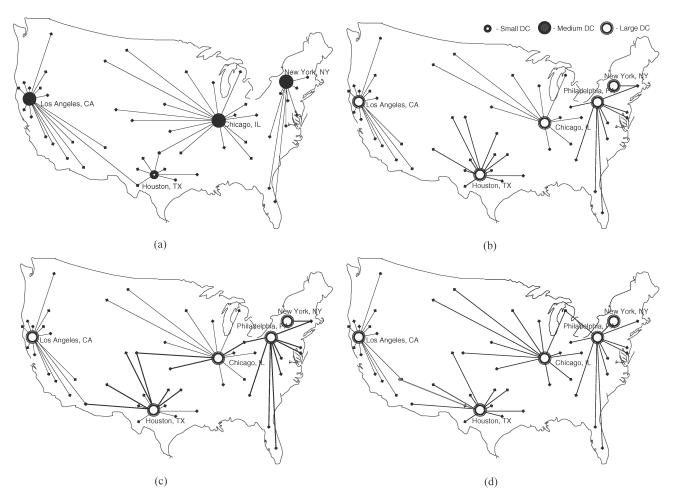


Fig. 5. Effect of changing response time cost on the supply chain network configuration: (a) $\theta = 0$; (b) the M/D/1 case, $\theta = 1000$; (c) the M/M/1 case, $\theta = 1000$; and (d) the M/G/1 case (CV = 1.5), $\theta = 1000$.

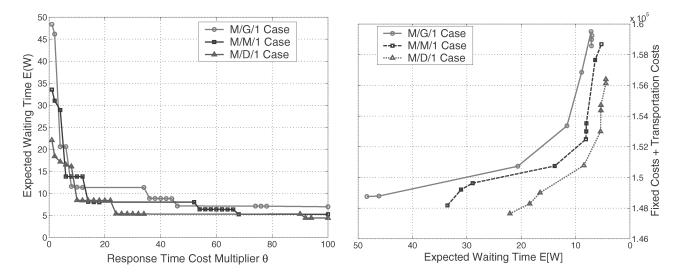


Fig. 6. (a) Effect of changing response time cost (t) on the total expected waiting time E[W]; and (b) effect of changing expected waiting time E[W] on the fixed costs plus the transportation costs.

DC represents the number of DCs opened. The table also displays the number of constraints generated (CUT), the number of iterations of the algorithm (ITR) and the total CPU time in seconds required to obtain the optimal solution.

The results show that the average CPU time for M/G/1, M/M/1 and M/D/1 cases are 48, 21 and 9 seconds respectively, whereas the average number of cuts required are 26, 25 and 25 respectively. Also, the maximum CPU time for M/G/1, M/M/1 and M/D/1 cases are 1147, 410 and 107 seconds respectively, whereas the maximum number of cuts required are 66, 60 and 50 respectively. The computation times reveal the stability and the efficiency of the cutting plane algorithm for different percentages of fixed, variable and response time costs, whereas the number of iterations imply that only a fraction of the constraints in $(P_L(H))$ is required. As the magnitude of response time cost (t) increases, the percentage of response time cost becomes more significant with respect to other cost components and the algorithm seems to require more CPU time and iterations as large number of cuts are generated. Furthermore, in almost all of the instances, the M/G/1 case requires more cuts, and hence more CPU time to solve than the M/M/1 and M/D/1 cases. This is attributed to the non-linearity in the expression of expected waiting time for M/G/1 queues. It is also worthwhile noting that the computational times for the second set of instances (I = 50, J = 20 and K = 3) are comparatively higher than others because the optimal solution has highly congested DCs. In the model, this corresponds to the value of R/(1+R) approaching one. At the flat portion of R/(1+R), a higher number of cuts is needed to close the gap.

4.4. Performance of the Lagrangean heuristic for ATO supply chain design

The computational performance of the Lagrangean heuristic for the two-echelon ATO supply chain model for the M/G/1, M/M/1 and M/D/1 cases is shown in Table 3. The second subproblem pertaining to the MTO echelon was solved to optimality using the cutting plane approach. In all these test problems, the heuristic is activated at the final iteration of the Lagrangean procedure. The Lagrangean bound (LAG-H) is expressed as the percentage of heuristic solution and the quality of the heuristic solution (GAP) is expressed as: $100 \times (Heuristic Solution - LAG-H)/LAG-H$. The table shows the computational time of the subproblems (SP), the master problem (MP) and the heuristic (H) expressed as a percentage of the total computational time (CPU) for various single (L=1) and multiple (L=3 and 5)product instances. From these results, it is evident that the proposed heuristic succeeds in finding feasible solutions that are within an average of 2.81, 2.58 and 2.99% of the Lagrangean bound in reasonable computational time: 427, 390 and 345 seconds for the M/G/1, M/M/1 and M/D/1cases respectively. The total computational time can be as high as 1038 seconds in some cases. In terms of the size of the test problems, the heuristic is able to solve problems with up to 35 plants, 20 DCs and 150 customers, five products, five capacity levels and five semi-finished products within a maximum of a 6% gap from the optimal solution. Table 4 shows that the solution of subproblem 2 accounts for most of the computational time, 89.08, 89.50 and 89.93% for M/G/1, M/M/1 and M/D/1 cases respectively. The master problem accounts for 9.87, 9.36 and 9.03%, whereas the

Table 2. Computational performance of the cutting plane method: MTO supply chain design

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as:	, <u>d</u>	٦,	0.93	0.85	.85	0.70	0.92	0.91	78.	98.	.74	.71	0.83	.83	25.0	57.	0.0	0.93	98.	0.85	77.	77.	0.70	7.4	7.74	0.05	65	0.65	16.0	0.91	0.91	0.75	0.67	0.93	88.	0.84	.83	8.(9.6	0.89	98.0	20.0).81).81	.61	0.93	?
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Table 3. Computational performance of the Lagrangean heuristic: ATO supply chain design

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	CPU(s)	99	62	6 i	7.2	C / 7	131	147	148	155	158	162	150	159	159	161	165	165	197 105	202	202	210	215	251	268	269	271	277	278	423	424	451	484	485	288	579 515	624	627	632	765	800	810	871	890	¥0.4	904	345
	$_{(\%)}^{H}$	0.75	0.60	2.01	1.62	1.65	0 97	1.77	0.52	1.65	2.01	0.64	1.82	0.55	1.61	0.78	0.12	1.68	0.46	1.30	1.01	1 30	1.67	1.99	1.46	0.68	1.83	1.19	0.24	0.81	1.20	0.56	0.70	1.16	0.37	0.00	1.2	0.06	0.55	0.77	1.65	0.65	0.07	0.08	1. /4 0. 0	2.01	1.04
ase	MP (%)	6.29	8.06	5.94	10.90	7.03	5.75	6.36	5.39	11.58	6.97	6.03	12.09	11.27	11.50	12.72	11.86	12.94	8.25	5 00	2.00	12.00	6.52	5.79	5.43	11.10	12.13	12.00	8.60	6.98	2.55	9.11	7.71	10.55	6.09	9.10	10.47	12.88	96.9	5.13	12.40	6.46	13.03	9.60	6.17	13.03	9.03
M/D/I	<i>SP</i> (%)	2.96	1.34	2.05	8.43	6.36 0.91	3.50	1.87	4.09	6.77	1.02	3.33	60.9	8.18	68.9	6.5	8.02	5.38	1.29	0.72	7.87	5.71	1.81	2.22	3.11	8.22	6.04	6.81	1.16	2.21	3.19 7.81	0.33	1.59	8.29	3.54	9.74	× × ×	7.06	2.49	4.1	5.95	2.89	6.9	0.32	2.09	94.10	9.93
M	GAP : (%)		•								•															••			•	•			•	••							••					5.88	-
	_																																														
	LAG-H $(%)$	98.3	94.5	8.86	200	0.00	0.00	94.7	95.9	99.7	97.7	97.0	98.5	95.3	95.0	8.66	98.8	94.9	95.4	24.7	000	06.6	94.8	95.4	98.6	966	94.9	94.1	96.1	95.0	0.00	99.1	97.2	94.2	94.9	90.4	95.7	99.9	97.4	95.0	95.9	98.3	94.3	99.9	799.7 1.40	99.94	97.0
	CPU(s)	85	82	98	8 2 2	101	176	179	181	185	186	189	168	169	171	176	180	175	217	612 CCC	222	227	234	283	285	285	286	289	293	486	499 513	536	54	547	645	691	769	869	200	922	935	945	955	972	9/6 85	976	390
	H	1.19	1.83	1.68	1.33	1.40	1.20	0.54		98.0	0.36	90.0	89.0	9.4	1.96	1.91	1.33	1.02	0.7	1 46	0.55	0.50	1.26	1.85	0.28	1.75	1.42	0.78	0.23	1.13	1.89	1.55	0.56	1.83	1.29	7 1 65	0.79	0.75	1.41	1.17	1.57	1.4	0.22	0.86	1.6/	2.00	1.14
ase	MP $(%)$	12.75	12.96	12.19	0.03	20.07	12.71	8.29	6.14	8.59	12.46	7.59	10.14	6.7	10.9	5.43	6.42	10.35	11.95	7.29	17.07	12.74	7.79	10.92	7.57	10.71	9.11	11.79	7.55	12.26	0 10	11.68	7.38	5.44	9.53	8 64	7.61	11.34	7.14	11.25	7.21	10.64	7.83	9.18	9.49 5.43	12.96	9.36
M/M/I	<i>SP</i> (%)	90.98	35.21	36.13	75.14	59.7 31.73	25.09	91.17	12.56	90.55	87.18)2.35	39.18	92.9	37.14	95.66)2.25	88.63	87.35	72.1	26.50	10.00	90.95	37.23	92.15	37.54	39.47	37.43)2.22	36.61	50.2 30.43	86.77	95.06)2.73	39.18 30.00	29 71	91.6	37.91	91.45	37.58	91.22	37.96	91.95	39.96	88.84 25.01	93.14	39.50
V	GAP (%)																																													5.99	
			_	_	•					_	_	•		_			_	_		•							- '			_				_	_					•	_		_			94.01 5	
	LAG-H	96	66	6 8	8 2	5	8	6	66	66	66	95	86	66	4	96	66	66	2 8	2 8	96	80	97	86	4	76	97	86	96	8 3	7, %	86	96	66	8 8	66.0	8 8	8	96	95	66	96	66	2,5	¥ 8	, 8	97
	CPU(s)	108	111	118	121	127	191	192	199	209	211	213	182	185	187	190	194	196	238	200	780	206	298	297	298	300	309	313	348	551	505	593	599	617	715	726	741	743	747	981	1000	1004	1007	1019	1038	1038	427
.5)	H	1.33	1.94	1.39	7.07	5.0	0.00	2.22	1.74	0.59	0.17	0.58	0.54	0.16	0.57	0.95	0.25	1.33	0.18	24.1	0.00	2.1	1.28	2.05	1.19	1.41	0.85	1.53	1.26	0.94	0.30	1.18	0.53	0.51	0.32	0.07	1.85	1.60	1.41	1.12	1.56	0.93	1.52	1.83	0.61	2.05	1.05
CV = I	MP $(%)$	14.36	13.51	11.51	14.98	0.04	11.17	13.15	13.04	10.73	5.17	6.67	5.68	14.39	12.64	5.83	6.64	5.06	8.09	07.0	7.29	7.41	13.22	12.14	5.91	11.13	7.47	12.88	9.64	9.93	13.90	90.6	13.66	12.07	9.29	5.32	7.57	99.9	7.15	86.9	8.58	5.87	14.16	12.35	14.67	14.98	9.87
case (<i>SP</i> (%)	4.31	4.55	7.1	5 1 57	2 2 2 2	7.85	5.03	5.22	8.68	4.66	9.75	3.78	5.45	6.79	3.22	3.11	3.61	1.73	0.51	0.03	117	5.5	5.81	2.9	7.46	1.68	5.59	9.1	9.13	2.04 2.04	9.76	5.81	7.42	0.39	1.5 4.55	47.0	1.74	1.44	1.9	98.6	3.2	4.32	5.82	4.72 200	94.66	80.6
M/G/I	$\begin{array}{cc} GAP & \Omega \\ (\%) & (\%) \end{array}$																																													5.94	
Ì	· ·																																														
	LAG-H (%)	66.	95.8	94.77	28.0	90.0	9.76	86	66	97.89	94.0	94.65	99.6	96.5	97.2	97.41	89.68	95.64	94.47	2.00	0.00	07 70	95.6	98.97	97.6	95.8	95.55	99.1	95.4	98.6	98.55	3.66	99.(8.66	99.23	95.7	97.1	95.2	98.1	98.31	89.96	95.12	95.7	98.64	4 7. 4 7. 5	99.97	97.1
	θ	0.1	-	ς,	10	100	0		· v	10	50	100	1	S	10	20	100	200	_ '	ر د	0.0	8 0	200	<u> </u>	S	10	50	100	200		o 5	50	100	200	- '	ر د	50	100	200	-	5	10	50	100	200	max	mean
	N	3					")					5						S					5						S					S					5							
	M	10					10	2					20					;	20					20					;	35					35					35							
	T	-					_	-					ε						\mathcal{C}					ж						S					S					5							
	K	3					'n	,					т						\mathcal{C}					æ						S					S					S							
	ſ	10					20	1					S					,	10					20						S					10					50							
	I	20					50	2					100						100					100					,	150					150					150							
	No.						C	1					3						4					S					,	9					7					∞							

Table 4. Comparison between the cutting plane method and the Lagrangean heuristic for ATO supply chain design for I = 100, J = 10, K = 3, M = 20 and N = 1

				Cutting	ing plane method	nethod							Lagran	Lagrangean heuristic	uristic			
θ	FC (%)	%) %C	RC (%)	E(W)	ō	DCs	CUT	ITR	$CPU \\ (s)$	FC (%)	VC (%)	RC (%)	E(W)	φ	DCs	LR (%)	$\begin{array}{c} GAP \\ (\%) \end{array}$	$CPU \\ (s)$
Tight capacities, $r = 3$																		
0.1	50	50	0	689.3		5	10	В	714	41	59	0	689.3	96.0	5	95.88	4.12	251
1	49	20	1	209.2		2	10	т	1029	41	59	1	218.2	96.0	5	82.96	3.22	268
5	48	20	2	169.3	0.95	5	10	ю	1585	43	57	_	195.9	0.94	S	95.04	4.96	569
10	51	49	-	32.5		5	10	ю	2180	42	99	7	51.84	92.0	5	95.81	4.19	271
50	51	47	7	14.51		5	5	7	1002	44	55	7	17.47	0.62	5	96.72	3.28	177
100	51	47	7	8.39		2	5	7	810	43	54	т	11.47	9.0	5	94.99	5.01	278
500	50	46	4	8.39		5	S	7	964	43	49	∞	10.82	0.65	S	96.4	3.6	423
1000	49	4	7	6.21		5	S	7	1100	40	46	14	9.82	0.44	S	88.96	3.12	427
2000	46	4	13	5.99		5	5	7	1148	39	41	21	4.75	0.43	9	97.11	2.89	444
5000	38	32	30	3.95		7	28	5	1699	33	33	34	3.98	0.32	7	97.01	2.99	451
Moderate capacities, $r = 5$																		
0.1	46	54	0	261.9	0.84	9	12	ю	1500	39	61	0	332.3	_	4	98.11	1.89	205
1	46	54	0	98.12	0.83	9	9	7	964	39	61	0	122.7	0.84	4	96.83	3.17	407
5	41	58	-	34.16	0.83	4	4	7	1019	38	61	1	40.72	_	4	69.96	3.31	325
10	41	58	1	34.16	0.83	4	4	7	868	38	61	1	40.72	_	4	95.52	4.48	280
50	41	99	4	21.84	0.76	4	4	7	1467	39	58	8	27.56	_	4	97.27	2.73	322
100	43	55	7	6.81	0.56	4	4	7	1495	40	57	7	7.74	_	4	97.11	2.89	333
500	42	54	4	6.81	0.56	4	4	7	1122	37	53	10	7.74	_	4	88.96	3.12	365
1000	40	20	10	6.81	0.56	4	4	7	1370	34	48	18	7.74	_	4	94.01	5.99	291
2000	41	4	15	5.52	0.44	2	10	ю	2524	40	38	22	6.63	_	9	92.6	4.4	589
5000	30	53	41	4.55	0.37	9	12	ю	1981	30	29	40	6.53	_	9	29.67	2.33	232
Loose capacities, $r = 10$																		
0.1	40	9	0	81.01	0.83	4	4	7	1103	40	09	0	81.66	0.83	4	96.57	3.43	546
1	40	9	0	62.75	0.83	4	4	7	955	39	09	0	63.85	0.83	4	96.65	3.35	435
5	40	9	1	40.27	0.83	4	4	7	906	39	09	_	42.23	0.83	4	98.91	1.09	487
10	39	59	_	40.27	0.83	4	4	7	875	39	09	-	41.78	0.83	4	94.41	5.59	327
50	40	28	7	11.71	0.67	4	4	7	626	40	28	7	12.97	0.67	4	96.19	3.81	354
100	40	99	4	11.71	0.67	4	4	7	1140	40	27	3	11.75	0.61	4	66.96	3.01	654
500	41	55	5	7.02	0.56	4	4	7	1080	38	52	11	8.96	0.56	4	97.27	2.73	765
1000	38	52	10	6.94	0.56	4	∞	ю	1765	34	47	19	7.84	0.56	4	98.1	1.9	642
2000	34	47	19	6.85	0.56	4	∞	ю	1884	41	38	21	7.54	0.37	9	95.59	4.41	822
5000	32	59	39	4.43	0.37	9	12	ю	2148	31	59	39	4.43	0.37	9	96.37	3.63	984
Min	30	53	0	3.95	0.32	4	4	7	714	30	29	0	3.98	0.32	4	94.01	1.09	177
Max	51	99	41	689.3	96.0	7	28	S	2524	44	61	40	689.3	96.0	7	98.91	5.99	984
Mean	43	20	7	63.38	99.0	2	7	7	1314	39	52	6	64	0.64	5	97.51	3.49	421

heuristic accounts for 1.05, 1.14 and 1.04%, on average for M/G/1, M/M/1 and M/D/1 cases respectively.

In Table 4, we compare the performance of the cutting plane algorithm and the Lagrangean heuristic and report the results for one problem set (I=100, J=10, K=3, M=20 and N=1) for different values of the ratio of plant capacities to total demand $(r=\sum_m P_m/\sum_i \lambda_i)$. The results show that the Lagrangean heuristic outperforms the cutting plane method in terms of computational time. On average, the Lagrangean heuristic takes 421 seconds whereas the cutting plane method takes 1344 seconds.

5. Conclusions

In this paper, we modeled and analyzed the effect of response time consideration on the design of MTO and ATO supply chain networks. We presented an MTO supply chain design model that captures the trade-off among response time, the fixed cost of opening DCs and equipping them with sufficient capacity, and the transportation cost associated with serving customers. Under the assumption that the customer demand follows a Poisson process and service times follow general distribution, the DCs were modeled as a network of single-server queues, whose capacity levels and locations are decision variables. We presented a non-linear MIP formulation, a linearization procedure and an exact solution approach based on a cutting plane method. Our computational results indicate that the cutting plane algorithm provides optimal solution for moderate instances of the problem in few iterations and reasonable computation

We also presented a model for designing two-echelon ATO supply chain networks, that consists of plants and DCs serving a set of customers. Lagrangean relaxation was applied to decompose the problem by echelon—one for the MTS echelon and the other for the MTO echelon. While Lagrangean relaxation provides a lower bound, a heuristic is proposed that uses the solution of the subproblems to construct an overall feasible solution. Computational results reveal that the heuristic solution is on average within 6% of its optimal. We used the models to demonstrate empirically that substantial improvement (decrease) in response time can be achieved with a minimal increase in total cost associated with designing supply chains. Also, we showed that the supply chain configuration (DC location and capacity, and allocation of customers to DCs) obtained using the model that considers congestion can be very different from those obtained using the traditional models that ignores response time.

The focus of our ongoing research is to develop models for the design of MTO and ATO supply chains under more general settings: general demand arrivals, general service time distributions and multiple servers. Due to the lack of an exact expression for the waiting time in these settings, we plan to explore two approaches to model the problem. The first approach relies on approximations of expected waiting

times whereas the second approach integrates simulation within an MIP framework.

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