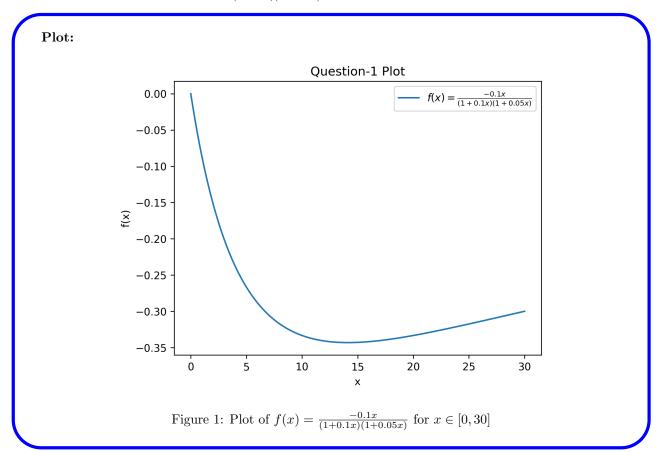
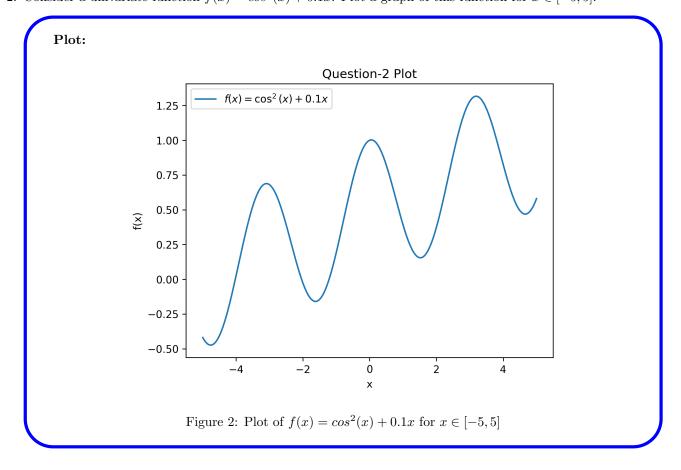
CL 603 Optimization Homework 1 : Preliminary Programming Priyam Nayak - 214026014 priyamnayak@iitb.ac.in 14 August 2024

1. Consider a univariate function $f(x) = \frac{-0.1x}{(1+0.1x)(1+0.05x)}$. Plot a graph of this function for $x \in [0, 30]$.



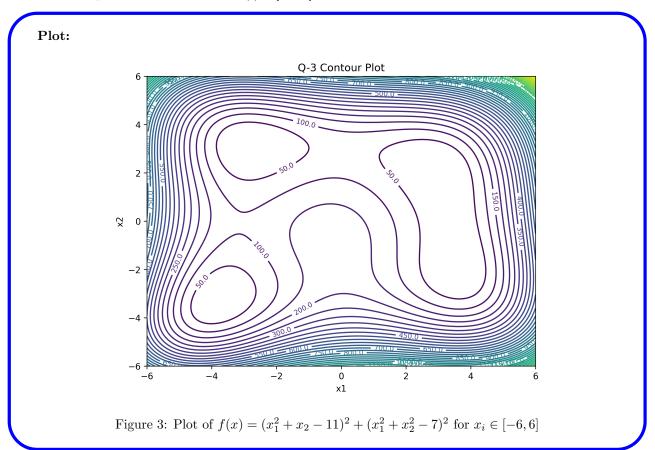
2. Consider a univariate function $f(x) = \cos^2(x) + 0.1x$. Plot a graph of this function for $x \in [-5, 5]$.



3. Consider the following multivariate function:

$$f(x) = (x_1^2 + x_2 - 11)^2 + (x_1^2 + x_2^2 - 7)^2$$
(1)

Plot a contour plot of this function for $x(i) \in [-6, 6]$.



4. Given a multivariate function f(x), write a code to compute its gradient and Hessian at a point. Use the center difference formula to compute the numerical derivative. You can test the code using the function given in Eq. (1). At point (1, 2), the following answer is expected:

$$\nabla f = \begin{bmatrix} -36 \\ -32 \end{bmatrix}$$

$$\nabla^2 f = \begin{bmatrix} -22 & 12\\ 12 & 26 \end{bmatrix}$$

Answer:

Gradient at (1, 2): [-36, -32]

Hessian at (1, 2): [[-22.00000182, 12.00000099], [12.00000099, 25.9999311]]

5. Given a symmetric matrix, write a code to determine its definiteness using a Gauss elimination-based approach. Use this code to determine if the Hessian obtained in the above question is positive definite or not.

Answer:

Hessian Matrix: [[-22, 12], [12, 26]] is Indefinite

A Python Code

A.1 Code for plotting of $f(x) = \frac{-0.1x}{(1+0.1x)(1+0.05x)}$ for $x \in [0, 30]$

```
#CL 603 - Optimization
  #Homework 1 - Problem 1
  #Priyam Nayak
  #214026014
  import numpy as np # Import the numpy library and assign it the name 'np'
  import matplotlib.pyplot as plt # Import the matplotlib.pyplot module and assign it the
     name 'plt'
 x = np.linspace(0,30,600) # Create an array of 600 evenly spaced values from 0 to 30
fx = -0.1*x/((1+0.1*x)*(1+0.05*x)) # Calculate the function values fx for each x, using
     the given mathematical expression
13
  plt.plot(x,fx,label=r'$f(x)_{u=u}frac{-0.1x}{(1+0.1x)(1+0.05x)}$') # Create a line plot of
14
     fx against x
  plt.title("Question-1_Plot") # Set the title of the plot
  plt.xlabel("x") # Set the label for the x-axis
16
 plt.ylabel("f(x)") # Set the label for the y-axis
18 plt.legend() #Create legend
 plt.savefig('Q1_Plot.png', dpi=300, bbox_inches='tight') #Save the plot as png file
plt.show() # Display the plot
```

A.2 Code for plotting of $f(x) = \cos^2(x) + 0.1x$ for $x \in [-5, 5]$

```
#CL 603 - Optimization
2 #Homework 1 - Problem 2
3 #Priyam Nayak
 #214026014
  import numpy as np # Import the numpy library and assign it the name 'np'
6
  import matplotlib.pyplot as plt # Import the matplotlib.pyplot module and assign it the
     name 'plt'
y = np.linspace(-5,5,1000) # Create an array of 1000 evenly spaced values from -5 to 5
  fx = np.cos(x)**2 + 0.1*x # Calculate the function values fx for each x, using the given
     mathematical expression
  plt.plot(x,fx,label=r'$f(x)=\cos^2(x)+0.1x$') # Create the plot of fx against x
12
  plt.title("Question-2_{\sqcup}Plot") # Set the title of the plot
13
  plt.xlabel("x") # Set the label for the x-axis
plt.ylabel("f(x)") # Set the label for the y-axis
plt.legend() #Create legend
17 plt.savefig('Q2_Plot.png', dpi=300, bbox_inches='tight') #Save the plot as png file
plt.show() # Display the plot
```

A.3 Code for plotting of $f(x) = (x_1^2 + x_2 - 11)^2 + (x_1^2 + x_2^2 - 7)^2$ for $x_i \in [-6, 6]$

```
#CL 603 - Optimization
2 #Homework 1 - Problem 3
3 #Priyam Nayak
4 #214026014
5
  import numpy as np # Import the numpy library and assign it the name 'np'
6
  import matplotlib.pyplot as plt # Import the matplotlib.pyplot module and assign it the
     name 'plt'
  # Define the function
  def f(x1, x2):
      return (x1**2 + x2 - 11)**2 + (x1 + x2**2 - 7)**2
11
# Generate the grid of values
^{14} x1 = np.linspace(-6, 6, 1000) # Create an array of 1000 evenly spaced values from -6 to 6
      for x1
```

```
x2 = np.linspace(-6, 6, 1000) # Create an array of 1000 evenly spaced values from -6 to 6
10 X1, X2 = np.meshgrid(x1, x2) # Create a meshgrid from x1 and x2 for plotting
Z = f(X1, X2) # Compute the function values over the grid
18
19 # Plot the contour
plt.figure(figsize=(8, 6)) # Create a new figure with a specific size
  contour = plt.contour(X1, X2, Z, levels=50, cmap='viridis') # Plot the contour with 50
21
     levels and 'viridis' colormap
  plt.clabel(contour, inline=True, fontsize=8, fmt="%.1f") # Display function values along
      contours
  plt.title('Q-3_Contour_Plot') # Set the title of the plot
 plt.xlabel('x1') # Set the label for the x-axis
24
  plt.ylabel('x2') # Set the label for the y-axis
#plt.legend() #Create legend
plt.savefig('Q3_Plot.png', dpi=300, bbox_inches='tight') #Save the plot as png file
28 plt.show() # Display the plot
```

A.4 Code for Computing Gradient and Hessian using Center Difference Formula

```
#CL 603 - Optimization
  #Homework 1 - Problem 4
  #Priyam Nayak
  #214026014
  import numpy as np # Import the numpy library and assign it the name 'np'
  # Define the function
  def f(x):
      return (x[0]**2 + x[1] - 11)**2 + (x[0] + x[1]**2 - 7)**2
11
# Gradient calculation using the center difference method
def gradient(f, x, h=1e-5):
      grad = np.zeros_like(x) # Initialize the gradient vector with zeros, same shape as x
14
      for i in range(len(x)): # Loop over each variable in x
          x_f = x.copy() # Create a copy of x to modify for forward difference
          x_b = x.copy() # Create a copy of x to modify for backward difference
17
          x_f[i] += h # Increment the i-th variable by h for forward difference
18
          x_b[i] -= h # Decrement the i-th variable by h for backward difference
19
          grad[i] = (f(x_f) - f(x_b)) / (2 * h) # Compute the central difference for the i
20
              -th variable
      return grad # Return the gradient vector
21
22
23
  # Hessian using center difference method
24
  def hessian(f, x, h=1e-5):
25
      n = len(x) # Determine the number of variables in x
26
      hess = np.zeros((n, n)) # Initialize the Hessian matrix with zeros, shape (n, n)
27
      for i in range(n): # Loop over each row index of the Hessian matrix
28
          for j in range(n): # Loop over each column index of the Hessian matrix
29
              x_ijpp = x.copy() # Create a copy of x to modify for both i and j
30
                  incremented
              x_{ijpp[i]} += h
              x_{ijpp[j]} += h
32
                                  # Create a copy of x to modify for i decremented and j
33
              x_{ijnp} = x.copy()
                  incremented
              x_{ijnp[i]} -= h
35
              x_{ijnp[j]} += h
36
              x_{ijpn} = x.copy()
                                  # Create a copy of x to modify for i incremented and j
                  decremented
              x_{ijpn[i]} += h
37
              x_{ijpn}[j] -= h
38
                                 # Create a copy of x to modify for both i and j
              x_{ijnn} = x.copy()
39
                  decremented
              x_ijnn[i] -= h
40
41
              x_{ijnn}[j] -= h
              hess[i, j] = (f(x_i)pp) - f(x_i)pp) - f(x_i)pp) + f(x_i)pn) / (4 * h**2)
                  Compute the second partial derivative for f with respect to x_i and x_j
      return hess # Return the Hessian matrix
43
44
45
```

```
x = np.array([1.0, 2.0]) # Test at point (1, 2)
48 grad_f = gradient(f, x)
49 hess_f = hessian(f, x)
#np.savetxt('Q4_Result.txt', grad_f, fmt='%.6f', header='Gradient Matrix:', comments='')
# Write results to a text file with rounded integers
  with open("Q4_Result.txt", "w") as file:
52
      file.write("Gradient_at_(1,_2):\n")
53
      file.write(np.array2string(np.round(grad_f).astype(int), separator=','))
54
       file.write("\nnHessian_{\square}at_{\square}(1,_{\square}2):\n")
5.5
      file.write(np.array2string(hess_f, separator=',__'))
print("Gradientuatu(1,u2):", np.round(grad_f).astype(int))
  print("Hessian_{\sqcup}at_{\sqcup}(1,_{\sqcup}2):\n", hess_{\perp}f)
```

A.5 Code to determine the Definiteness of a Symmetric Matrix using Gauss Elimination-based Approach

```
#CL 603 - Optimization
  #Homework 1 - Problem 5
  #Priyam Nayak
  #214026014
  import numpy as np # Import the numpy library and assign it the alias 'np'
  def to_ut(A): #Function to convert a symmetric matrix A to its upper triangular form
      using Gaussian elimination.
      A = A.astype(float) # Ensure the matrix is treated as floating-point
      n = A.shape[0] # Get the number of rows (and columns) in the matrix
      for i in range(n):
11
          # Perform row elimination to create zeros below the diagonal
12
          for j in range(i + 1, n):
               if A[i, i] == 0: # If the pivot element is zero, skip to avoid division by
14
                  zero
                   continue
               factor = A[j, i] / A[i, i] # Calculate the factor for row elimination
               A[j, i:] -= factor * A[i, i:] # Subtract the factor times the pivot row from
17
                   the current row
      return A
18
19
  def cons_dm(utm): # Function to construct a diagonal matrix from the pivot elements of
20
      the upper triangular matrix.
      n = utm.shape[0] # Get the number of rows (and columns)
21
      dm = np.zeros((n, n)) # Initialize an n x n zero matrix
22
      # Extract the diagonal elements (pivot elements) and place them in the diagonal
23
          matrix
      for i in range(n):
24
          dm[i, i] = utm[i, i]
25
      return dm
26
27
  def check_def(dm): # Function to check the definiteness of a matrix based on its pivot
28
      elements
      pivots = np.diag(dm) # Extract the diagonal elements (pivot elements)
29
      if all(p > 0 for p in pivots):
30
          return "Positive definite"
31
      elif all(p < 0 for p in pivots):</pre>
32
          return "Negative definite"
33
      elif all(p >= 0 for p in pivots):
34
          return "Positive⊔semi-definite"
35
      elif all(p <= 0 for p in pivots):</pre>
36
          return "Negative_semi-definite"
37
      else:
38
          return "Indefinite"
39
40
  # Hessian matrix from Q4
41
42
  Hessian = np.array([[-22, 12],
                       [12, 26]])
43
44
utm = to_ut(Hessian.copy()) # Convert to upper triangular matrix
do dm = cons_dm(utm) # Construct diagonal matrix using the pivot elements
```

```
definiteness = check_def(dm) # Check definiteness based on the diagonal matrix

with open("Q5_Result.txt", "w") as file:
    file.write("Hessian_Matrix:\n")
    file.write(np.array2string(Hessian, separator=',') +"\n")
    file.write(f"is_{definiteness}\n")

print("Hessian_Matrix_from_Q4:")
print(Hessian)
print(f"is_{definiteness}")
```