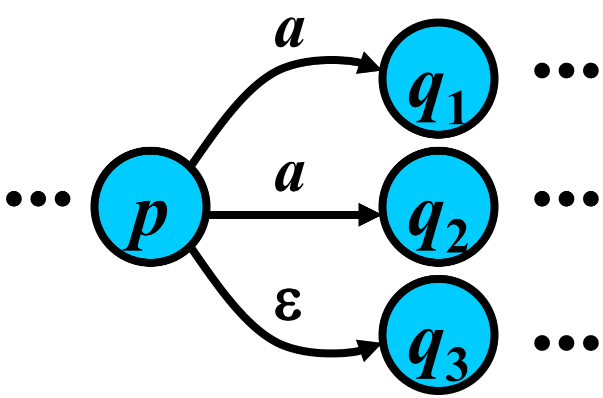
Part IV. Variants of Finite Automata

Theory vs. Practice

a) Configuration: pax



Next Configuration:
q_1x or q_2x or q_3ax ?

Theory: ☺ × Practice: ☹

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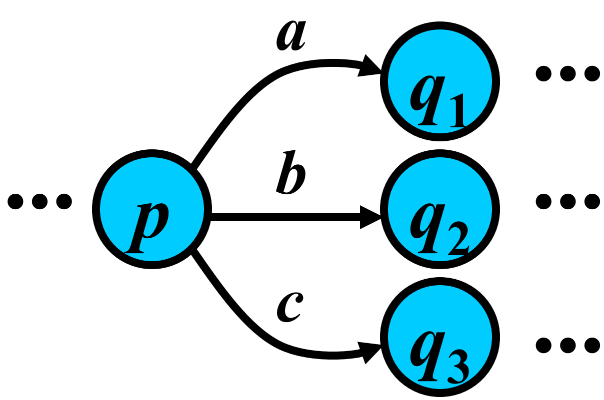
b) Configuration: pax



Next Configuration:
only q_1x

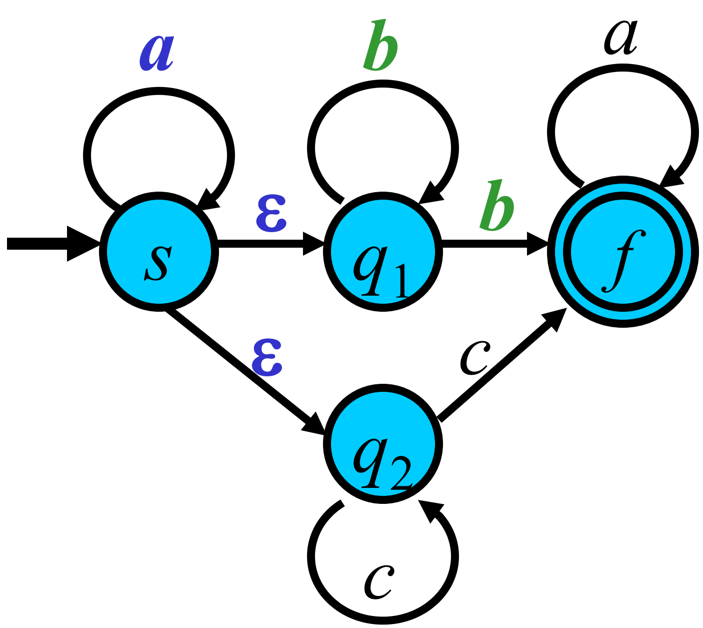
Theory: ☹ × Practice: ☺

Use of FA in General

Simulation of all possible moves from every configuration.

Example:

FA M is defined as:



$sab \begin{cases} \vdash q_1ab \\ \vdash q_2ab \\ \vdash sb \begin{cases} \vdash q_2b \\ \vdash q_1b \begin{cases} \vdash q_1 \\ \vdash f \end{cases} \end{cases} \end{cases}$

No next configuration

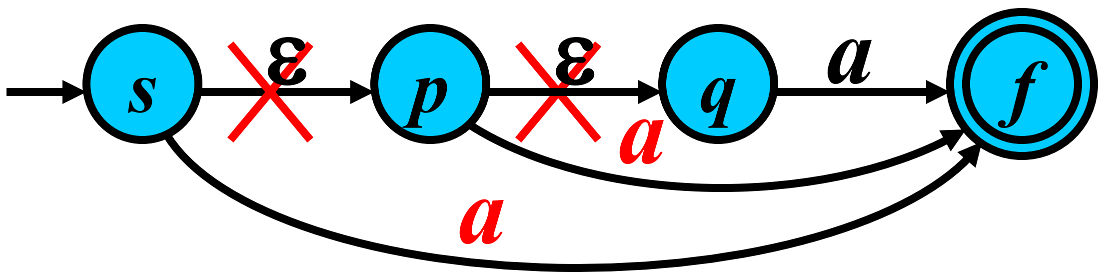
Question: $ab \in L(M)$?

Answer: YES, $ab \in L(M)$ because $f \in F$.

From FA to DFA in Essence 1/2

Preference in practice: *Determinictic FA* (DFA) that makes no more than one move from every configuration.

1) Gist: Removal of ε-moves

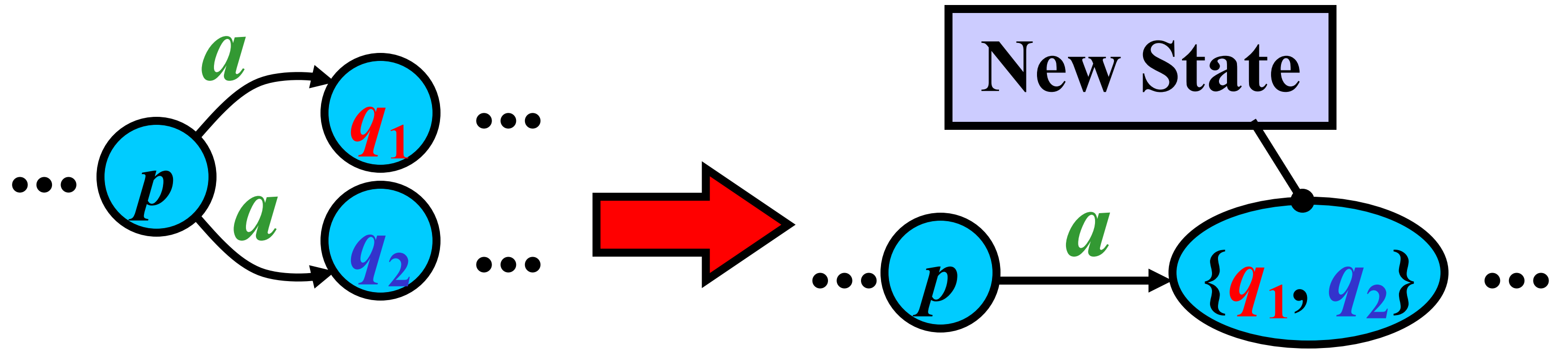


Definition: Let $M = (Q, \Sigma, R, s, F)$ be a FA. M is an ***ε-free finite automaton*** if for all rules $pa \rightarrow q \in R$, where $p, q \in Q$, holds

$$a \in \Sigma \; (a \neq \varepsilon\,)$$

From FA to DFA in Essence 2/2

2) Gist: Removal of nodeterminism



Definition: Let $M = (Q, \Sigma, R, s, F)$ be an **ε-free FA**. M is a ***deterministic finite automaton*** (DFA) if for each rule $pa \rightarrow q \in R$ it holds that $R - \{pa \rightarrow q\}$ contains no rule with the left-hand side equal to pa.

Theorem

- For every FA M, there is an equivalent DFA M_d.

Proof is based on these conversions:

Finite Automaton *M*

↓

ε-free Finite Automaton *M'*

$L(M) = L(M')$

↓

DFA M_d

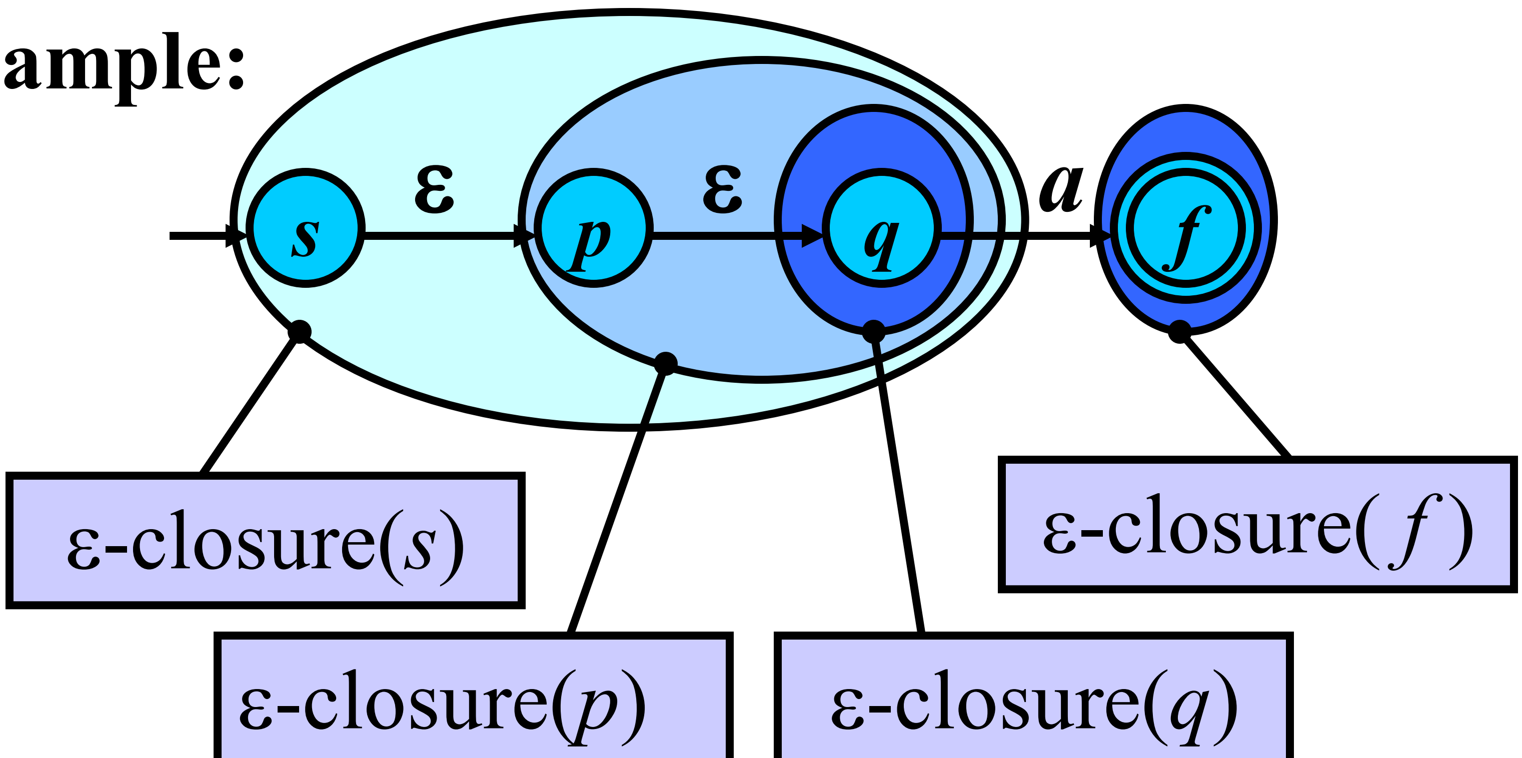
$L(M') = L(M_d)$

ε-closure

Gist: *q* is in ε-closure(*p*) if FA can reach *q* from *p* without reading.

Definition: For every states $p \in Q$, we define a set $\varepsilon\text{-}closure(p)$ as ε-closure(p) = $\{q: q \in Q, p \vdash^* q\}$

Example:



Algorithm: ε-closure

- **Input:** $M = (Q, \Sigma, R, s, F)$; $p \in Q$
- **Output:** ε-closure(p)

- **Method:**
- $i := 0$; $Q_0 := \{p\}$;
- **repeat**

$$i := i + 1;$$

$$Q_i := Q_{i-1} \cup \{\, p' : p' \in Q,\ q \rightarrow p' \in R,\ q \in Q_{i-1} \,\};$$

until $Q_i = Q_{i-1}$;

- ε-closure(p) $:= Q_i$.

ε-closure: Example

$M = (Q, \Sigma, R, s, F)$, where: $Q = \{s, p, q, f\}$, $\Sigma = \{a\}$,
$R = \{s \to p, p \to q, qa \to f\}$, $F = \{f\}$

Task: ε-closure(s)

$Q_0 = \{\mathbf{s}\}$

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1) $s \to p'; p' \in Q$: $s \to p$

$Q_1 = \{\mathbf{s}\} \cup \{\mathbf{p}\} = \{\mathbf{s}, \mathbf{p}\}$

---

2) $s \to p'; p' \in Q$: $s \to p$

$p \to p'; p' \in Q$: $p \to q$

$Q_2 = \{\mathbf{s}, \mathbf{p}\} \cup \{\mathbf{p}, \mathbf{q}\} = \{\mathbf{s}, \mathbf{p}, \mathbf{q}\}$

---

3) $s \to p'; p' \in Q$: $s \to p$

$p \to p'; p' \in Q$: $p \to q$

$q \to p'; p' \in Q$: **none**

$Q_3 = \{\mathbf{s}, \mathbf{p}, \mathbf{q}\} \cup \{\mathbf{p}, \mathbf{q}\} = \{\mathbf{s}, \mathbf{p}, \mathbf{q}\} = Q_2 =$ **ε-closure(s)**

Algorithm: FA to ε-free FA

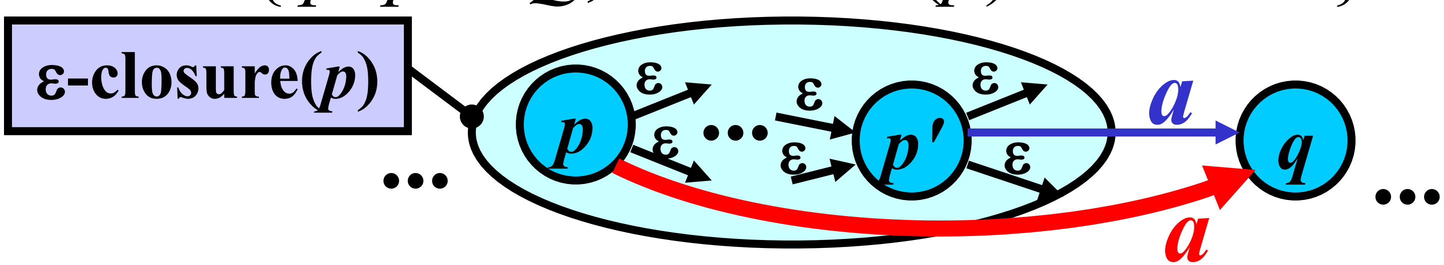
Gist: Skip all ε-moves

- **Input:** FA $M = (Q, \Sigma, R, s, F)$
- **Output:** ε-free FA $M' = (Q, \Sigma, R', s, F')$

- **Method:**
- $R' := \emptyset$;
- **for all** $p \in Q$ **do**

$$R' := R' \cup \{\, pa \to q : p'a \to q \in R,\ a \in \Sigma,\ p' \in \varepsilon\text{-closure}(p),\ q \in Q \,\};$$

- $F' := \{\, p : p \in Q,\ \varepsilon\text{-closure}(p) \cap F \neq \emptyset \,\}$.



FA to ε-free FA: Example 1/3

$M = (Q, \Sigma, R, s, F)$, where:

$Q = \{s, q_1, q_2, f\}$; $\Sigma = \{a, b, c\}$;

$R = \{sa \to s, s \to q_1, q_1b \to q_1, q_1b \to f, s \to q_2,$
$q_2c \to q_2, q_2c \to f, fa \to f\}$; $F = \{f\}$

---

1) for $p = \mathbf{s}$: ε-closure($\mathbf{s}$) = $\{\mathbf{s}, \mathbf{q_1}, \mathbf{q_2}\}$

A. $\mathbf{s}d \to q', d \in \Sigma, q' \in Q$: $\mathbf{sa \to s}$

B. $\mathbf{q_1}d \to q', d \in \Sigma, q' \in Q$: $\mathbf{q_1b \to q_1}, \mathbf{q_1b \to f}$

C. $\mathbf{q_2}d \to q', d \in \Sigma, q' \in Q$: $\mathbf{q_2c \to q_2}, \mathbf{q_2c \to f}$

$R' = \varnothing \cup \{\mathbf{sa \to s}, \mathbf{sb \to q_1}, \mathbf{sb \to f}, \mathbf{sc \to q_2}, \mathbf{sc \to f}\}$

FA to ε-free FA: Example 2/3

2) for $p = q_1$: ε-closure(q_1) = {q_1}

A. $q_1 d \to q'; d \in \Sigma; q' \in Q$: $q_1 b \to q_1, q_1 b \to f$

$R' = R' \cup \{q_1 b \to q_1, q_1 b \to f\}$

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3) for $p = q_2$: ε-closure(q_2) = {q_2}

A. $q_2 d \to q'; d \in \Sigma; q' \in Q$: $q_2 c \to q_2, q_2 c \to f$

$R' = R' \cup \{q_2 c \to q_2, q_2 c \to f\}$

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4) for $p = f$: ε-closure(f) = {f}

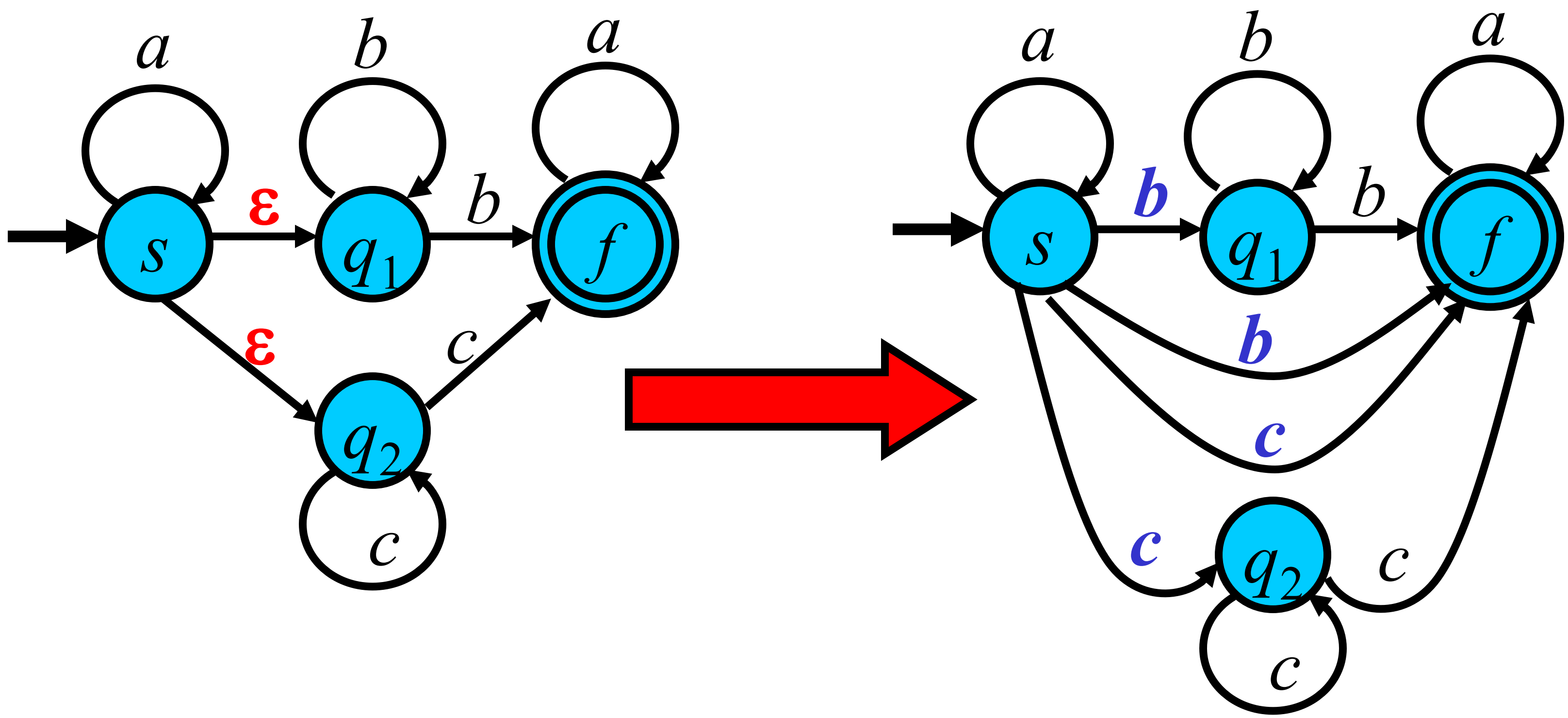
A. $fd \to q'; d \in \Sigma; q' \in Q$: $fa \to f$

$R' = R' \cup \{fa \to f\}$

$R' = \{sa \to s, sb \to q_1, sb \to f, sc \to q_2, sc \to f,$
$q_1 b \to q_1, q_1 b \to f, q_2 c \to q_2, q_2 c \to f, fa \to f\}$

FA to ε-free FA: Example 3/3

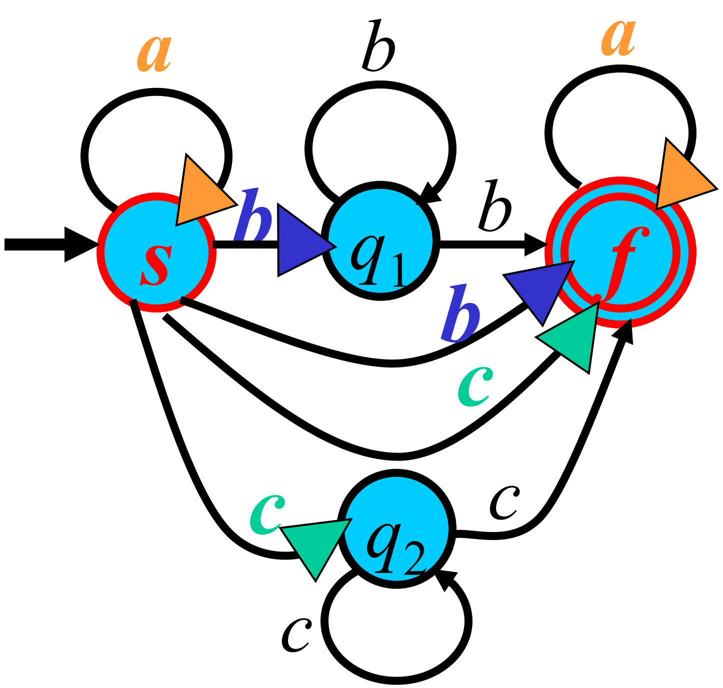
$$\left.\begin{array}{l}
\varepsilon\text{-closure}(s) \cap F = \{s, q_1, q_2\} \cap \{f\} = \emptyset \\
\varepsilon\text{-closure}(q_1) \cap F = \{q_1\} \cap \{f\} = \emptyset \\
\varepsilon\text{-closure}(q_2) \cap F = \{q_2\} \cap \{f\} = \emptyset \\
\varepsilon\text{-closure}(f) \cap F = \{f\} \cap \{f\} = \{f\} \neq \emptyset
\end{array}\right\} \boldsymbol{F'} = \{f\}$$



Algorithm: ε-free FA to DFA 1/2

Gist: In DFA, make states from all subsets of states in ε-free FA and move between them so that all possible states of ε-free FA are simultaneously simulated.

Illustration:

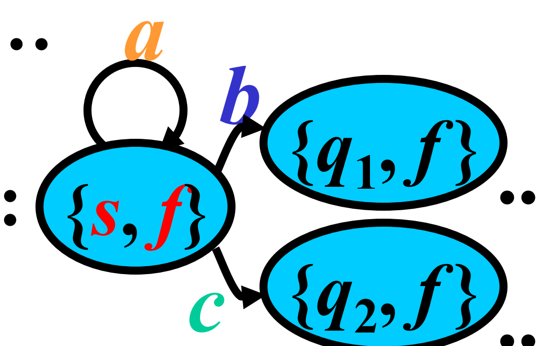


$Q_{DFA} = \{\{s\}, \{q_1\}, \{q_2\}, \{f\}, \{s,q_1\}, \{s,q_2\}, \{s, f\}, \{q_1,q_2\}, \{q_1,f\}, \{q_2,f\}, \{s,q_1,q_2\}, \{s,q_1,f\}, \{s,q_2,f\}, \{q_1,q_2,f\}, \{s,q_1,q_2,f\}\}$

For state $\{s\}$: …

⋮

For state $\{s, f\}$:



⋮

For state $\{s,q_1,q_2,f\}$: …

Algorithm: ε-free FA to DFA 2/2

- **Input:** ε-free FA: $M = (Q, \Sigma, R, s, F)$
- **Output:** DFA: $M_d = (Q_d, \Sigma, R_d, s_d, F_d)$

- **Method:**
- $Q_d := \{Q' : Q' \subseteq Q, Q' \neq \emptyset\}$; $R_d := \emptyset$;
- **for each** $Q' \in Q_d$, **and** $a \in \Sigma$ **do begin**

  $Q'' := \{q : p \in Q', pa \to q \in R\}$;

  if $Q'' \neq \emptyset$ **then** $R_d := R_d \cup \{Q'a \to Q''\}$;

  end
- $s_d := \{s\}$;
- $F_d := \{F' : F' \in Q_d, F' \cap F \neq \emptyset\}$.

ε-free FA to DFA: Example 1/5

$M = (Q, \Sigma, R, s, F)$, where:

$Q = \{s, q_1, q_2, f\}$; $\Sigma = \{a, b, c\}$; $F = \{f\}$

$R = \{sa \to s, sb \to q_1, sb \to f, sc \to q_2, sc \to f,$
$q_1b \to q_1, q_1b \to f, q_2c \to q_2, q_2c \to f, fa \to f\}$;

$Q_d = \{\{s\}, \{s,q_1\}, \{s,q_1,q_2\}, \{s,q_1,f\}, \{s,q_1,q_2,f\}, \{s,q_2\}, \{s,q_2,f\},$
$\{s,f\}, \{q_1\}, \{q_1,q_2\}, \{q_1,f\}, \{q_1,q_2,f\}, \{q_2\}, \{q_2,f\}, \{f\}\}$

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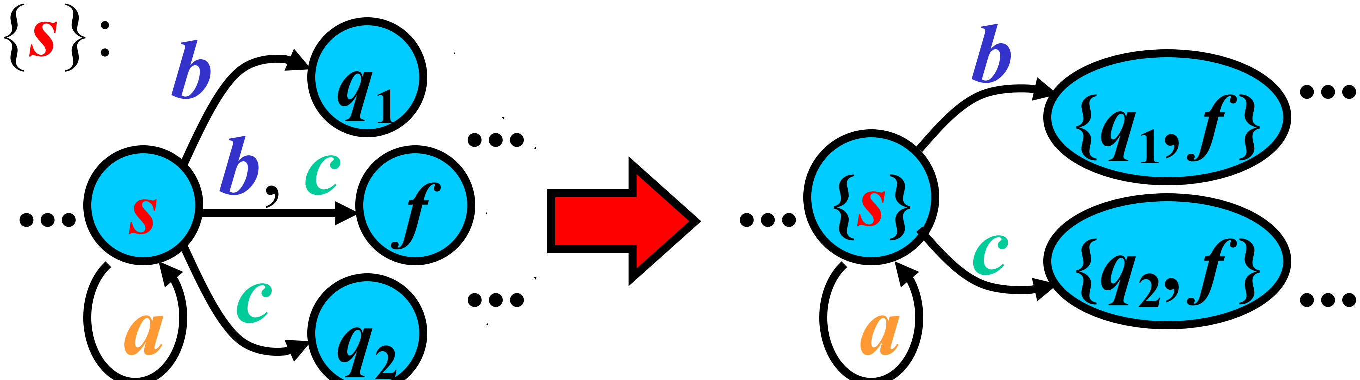
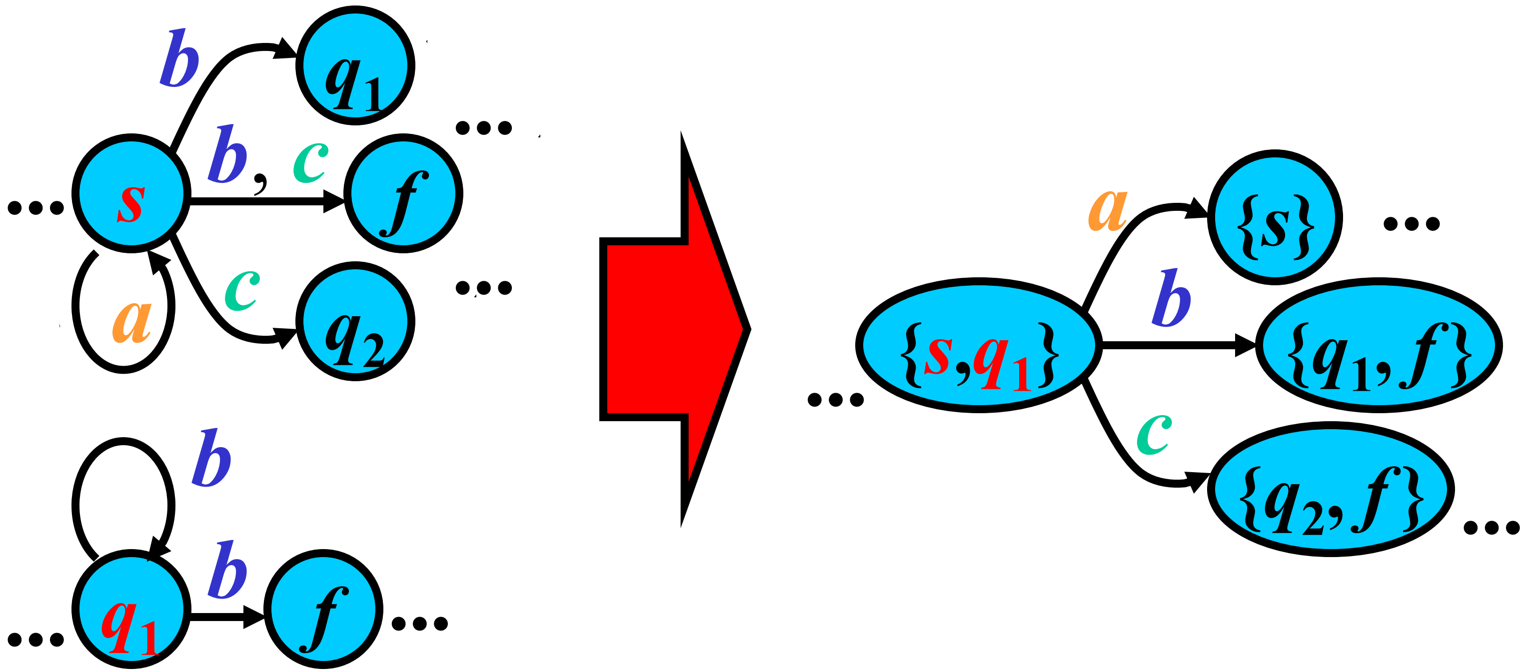
for $Q' = \{s\}$:



$R_d = \varnothing \cup \{\{s\}a \to \{s\}, \{s\}b \to \{q_1, f\}, \{s\}c \to \{q_2, f\}\}$

ε-free FA to DFA: Example 2/5

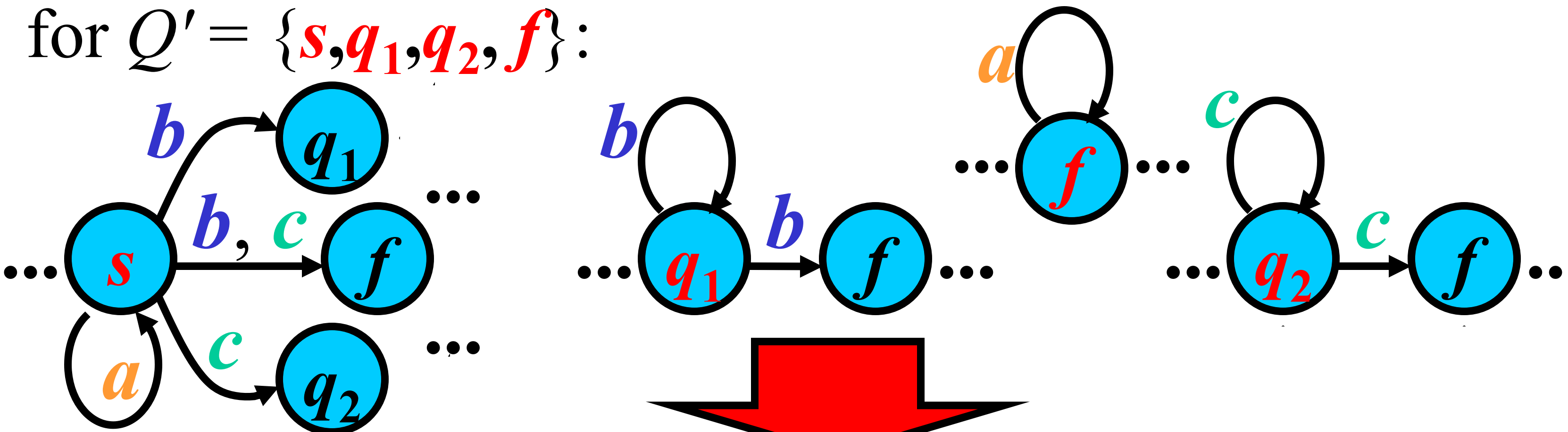
for $Q' = \{s, q_1\}$:

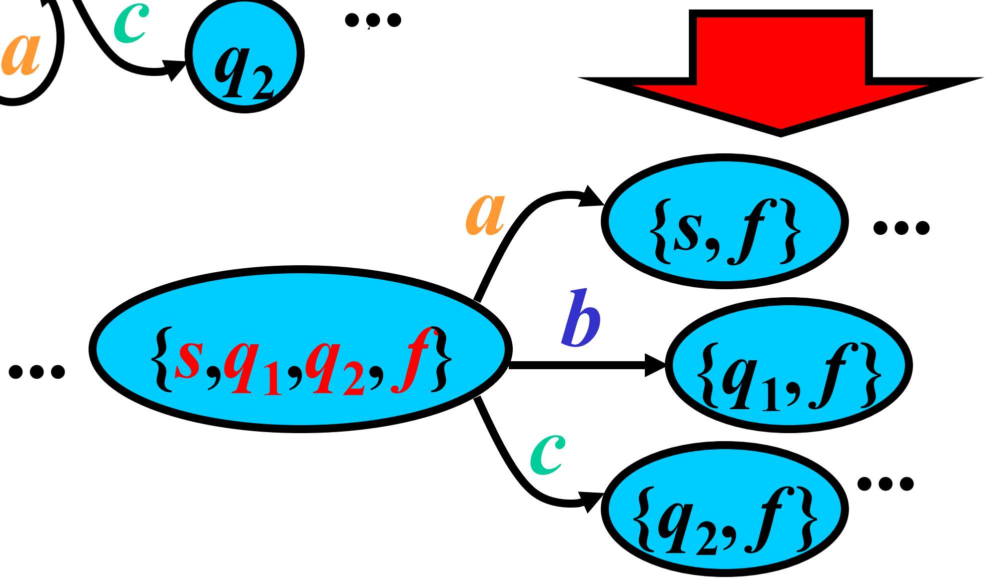


$R_d = R_d \cup \{\{s,q_1\}a \rightarrow \{s\},\ \{s,q_1\}b \rightarrow \{q_1, f\},\ \{s,q_1\}c \rightarrow \{q_2, f\}\}$

ε-free FA to DFA: Example 3/5

for $Q' = \{s, q_1, q_2, f\}$:





Construct the other states analogically…

$$R_d = R_d \cup \{\{s,q_1,q_2,f\}a \to \{s,f\},\ \{s,q_1,q_2,f\}b \to \{q_1,f\},$$
$$\{s,q_1,q_2,f\}c \to \{q_2,f\}\}$$

ε-free FA to DFA: Example 4/5

Final states: $F_d := \{F': F' \in Q_d, F' \cap F \neq \emptyset\}$

for $F = \{f\}$:

$\{s\} \cap \{f\} = \emptyset \Rightarrow \{s\} \notin F_d$

$\{s, q_1\} \cap \{f\} = \emptyset \Rightarrow \{s, q_1\} \notin F_d$

$\{s, q_1, q_2\} \cap \{f\} = \emptyset \Rightarrow \{s, q_1, q_2\} \notin F_d$

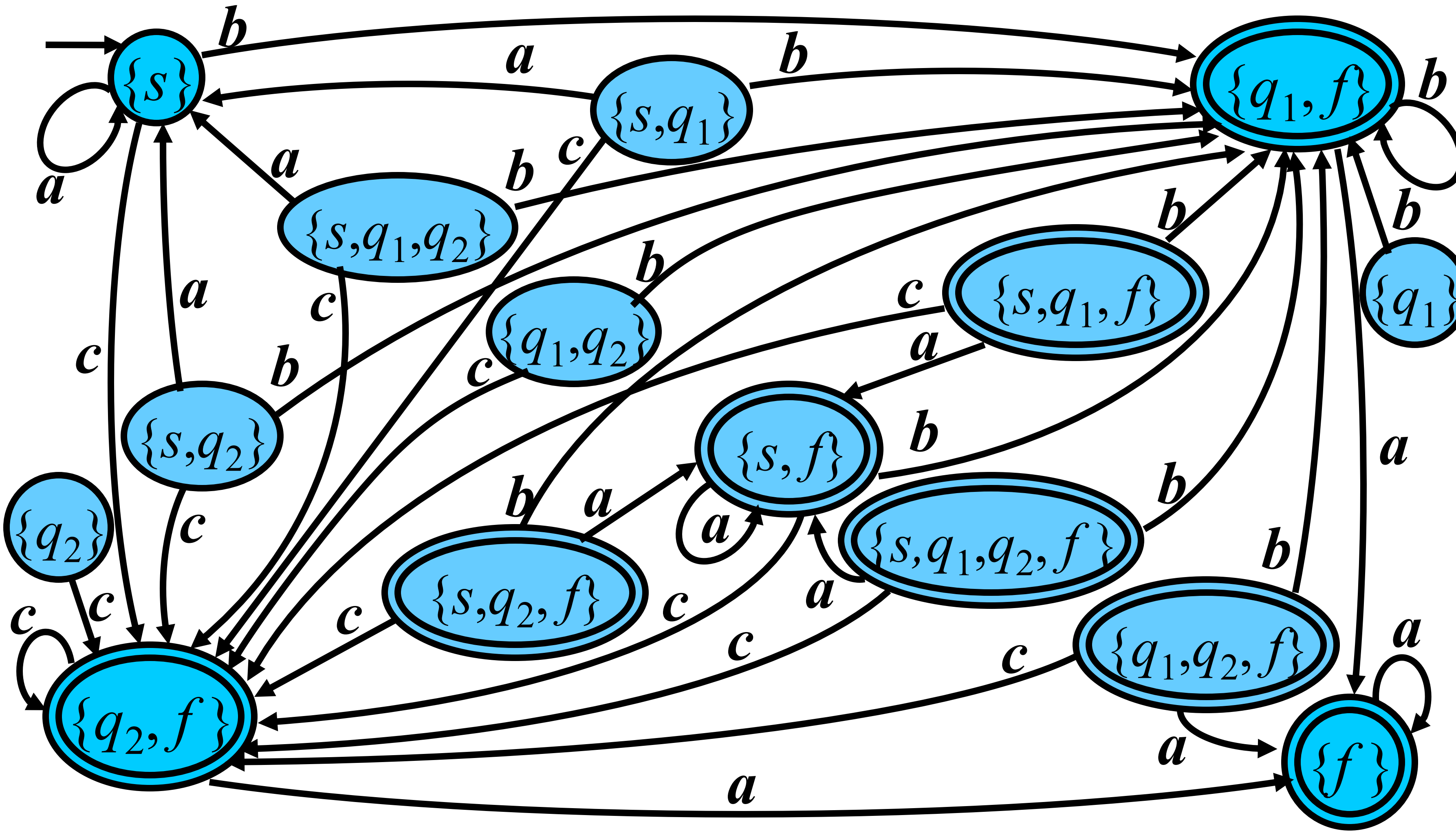
$\{s, q_1, f\} \cap \{f\} = \{f\} \neq \emptyset \Rightarrow \{s, q_1, f\} \in F_d$

$\{s, q_1, q_2, f\} \cap \{f\} = \{f\} \neq \emptyset \Rightarrow \{s, q_1, q_2, f\} \in F_d$

$\vdots$

$F_d = \{\{s, q_1, f\}, \{s, q_1, q_2, f\}, \{s, q_2, f\}, \{s, f\}, \{q_1, f\}, \{q_1, q_2, f\}, \{q_2, f\}, \{f\}\}$

ε-free FA to DFA: Example 5/5



Question: Can we make DFA smaller?

Answer: YES

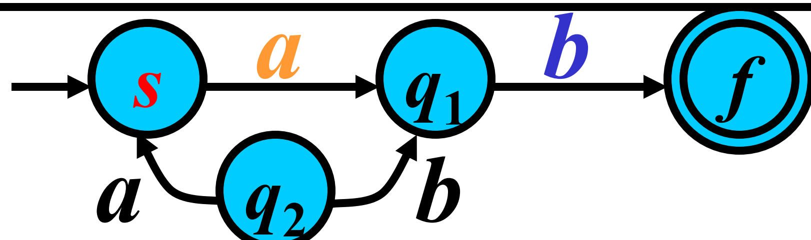
Accessible States

Gist: State q is *accessible* if a string takes DFA from s (the start state) to q.

Definition: Let $M = (Q, \Sigma, R, s, F)$ be an FA. A state $q \in Q$ is *accessible* if there exists $w \in \Sigma^*$ such that $sw \vdash^* q$; otherwise, q is *inaccessible*.

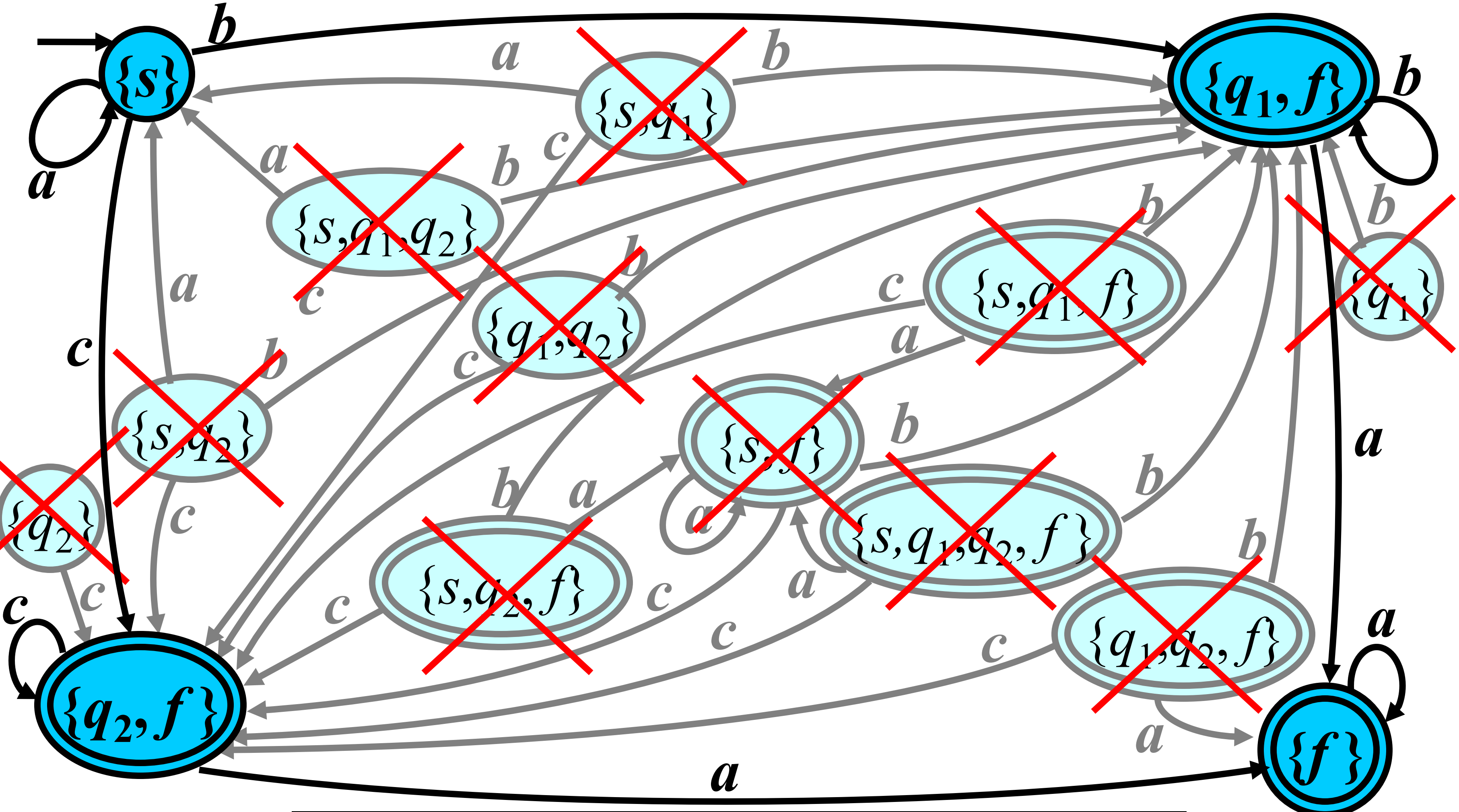
Note: Each inaccesible state can be removed from FA

Example:



State s - accesible: $w = \varepsilon$: $s \vdash^0 s$
State q_1 - accesible: $w = a$: $sa \vdash q_1$
State f - accesible: $w = ab$: $sab \vdash q_1 b \vdash f$
State q_2 - **inaccessible** (there is no $w \in \Sigma^*$ such that $sw \vdash^* q_2$)

Previous Example

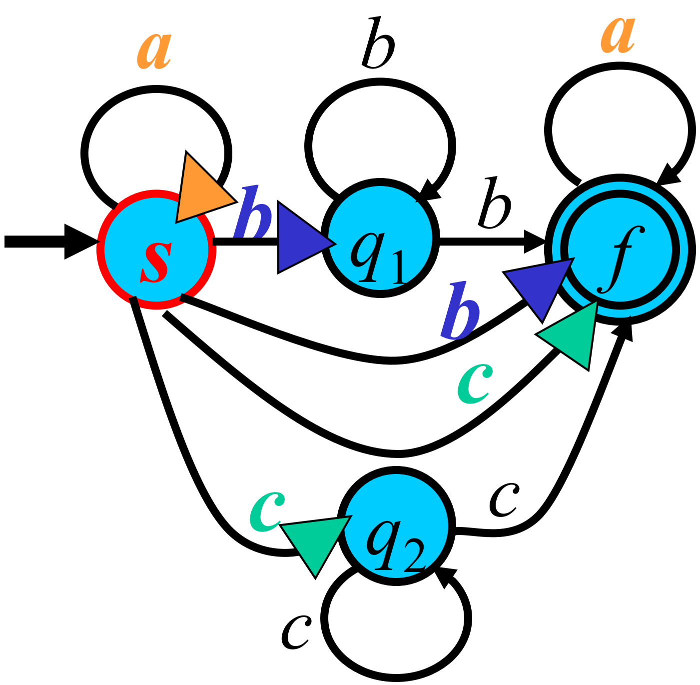


Many inaccessible states

Algorithm II: ε-free FA to DFA 1/2

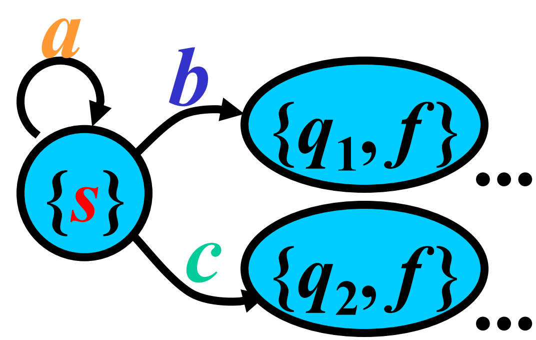
Gist: Analogy to the previous algorithm except that only sets of accessible states are introduced.

Illustration:



$Q_{DFA} = \{\{s\}\}$

For state $\{s\}$:



Add new states $\{q_1, f\}$, $\{q_2, f\}$ to Q_{DFA}

For state $\{q_1, f\}$: …

For state $\{q_2, f\}$: …

Add new states …

⋮

Algorithm II: ε-free FA to DFA 2/2

- **Input:** ε-*free* FA: $M = (Q, \Sigma, R, s, F)$
- **Output:** DFA: $M_d = (Q_d, \Sigma, R_d, s_d, F_d)$
  without any inaccessible states

- **Method:**
- $s_d := \{s\}$; $Q_{new} := \{s_d\}$; $R_d := \emptyset$; $Q_d := \emptyset$; $F_d := \emptyset$;
- **repeat**

  let $Q' \in Q_{new}$; $Q_{new} := Q_{new} - \{Q'\}$; $Q_d := Q_d \cup \{Q'\}$;
  for each $a \in \Sigma$ **do begin**
  $Q'' := \{q\colon p \in Q', pa \rightarrow q \in R\}$;
  if $Q'' \neq \emptyset$ **then** $R_d := R_d \cup \{Q'a \rightarrow Q''\}$;
  if $Q'' \notin Q_d \cup \{\emptyset\}$ **then** $Q_{new} := Q_{new} \cup \{Q''\}$
  end;
  if $Q' \cap F \neq \emptyset$ **then** $F_d := F_d \cup \{Q'\}$

until $Q_{new} = \emptyset$.

ε-free FA to DFA: Example 1/3

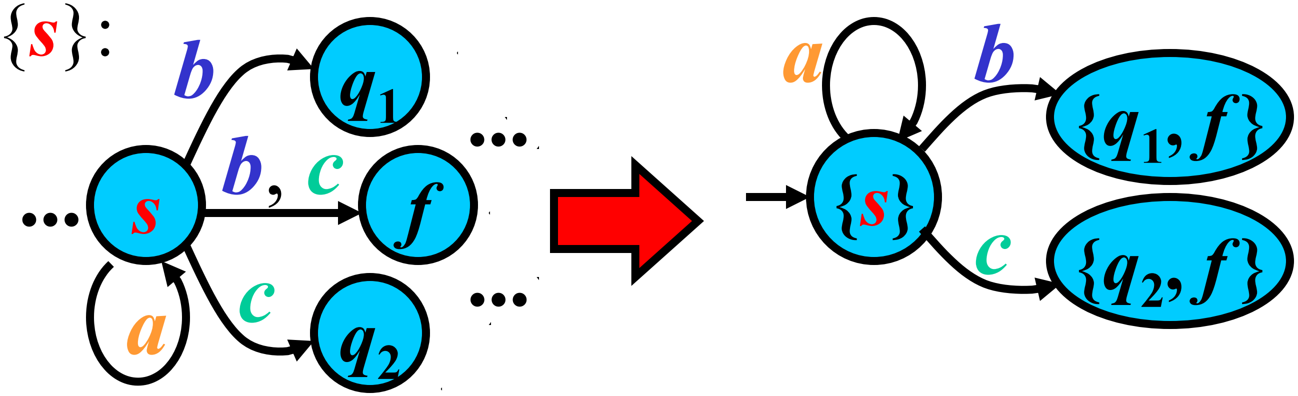
$M = (Q, \Sigma, R, s, F)$, where:

$Q = \{s, q_1, q_2, f\}$; $\Sigma = \{a, b, c\}$; $F = \{f\}$

$R = \{sa \to s, sb \to q_1, sb \to f, sc \to q_2, sc \to f,$
$q_1b \to q_1, q_1b \to f, q_2c \to q_2, q_2c \to f, fa \to f\}$;

$Q_{new} = \{\{s\}\}$; $R_d = \varnothing$; $Q_d = \varnothing$; $F_d = \varnothing$

for $Q' = \{s\}$:

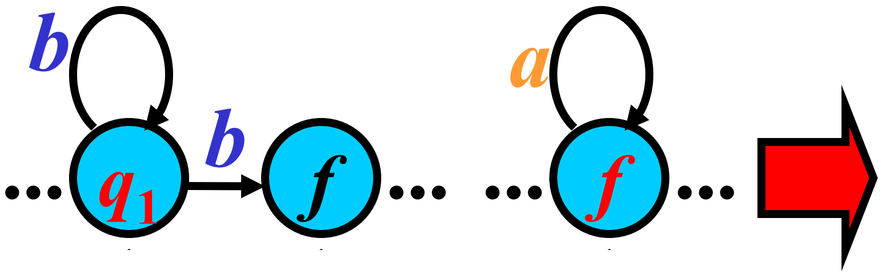


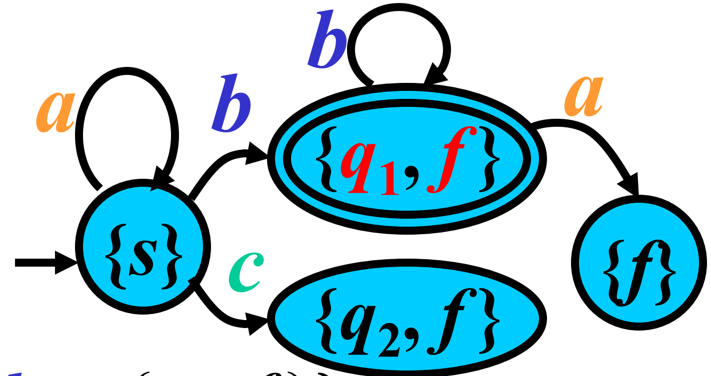
$R_d := \varnothing \cup \{\{s\}a \to \{s\}, \{s\}b \to \{q_1, f\}, \{s\}c \to \{q_2, f\}\}$

$Q_{new} = \{\{q_1, f\}, \{q_2, f\}\}$, $Q_d = \varnothing \cup \{\{s\}\}$, $F_d = \varnothing$

ε-free FA to DFA: Example 2/3

for $Q' = \{q_1, f\}$:





$R_d := R_d \cup \{\{q_1, f\}a \rightarrow \{f\},\ \{q_1, f\}b \rightarrow \{q_1, f\}\}$

$Q_{new} = \{\{q_2, f\},\ \{f\}\},\ Q_d = Q_d \cup \{\{q_1, f\}\}, F_d := \emptyset \cup \{\{q_1, f\}\}$

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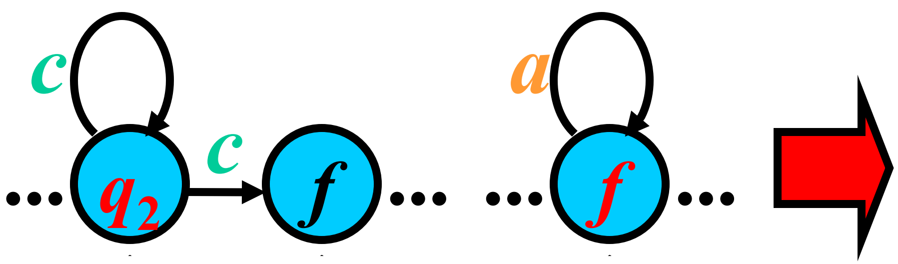
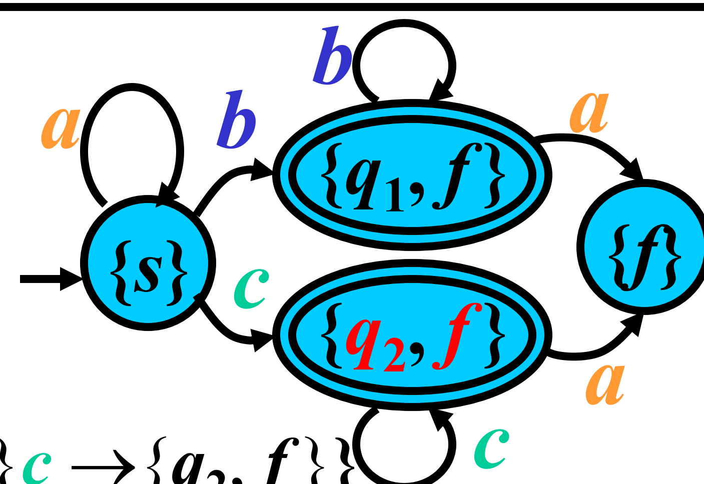
for $Q' = \{q_2, f\}$:



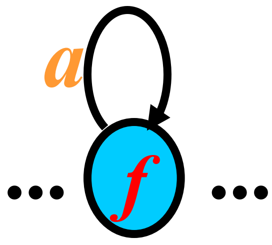


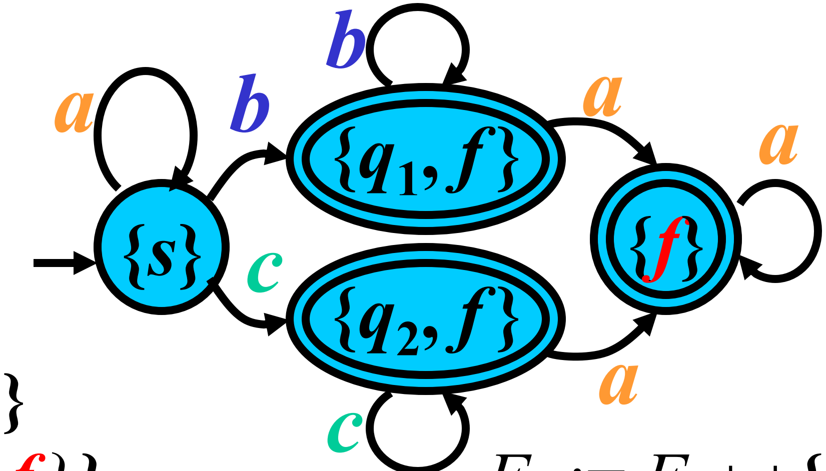
$R_d := R_d \cup \{\{q_2, f\}a \rightarrow \{f\},\ \{q_2, f\}c \rightarrow \{q_2, f\}\}$

$Q_{new} = \{\{f\}\},\ Q_d = Q_d \cup \{\{q_2, f\}\},\ F_d := F_d \cup \{\{q_2, f\}\}$

ε-free FA to DFA: Example 3/3

for $Q' = \{f\}$:



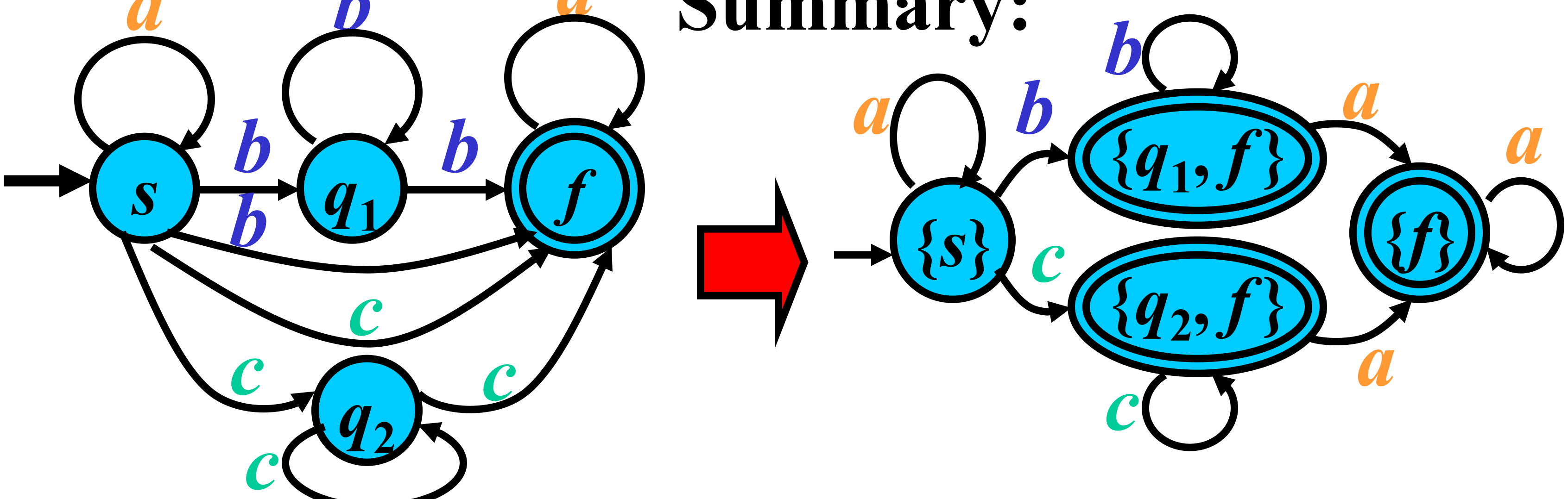


$R_d := R_d \cup \{\{f\}a \rightarrow \{f\}\}$

$Q_{new} = \emptyset$, $Q_d = Q_d \cup \{\{f\}\}$,

$F_d := F_d \cup \{\{f\}\}$

Summary:



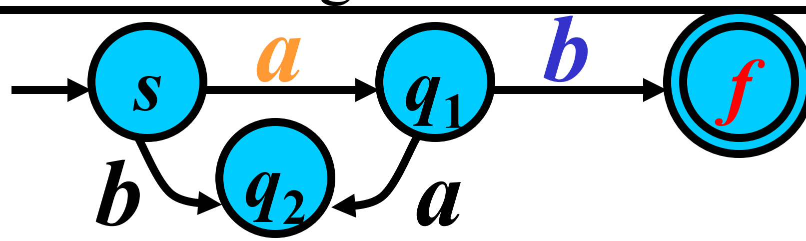
Terminating States

Gist: State q is *terminating* if a string takes DFA from q to a final state.

Definition: Let $M = (Q, \Sigma, R, s, F)$ be a DFA. A state $q \in Q$ is *terminating* if there exists $w \in \Sigma^*$ such that $qw \vdash^* f$ with $f \in F$; otherwise, q is *nonterminating*.

Note: Each nonterminating state can be removed from DFA

Example:



State s - terminating: $w = ab$: $sab \vdash q_1b \vdash f$

State q_1 - terminating: $w = b$: $q_1b \vdash f$

State f - terminating: $w = \varepsilon$: $f \vdash^0 f$

State q_2 - **nonterminating** (there is no $w \in \Sigma^*$ such that $q_2w \vdash^* q, q \in F$)

Algorithm: Removal of nont. states

- **Input:** DFA: $M = (Q, \Sigma, R, s, F)$
- **Output:** DFA: $M_t = (Q_t, \Sigma, R_t, s, F)$

- **Method:**
- $Q_0 := F$; $i := 0$;
- **repeat**

  $i := i + 1$;

  $Q_i := Q_{i\text{-}1} \cup \{q\text{: } qa \rightarrow p \in R,\ a \in \Sigma,\ p \in Q_{i\text{-}1}\}$;

until $Q_i = Q_{i\text{-}1}$;
- $Q_t := Q_i$;
- $R_t := \{qa \rightarrow p\text{: } qa \rightarrow p \in R,\ p, q \in Q_t,\ a \in \Sigma\}$.

Nonterminating States: Example

$M = (Q, \Sigma, R, s, F)$, where: $Q = \{s, q_1, q_2, f\}$, $\Sigma = \{a, b\}$,
$R = \{sa \to q_1, sb \to q_2, q_1a \to q_2, q_1b \to f\}$, $F = \{f\}$

$Q_0 = \{f\}$

---

1) $qd \to f$; $q \in Q$; $d \in \Sigma$: $\quad q_1b \to f$

$Q_1 = \{f\} \cup \{q_1\} = \{f, q_1\}$

---

2) $qd \to f$; $q \in Q$; $d \in \Sigma$: $\quad q_1b \to f$

$qd \to q_1$; $q \in Q$; $d \in \Sigma$: $\quad sa \to q_1$

$Q_2 = \{f, q_1\} \cup \{q_1, s\} = \{f, q_1, s\}$

---

3) $qd \to f$; $q \in Q$; $d \in \Sigma$: $\quad q_1b \to f$

$qd \to q_1$; $q \in Q$; $d \in \Sigma$: $\quad sa \to q_1$

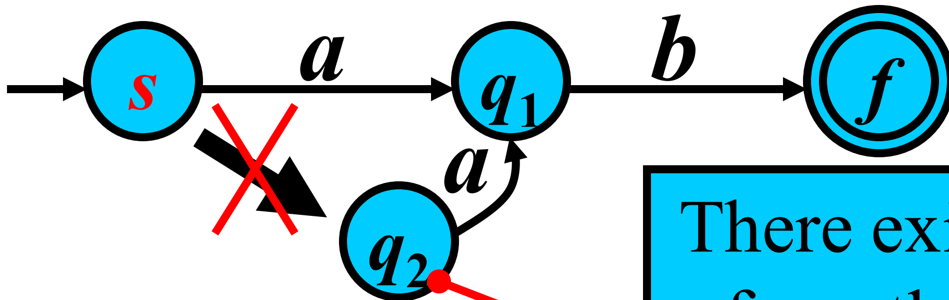
$qd \to s$; $q \in Q$; $d \in \Sigma$: **none**

$Q_3 = \{f, q_1, s\} \cup \{q_1, s\} = \{f, q_1, s\} = Q_2 = Q_t$

$R_t = \{sa \to q_1, sb \cancel{\to} q_2, q_1a \cancel{\to} q_2, q_1b \to f\}$

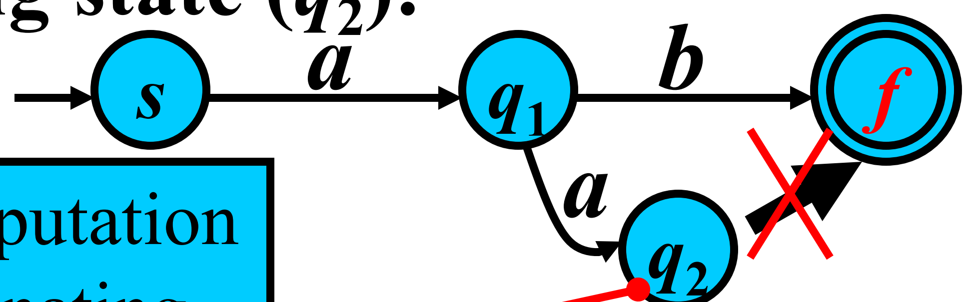
Summary: States to Remove

1) Inaccessible state (q_2):



There exists no computation from the start state to this inaccessible state.

2) Nonterminating state (q_2):



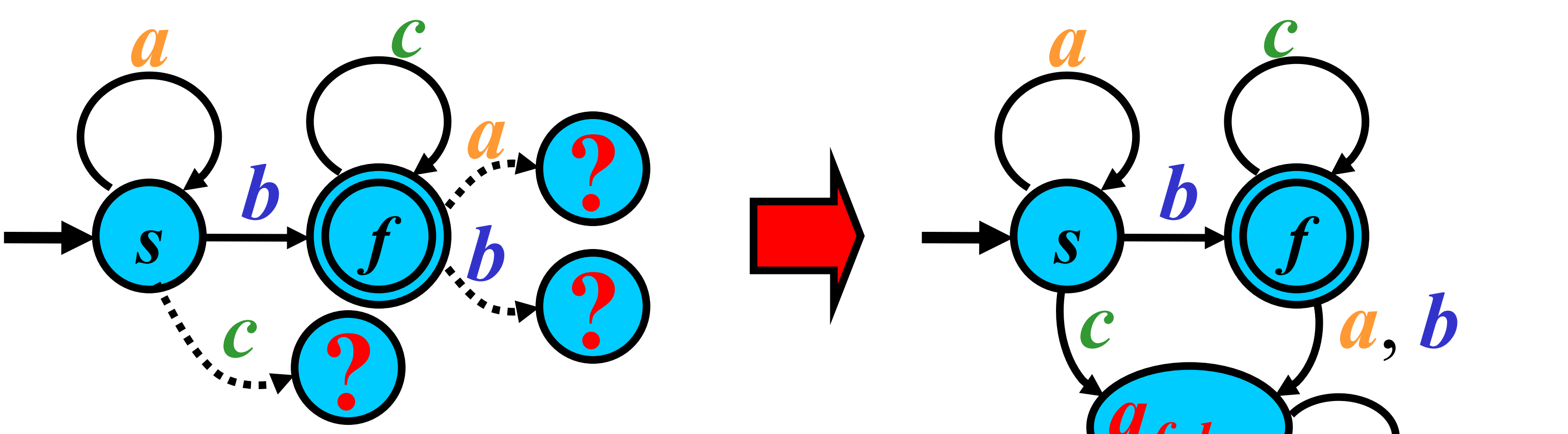
There exists no computation from this nonterminating state to a final state.

Complete DFA

Gist: Complete DFA cannot get stuck.

Definition: Let $M = (Q, \Sigma, R, s, F)$ be a **DFA**. M is ***complete***, if for any $p \in Q$, $a \in \Sigma$ there is exactly one rule of the form $pa \rightarrow q \in R$ for some $q \in Q$; otherwise, M is ***incomplete***

Conversion: **Incomplete DFA** **to Complete DFA**



$\Sigma = \{a, b, c\}$

Algorithm: DFA to Complete DFA

Gist: Add a "trap" state

- **Input:** Incomplete DFA $M = (Q, \Sigma, R, s, F)$
- **Output:** Complete DFA $M_c = (Q_c, \Sigma, R_c, s, F)$

- **Method:**
- $Q_c := Q \cup \{q_{false}\}$;
- $R_c := R \cup \{qa \rightarrow q_{false}: a \in \Sigma, q \in Q_c,$
  $qa \rightarrow p \notin R,\ p \in Q\}$.

Well-Specified FA

Definition: Let $M = (Q, \Sigma, R, s, F)$ be a **complete DFA**. Then, M is ***well-specified FA*** (WSFA) if:

1) Q has no inaccessible state

2) Q has no more than one nonterminating state

Note: If well-specified FA has one nonterminating state, then it is q_{false} from the previous algorithm.

Theorem: For every FA M, there is an equivalent WSFA M_{ws}.

Proof: Use the next algorithm.

Algorithm: FA to WSFA

- **Input:** FA M
- **Output:** WSFA M_{ws}

- **Method:**
- convert a FA M to an equivalent ε-free FA M'
- convert a M' to an equivalent DFA M_d without any inaccessible state
- convert M_d to an equivalent DFA M_t without any nonterminating state
- convert M_t to an equivalent complete FA M_c
- $M_{ws} := M_c$

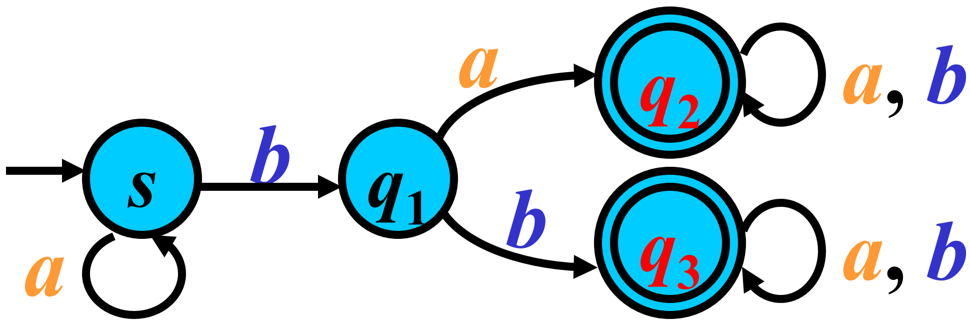
Note: No more than one nonterminating state in M_{ws}—q_{false}

Distinguishable States

Gist: String w *distinguishes* states p and q if WSFA reaches a final state from <u>precisely</u> one of configurations pw and qw.

Definition: Let $M = (Q, \Sigma, R, s, F)$ be a WSFA, and let $p, q \in Q$, $p \neq q$. States p and q are *distinguishable* if there exists $w \in \Sigma^*$ such that: $pw \vdash^* p'$ and $qw \vdash^* q'$, where $p', q' \in Q$ and $((p' \in F$ and $q' \notin F)$ or $(p' \notin F$ and $q' \in F))$; otherwise, states p and q are *indistinguishable*

Distinguishable States: Example



- s and q_1 are **distinguishable**, because for $w = a$:

$$sa \vdash s\ ,\ s \notin F$$
$$q_1 a \vdash q_2\ ,\ q_2 \in F$$

- q_2 and q_3 are **indistinguishable**, because for each $w \in \Sigma^*$:

$$q_2 w \vdash^* q_2,\ q_2 \in F$$
$$q_3 w \vdash^* q_3,\ q_3 \in F$$

- Other pairs of states are trivially **distinguishable** for $w = \varepsilon$.

Minimum-State FA

Definition: Let M be a **WSFA**. Then, M is ***minimum-state FA*** if M contains only distinguishable states.

Theorem: For every WSFA M, there is an equivalent minimum-state FA M_m

Proof: Use the next algorithm.

Algorithm: WSFA to Min-State FA

- **Input:** WSFA $M = (Q, \Sigma, R, s, F)$
- **Output:** Minimum-State FA $M_m = (Q_m, \Sigma, R_m, s_m, F_m)$
- **Method:**
- $Q_m = \{\{p: p \in F\}, \{q: q \in Q - F\}\}$;
- **repeat**

  if there exist $X \in Q_m$, $d \in \Sigma$, $X_1, X_2 \subset X$ such that

  $X = X_1 \cup X_2$, $X_1 \cap X_2 = \emptyset$ **and**

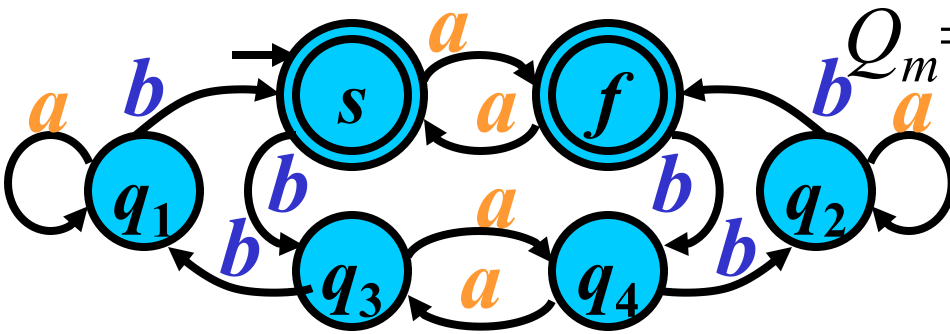
  $\{q_1: p_1 \in X_1, p_1 d \to q_1 \in R\} \subseteq Q_1, Q_1 \in Q_m,$

  $\{q_2: p_2 \in X_2, p_2 d \to q_2 \in R\} \cap Q_1 = \emptyset$

  then divide X into X_1 and X_2 in Q_m

  until no division is possible;
- $R_m = \{ Xa \to Y: X, Y \in Q_m, pa \to q \in R, p \in X, q \in Y, a \in \Sigma\}$;
- $s_m = X$ with $s \in X$; $F_m := \{X: X \in Q_m, X \cap F \neq \emptyset\}$.

Minimization: Example 1/4



$Q_m = \{\underbrace{\{s, f\}}_{\text{Final States}}, \underbrace{\{q_1, q_2, q_3, q_4\}}_{\text{Other States}}\}$

1) $X = \{s, f\}$:

$d = a$: $sa \to f$, $fa \to s$ — **From one set**

$d = b$: $sb \to q_3$, $fb \to q_4$ — **From one set**

2) $X = \{q_1, q_2, q_3, q_4\}$:

$d = a$: $q_1a \to q_1$, $q_2a \to q_2$, $q_3a \to q_4$, $q_4a \to q_3$ — **From one set**

$d = b$: $q_1b \to s$, $q_2b \to f$; $\{s, f\} \subseteq Q_1 = \{s, f\}$

$q_3b \to q_1$, $q_4b \to q_2$; $\{q_1, q_2\} \cap Q_1 = \varnothing$

Division: $\{q_1, q_2, q_3, q_4\} \Rightarrow \underbrace{\{q_1, q_2\}}_{X_1}, \underbrace{\{q_3, q_4\}}_{X_2}$

Minimization: Example 2/4

$Q_m = \{\{s,f\}, \{q_1,q_2\}, \{q_3,q_4\}\}$

---

1) $X = \{s,f\}$:

$d = a$: $sa \to f$, $fa \to s$ — **From one set**

$d = b$: $sb \to q_3$, $fb \to q_4$ — **From one set**

---

2) $X = \{q_1,q_2\}$:

$d = a$: $q_1a \to q_1$, $q_2a \to q_2$ — **From one set**

$d = b$: $q_1b \to s$, $q_2b \to f$ — **From one set**

---

3) $X = \{q_3,q_4\}$:

$d = a$: $q_3a \to q_3$, $q_4a \to q_4$ — **From one set**

$d = b$: $q_3b \to q_1$, $q_4b \to q_2$ — **From one set**

No next divisions !!!

Minimization: Example 3/4

$Q_m = \{\{s,f\}, \{q_1,q_2\}, \{q_3,q_4\}\}$

$\left.\begin{array}{l} sa \rightarrow f \in R: \\ fa \rightarrow s \in R: \end{array}\right\} \Rightarrow \{s,f\}a \rightarrow \{s,f\} \in R_m$

$\left.\begin{array}{l} sb \rightarrow q_3 \in R: \\ fb \rightarrow q_4 \in R: \end{array}\right\} \Rightarrow \{s,f\}b \rightarrow \{q_3,q_4\} \in R_m$

$\left.\begin{array}{l} q_1a \rightarrow q_1 \in R: \\ q_2a \rightarrow q_2 \in R: \end{array}\right\} \Rightarrow \{q_1,q_2\}a \rightarrow \{q_1,q_2\} \in R_m$

$\left.\begin{array}{l} q_1b \rightarrow s \in R: \\ q_2b \rightarrow f \in R: \end{array}\right\} \Rightarrow \{q_1,q_2\}b \rightarrow \{s,f\} \in R_m$

$\left.\begin{array}{l} q_3a \rightarrow q_3 \in R: \\ q_4a \rightarrow q_4 \in R: \end{array}\right\} \Rightarrow \{q_3,q_4\}a \rightarrow \{q_3,q_4\} \in R_m$

$\left.\begin{array}{l} q_3b \rightarrow q_1 \in R: \\ q_4b \rightarrow q_2 \in R: \end{array}\right\} \Rightarrow \{q_3,q_4\}b \rightarrow \{q_1,q_2\} \in R_m$

Minimization: Example 4/4

$s \in \{s, f\} \Rightarrow s_m := \{s, f\}$

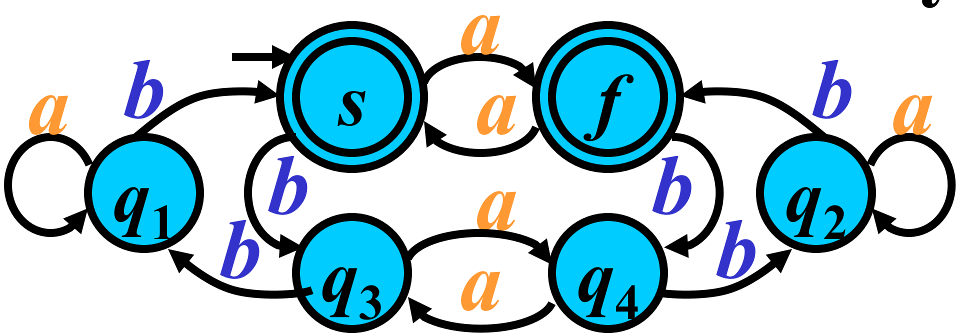
$\left.\begin{array}{l} s \in F: \\ f \in F: \end{array}\right\} \Rightarrow \{s, f\} \in F_m$

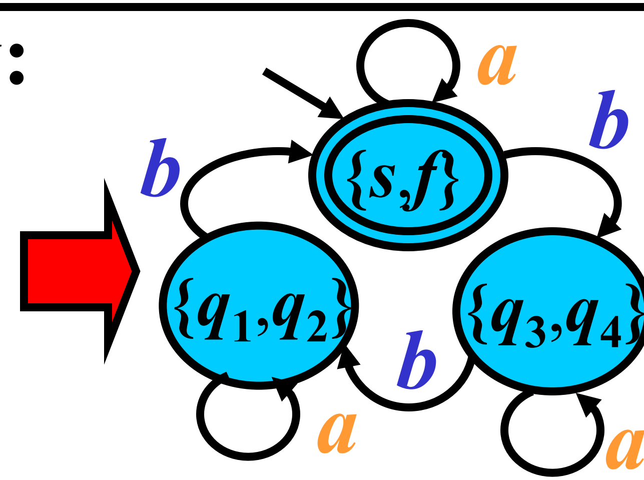
$M_m = (Q_m, \Sigma, R_m, s_m, F_m)$, where: $\Sigma = \{a, b\}$, $s_m = \{s, f\}$

$Q_m = \{\{s, f\}, \{q_1, q_2\}, \{q_3, q_4\}\}$, $F_m = \{\{s, f\}\}$

$R_m = \{\{s, f\}a \to \{s, f\}, \{s, f\}b \to \{q_3, q_4\}, \{q_1, q_2\}a \to \{q_1, q_2\}, \{q_1, q_2\}b \to \{s, f\}, \{q_3, q_4\}a \to \{q_3, q_4\}, \{q_3, q_4\}b \to \{q_1, q_2\}\}$

Summary:





Variants of FA: Summary

	FA	ε-free FA	DFA	Complete FA	WSFA	Min-State FA
Number of rules of the form $p \rightarrow q$, where $p, q \in Q$	**0-*n***	**0**	**0**	**0**	**0**	**0**
Number of rules of the form $pa \rightarrow q$, for any $p \in Q$, $a \in \Sigma$	**0-*n***	**0-*n***	**0-1**	**1**	**1**	**1**
Number of inaccessible states	**0-*n***	**0-*n***	**0-*n***	**0-*n***	**0**	**0**
Number of nonterminating states	**0-*n***	**0-*n***	**0-*n***	**0-*n***	**0-1**	**0-1**
Number of this FAs for any regular language.	∞	∞	∞	∞	∞	**1**