

Federated Learning in Intelligent Systems & ITS

This presentation explores the application of Federated Learning(FL) in real-world intelligent systems and specifically within Intelligent Transportation Systems(ITS), highlighting its benefits, challenges ,and future directions.

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Introduction to Federated Learning

What This Paper Is About

- Focuses on applying FL in real-world intelligent systems.
Emphasizes privacy-preserving machine learning.
- Addresses distributed data environments and edge systems.
- Application-oriented, studying deployment and challenges.
- Evaluates accuracy, communication cost, and privacy.
- Reviews existing research for ITS applications.



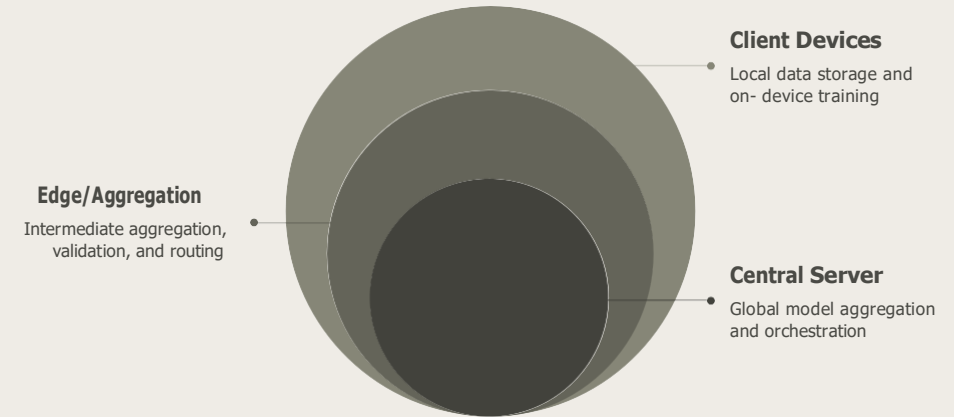
Motivation: Why FL is Needed

- ♦ **Centralized Data Collection Is Risky:** Personal and location data lead to privacy leakage and regulatory issues (GDPR, HIPAA).
- ♦ **Distributed Data Can not Be Easily Merged:**
Data on edge/mobile devices is expensive, slow, and energy-consuming to transfer.
- ♦ **Resource Constraints at the Edge:** Limited CPU, memory, and battery make heavy models impractical.
- ♦ **High Response Latency in ITS:** Cloud-based decisions are too slow for real-time tasks like collision avoidance.
- ♦ **Privacy and Security Issues in ITS:** Sensitive vehicle data risks leakage and attacks when sent to the cloud.
- ♦ **Low Decision-Making Accuracy in ITS:** Uneven, incomplete, and Non-IID data leads to poor model generalization.



FL System Architecture & Workflow

- ♦ **Three-Tier Architecture** :Client, Edge/Aggregation, and Central Server layers.
- ♦ **Client Layer:** Edge devices store local data, perform local training and feature extraction.
- ♦ **Edge/Aggregation Layer:** Optional intermediate layer reduces latency and communication cost, support spartial aggregation.
- ♦ **Central Server:** Coordinates training rounds, performs model aggregation and global synchronization.
- ♦ **Training Workflow:** Server initializes global model, sends to clients for local training, clients send updates, server aggregates using Fed Avg.
- ♦ **ITS Architecture** :Cloud server (global model), RSUs/Edge servers(partial aggregation),Vehicles(local models).



This architecture is scalable, fault-tolerant, and suitable for ITS environments.

Algorithms and Techniques Used

1

Federated Averaging (FedAvg)

Main aggregation algorithm: simple, communication-efficient, but sensitive to non-IID data and client heterogeneity.

2

Local Training Algorithms

Clients use CNNs, DNNs, or light weight models with SGD and mini-batch training for edge efficiency.

3

Non-IID Data Handling

Addresses model drift and slower convergence due to differing client data distributions via adaptive weights

Privacy & Communication Optimization

- **Differential Privacy(DP):** Adds noise to model updates to prevent inference attacks, with a privacy-accuracy trade-off.
- **Secure Aggregation :** Server only sees aggregated model, protecting individual updates from honest-but-curious servers.
- **Model Compression:** Techniques like parameter pruning and quantization reduce communication overhead.
- **Client Selection :** Not all clients participate every round; selection based on network quality and resource availability.
- **Update frequency Control:** Fewer communication rounds with more local computation to optimize communication.
- **Blockchain Integration:** Provides trust and trace ability for data and model updates in FL systems.



FL in Intelligent Transportation Systems(ITS)

- ♦ **Lower Communication Cost:** Only light weight model updates are shared, not raw data, ideal for limited bandwidth.
- ♦ **Enhanced Privacy Protection:** Data stays local within vehicles, combined with DP and secure aggregation.
- ♦ **Improved Scalability:** Supports large-scale ITS with dynamic vehicle populations, as vehicle can join and leave.
- ♦ **Increased Robustness:** System continues to function even if some vehicles disconnect, avoiding single points of failure.
- ♦ **Non-IID Data Handling:** FL is designed for uneven data distributions common in ITS, using personalized and grouped aggregation.
- ♦ **Support for Local Personalized Decisions:** Each vehicle can adapt the global model for better local performance and real-time responses.



ITS Application Scenarios

- **Object Recognition (Perception):** Obstacle detection, traffic sign recognition using CNNs, YOLO, Mask R-CNN.
- **Traffic Status Identification(Perception + Prediction):** Vehicle positioning, traffic flow prediction using DNN,LSTM, TCN.
- **Traffic Management (Decision):** Parking management, traffic signal control using FL+ Reinforcement Learning.
- **Service Providing Tasks:** EV charging services, route planning using graph search, DRL.
- **Challenges :**High-speed mobility, limited storage/computing, high information sensitivity.
- **Solutions:** Asynchronous FL, edge computing, model compression, blockchain, DP, anomaly detection.



Future Directions & Conclusion

- ♦ **Lightweight FL Models:** Essential for resource-constrained edge devices.
- ♦ **Adaptive Aggregation Strategies:** To better handle non-IID data and client heterogeneity.
- ♦ **Cross-Layer Optimization:** Integrating network and learning optimizations for better performance.
- ♦ **Real-World Deployment:** Benchmarking and commercial deployment using platforms like Open Daylight.
- ♦ **Generalized FL for Multiple ITS Scenarios:** One FL system serving diverse tasks efficiently.
- ♦ **Deep Integration of FL and ITS:** Developing task-specific FL architectures for optimal performance.



Federated Learning is a strong candidate for future ITS, solving privacy, communication, and scalability issues, but requires continued research in to security, resource limitations, and deployment challenges.