

## LAB-6 - Implementing A\* and Hill Climbing Algorithm on 8 Queens.

Observation book:

classmate  
Date \_\_\_\_\_  
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LAB-6

~~A\* search Algorithm~~ Hill climbing for 8-Queen

1. Initial state : random configuration, one queen per row in random columns.
2.  $h \rightarrow$  number of pairs of queens attacking each other.
3. Goal :  $h = 0$ .
4. Check for conflict : same column, same row or same diagonal.
5. For each queen, count how many other queens it conflicts and add this to  $h$ .
6. Divide the final count by 2, each conflict is counted twice. i.e once for each queen in the pair.

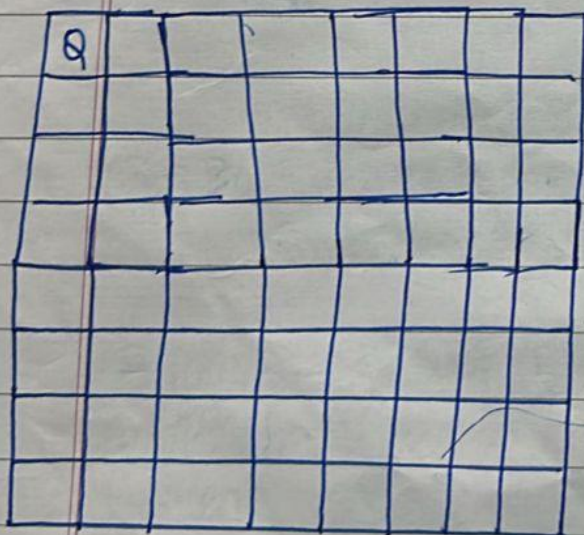
Output :

.	.	.	.	.	.	Q
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Q	.	.	.	.	.	.
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.	.	.	Q	.	.	.
.	Q	.	.	.	.	.
.	.	.	.	Q	.	.

## A\* algorithm for 8 Queens:

1. Initial state: ~~Empty board~~ Random configuration of, one queen every row in random column. Empty Board and place queen.
2. Cost for each ~~queen~~ setup:
  - steps taken so far ( $g$ ): This is the number of queen placed.
  - Conflicts ( $h$ ): how many Queens are conflicting each other.
3. Calculate  $f(n) = g + h(n)$
4. Choose the setup with lowest score ~~is the~~.
5. Goal: If setup has no conflicts i.e  $h=0$  and all Queens are placed.  
If not keep repeating until final solution.

Example:



$$g = 1$$

### **A \* Code:**

```
import numpy as np
```

```
import heapq
```

```
class Node:
```

```
    def __init__(self, state, g, h):
```

```
        self.state = state # current state of the board
```

```
        self.g = g # cost to reach this state
```

```
        self.h = h # heuristic cost to reach goal
```

```
        self.f = g + h # total cost
```

```
    def __lt__(self, other):
```

```
        return self.f < other.f
```

```
def heuristic(state):
```

```
    # Count pairs of queens that can attack each other
```

```
    attacks = 0
```

```
    for i in range(len(state)):
```

```
        for j in range(i + 1, len(state)):
```

```
            if state[i] == state[j] or abs(state[i] - state[j]) == j - i:
```

```
                attacks += 1
```

```
    return attacks
```

```
def a_star_8_queens():
```

```
    initial_state = [-1] * 8 # -1 means no queen placed
```

```
    open_list = []
```

```

closed_set = set()
initial_h = heuristic(initial_state)
heapq.heappush(open_list, Node(initial_state, 0, initial_h))

while open_list:
    current_node = heapq.heappop(open_list)
    current_state = current_node.state
    closed_set.add(tuple(current_state))

    # Check if we reached the goal
    if current_node.h == 0:
        return current_state

    for col in range(8):
        for row in range(8):
            if current_state[col] == -1: # Only place a queen if none is present in
this column
                new_state = current_state.copy()
                new_state[col] = row
                if tuple(new_state) not in closed_set:
                    g_cost = current_node.g + 1
                    h_cost = heuristic(new_state)
                    heapq.heappush(open_list, Node(new_state, g_cost, h_cost))

return None

solution = a_star_8_queens()

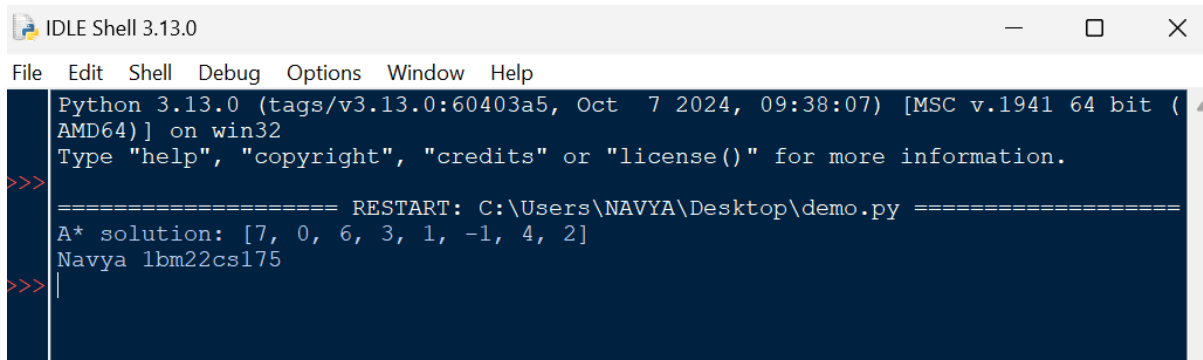
```



```
print("A* solution:", solution)

print("Navya 1bm22cs175")
```

output:



```
Python 3.13.0 (tags/v3.13.0:60403a5, Oct 7 2024, 09:38:07) [MSC v.1941 64 bit (AMD64)] on win32
Type "help", "copyright", "credits" or "license()" for more information.
>>>
===== RESTART: C:\Users\NAVYA\Desktop\demo.py =====
A* solution: [7, 0, 6, 3, 1, -1, 4, 2]
Navya 1bm22cs175
>>>|
```

Hill climbing :

Code:

```
import random
```

```
def heuristic(state):
```

```
    attacks = 0
```

```
    for i in range(len(state)):
```

```
        for j in range(i + 1, len(state)):
```

```
            if state[i] == state[j] or abs(state[i] - state[j]) == j - i:
```

```
                attacks += 1
```

```
    return attacks
```

```
def hill_climbing_8_queens():
```

```
    state = [random.randint(0, 7) for _ in range(8)] # Random initial state
```

```
    while True:
```

```

current_h = heuristic(state)
if current_h == 0: # Found a solution
    return state

next_state = None
next_h = float('inf')

for col in range(8):
    for row in range(8):
        if state[col] != row: # Only consider moving the queen
            new_state = state.copy()
            new_state[col] = row
            h = heuristic(new_state)
            if h < next_h:
                next_h = h
                next_state = new_state

if next_h >= current_h: # No better neighbor found
    return None # Stuck at local maximum

state = next_state

solution = hill_climbing_8_queens()
print("Hill Climbing solution:", solution)
print("Navya 1bm22cs175")

```

Output :

```
Hill Climbing solution: None
navya 1bm22cs175
>>>
```