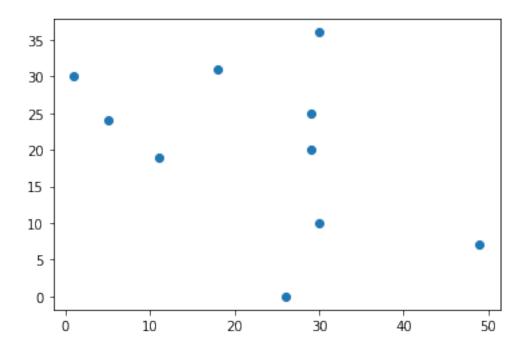
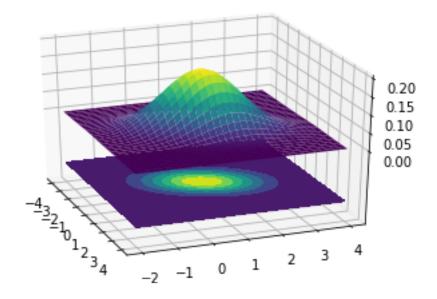
$Programming Solution_Sheet 2_Nayan Man Singh Pradhan$

February 23, 2021

```
[1]: ## Done By: Nayan Man Singh Pradhan
[2]: ## Importing
     import numpy as np
     import matplotlib.pyplot as plt
     from matplotlib import cm
     from mpl_toolkits.mplot3d import Axes3D
[3]: ## a)
     n = 10 ## number of random points
     x = np.random.randint(0, 50, n) ## generates n random integers between 0 and 50
     # print(x) ## test
     y = np.random.randint(0, 50, n) ## generates n ranodm integers between 0 and 50
     # print(y) ## test
     coordinates = tuple(zip(x,y))
     # print(coordinates) ## test
     plt.scatter(x, y) ## create scatter
     plt.show() ## plot scatter
```



```
[4]: ## b)
     ## define 2d distribution over X and Y
     N = 100 \#\# smoothning
     X = np.linspace(-4, 4, N)
     Y = np.linspace(-2, 4, N)
     X, Y = np.meshgrid(X, Y)
     ## mean matrix and sigma matrix
     mean_matrix = np.array([0,1]) ## making mean matrix
     sigma_matrix = np.array([[1, 0.25], [0.5, 1]]) ## making sigma matrix
     ## pack X and Y into single 3d array
     pos = np.empty(X.shape + (2,))
     pos[:, :, 0] = X
     pos[:, :, 1] = Y
     ## define function that calculates the gaussian function
     def twoD_Gaussian(pos, mean_matrix, sigma_matrix):
         shape = mean_matrix.shape[0]
         sigma_inv = np.linalg.inv(sigma_matrix) ## inverse of sigma matrix
         sigma_det = np.linalg.det(sigma_matrix) ## determinant of sigma matrix
         temp_denominator = np.sqrt((2*np.pi)**shape * sigma_det) ## temporary_
      \rightarrow denominator used later
         fac = np.einsum('...k,kl,...l->...', pos - mean_matrix, sigma_inv, pos -_{\sqcup}
      →mean_matrix)
```



[]: