



ESEIAAT



Escola Superior d'Enginyeries Industrials,  
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UNIVERSITAT POLITÈCNICA DE CATALUNYA

# Cubesat Constellation Astrea

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## Report

**Degree:** Aerospace Engineering

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**Students:**

Cebrián Galán, Joan

Foreman Campins, Lluís

Fuentes Muñoz, Óscar

Harrán Albelda, Fernando

Martínez Viol, Víctor

Pla Olea, Laura

Puig Ruiz, Josep

Tarroç Gil, Sergi

Urbano González, Eva María

Fontanes Molina, Pol

Fraixedas Lucea, Roger

González García, Sílvia

Kaloyanov Naydenov, Boyan

Morata Carranza, David

Pons Daza, Marina

Serra Moncunill, Josep Maria

Tió Malo, Xavier

**Customer:** Pérez Llera, Luís Manuel



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## Part I

# Communications

## Chapter 1

# Space Segment Protocol Stack

*"The wonder is, not that the field of  
stars is so vast, but that man has  
measured it."*

---

Anatole France, 1894

## 1.1 Introduction

Over this chapter, the **space communication protocols** are going to be defined. That is, a set of rules are going to be established in order to achieve the actual node-to-node communication. Although the scope of the chapter is limited to the space segment, this initial introduction on the protocol definition is useful for the ground segment. Having said that, several factors constrain the design of this relation of rules:

- **Speed:** As it has already been mentioned, each node should be capable of handling at least **25 Mbit/s**. Even though this doesn't mean that the design should be able to fit 25 Mbit/s of pure customer data, it is still a strong requirement with many effects over the system. For example, some protocols are just too slow establishing the connection; those will be directly discarded.
- **Reliability:** The protocols have to assure that the messages are going to arrive to their destination. In order to achieve this, a routing protocol has to be used as well.
- **Security:** Messages are not just required to arrive to their destination but they also must be ordered and coherent when they reach the client. That is the reason why error control is taken into consideration very seriously along the design process.

In the diagram 1.5.1, it can be clearly seen the structure of a protocol stack. Each layer has an underlying protocol, designed to achieve a specific task. There are **low-level** protocols, dealing with *hardware* or with the establishment of the *physical* path between two nodes. Also, there are the **high-level** protocols, dealing with session control, optimum *logical* paths generation and bridging the application layer with the physical layer.

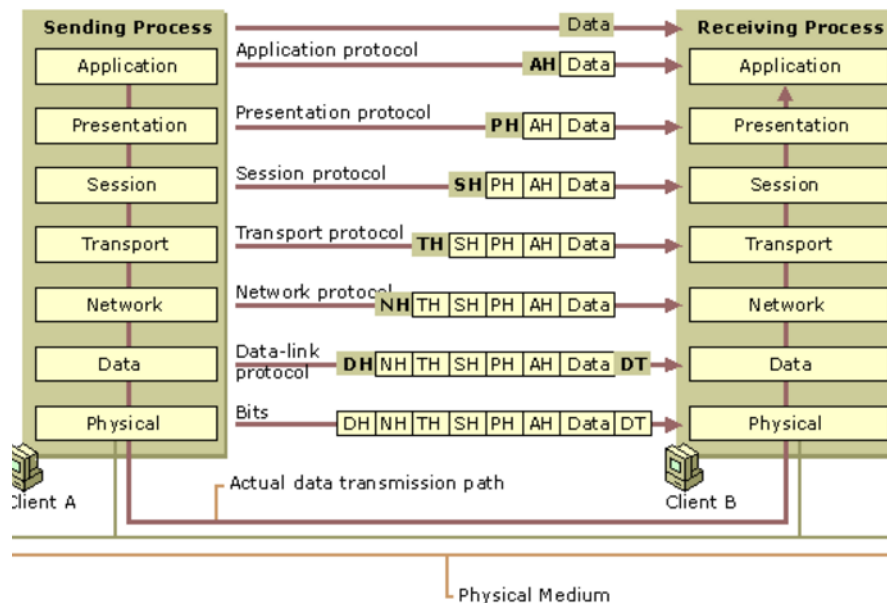


Figure 1.1.1: OSI Model layers

As it can be deduced, both the sending and the receiving node have to work in coordination. Also, each layer is designed with encapsulation in mind. Therefore, each layer does not depend on the others and develops its own task independently.

This philosophy has been started by the *International Telecommunications Unit* or **ITU** who first proposed, in the late 1970, the previously depicted **OSI Model**. Basically, it establishes a conceptual framework for when new protocols are to be designed. Each layer can be understood easily if one thinks as the act of sending mail by post, for instance.

As far as *Astrea constellation* is concerned, the physical layer is already defined in detail in the **Satellite Design** part. Since the **Data Link layer**, the **Network layer** and the **Transport/Session layer** are of vital importance for the communication to work, the aim of the next sections will be to define the protocol that the constellation will be using for each one of those layers.

The presentation and the application layer are more client oriented. In other words, if one client's satellite sends some data formatted with an unknown application protocol, *Astrea* will not be affected in any way. What *astrea* will do is add to this stream of bits, some headers, in order for the message to arrive in time to its destination. This methodology is undoubtedly positive for *Astrea* since the responsibility of the application data will be solely for the customer.

## 1.2 Layer 2: Data Link

### 1.2.1 Functions of the DLL

The Data-Link layer is the protocol layer in a program that handles the moving of data in and out across a physical link in a network. The Data-Link layer is layer 2 in the Open Systems Interconnect (OSI) model for a set of telecommunication protocols. According to the IEEE-802 LAN standards, the DLL can be divided into two sublayers:

- Logical Link Control (LLC): Deals with protocols, flow-control, and error control.
- Media Access Control (MAC): Deals with actual control of the media.

The DLL is responsible for converting data stream to signals bit by bit and to sent that over the underlying hardware. At the receiving end, DLL picks up data from hardware which are in the form of electrical signals, assembles them in a recognizable frame format, and hands over to upper layer. The DLL also ensures that an initial connection has been set up, divides output data into data frames, and handles the acknowledgements from a receiver that the data arrived successfully. It also ensures that incoming data has been received successfully by analyzing bit patterns at special places in the frames. The specific functions of the DLL are explained in the following lines.

- **Framing:** Data-link layer takes packets from Network Layer and encapsulates them into Frames. Then, it sends each frame bit-by-bit on the hardware. At receiver end, data link layer picks up signals from hardware and assembles them into frames.
- **Addressing:** Each device on a network has a unique number, usually called a hardware address or MAC address, that is used by the data link layer protocol to ensure that data intended for a specific machine gets to it properly.
- **Synchronization:** When data frames are sent on the link, both machines must be synchronized in order to transfer to take place.
- **Error control:** Sometimes signals may have encountered problem in transition and the bits are flipped. These errors are detected and attempted to recover actual data bits.
- **Flow control:** Stations on same link may have different speed or capacity. Data-link layer ensures flow control that enables both machine to exchange data on same speed.

### 1.2.2 Working procedure

In the previous section, the functions of the DLL have been determined. Now, the way it is achieved will be exposed. To do so, a list of possible protocols from the simplest one to the more complex will be explained. A ranking of the preferred working procedures will be done. All the images have been extracted from [1].

#### 1.2.2.1 Simplest Protocol

This protocol has no error or flow control. It is supposed that the frames are traveling only in one direction, from the sender to the receiver. It is also supposed that the receiver can immediately handle the frames received, so there is no overwhelming. The DLL of the sender site gets data from its network layer, makes a frame out of the data and sends it. The DLL at the receiver site receives a frame from its physical layer, extracts data from the frame and delivers the data to its network layer. The problem here is that the sender site cannot send a frame until its network layer has a data packet to send and the receiver site cannot deliver a data packet to its network layer until a frame arrives. There is the need to introduce the idea of events in the protocol. The procedure at the sender site is constantly running; there is no action until there is a request from the network layer. The procedure at the receiver site is also constantly running, but there is no action until notification from the physical layer arrives.

```
1 while (true)                                // Repeat forever
2 {
3     WaitForEvent()                           // Sleep until an event occurs
4     if(Event(RequestToSend))                 // There is a packet to send
5     {
6         GetData()
7         MakeFrame()
8         SendFrame()                           // Send the frame
9     }
10 }
```

Figure 1.2.1: Sender algorithm for the simplest protocol.

```

1 while(true)                                // Repeat forever
2 {
3   WaitForEvent()i                          // Sleep until an event occurs
4   if(Event(ArrivalNotification)»          //Data frame arrived
5   {
6     ReceiveFrame()i
7     ExtractData()i
8     DeliverData ()i                        //Deliver data to network layer
9   }
10 }

```

Figure 1.2.2: Receiver algorithm for the simplest protocol.

### 1.2.2.2 Stop-and-Wait Protocol

If data frames arrive at the receiver site faster than they can be processed, the frames must be stored until their use. Normally, the receiver does not have enough storage space, especially if it is receiving data from many sources. This may result in either the discarding of frames or denial of service. To prevent the receiver from becoming overwhelmed with frames, we somehow need to tell the sender to slow down. There must be feedback from the receiver to the sender.

In the Stop-and-Wait Protocol the sender sends one frame, stops until it receives confirmation from the receiver and then sends the next frame. We still have unidirectional communication for data frames, but auxiliary ACK frames (simple tokens of acknowledgment) travel from the other direction. We add flow control to our previous protocol. In this case the algorithms of the sender and the receiver are the following ones.

```

1 while (true)                                //Repeat forever
2 canSend = true                               //Allow the first frame to go
3 {
4   WaitForEvent()i                          // Sleep until an event occurs
5   if(Event(RequestToSend) AND canSend)
6   {
7     GetData() i
8     MakeFrame() f
9     SendFrame()i                          //Send the data frame
10    canSend = false;                       //cannot send until ACK arrives
11  }
12  WaitForEvent()i                          // Sleep until an event occurs
13  if(Event(ArrivalNotification) // An ACK has arrived
14  {
15    ReceiveFrame();                        //Receive the ACK frame
16    canSend = true;
17  }
18 }

```

Figure 1.2.3: Sender algorithm for the Stop-and-Wait Protocol.

1	while (true)	<i>II Repeat forever</i>
2	{	
3	WaitForEvent();	<i>II Sleep until an event occurs</i>
4	if(Event(ArrivalNotification))	<i>II Data frame arrives</i>
5	{	
6	ReceiveFrame();	
7	ExtractData();	
8	Deliver(data);	<i>II Deliver data to network layer</i>
9	SendFrame();	<i>II Send an ACK frame</i>
10	}	
11	}	

Figure 1.2.4: Receiver algorithm for the Stop-and-Wait Protocol.

The two protocols explained are protocols that can be suitable for noiseless channels. However, noiseless channels are nonexistent. There is a need to add error control to the protocol. Three protocols are discussed with the aim of doing so.

### 1.2.2.3 Stop-and-Wait Automatic Repeat Request

The Stop-and-Wait ARQ adds a simple error control mechanism to the Stop-and-Wait Protocol. To detect and correct corrupted frames, we need to add redundancy bits to our data frame. When the frame arrives at the receiver site, it is checked and if it is corrupted, it is silently discarded. The detection of errors in this protocol is manifested by the silence of the receiver. Frames are also numbered so if the receiver receives a data frame that is out of order, this means that frames were either lost or duplicated. What is done to solve the error is that when the sender sends a frame, it keeps a copy of the sent frame. At the same time, it starts a timer. If the timer expires and there is no ACK for the sent frame, the frame is resent, the copy is held, and the timer is restarted. Since the protocol uses the stop-and-wait mechanism, there is only one specific frame that needs an ACK even though several copies of the same frame can be in the network. Since an ACK frame can also be corrupted and lost, it too needs redundancy bits and a sequence number. In the following figure is possible to see more clearly what is going on with this protocol.



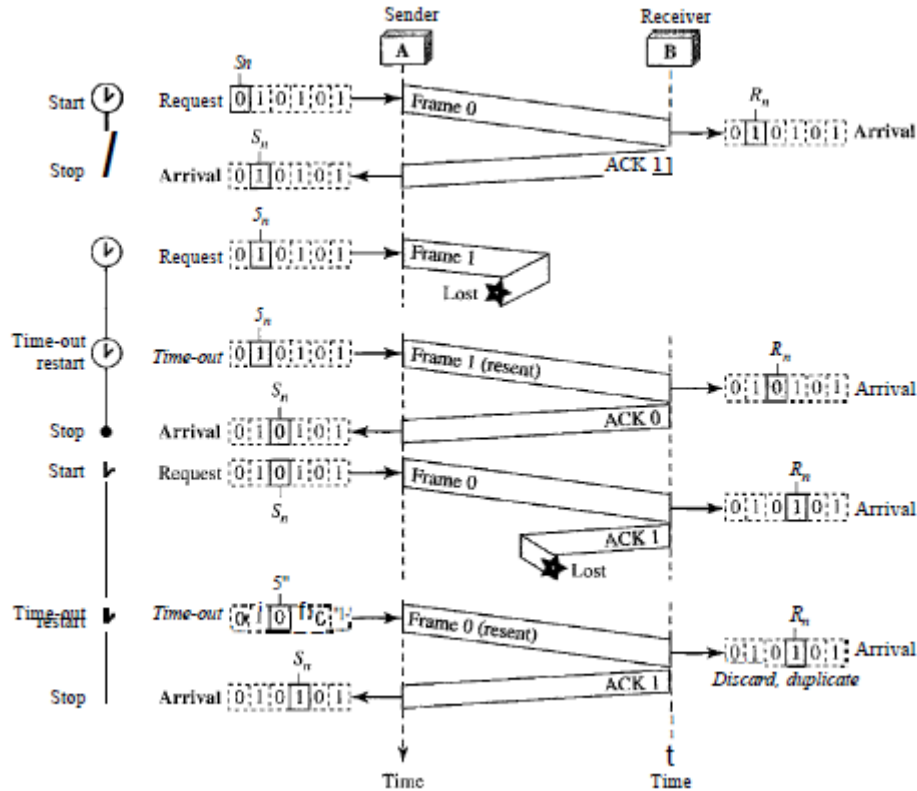


Figure 1.2.5: Flow diagram of the Stop-and Wait ARQ.

The main problem of this protocol is its efficiency. The Stop-and-Wait ARQ is very inefficient if our channel is thick and long. The product of thickness and longitude is called the bandwidth-delay product. We can think of the channel as a pipe. The bandwidth-delay product then is the volume of the pipe in bits. The pipe is always there. If we do not use it, we are inefficient.

#### 1.2.2.4 Go-Back-N Automatic Repeat Request

To improve the efficiency of transmission (filling the pipe), multiple frames must be in transition while waiting for acknowledgment. In other words, we need to let more than one frame be outstanding to keep the channel busy while the sender is waiting for acknowledgment. In the Go-Back-N Automatic Repeat Request the sender sends several frames before receiving acknowledgments. It also keeps a copy of these frames until the acknowledgments arrive. Although there can be a timer for each frame that is sent, in this protocol only one is used. The reason is that the timer for the first outstanding frame always expires first and then all outstanding frames when this timer expires are sent again. The receiver sends a positive acknowledgment if a frame has arrived safe and sound and

## Layer 2: Data Link

in order. If a frame is damaged or is received out of order, the receiver is silent and will discard all subsequent frames until it receives the one it is expecting. The silence of the receiver causes the timer of the unacknowledged frame at the sender site to expire. This, in turn, causes the sender to go back and resend all frames, beginning with the one with the expired timer. The receiver does not have to acknowledge each frame received. It can send one cumulative acknowledgment for several frames. That is the reason why the protocol is called Go-Back-N. The flow diagram and the algorithms of the sender and the receiver are shown next.

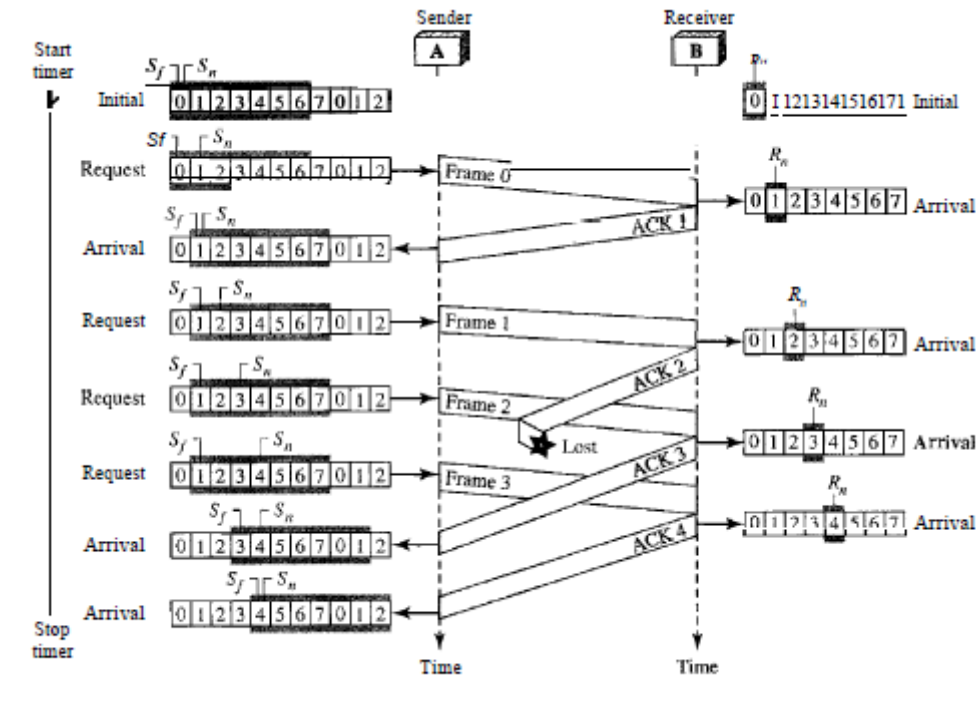


Figure 1.2.6: Flow diagram of the Go-Back-N ARQ.

```

1   $R_n = 0;$ 
2
3  while (true)                                II Repeat forever
4  {
5      WaitForEvent();
6
7      if(Event{ArrivalNotification}» /Data frame arrives
8      (
9          Receive(Frame);
10         if(corrupted(Frame)»
11             Sleep();
12         if(seqNo ==  $R_n$ )                III If expected frame
13         {
14             DeliverData()i             IID Deliver data
15              $R_n = R_n + 1;$              IISlide window
16             SendACK( $R_n$ );
17         }
18     }
19 }
```

Figure 1.2.7: Receiver algorithm for the Go-Back-N ARQ.

```

1 Sw = 232 - 1;
2 Sf = 0;
3 Sn = 0;
4
5 while (true)                                //Repeat forever
6 {
7   WaitForEvent();
8   if(Event{RequestToSend})                  //A packet to send
9   {
10    if(Sn-Sf == Sw)                          //If window is full
11      Sleep();
12    GetData();
13    MakeFrame(Sn);
14    StoreFrame(Sn);
15    SendFrame(Sn);
16    Sn = Sn + 1;
17    if(timer not running)
18      StartTimer();
19  }
20
21  if(Event{ArrivalNotification})             //ACK arrives
22  {
23    Receive(ACK);
24    if(corrupted{ACK})
25      Sleep();
26    if((ackNo==sf)&&(ackNo==Sn))              //If a valid ACK
27      While(Sf == ackNo)
28      {
29        PurgeFrame(Sf);
30        Sf = Sf + 1;
31      }
32    StopTimer();
33  }
34
35  if(Event{TimeOut})                          //If the timer expires
36  {
37    StartTimer();
38    Temp = Sf;
39    while(Temp < Sn);
40    {
41      SendFrame(Sf);
42      Sf = Sf + 1;
43    }
44  }
45 }

```

Figure 1.2.8: Sender algorithm for the Go-Back-N ARQ.

### 1.2.2.5 Selective Repeat Automatic Repeat Request

Go-Back-N ARQ simplifies the process at the receiver site. The receiver keeps track of only one variable, and there is no need to buffer out-of-order frames; they are simply discarded. However, this protocol is very inefficient for a noisy link. In a noisy link a frame has a higher probability of damage, which means the resending of multiple frames. In the case of these protocol, the Selective Repeat ARQ, the processing at the receiver is more complex but is more efficient for noisy links. The Selective Repeat Protocol allows a number of frames to arrive out of order and be kept until there is a set of in-order frames to be delivered to the network layer. The handling of the request event is similar to that of the previous protocol except that one timer is started for each frame sent. The arrival event is more complicated here. An ACK or a NAK frame may arrive. If a valid NAK frame arrives, the corresponding frame is resent. If a valid ACK arrives the corresponding timer stops. When the time for a frame has expire, only this frame is resent.

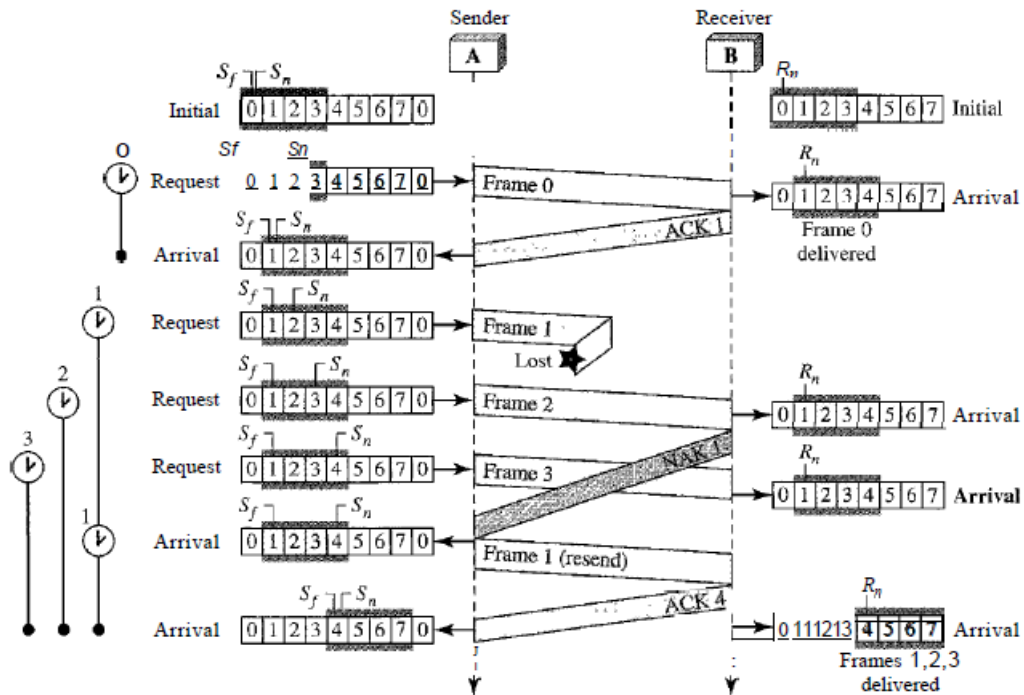


Figure 1.2.9: Flow diagram of the Selective Repeat ARQ.

```

1  =  $2^{m-1} - i$ 
2  =  $O_i$ 
3  =  $O_i$ 
4
5  hile (true)                //Repeat forever
6  {
7      WaitForEvent(i)
8      if(Event(RequestToSend)) //There is a packet to sen
9      {

```

```

10   if(Sn-S;E >= Sw)           I/If window is full
11       Sleep();
12   GetData();
13   MakeFrame(Sn);
14   StoreFrame(Sn);
15   SendFrame(Sn);
16   Sn = Sn + 1;
17   StartTimer(Sn);
18   }
19
20   if(Event{ArrivalNotification» IIACK arrives
21   {
22       Receive{frame};          I/Receive ACK or NAK
23       if{corrupted{frame»
24           Sleep();
25       if (FrameType == NAK)
26           if (nakNo between Sf and So)
27           {
28               resend(nakNo);
29               StartTimer(nakNo);
30           }
31       if (FrameType == ACK)
32           if (ackNo between Sf and So)
33           {
34               while(sf < ackNo)
35               {
36                   Purge(sf);
37                   stopTimer(Sf);
38                   Sf = Sf + 1;
39               }
40           }
41   }
42
43   if(Event{TimeOut{t»}         liThe timer expires
44   {
45       StartTimer(t);
46       SendFrame{t};
47   }
48   }

```

Figure 1.2.10: Sender algorithm for the Selective Repeat ARQ.

```

1  Rn = 0;
2  NakSent = false;
3  AckNeeded = false;
4  Repeat(for all slots)
5      Marked(slot) = false;
6
7  !while (true)                                IIRepeat forever
8  {
9      WaitForEvent();
10
11     if{Event{ArrivalNotification»           jData frame arrives
12     {
13         Receive(Frame);
14         if(corrupted(Frame)&& (NOT NakSent)
15         {
16             SendNAK(Rn);
17             NakSent = true;
18             Sleep();
19         }
20         if(seqNo <> Rn)&& (NOT NakSent)
21         {
22             SendNAK(Rn);
23             NakSent = true;
24             if ((seqNo in window)&&(IMarked(seqNo)
25             {
26                 StoreFrame{seqNo)
27                 Marked(seqNo)= true;
28                 while(Marked(Rn)
29                 {
30                     DeliverData(Rn);
31                     Purge(Rn);
32                     Rn = Rn + 1;
33                     AckNeeded = true;
34                 }
35                 if(AckNeeded);
36                 {
37                     SendAck(Rn);
38                     AckNeeded = false;
39                     NakSent = false;
40                 }
41             }
42         }
43     }
44 }

```

Figure 1.2.11: Receiver algorithm for the Selective Repeat ARQ.

### 1.2.2.6 Bidirectional links: Piggybacking

Piggybacking is not a protocol, is a technique. All que protocols explained until now are all unidirectional: data frames flow in only one direction although control information such as ACK and NAK frames can travel in the other direction. In real life, data frames are normally flowing in both directions: from node A to node B and from node B to node A. This means that the control information also needs to flow in both directions. Piggybacking is used to improve the efficiency of the bidirectional protocols. When a frame is carrying data from A to B, it can also carry control information about arrived (or lost)

frames from B; when a frame is carrying data from B to A, it can also carry control information about the arrived (or lost) frames from A.

#### **1.2.2.7 Working procedure ranking**

Now its time to choose the working procedure that best fits the needs of the mission. To do so, an OWA (Ordered Weighted Average) will be used. The criteria to consider is the following one:

- Efficiency: This fact deals with how the channel is being used. Protocols will be classified as non-efficient or efficient.
- Time: This fact deals about the time needed to transmit the data satisfactory.
- Error correction: Deals about whether a protocol can correct an error of transmission or not.

It is important also to take into account that the protocol to use should have a flow control, that is, should know if the receiver is available or not to receive the data. For this reason the Simplest Protocol is rejected and won't be studied in the OWA. Regarding the factors of the OWA, all of them will be rated from 0 to 1. In this project the fact of transmitting the data without errors is more important than transmitting it fast, as is possible to appreciate un the project charter ( the latency can be relative high, but incorrect information is useless). The efficiency of the protocol is very important too, because the less the efficiency the less power provided by the CubeSat is being used. Since the CubeSat has limited space, ideally al the power it can gives for transmission will be used for it. Then, the weights of the different factors are the following ones:

- Efficiency: 40
- Time: 30
- Error correction: 60

In the following table the rating of each protocol together with the corresponding OWA is shown.



Protocol	Efficiency	Time	Error correction	OWA
Stop-and-Wait Protocol	0	0	0	0
Stop-and-Wait ARQ	0	0	1	0,46
Go-Back-N ARQ	1	0	1	0.69
Selective Repeat ARQ	1	1	1	1

Table 1.2.1: OWA of the DLL protocols.

Then, the ranking of working procedures is the following one:

<b>1</b>	Selective Repeat ARQ
<b>2</b>	Go-Back-N ARQ
<b>3</b>	Stop-and-Wait ARQ
<b>4</b>	Stop-and-Wait Protocol

Table 1.2.2: Ranking of working procedures

It has to be said that when dealing with bidirecional links piggybacking technique will be used if possible.

### 1.2.3 Protocols

The standards of the CCSDS will be followed in order to allow interoperability with other satellites such as the one of the client. The CCSDS has developed four protocols for the Data Link Protocol Sublayer of the Data Link Layer [2]:

- TM Space Data Link Protocol
- TC Space Data Link Protocol
- AOS Space Data Link Protocol
- Proximity-1 Space Link Protocol-Data Link Layer

These protocols provide the capability to send data over a single space link. TM, TC, and AOS can have secured user data into a frame using the Space Data Link Security (SDLS) Protocol.

CCSDS has also developed three standards for the Synchronization and Channel Coding Sublayer of the DLL:

- TM Synchronization and Channel Coding

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- TC Synchronization and Channel Coding
- Proximity-1 Space Link Protocol—Coding and Synchronization Layer

TM Synchronization and Channel Coding is used with the TM or AOS Space Data Link Protocol, TC Synchronization and Channel Coding is used with the TC Space Data Link Protocol and the Proximity-1 Space Link Protocol—Coding and Synchronization Layer is used with the Proximity-1 Space Link Protocol—Data Link Layer. This can be seen better in the following image.

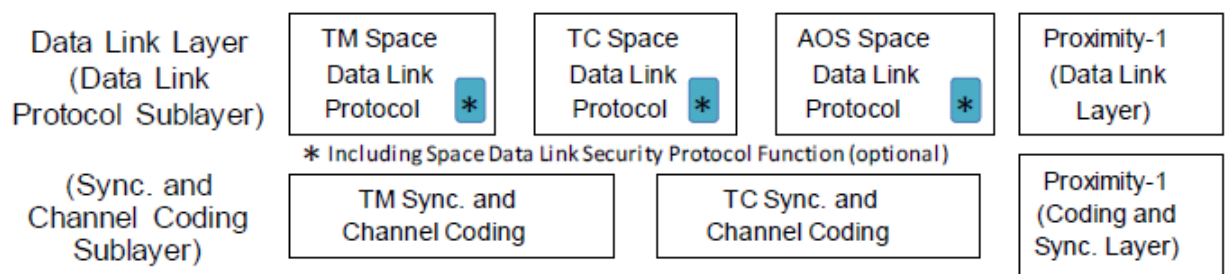


Figure 1.2.12: DLL of the CCSDS.

Now the reliability of each of the protocols of the Data Link Protocol Sublayer will be compared in order to know which one is the best of them. This will be done because reliability is the most important feature of the DLL.

Protocol	System used for reliability
TM	Stop-and-Wait Protocol
TC	Type-A: Go-Back-N ARQ, Type-B: Stop-and-Wait Protocol
AOS	Stop-and-Wait Protocol
Proximity-1	Go-Back-N ARQ

Table 1.2.3: Reliability of CCSDS protocols

According to the table and to the ranking of working procedures done previously, only TC Type-A and Proximity-1 will be considered from now on. Security is another important feature to take into account when taking this decision. TM Space Data Link Protocol has provision for inserting secured data into a frame using the Space Data Link Security (SDLS) Protocol. However, there have been no security requirements to date established for Proximity-1. The SLDS protocol can provide security services, such as authentication and confidentiality for TC Transfer Frames (it can also do it with TM and AOS, that have been previously discarded). Both the TC and the Proximity-1 use variable-length

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Transfer Frames to facilitate reception of short messages with short delay. Another key feature to take into account when deciding a protocol, is the concept of "Virtual Channels". The Virtual Channel facility allows one Physical Channel (a stream of bits transferred over a space link in a single direction) to be shared among multiple higher-layer data streams, each of which may have different service requirements. A single Physical Channel may therefore be divided into several separate logical data channels, each known as a Virtual Channel (VC). The TC has the following identifiers: the Transfer Frame Version Number (TFVN), the Spacecraft Identifier (SCID), and the Virtual Channel Identifier (VCID). It also uses an optional identifier, called the Multiplexer Access Point Identifier (MAP ID), that is used to create multiple streams of data within a Virtual Channel. In contrast, the Proximity-1 uses a triad of multiplexing capabilities, which is incorporated for specific functionality within the link. The Spacecraft Identifier (SCID) identifies the source or destination of Transfer Frames transported in the link connection based upon the Source-or-Destination Identifier. The Physical Channel Identifier (PCID) provides up to two independently multiplexed channels. The Port ID provides the means to route user data internally to specific logic ports, such as applications or transport processes, or to physical ports, such as onboard buses or physical connections. Now a table with the identifiers of the TC and the Proximity-1 will be shown:

Identifiers	TC Space Data Link Protocol	Proximity-1 Space Link Protocol- Data Link Layer
TFVN	00	10
SCID	0 to 1023	0 to 2013
PCID	N/A	0 to 1
VCID	0 to 63	N/A
MAP ID	0 to 63	N/A
Port identifier	N/A	0 to 7

Table 1.2.4: Identifiers of TC and Proximity-1 Space Data Link Layer Protocols

Having Virtual Channels is important for the mission that is exposed in this project because it allows having more than one stream of bits to take place at the same time, that is to say that more than one client can communicate with their satellite without having to wait for another client to finish.

The decision taken is to use the TC Space Data Link Protocol with the TC sync. and channel coding together with the Space Data Link Security Protocol. The reasons for doing so are mainly:

- Security: Incorporating the SLDS authentication and confidentiality is provided.
- More virtual channels: This feature allow more clients communicating with their satellites at the same time.

### 1.2.4 TC Space Data Link Protocol

Now some specifications of the chosen protocol will be exposed in order to know how it is structured and how many bits it adds to the original data. Further information of the protocol can be found in [3]. The protocol specifications will be explained when it is used with the support of the SDLS protocol. In this section is important to know that 1 octet is an eight-bit word. The structure of the transfer frame in this protocol is the following one:

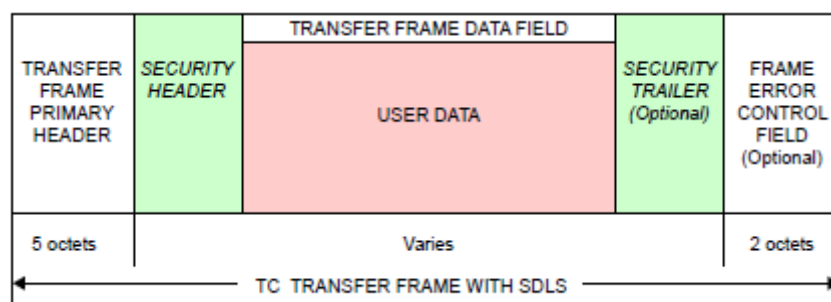


Figure 1.2.13: Transfer frame structure of the TC Space DL Protocol with SDLS.

In the transfer frame primary header, the following information is contained:

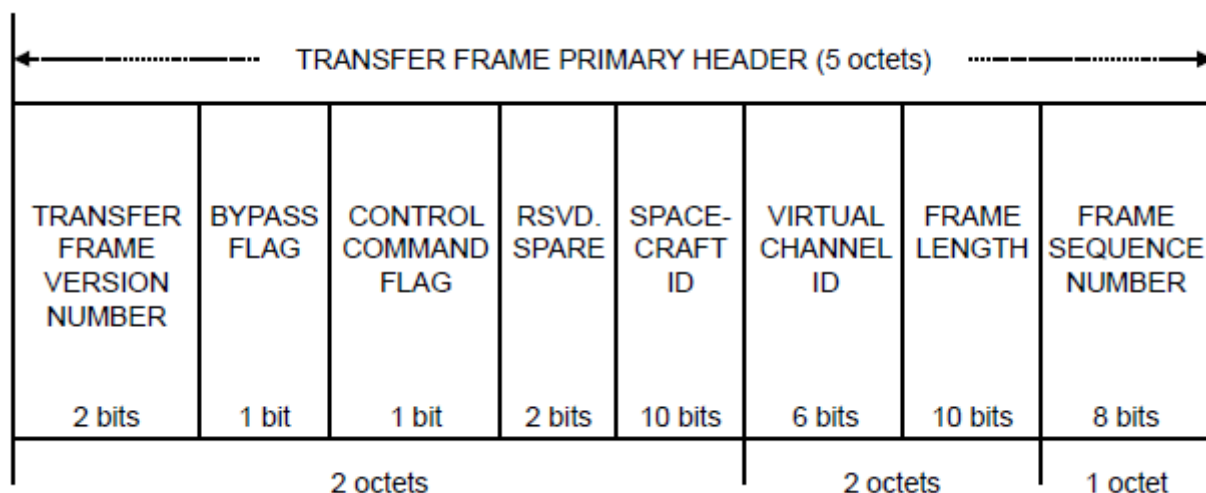


Figure 1.2.14: Transfer frame primary header.

With this data, is possible to say that the TC Space Data Link Protocol will add to data coming from the Network layer at least 5 octets (40 bits).

### 1.2.5 TC Sync and Channel Coding

This protocol is the corresponding to the Synchronization and Channel Coding Sublayer that has been used with the TC Space and Data Link Protocol. It has functions as for example, encapsulate the data units so that the start and end can be detected by the receiving end, ensure there are sufficient bit transitions in the transmitted bit stream so that the receiver can maintain bit synchronization during the reception of the data unit, etc. In a nutshell, one instance of the Synchronization and Channel Coding Sublayer processes the data stream for a single Physical Channel, making it a stream of bits that can be transferred over a space link in a single direction. The procedures can be differentiated between the ones that occur in the sending end and the one that occur in the receiving end. The procedures are the following ones:

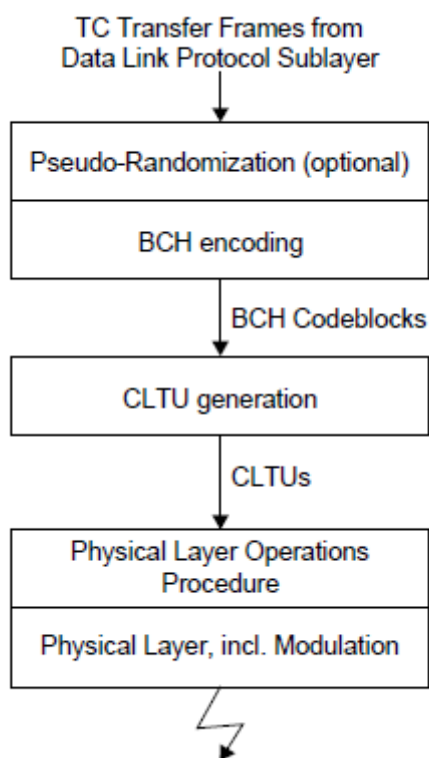


Figure 1.2.15: Procedure at the sending end.

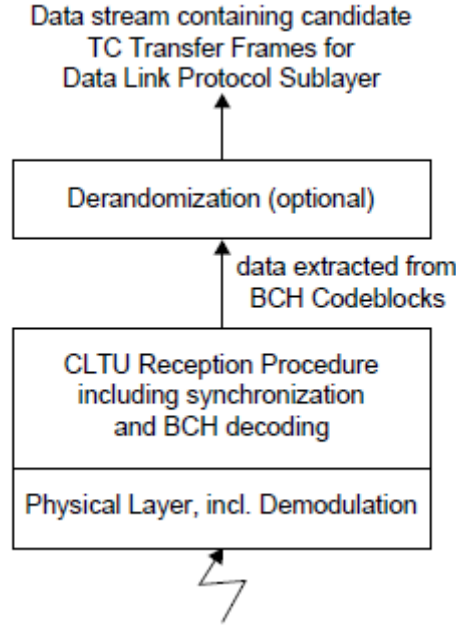


Figure 1.2.16: Procedure at the receiving end.

Is possible to see that two packets of data are created, BCH Codeblocks and CLTUs. From the point of view of the Synchronization and Channel Coding Sublayer, the content of the Frames parameter is a single block of data. For a single Channel Access request, the Synchronization and Channel Coding Sublayer generates a set of BCH Codeblocks, and that set of BCH Codeblocks is placed in a single CLTU. One of the managed parameters for the Physical Channel is the maximum length of a CLTU. The length of the CLTU can be calculated as follows (in octets):

$$LengthoftheCLTU = 10 + 8 \cdot \left( \frac{Totallengthoftheframes + 6}{7} \right) \quad (1.2.1)$$

Since with the TC Space Data Link protocol the frames can have different sizes, the CLTU can also have different sizes. More information about this sublayer of the DLL can be found in reference [4]

## 1.3 Layer 3: The Network

### 1.3.1 Functions of the Network Layer

According to [5], the Network layer is the third layer in the Open Systems Interconnection (OSI) model. It is located above the Data link layer and below the Transport layer. This layer is used for transmitting data sequences called datagrams between a sender and a receiver that may not be directly connected through only one link. The Network layer provides the following functions:

- **Routing:** Selects the best path between two nodes in a network, often using intermediate nodes called routers.
- **Network flow control:** Routers may indicate a transmitting node to reduce its transmission when the router's buffer becomes full.
- **Package fragmentation:** If the message to be transmitted is too large to be transmitted in the Data link layer, the network may split it into several packages in one node, send them independently and reassemble them in another node. Optionally, it can provide error control.
- **Logical-physical address allocation:** Translates the logical address (or names) of the network nodes into a unique physical address.
- **Message forwarding:** A network may be divided into subnetworks, connected through specialized hosts, called gateways or routers, that forward packets between those subnetworks.

### 1.3.2 Protocols

The Consultative Committee for Space Data Systems (CCSDS) [6] has two standards for using in the Network layer in conjunction with the Space Data Link Layer Protocols recommended by the CCSDS. Those two standards are the Space Packet Protocol (SPP) [7] and the Encapsulation Service [8]. With the Space Packet Protocol, application processes generate and consume Protocol Data Units (PDU). The Encapsulation Service encapsulates PDU of recognized protocols defined in a Space Assigned Number Authority (SANA) [9] registry into two types of packets, either Space Packets or Encapsulation Packets. External protocols data units, such as the Internet Protocol datagrams, can be transmitted by CCSDS Space Data Link Protocols, although they cannot be directly encapsulated by the Encapsulation Service, and an intermediate service, such as IP over CCSDS (IPoC) [10], must be used.

### Layer 3: The Network

Figure 1.3.1, shows the recommended protocols by the CCSDS for Space Communications. In Figure 1.3.2 those protocols are arranged in some possible combinations. As it can be seen, IP cannot be directly used neither by the protocols in the Data Link layer nor the Encapsulation Service.

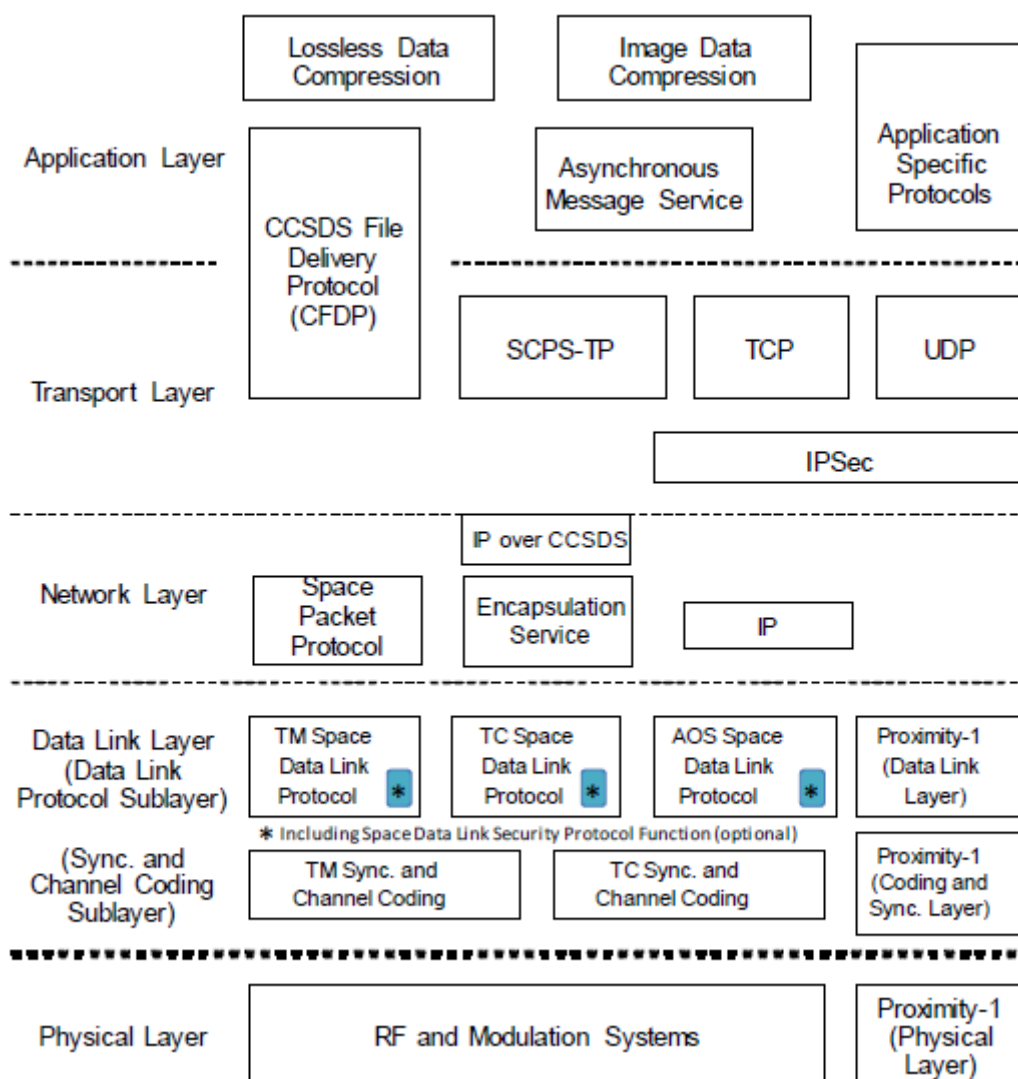
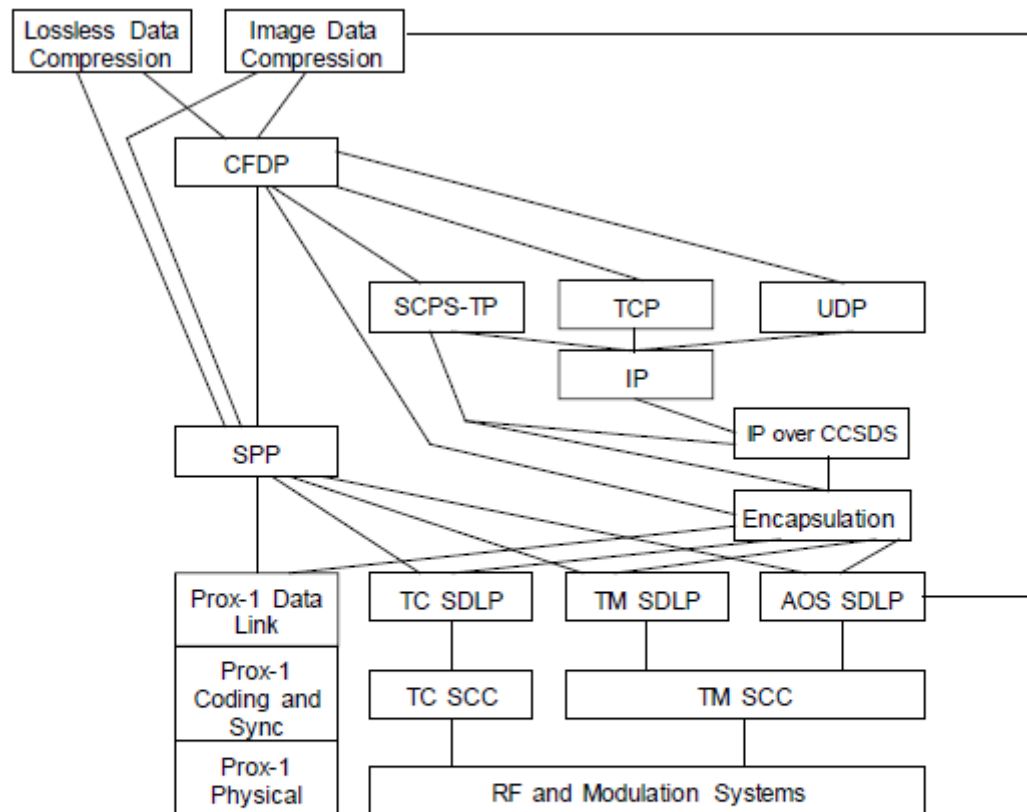


Figure 1.3.1: Protocols recommended by the CCSDS, classified in their respective OSI layers. Extracted from [6].





SCPS-SP and IPsec can be used between the Transport and Network layers in any combination of protocols.

SPP = Space Packet Protocol

SDLP = Space Data Link Protocol & Space Data Link Security (opt.)

SCC = Synchronization and Channel Coding

Figure 1.3.2: Possible Combinations of the CCSDS recommended protocols. Extracted from [6].

Protocols in the Network Layer can be classified according if they are the main protocol (SPP or IP, for example) or they provide additional features so that the main protocol can work efficiently. An example of the latter are routing protocols, and also for IP, IPoC and Encapsulation Service.

In the following pages, a brief review of distinct protocols on the Network layer will take place. Since CCSDS recommends using SPP or Encapsulation Service, only SPP and protocols that can be encapsulated by the Encapsulation Service, either directly or indirectly, will be reviewed. The protocols reviewed will be classified according if they are the main protocol, auxiliary protocols, or routing protocols.

### 1.3.2.1 Main protocols

#### Space Packet Protocol (SPP) [7]

The Space Packet Protocol (SPP) is a protocol designed to efficiently transfer application data over a network of space links. SPP provides a unidirectional data transfer service from a single source user application to one or more destination user applications through one or more subnetworks. The path from the source user application to the destination user application is called a Logical Data Path (LDP). Every LDP is uniquely identified by a Path Identifier (Path ID). The protocol data unit used by this protocol is the Space Packet. Each Space Packet is defined by a header section and a data section.

Each LPD is uniquely identified by a Path ID. A Path ID consists of an Application Process Identifier (APID) and an optional APID Qualifier. APID Qualifiers identify the naming domain for an APID. APIDs are unique in a single naming domain. The APID is part of the header of the Space Packet, but the APID Qualifier must be carried by a protocol of an underlying layer.

The following features are common to the services of the SPP:

- **Pre-configured Services.** The user can send or receive data only through a preconfigured LDP established by management.
- **Unidirectional Services.** One end of an LDP can send, but not receive, data through the LDP, while the other end can receive, but not send. This means A can send to B through a LPD, but for B to send to A has to use a different LDP
- **Asynchronous Services.** There are no predefined timing rules for the transfer of service data units supplied by the service user. The user may request data transfer at any time it desires, but there may be restrictions imposed by the provider on the data generation rate.
- **Unconfirmed Services.** The sending user does not receive confirmation from the receiving end that data has been received.
- **Incomplete Services.** The services do not guarantee completeness, nor do they provide a retransmission mechanism.
- **Non-sequence Preserving Services.** The sequence of service data units supplied by the sending user may not be preserved through the LDP.

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The following services are assumed from the underlying layers:

- Addressing and routing capabilities for establishing LDPs
- Capability for associating an APID Qualifier for each Space Packet.

The structure of a Space Packet consists of a Packet Primary Header, and a Packet Data Field, which can contain an optional Secondary Header. Figure 1.3.3 shows the structure of the SPP primary header:

Offsets	Octet	0								1							
Octet	Bit	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
0	0	Packet Version Number			Packet Type	Secondary Header Flag	Application Process Identifier (APID)										
4	32	Sequence Flags		Packet Sequence Count or Packet Name													
8	64	Packet Data Length															

Figure 1.3.3: Example of a header for an SPP Space Packet.

## Internet Protocol version 4 (IPv4) [11]

The Internet Protocol version 4 (IPv4) is the fourth version of the Internet Protocol (IP). It is one of the core protocols of standards-based internetworking methods in the Internet. Despite the ongoing deployment of a successor protocol (IPv6), the IPv4 still routes most of the Internet traffic. IPv4 is a connectionless protocol and does not guarantee delivery, nor does it assure proper sequencing or avoidance of duplicate delivery. These aspects are addressed by a transport layer protocol.

One of the features of IPv4 are addresses. Network addresses are the identification number of any device that is part of a network. IPv4 uses 32-bit (4 byte) addresses. Therefore, the address space is limited to 4294967296 ( $2^{32}$ ) addresses. A IPv4 address is usually represented in two ways: in binary notation, where each group of 8 bits is separated by a dot, or in decimal notation, where each 8-bit binary number is translated to decimal, as it can be seen in Table 1.3.1.

IP address	10101100000100001111111000000001
Dot-binary notation	10101100.00010000.11111110.00000001
Dot-decimal notation	172.16.254.1

Table 1.3.1: IP address notation in dot-decimal and dot-binary.

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Packets in the IPv4 consist of a header section and a data section. There is no footer at the end of the data section since the protocols in the data link layer and the transport layer provide error correction controls. Headers in a IPv4 packet contain 14 fields, one of them being optional. The fields are packed with the most significant byte first, and the most significant bit is also the first. Headers have a length between 20 and 60 bytes. The data section comes after the header, and its format depends on the protocol used (for example, ICMP, IGMP, TCP, etc.). Figure 1.3.4 shows the structure of a IPv4 header.

Offsets	Octet	0								1								2								3							
Octet	Bit	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31
0	0	Version				IHL				DSCP				ECN				Total Length															
4	32	Identification																Flags				Fragment Offset											
8	64	Time to Live								Protocol								Header Checksum															
12	96																	Source IP Address															
16	128																	Destination IP Address															
20	160	Options (if IHL>5)																															
24	192																																
28	224																																
32	256																																

Figure 1.3.4: Example of a header for an IPv4 packet. In this case, it has a length of 36 bytes.

IPv4 provides fragmentation of packets. If size of the packet is bigger than the maximum transmission unit (MTU) of the destination, and the message allow fragmentation (the option of Do not Fragment in the header of the packet is set to 0) the transmitting router will divide the packet in fragments smaller than the MTU.

## Internet Protocol version 6 (IPv6) [12]

The Internet Protocol version 6 (IPv6) is the most recent version of the Internet Protocol, developed to solve the problem of the exhaustion of IP addresses of the IPv4. IPv6 is intended to replace IPv4. The new features of the IPv6 compared of those of the IPv4 are the following:

- Larger adress space: The length of IPv6 addresses is 128 bits, which is four times the length of IPv4 addresses. It offers a capacity of  $2^{128}$  addresses.
- Multicasting: IPv6 acomplishes multicasting without using other protocols (such as IGMP for IPv4)
- Stateless address autoconfiguration (SLAAC): IPv6 hosts can configure themselves automatically when they are connected to a IPv6 network using the Neighbor Discovery Protocol via Internet Control Message Protocol version 6 (ICMPv6) router discovery messages. When a host is connectes for the first time, it sends a link-local router solicitation multicast request for its configuration parameters. Then, routers

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respond to the request with a router advertisement packet that contains Internet Layer configuration parameters.

- Network-layer security: Internet Protocol Security was developed for IPv6 before it was adapted for IPv4.
- Simplified processing by routers: Packet headers and the process of packet forwarding have been simplified, so packet processing by routers is more efficient. Headers now have a fixed length of 40 bytes, and may have an optional section aimed for options between the header section and the data section. Figure 1.3.5 shows the structure of a IPv6 header. IPv6 routers do not perform fragmentation.
- Mobility: Mobile IPv6 avoids triangular routing (unlike IPv4) and is as efficient as native IPv6.
- Options extensibility: IPv6 headers have a structure capable of extending the protocol in the future without affecting the core packet structure.
- Jumbograms: IPv4 limits packets to  $(2^{\text{power } 16}) - 1$  octets per payload. A IPv6 node can handle packets of  $(2^{\text{power } 32}) - 1$  octets (called jumbograms).

Offsets	Octet	0								1								2								3							
Octet	Bit	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31
0	0	Version				Traffic Class								Flow Label																			
4	32	Payload Length																Next Header								Hop Limit							
8	64	Source Address																															
12	96																																
16	128																																
20	160																																
24	192	Destination Address																															
28	224																																
32	256																																
36	288																																

Figure 1.3.5: Example of a header for an IPv6 packet.

### 1.3.2.2 Auxiliary protocols

#### Encapsulation service [8]

The Encapsulation Service is a service used to transfer data units that can not be directly transferred by the CCSDS Space Data Link Protocols. In order to be directly transferred by a Space Data Link Protocol, a data unit must have a Packet Version Number authorized by the CCSDS (a list of PVN authorized by CCSDS is contained in [13]). With the Encapsulation Service, data units that do not have an authorized VPN can be transmitted with Space Data Link Protocols. The data unit to be transmitted must be of an integral number of octets.

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A user of the Encapsulation Service is identified by the combination of the following:

- A Packet Version Number (PVN) that indicates whether Space Packets (PVN=1) or Encapsulation Packets (PVN=8) are used for encapsulation,
- An Encapsulated Protocol Identifier (EPI), which is either:
  - An Application Process Identifier (APID) defined in reference (if Space Packets are used).
  - a Protocol ID defined in section 4 of this document (if Encapsulation Packets are used).

The APIDs used by the Encapsulation Service must be registered as ‘reserved APIDs’ in [14]. The Protocol IDs used by the Encapsulation Service must be registered as ‘defined Protocol IDs’ in [15].

If the Data Unit is encapsulated in a Space Packet, the header format of the Space Packet is the same as the one used by Space Packet Protocol, only that the values of the parameters are restricted to some values. On the other hand, if the Data Unit is encapsulated in a Encapsulation Packet, a different header format will be used. This header have a length of 1-8 octets, and for the case of 8 octet it can be shown in Figure 1.3.6

	Bit							
Octet	0	1	2	3	4	5	6	7
0	Packet VersionNumber			Protocol ID			Length of length	
1	User defined fields				Protocol ID extension			
2	CCSDS defined field							
3								
4	Packet length							
5								
6								
7								

Figure 1.3.6: Example of a header for an Encapsulation Packet of maximum length. Some parameters may vary its length in other cases.

### IP over CCSDS (IPoC) [10]

The IP over CCSDS is used to transfer IP Data Units over CCSDS Space Data Link Protocols. IP Data Units are encapsulated in Encapsulation Packets and sent through

Space Data Link Protocols. IPoC uses the CCSDS Internet Protocol Extension (IPE) convention in conjunction with the CCSDS Encapsulation Service. The IPE convention is used to add IPE octets at the beginning of a IP Data Unit, encapsulate the result in an Encapsulation Packet, and transmit it with a CCSDS Space Data Link Protocol. It is used because not all protocols that use an IP datagram have a Protocol ID used by the Encapsulation Packet.

IPoC adds a header at the beginning of the IP Data Unit, called IPE header. The sum of the IP Data Unit and the IPE header is the Data Unit used by the Encapsulation Service. In other words, for the Encapsulation Service, the IPE header and the IP Data Unit are a whole.

The structure of the IPE header will be the following. It must be of a length of an integral number of octets, with a minimum length of 1 octet. Each octet will be divided into two parts: the first seven bits (bits 0-6), and the least significant bit (LSB, bit 7). If more octets are added, the LSB of all octets except the last octet are set to '0'. The value of the IPE header is the decimal value of all the octets. The value of the IPE header must be one of the possible values in [16].

### **Internet Control Message Protocol (ICMP) [17]**

The Internet Control Message Protocol (ICMP) is one of the main protocols of the TCP/IP protocol suite. It is used to send error messages to the source IP of the data packet. It is assigned IP protocol number 1. ICMP messages are typically used for diagnostic, control purposes or generated in response to errors in IP operations. They are processed differently than normal IP processing.

There are many types of control messages that the ICMP can send:

- Source quench: Used to request the sender to decrease the rate of messages sent to a router.
- Redirect: Used to request the sender to send the data to another router.
- Time exceeded: Used by a gateway to inform the sender of a discarded datagram due to the time to life field reaching zero. It is also used to inform the sender that a fragment of a message has not been reassembled within the time limit
- Timestamp: Used for time synchronization. The sender sends the timestamp it last touched the packet (in milliseconds since midnight)

- **Timestamp reply:** Used to reply a timestamp. The receiver of the timestamp message replies the sender with the original timestamp, the timestamp when the message was received, and the timestamp when the reply was sent.
- **Address mask request:** Used by a host to obtain the subnet mask of a router
- **Address mask reply:** Used to reply the address mask request returning the subnet mask.
- **Destination unreachable:** Used by the host or its inbound gateway to inform the client that the destination is unreachable.

### **Internet Control Message Protocol version 6 (ICMPv6) [18]**

The Internet Control Message Protocol version 6 (ICMPv6) is the implementation of the ICMP for IPv6. Several extensions have been published that define new types of ICMPv6 messages, as well as new options for existing message types. One of those is the Neighbor Discovery Protocol (NDP), a node discovery protocol for IPv6 that replaces and enhances the features of the Address Resolution Protocol (ARP). Secure Neighbor Discovery (SEND) is, respectively, an extension of NDP with extra security. Multicast Router Discovery (MRD) allows discovery of multicast routers.

### **Internet Group Management Protocol (IGMP) [19]**

The Internet Group Management Protocol (IGMP) is used by hosts and adjacent routers on IPv4 networks to establish multicast group memberships. It is a part of IP multicast, and it is used in one-to-many networking applications such as online streaming video. IGMP operates between the client computer and a local multicast router. IGMP messages are carried in bare IP packets with protocol number 2.

### **Internet Protocol Security (IPsec) [20]**

The Internet Protocol Security (IPsec) is a protocol suite for secure Internet Protocol (IP) communications. It authenticates and encrypts each IP packet of a communication session. IPsec includes protocols for establishing mutual authentication between agents at the beginning of the session and negotiation of cryptographic keys to be used during the session. IPsec can be used in protecting data flows between a pair of hosts (host-to-host), between a pair of security gateways (network-to-network), or between a security gateway and a host (network-to-host). It supports network-level peer authentication, data origin authentication, data integrity, data confidentiality (encryption), and replay protection.



IPsec uses the following protocols to perform various functions;

- Authentication Headers (AH): Provides connectionless data integrity and data origin authentication for IP datagrams, and provides protection against replay attacks.
- Encapsulating Security Payloads (ESP): Provide confidentiality, data-origin authentication, connectionless integrity, an anti-replay service, and limited traffic-flow confidentiality.
- Security Associations (SA): Provides the bundle of algorithms and data that provide the parameters necessary for AH and ESP operations.

### **Protocol Independent Multicast (PIM) [21] [22]**

The Protocol Independent Multicast (PIM) is a family of multicast routing protocols for Internet Protocol (IP) networks that provide one-to-many and many-to-many distribution of data. PIM does not include its own topology discovery mechanism, but instead uses routing information supplied by other routing protocols.

There are four variants of PIM:

- PIM Sparse Mode (PIM-SM): It builds unidirectional shared trees rooted at a rendezvous point (RP) per group, and optionally creates shortest-path trees per source. It is called sparse-mode because it is suitable for groups where low percentage of the nodes will subscribe to the multicast session.
- PIM Dense Mode (PIM-DM): It uses dense multicast routing. It builds shortest-path trees by flooding multicast traffic domain wide, and then pruning back branches of the tree where no receivers are present. Dense mode is ideal for groups where many of the nodes will subscribe to receive the multicast packets.
- Bidirectional PIM: It builds shared bi-directional trees. It never builds a shortest path tree, so may have longer end-to-end delays than PIM-SM.
- PIM Source-Specific Multicast (PIM-SSM): It builds trees that are rooted in just one source, offering a more secure model for a limited amount of applications (mostly broadcasting of content). In SSM, an IP datagram is transmitted by a source S to an SSM destination address G, and receivers can receive this datagram by subscribing to channel (S,G).

### **1.3.2.3 Routing protocols**

#### **Enhanced Interior Gateway Routing Protocol (EIGRP) [23]**

The Enhanced Interior Gateway Routing Protocol (EIGRP) is a routing protocol used on a computer networks for automating routing decisions and configuration. This protocol was designed by Cisco Systems and it was only available for Cisco routers. In 2003, partial functionality of EIGRP was converted to an open standard and in 2016 was published with informational status. EIGRP is used on a router to share routes with other routers in the same autonomous system.

All routers contain a routing table that lists the routes to network destinations. If a router cannot find a valid path to the destination, the traffic is discarded. EIGRP is a dynamic routing protocol, which means that routers automatically exchange information about routes and, therefore, the administrator does not have to change the routing table manually. Besides the routing table, routers additionally have two more tables.

- Neighbour table. It stores the IP address of the routers that have a direct connection with this router. If a router is connected to another with an intermediate router, it will not be recorded in this table.
- Topology table. It keeps record of routes that has learned from neighbouring router tables, and also records the distance (number of intermediate routers) of each route, the feasible successor and the successors (other routes that have the same destination and are loop free). Routes in this table are either labelled as "passive" or "active". Passive means that EIGRP has determined the path for the specific route and has finished processing. Active means that EIGRP is still trying to calculate the best path for the specific route. The router does not use the routes in this table. A route in this table will be inserted in the routing table when is marked as passive, is not a feasible successor and does not have a higher distance than an equivalent path

If there is a change in the network (a link fails, or a router is disconnected), the path becomes unavailable, and is removed from the routing table. The routing table of a router will be updated, and only the changes since the previous update will be transmitted to the neighbouring routers. The information about the changes in the routing table is not transmitted periodically, but only when a change actually occurs.

EIGRP supports the following features:

### Layer 3: The Network

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- Support for Classless Inter-Domain Routing (CIDR) and variable length subnet masking. Routes are not summarized at the classful network boundary unless auto summary is enabled.
- Support for load balancing on parallel links between sites.
- The ability to use different authentication passwords at different times.
- MD5 authentication between two routers.
- Sends topology changes, rather than sending the entire routing table when a route is changed.
- Periodically checks if a route is available and propagates routing changes to neighboring routers if any changes have occurred.
- Runs separate routing processes for Internet Protocol (IP), IPv6, IPX and AppleTalk through the use of protocol-dependent modules (PDMs).

EIGRP does not operate using the Transmission Control Protocol (TCP) or the User Datagram Protocol (UDP). This means that EIGRP does not use a port number to identify traffic. Rather, EIGRP is designed to work on top of layer 3. Since EIGRP does not use TCP for communication, it implements Cisco's Reliable Transport Protocol (RTP) to ensure that EIGRP router updates are delivered to all neighbors completely.

### Open Shortest Path First (OSPF) [24] [25]

The Open Shortest Path First (OSPF) is a routing protocol for Internet Protocol (IP) networks that operates in a single autonomous system. OSPF version 2 is designed for IPv4, while OSPF version 3 is designed for IPv6. It works by gathering link state information from available routers and constructing a topology map of the network. The topology is presented as a routing table to the Internet layer which routes packets based solely on their destination IP address. OSPF detects changes in the topology, such as link failures, and creates a new loop-free routing structure. It computes the shortest-path tree for each route using a method based on Dijkstra's algorithm. OSPF does not use a transport protocol, such as UDP or TCP, but encapsulates its data directly in IP packets with protocol number 89. It implements its own transport layer error detection and correction functions. OSPF uses multicast addressing for distributing route information within a broadcast domain.

OSPF supports complex networks with multiple routers, including backup routers, to balance traffic load on multiple links to other subnets. Routers form adjacencies when

they have detected each other. This detection is initiated when a router identifies itself in a Hello protocol packet. Upon acknowledgment, this establishes a two-way state and the most basic relationship. The routers in an Ethernet or Frame Relay network select a Designated Router (DR) and a Backup Designated Router (BDR) which act as a hub to reduce traffic between routers. OSPF establishes and maintains neighbor relationships for exchanging routing updates with other routers. The neighbor relationship table is called an adjacency database. Two OSPF routers are neighbors if they are members of the same subnet and share the same area ID, subnet mask, timers and authentication. OSPF adjacencies are formed between selected neighbors and allow them to exchange routing information. Two routers become adjacent if at least one of them is Designated Router or Backup Designated Router (on multiaccess type networks), or they are interconnected by a point-to-point or point-to-multipoint network type.

OSPF does not carry data via a transport protocol. Instead, OSPF forms IP datagrams directly, packaging them using protocol number 89 for the IP Protocol field. OSPF defines five different message types, for various types of communication:

- **Hello:** It is used to allow a router to discover other adjacent routers on its local links and networks. The messages establish adjacencies between neighboring devices. During normal operation, routers send hello messages to their neighbors at regular intervals. If a router stops receiving hello messages from a neighbor, after a set period the router will assume the neighbor has gone down.
- **Database Description:** It contains descriptions of the topology of the autonomous system or area. They convey the contents of the link-state database (LSDB) for the area from one router to another. Communicating a large LSDB may require several messages to be sent.
- **Link State Request:** These messages are used by one router to request updated information about a portion of the LSDB from another router. The message specifies exactly which link about which the requesting device wants more current information.
- **Link State Update:** These messages contain updated information about the state of certain links on the LSDB. They are sent in response to a Link State Request message, and also broadcast or multicast by routers on a regular basis. Their contents are used to update the information in the LSDBs of routers that receive them.
- **Link State Acknowledgment:** These messages provide reliability to the link-state exchange process, by explicitly acknowledging receipt of a Link State Update message.

**Routing Information Protocol (RIP) [26] [27]**

The Routing Information Protocol (RIP) is a routing protocol. It uses a hop count to establish the distance between two routers and, in order to prevent loops, establishes 15 as the limit number of hops in a route. If the number of hops is 16, the distance between the two routers is considered infinite. Each router has a routing table with all the routes to each possible destination, and the number of hops to get there. There are 3 versions of RIP: RIPv1, which is the original, RIPv2, which is an updated version of RIPv1, and RIPv2, which is the new generation of RIP compatible with IPv6.

The operating principle of the RIP is the following: When a RIP router comes online, it sends a broadcast message to all of its RIP enabled interfaces. All the neighbouring routers that receive the Request message respond back with the Response Message containing their Routing table. The Response Message is also gratuitously sent when the Update timer expires (by default, 30 seconds). On receiving the Routing table, the router processes each entry of the routing table as per the following rules:

- If there are no route entries matching the one received then the route entry is added to the routing table automatically, along with the information about the router from which it received the routing table.
- If there are matching entries but the hop count metric is lower than the one already in its routing table, then the routing table is updated with the new route.
- If there are matching entries but the hop count metric is higher than the one already in its routing table, then the routing entry is updated with hop count of 16 (infinite hop). The packets are still forwarded to the old route. A Hold-down timer is started and all the updates for that route from other routers are ignored. If after the Hold-down timer (per default 180 seconds) expires and still the router is advertising with the same higher hop count then the value is updated into its routing table. Only after the timer expires, the updates from other routers are accepted for that route.

If the Invalid timer (per default 180 seconds) expires and a routing entry has not been updated, the hop counter of that route will be set to 16, marking the route as invalid. Then, if the Flush timer (per default 240 seconds) expires, the invalid route entry will be removed

### 1.3.3 Protocol Selection

#### 1.3.3.1 Choice of the main protocol

The choice of the main protocol will be between SPP, IPv4 and IPv6. To make the choice, it is important to take into account that the Astrea constellation is a network that can be of more than two hundred satellites, which will communicate point-to-point. Each node can be the source, the destination or an intermediate node of a communication route.

SPP has the advantage of being designed to work easily with the protocols of the adjacent layers, while IP needs IP over CCSDS and Encapsulation Service. However, SPP requires a parameter called Path ID, which is the identifier of a Logical Data Path. Since each satellite of Astrea constellation can be the source or the destination of a data path, this means that for a network of 200 nodes, there are  $200 \times 199 = 39800$  possible routes. The parameter to indicate the Path ID has a length of 11 bits, which can identify 2048 different routes, which is not enough. Another issue to take into account is that since the ground station nodes of the constellation are moving respect the satellite nodes, their relative position changes and, therefore, paths also change. If the path associated to a Path ID changes during a transmission, or if it is not updated for all nodes at the time of the transmission, errors can occur. This does not happen with IP, since instead of Path ID it uses the IP address of the source and destination node. For this reason, SPP is discarded.

The main differences between IPv4 and IPv6 are the header of the datagram and the IP addresses of the nodes. Since our network is private and it is not intended to be connected to the Internet, nodes can have an arbitrary IP address assigned. For this reason, IPv4 addresses are better, since they are shorter than IPv6 addresses. The size of the header would also be smaller in IPv4 than IPv6. However, for long datagrams, the extra length of IPv6 headers is irrelevant. Another difference is that IPv6 datagrams require less processing power, however, since the processing power is very small compared to the power required by the antennas this factor also has little importance in terms of power. However, it is important in terms of time, since less processing means less time to process. Other features of IPv6 that, in Astrea network, do not provide benefits are the multicast and mobility features, which the network will not have. Additionally, due to the changing nature of the constellation, jumbograms will not be used because a packet so long may be interrupted when the path changes.

The real benefits of IPv6 over IPv4 is that there are less additional protocols compared to IPv4 to perform the same features, since ICMPv6 provides the features of ICMP, ARP and

IGMP, and some features of IPv6 itself and its additional protocols have been eliminated since they were already performed by other layer protocols and were redundant. All of this helps to reduce the time required to process the data and this, in long paths, is a significant factor.

If reliable adjacent layer protocols are provided, IPv6 is the best option, due to less processing in routers and more simple additional protocols. Additionally, IPv6 is progressively replacing IPv4 and, therefore, using IPv6 has no risk of being obsolete.

### **1.3.3.2 Choice of routing protocol**

The choice of the routing protocol will be between EIGRP, OSPF and RIP.

EIGRP is a protocol compatible with either IPv4 and IPv6. Contrary to other protocols, it only sends topology changes instead of the whole routing table, allowing for less data transmitted. It also contains more information about routes than other routing protocols, and provides authentication processes.

RIP is a protocol that, compared to EIGRP and OSPF, has the drawback that its time to converge and its scalability are poor. Additionally, RIP uses the User Datagram Protocol (UDP) as its transport protocol. On the other, it is easier to configure than other protocols.

OSPF is a protocol also compatible with IPv4 and IPv6. Unlike EIGRP, each router exchanges its adjacency links with adjacent routers and then, each router creates its own map of the network and, using this map, each router creates its own routing table. However, it has mechanisms to ensure that there are not loops in the network.

Taking into account that nodes in the Astrea network have an order of magnitude of 200 and is continuously changing the data paths. Also, since Astrea is a network where a node can be the beginning or the end of a communication, this means that for a given node there has to be a route to every other node in the network, and for a network of 200 nodes, there are 199 possible routes for the 200 nodes, which is a total of 39800 different entries in the routing table only for the satellite nodes. Since RIP has longer time to converge compared to other protocols, and due to the huge size of the routing table, RIP is discarded.

EIGRP does not have this problem because it does not transmit the whole routing table, but only the changes. Although the network is continuously moving, the paths between the satellite nodes remain the same. The problem happens with the ground nodes, which are continuously changing its position respect the satellite nodes due to Earth's rotation. And since each satellite node can communicate with every ground station, the number of entries in the routing table that will be updated for a network of 200 satellite nodes and 5 ground stations is  $200 \times 5$ , which is 1000 entries that will be updated frequently. Since OSPF does not transmit the routing table but only the adjacencies, only 205 entries will be transmitted. This reduces the time to share the updated information to the whole network. For this reason, OSPF is chosen.

#### **1.3.3.3 Choice of complementary protocols**

The choice of which protocols include will depend on the main protocol of the network layer and the degree of services featured by the communication process.

Since IPv6 has been chosen, IP over CCSDS and Encapsulation Service are necessary. Additionally, ICMPv6 greatly expand the features of IPv6 such as flow control. Security features are already provided in the Data Link layer and, therefore, IPsec is not necessary. Also, no multicast features are required, so no multicast protocols will not be used.

#### **1.3.3.4 Conclusion**

It has been decided that IPv6 will be the network layer protocol, complemented with IPoC, Encapsulation Service and ICMPv6, and with OSPF as the routing protocol.

### **1.3.4 Final structure**

As the protocols have already been chosen, it is time to establish how will be the headers of the different protocols.

The IPv6 header will depend greatly on the protocol of the upper layers, or the auxiliary protocol (OSPF, ICMPv6). The main parameters of the IPv6 header, that can be seen in Figure 1.3.5, are the following:

- **Version** Current version of IP, which for IPv6 is 6 (bit sequence 0110).



- **Traffic Class.** The bits of this field hold two values. The 6 most-significant bits are used for differentiated services, which is used to classify packets. The remaining two bits are used for ECN; priority values subdivide into ranges: traffic where the source provides congestion control and non-congestion control traffic.
- **Flow Label.** The flow label when set to a non-zero value now serves as a hint to routers and switches with multiple outbound paths that these packets should stay on the same path so that they will not be reordered.
- **Payload Length.** The size of the payload in octets, including any extension headers. The length is set to zero when a Hop-by-Hop extension header carries a Jumbo Payload option.
- **Next Header.** Specifies the type of the next header. This field usually specifies the transport layer protocol used by a packet's payload. When extension headers are present in the packet this field indicates which extension header follows. The values are shared with those used for the IPv4 protocol field, as both fields have the same function (see List of IP protocol numbers in [28]).
- **Hop Limit.** This value is decremented by one at each intermediate node visited by the packet. When the counter reaches 0 the packet is discarded.
- **Source Address.** The IPv6 address of the sending node.
- **Destination Address.** The IPv6 address of the destination node.

It has been stated that, since Astrea network is a private network that will not be connected to the Internet, IP addresses will be arbitrary assigned to the nodes of the network.

For the IPoC header, the value for IPv6 datagrams is 87, so the header of OPoC will be 01010111

For the Encapsulation Service, depending of the length of the data unit transmitted, the header will vary. For data units up to 65531 octets, the Encapsulation Service header will be the following: 11101010-00000000-XXXXXXXX-XXXXXXXX, where XXXXXXXX-XXXXXXXX is the binary number of the total length of the Encapsulation Packet, including the Encapsulation Packet header.

## 1.4 Layer 4: Transport and Session

This layer is the one in charge of the free-of-error transference of data from one process to another. Therefore, its goal is to provide and guarantee a reliable and cheap flow of the data.

Whereas the network layer oversees source-to-destination delivery of individual packets, it does not recognize any relationship between those packets. It treats each one independently, as though each piece belonged to a separate message, whether or not it does. The transport layer, on the other hand, ensures that the whole message arrives intact and in order, overseeing both error control and flow control source-to-destination level.

A transport layer can be either connectionless or connection-oriented. A connectionless transport layer treats each segment as an independent packet and delivers it to the transport layer at the destination machine. A connection-oriented transport layer makes a connection with the transport layer at the destination machine first before delivering the packets. After all the data is transferred, the connection is terminated.

In the transport layer, a message is normally divided into transmittable segments. A connectionless protocol, such as UDP, treats each segment separately. A connectionoriented protocol, such as TCP and SCTP, creates a relationship between the segments using sequence numbers.

The transport layer is responsible for process-to-process delivery, i.e, the delivery of a packet, part of a message, from one process to another. Two processes communicate in a client/server relationship.

Regarding addressing, at the transport layer, it is necessary a transport layer address, called a port number, to choose among multiple processes running on the destination host. The destination port number is needed for delivery, whereas the source port number is needed for the reply.

The addressing mechanism allows multiplexing and demultiplexing by the transport layer.

### 1.4.1 User Datagram Protocol (UDP)

The User Datagram Protocol (UDP) is a connectionless, unreliable transport protocol. The only new feature regarding IP is that it provides process-to-process communication

instead of host-to-host communication, and performs a very limited error checking. It might seem a powerless protocol, but its main point is that is a very simple protocol using a minimum of overhead. Therefore, if a process wants to send a small message and no extremely reliability is required, UDP is a good choice.

Nevertheless, regarding the aim of this project, it is unacceptable to use UDP, since reliability is a key factor and must be taken into account.

### **1.4.2 Stream Control Transmission Protocol (SCTP)**

The Stream Control Transmission Protocol is a new reliable, message-oriented transport layer protocol. Nevertheless, it has been designed and implemented mostly for Internet applications, such as IUA or SIP. But precisely it does not fit the goal of this project.

Therefore, as there is a better choice (which will be deeply and widely explained in the following section), this protocol will not be considered.

### **1.4.3 Transmission Control Protocol (TCP)**

The Transmission Control Protocol is again a process-to-process protocol. Consequently it uses port numbers. The main difference with the UDP is that TCP is a connection-oriented protocol, which means that creates a virtual connection between two TCP's in order to send data. Moreover, TCP uses flow and error control mechanisms. It is then a more reliable protocol than UDP. It adds connection-oriented and reliability features to the services of IP.

This will be the protocol chosen for this project, so it will be explained in detail in this section.

#### **1.4.3.1 TCP Services**

Process-to-process communication: Like UDP, TCP provides this type of communication, using port numbers. In the following image there are the main well-known port numbers used by TCP.

## Layer 4: Transport and Session

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<i>Port</i>	<i>Protocol</i>	<i>Description</i>
7	Echo	Echoes a received datagram back to the sender
9	Discard	Discards any datagram that is received
11	Users	Active users
13	Daytime	Returns the date and the time
17	Quote	Returns a quote of the day
19	Chargen	Returns a string of characters
20	FIP, Data	File Transfer Protocol (data connection)
21	FIP, Control	File Transfer Protocol (control connection)
23	TELNET	Tenninal Network
25	SMTP	Simple Mail Transfer Protocol
53	DNS	Domain Name Server
67	BOOTP	Bootstrap Protocol
79	Finger	Finger
80	HTTP	Hypertext Transfer Protocol
111	RPC	Remote Procedure Call

Stream Delivery Service: as has been mentioned before, TCP, unlike UDP, is a stream-oriented protocol. UDP does not recognize any relationship between the datagrams. TCP, in contrast, allows the sending process to deliver data as a stream of bytes and allows the receiving process to obtain data as a stream of bytes. A way of explaining this would be an environment in which the two processes seems to be linked by and imaginary "tube" that carries the data across the Internet. The sending process produces the stream of bytes and the receiving process consumes them. This is, the first writes and the last reads.

Sending and Receiving Buffers: Since the sending and receiving processes might not write or read data at the same speed, there is a need for storage in TCP. Therefore, TCP includes two buffers, the sending buffer and the receiving buffer. A deeper look into those buffers can be performed by looking at the bibliography.

Full-Duplex Communication: TCP allows full-duplex service, so that data can flow in both directions at the same time. Each TCP has a sending and receiving buffer, and segments move in both directions. This feature is very important for the goal of this project.

Segments: Although buffering solves the problem of different speeds of producing and consuming, there is still one important feature to be discussed. The data needs to be sent in packets, not as an endless stream of bytes. Therefore, TCP groups a number of bytes together into a packet called a segment. A header is added to each segment for control purposes.

#### **1.4.3.2 TCP features**

In order to provide the services that have been explained, TCP has some features that will be briefly discussed.

#### **1.4.3.3 Numbering Systems**

TCP keeps track of the segments being transmitted or received, using the header previously discussed. There are in addition two fields, the sequence number and the acknowledgement number, which refer to the byte number, not the segment number.

TCP numbers all data bytes that are transmitted in a connection. Numbering is independent in each direction. When TCP receives bytes of data from a process, it stores them in the sending buffer and numbers them. Typically, it generates randomly a number between 0 and  $2^{32} - 1$  for the number of the first byte. For example, if the random number happens to be 1427 and the total data to be sent are 5000 bytes, the bytes are numbered from 1427 to 6426. This system is used for flow and error control.

After the bytes have been numbered, TCP assigns a sequence number to each segment that is being sent. The sequence number for each segment is the number of the first byte carried in that segment. This is, the value in the sequence number field of a segment defines the number of the first data byte contained in that segment.

The value of the acknowledgement field in a segment defines the number of the next byte a party expects to receive. It is a cumulative number.

#### **1.4.3.4 Flow Control**

TCP provides flow control, which means that the receiver can control the amount of data that is to be sent by the sender. The purpose of this is to avoid over-whelmed receivers.

#### 1.4.3.5 Error Control

In order to provide a reliable service, TCP implements an error control mechanism. It considers a segment as the unit of data for error detecting, even though there is also a byte-oriented control mechanism.

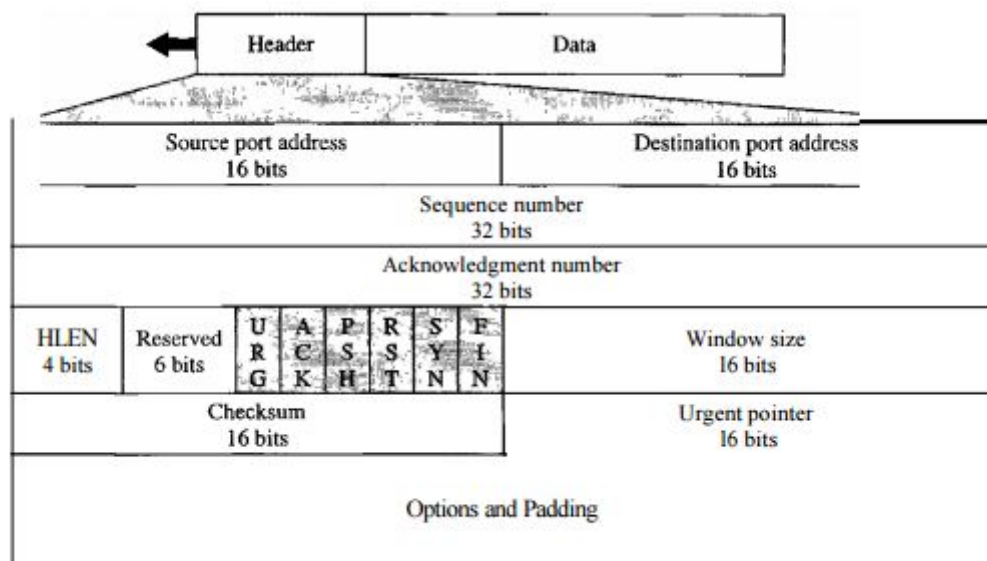
#### 1.4.3.6 Congestion Control

TCP also takes into account congestion in the network, by the deterring of the flow depending on the level of congestion in the network.

#### 1.4.3.7 Segment

As has been explained before, a packet in TCP is called a segment. The aim of this point is to explain in detail what a segment is and how its structure is.

The typical format of the segment is shown in the next figure.



The segment consists of a 20 to 60-byte header, followed by data from the application program. The byte is 20-byte long if there are no options, and up to 60-bytes if there are options.

The main parts of the format are to be discussed in the following lines.

**1.4.3.8 Source Port Address**

This is a 16-bit field that states the port number of the application program in the host that is sending the segment.

**1.4.3.9 Destination Port Address**

It is also a 16-bit that defines the port number of the application program in the host that is receiving the segment.

**1.4.3.10 Sequence Number**

This 32-bit field defines the number assigned to the first byte of the data contained in the segment considered. This numeration has been previously explained.

**1.4.3.11 Acknowledgement Number**

This is a 32-bit field that defines the byte number that the receiver of the segment is expecting to receive from the other party. If the receiver of the segment has successfully received byte number  $x$ , it defines  $x + 1$  as the acknowledgement number.

**1.4.3.12 Header Length**

A 4-bit field that indicates the number of 4-byte words in the TCP header. As seen, the length of the header can be between 20 and 60 bytes. Then, the value of this field can be between 5 and 15 (since  $5 \times 4 = 20$ , and  $15 \times 4 = 60$ ).

**1.4.3.13 Reserved**

This is a 6-bit field reserved for future usage.

**1.4.3.14 Control**

This field defines 6 different control bits or flags. One or more of those bits can be set at a time.

#### 1.4.3.15 Window Size

This field defines the size of the window, in bytes, that the other party must maintain. Since the length of this field is 16 bits, the maximum size of the windows is  $2^{16} = 65535$  bytes.

#### 1.4.3.16 Urgent Pointer

Another 16-bit field, which is only valid if the urgent flag is set, which means that the segment contains urgent data. It actually defines the number that must be added to the sequence number to obtain the number of the last urgent byte in the data section of the segment.

#### 1.4.3.17 Options

As has been explained, there can be up to 40 bytes of optional information in the TCP Header. This is the purpose of this last field.

#### 1.4.3.18 Adaptation to space needs

TCP was established for wired connections initially. Therefore, in order to be eligible for the purpose of this project, it is highly recommended that some slight modifications are done. The Space Communications Protocols Specification (SCPS) defines a set of revisions to the protocols to enable them to operate properly. This is, SCPC-TCP becomes an "upgraded" TCP, specially designed for space application.

With SCPS, TCP the bandwidth of an existing link will be utilized to a significantly higher percentage and more efficiently. It also supports end-to-end communications between applications and is designed to meet the needs of a broad range of space missions.

This is all achieved because of an extension that is added to the header shown before. This extension header is shown next. Each line is a octet of bits; i.e, 8 bits:

SCPS Option Type (20)							
SCPS Option Length							
BETS	SN1	SN2	Com	NL TS			ext



#### **1.4.4 Choice of protocol for the transport layer**

Three protocols have been discussed, the UDP, the SCTP and the TCP. The first one has some disadvantages which make it not suitable for the purpose of the project, such as the fact that no reliability is guaranteed, for example, amongst others. The second one is designed mostly for Internet applications, which does not fit the goals of this project. Therefore, the only candidate suitable for the project is the TCP, Transmission Control Protocol, which has already been widely explained and analyzed. As it has the required features that the project demands, it is the chosen protocol for this layer. Also, as it has been established, it is very recommended to use the extension SCPS, due to adaptation to space needs.

## 1.5 Global Overview

For the sake of clarification, all the elected options are going to be put together obtaining the desired fully designed **protocol stack**.

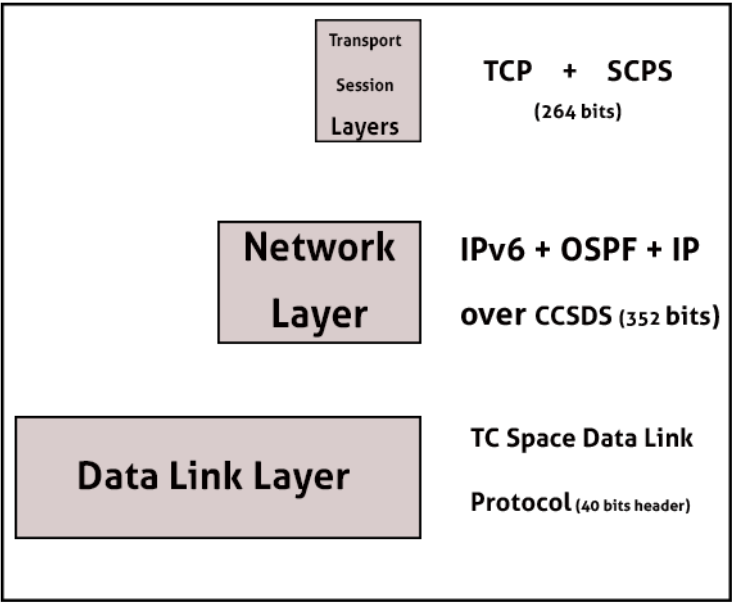


Figure 1.5.1: Overall space communication protocol stack

In total, the overhead is **656 bits**, with conservative calculations. Hence, the quantity is negligible in comparison to the data rate.

## Chapter 2

# Ground Segment Protocols

## Part II

# Ground segment

## Chapter 3

# Ground Station Design

### **3.1 Decision taking**

In this subsection the decision between building ground stations or renting existent ones will be taken. There are a few things to be taken into account before starting to talk about the benedits and drawbacks of each of the options. First of all, the number of ground stations required is needed. If there is no communication with the satellites, the mission would not be accomplished. For this reason, the nodes of the ground stations are very important. The number of ground stations required is the minimum number that, with two failures, can still transfer the data from the satellite of the client to the client itself in less than 5 minutes. Supposing that three ground stations are built or rent, if two of them fail the communication between the client and its satelline can still be done using the left ground station. Regarding the latency, as it has been already exposed, the communication will take place with a latency of less than 5 minutes, as only one ground station that may fall will be in the communication path and is very improbable that if the ground station fails and the information is redirected to another, the latter falls too in less than three minutes. Regarding the position of the ground station, as the code developed shows, the ideal will be to have them close to the equator, because they would be capable to stablsh more links with different satellites and then the communication to the client's satellite is assured. In the following lines the factors to take into account to decide the ground stations will be explained. After doing so, an OWA will be done if needed.

#### **3.1.1 Availability**

##### **3.1.1.1 Building a ground station**

If the decision to build a ground station is taken, it will be available as soon as it is constructed. The time taken to construct the ground stations depend on the efforts employed, but the three ground stations will be surely completed at the time the satellite network is completely deployed. From the moment the ground stations are built, they are totally available to accomplish the missions of Astrea constellation.

##### **3.1.1.2 Renting a ground station**

The sections regarding the renting of a ground station will be done considering LeafSpace (as it has been already said). LeafSpace is a company that does not work only with Astrea constellation, so total availability of the antenna's and its transmissions can not be assured. For this reason, is not possible to assure that the communication rate established in the project charter will be accomplished. Moreover, LeafSpace's Ground Stations are

still non-existent, and they predict that the first ones will be available next year.

### 3.1.2 Cost

#### 3.1.2.1 Building a ground station

The costs of building a ground station can be divided into an initial investment and a maintenance. The initial investment has been estimated in 208160 € and the maintenance in 30000 €/year. The Net Present Cost (NPC) in 10 years will be calculated in order to compare this option with the option of renting a ground station. The discount rate used to do so will be 12%.

$$NPC = +I_o + \sum_{i=1}^{10} \frac{CF_i}{(1+r)^i} \quad (3.1.1)$$

$$NPC = 208160 + \sum_{i=1}^{10} \frac{30000}{(1+0.12)^i} = 377670 \quad (3.1.2)$$

#### 3.1.2.2 Renting a ground station

In this case maintenance is not needed as it is carried out by the owners of the ground station. The cost, however, comes from the amount of data that is transferred from the satellites to the client. The estimation of the Mbyte transferred over a whole year is difficult to calculate. LeafSpace provides a minimum cost per month of 2400 €. This has been calculated for small communications with X-band. To calculate an approximation, this number will be increased a 40% because Astrea constellation will probably have quite higher transfer of data. The cost per year is, then 40320 €. The NPC will be calculated too:

$$NPC = \sum_{i=1}^{10} \frac{40320}{(1+0.12)^i} = 227820 \quad (3.1.3)$$

### 3.1.3 Position

#### 3.1.3.1 Building a ground station

In the case the ground station is constructed and operated for the Astrea constellation, there is the possibility of building them in latitudes close to the ideal ones (from 45° to 70°), so more links will be available during more time. Moreover, there is also the possibility of building them in different longitudes (approximately with a difference of 120°).

### **3.1.3.2 Renting a ground station**

In the case the ground station is rented, there is no possibility to choose the position of the ground station. In the case of LeafSpace, most of the ground stations that will be built in 2017 are located at  $45^{\circ}$  north. This can seem quite good from the point of view of visibility and links. However, all of them are more or less in the same longitude, so at the same time the links at the different ground stations are the same. With ground station at different longitudes, the performance of the constellation would be better than having them in the same longitude.

### **3.1.4 Ease to improve**

#### **3.1.4.1 Building a ground station**

The fact of building a ground station implies that it can be improved and adapted to the constellation and the needs of the clients along the developement of the mission.

#### **3.1.4.2 Renting a ground station**

If the ground station is rented, it can not be improved according to the needs of the constellation, and maybe the constellation will have to be adapted to the ground station in order to accomplish the mission. The improvement in this case is, then, difficult and probably impossible.



## 3.2 Decision

The factors used to decide will be the ones presented previously. They will be rated from 1 to 2, being 2 the best option and 1 the worst option. As there are only two options, no linear interpolation is needed. Taking into account the requirements and needs of the project, the weights are the following ones:

- Availability: 6
- Cost: 9
- Position: 6
- Ease to improve: 5

The rating and the OWA of the decision between building a ground station or renting an existent one is:

	Availability	Cost	Position	Ease to improve	OWA
<b>Build</b>	2	1	2	2	0.83
<b>Rent</b>	1	2	1	1	0.67

Table 3.2.1: OWA of the GS

Looking at the results, the fact of building a ground station is the best option for the Atrea Constellation in order to accomplish its requirements and to give a high-quality service.

### 3.3 Ground Station localization

The place where the Ground Stations would be placed has to be studied in order to obtain maximum rendement of them. This decision will depend mainly of the constellation characteristics, the earth topography and the country legislation and resources. In this chapter the analysis and procedures for arriving to the final decision of where the Ground Stations would be placed are exposed.

Given the constellation topology, the coverage of a Ground Station depending on its longitude and latitude will be studied. The aim of this analysis is to show where a Ground Station would have more coverage and give a first approximation and proposal of the 3 Ground Station placement.

#### 3.3.1 Method

For the purpose above explained, a Matlab algorithm is developed. This algorithm calculates, on a given moment, how many satellites can be seen from a Ground Station. This calculation will be done several times in order to obtain results along time. In order to elaborate the algorithm the steps showed below are followed:

1. Calculate where the satellites are referred to an inertial Cartesian coordinates system, with the origin at the center of the Earth. This state analysis is done for several time periods with an adequate time-step.
2. Calculate the Ground Station position referred to the mentioned system. Since the system is inertial, the Ground Station will describe a circle in the rotational plane of the Earth relative to this system. This trajectory depend on the latitude and longitude of the place. This position is calculated for the same time period used before.
3. Calculate, for each time step, how many links can the GS establish. It will depend on the angle between the station and every satellite, and also on the minimum elevation angle.

After seeing reasonable results modifying the parameters of the constellation and of the Ground station, the algorithm will be verified simulating the Iridium constellation. Entering the parameters of this system, the results verifies the algorithm.

Once the algorithm is tested and verified, the links during the day for several longitudes and latitudes and how this parameters affect to the coverage of the station are studied<sup>1</sup>

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<sup>1</sup>The code can be found at the annexes.

### 3.3.2 Latitude analysis

Is easy to see that the effect of changing the latitude is practically independent for the longitude. For this reason, the links during the day for a given longitude are studied independently of the latitude and viceversa. Doing the analysis for latitudes between  $0^\circ$  and  $90^\circ$  during 2 days, with 5 minutes time-step, this are the results:

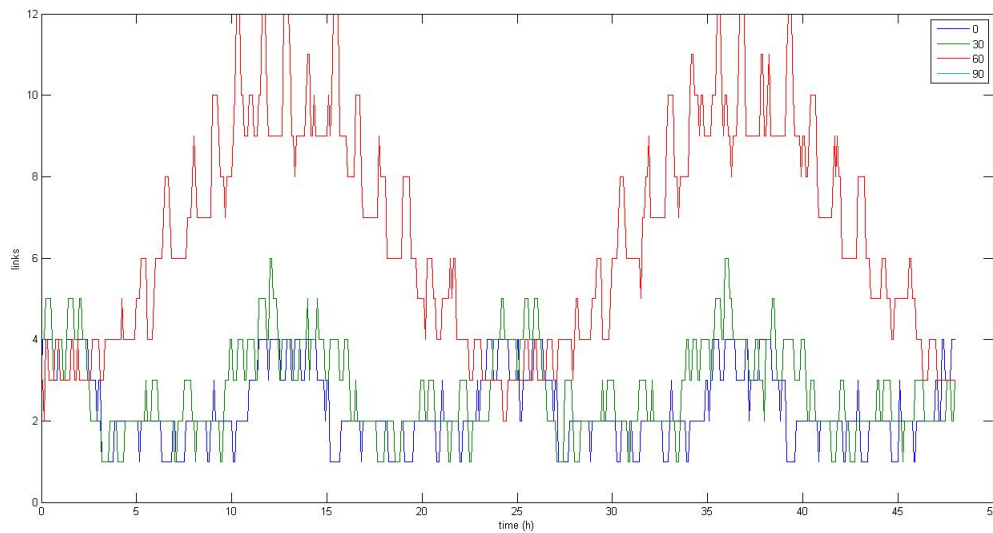


Figure 3.3.1: Links vs time for latitudes from  $0^\circ$  to  $90^\circ$

As is shown in Figure 1.1, the behaviour is not constant during the day. For every day there is a peak and a valley. This is produced for the cylindrical asymmetry of the constellation. It can also be seen that the pole is not covered. This fact was considered and assumed at the design of the constellation since it doesn't involve any problem at the performance of the system. It can also be seen that for an equatorial latitude there is always 1 link, at least. The equator is the most critical place because is where satellites from different planes are more separated. Global coverage can be ensured, but is important to appreciate that for higher latitudes the coverage is better.

Doing the same analysis but for negative latitudes, the following results are obtained:

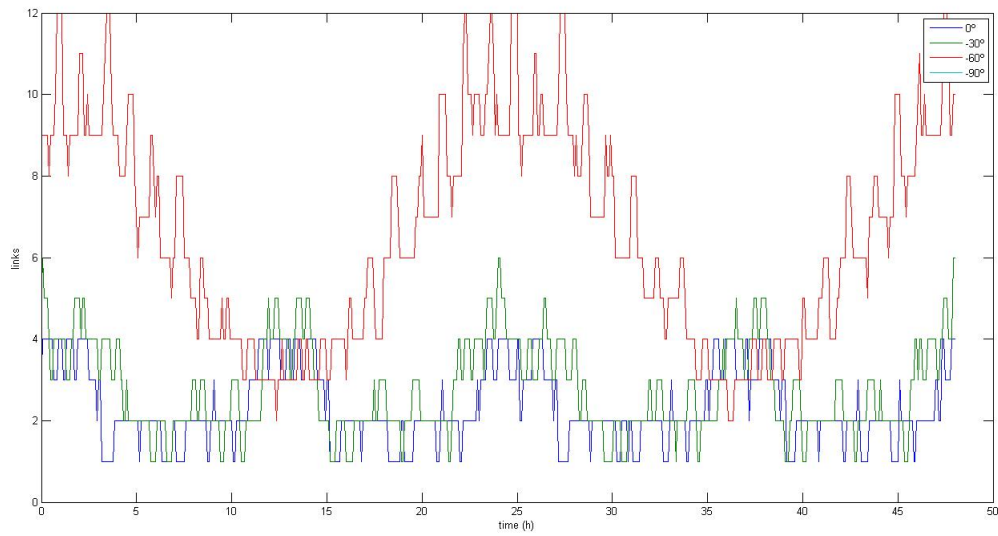


Figure 3.3.2: Links vs time for latitudes from  $0^\circ$  to  $-90^\circ$

Comparing the results of Figure 1.2 with the ones of Figure 1.1 it is seen that they are practically the same but with an offset of 12 hours. They are also seen small local deviations, but these are not much significant because of the time-step. This time-step is of 5 minutes for a first sight of the tendencies, and it do not allow extremely precise results.

Taking into account that the results of positive latitudes can be extrapolated to negative ones, the rest of the analysis will be done only for positive latitudes. It is important to know at which latitude, close to the poles, the coverage is lost due to the geometry of the constellation.

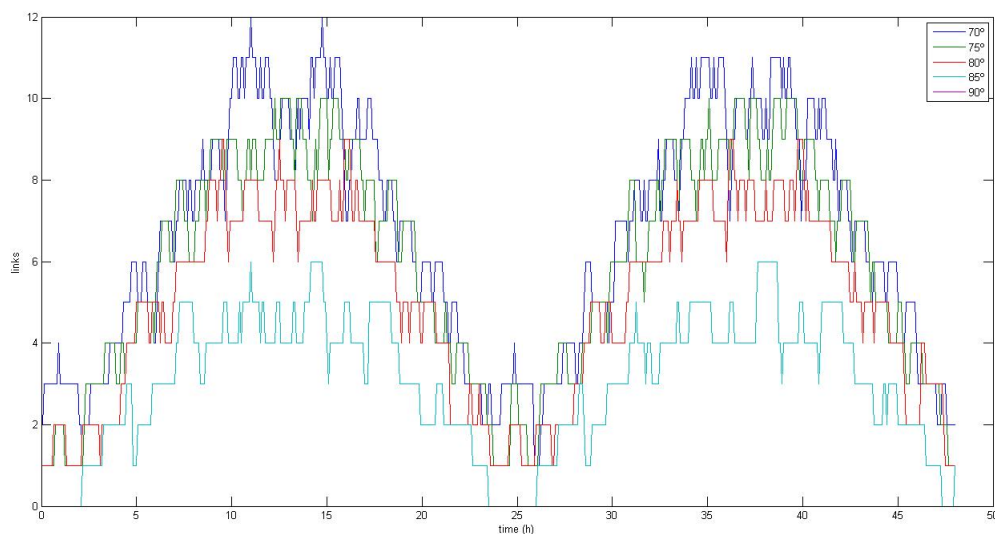


Figure 3.3.3: Links vs time for latitudes from 70° to 90°

It is seen that over 80° of latitude the system starts to lose coverage. It does not cause any problem because there are not inhabited zones over +80° or under -80°. For situating the Ground Stations it has to be considered this restriction.

Now, the latitudes that can provide more links are, around 60°:

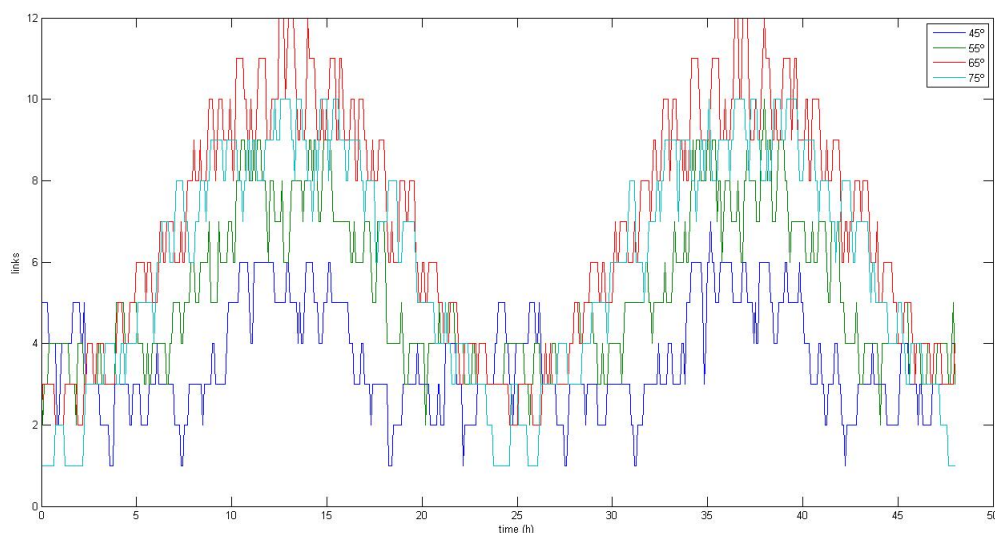


Figure 3.3.4: Links vs time for latitudes from 45° to 75°

As it can be seen in Figure 1.4, the optimal latitude must be between 55° and 75°.

Expanding the analysis:

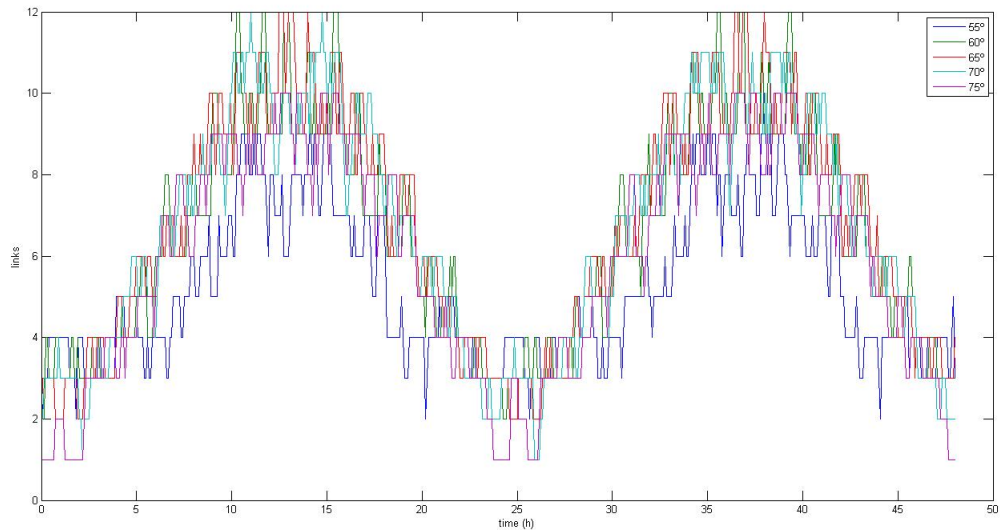


Figure 3.3.5: Links vs time for latitudes from 55° to 75°

The better performance is registered around 60° and 65°. Figure 1.5 suggest that between 50° and 60° there is always at least 1 link. But looking it carefully, at the hour 37, there is a local deviation to 0 links. This requires a more accurate analysis decreasing the time-step. For 30 seconds time-step:

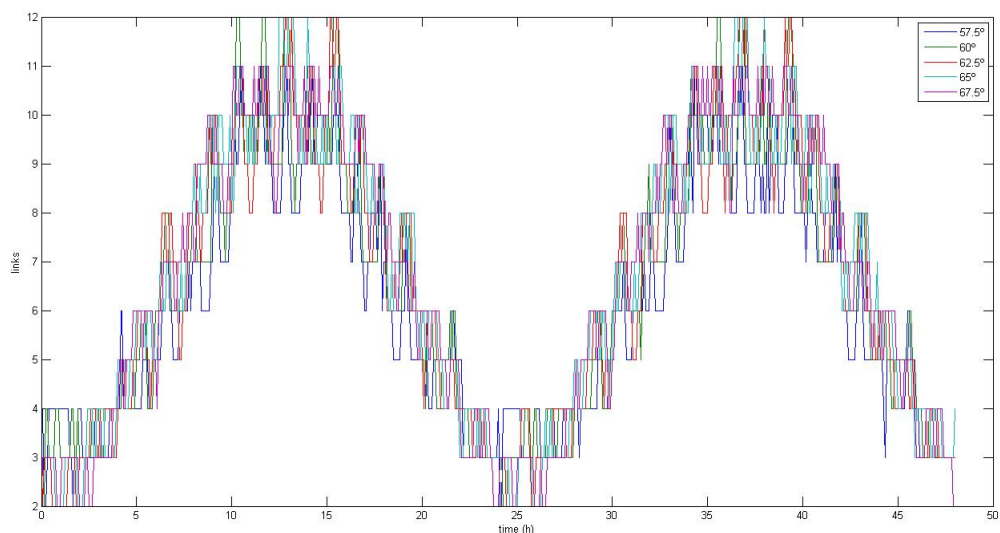


Figure 3.3.6: Links vs time for latitudes from 57.5° to 67.5°

In Figure 1.6 there is no problem with the coverage. For ensuring the results and to avoid possible loses of links locally in time, the same range of latitudes is analyze with a smaller time-step.

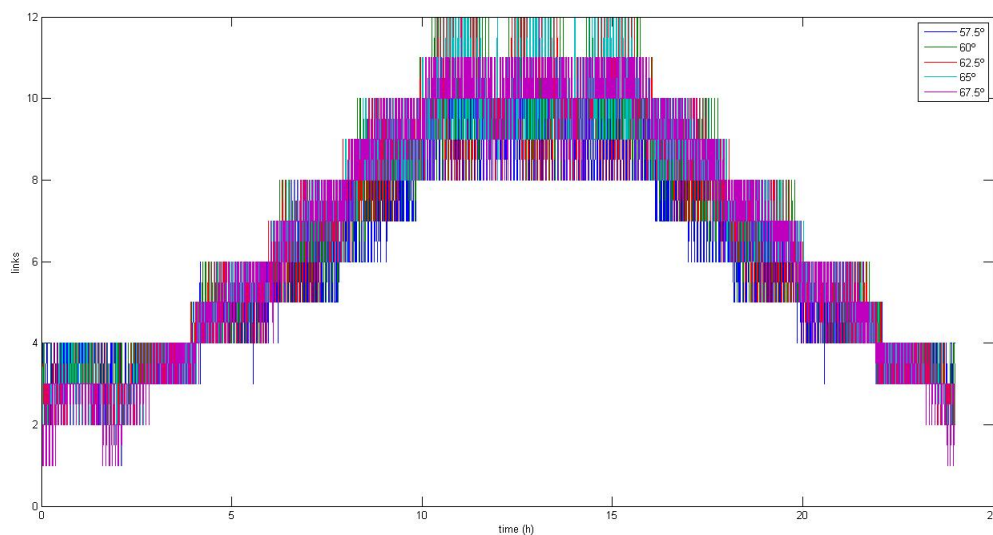


Figure 3.3.7: Links vs time for latitudes from  $57.5^\circ$  to  $67.5^\circ$  with 30 seconds time-step

It can be seen that between  $65^\circ$  and  $67.5^\circ$  the system loses the 2nd link and for a while the station would be connected only to 1 satellite. It is optimum to place the stations between  $+57.5^\circ$  and  $+62.5^\circ$  of latitude. In order to verify the results for the opposite latitudes:

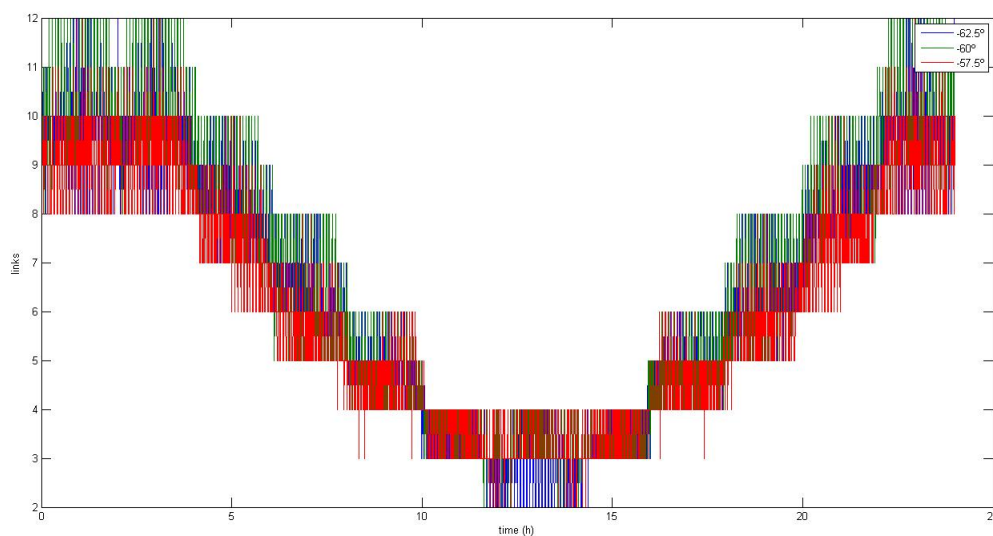


Figure 3.3.8: Links vs time for latitudes from  $-62.5^\circ$  to  $-57.5^\circ$  with 30 seconds time-step

In conclusion, the optimum latitudes for the Ground Station are:

- Between  $-62.5^\circ$  and  $-57.5^\circ$
- Between  $+57.5^\circ$  and  $+62.5^\circ$

### 3.3.3 Longitude analysis

It is intuitive to think that the effect of changing the longitude is delaying the evolution of the coverage. This effect is verified by the algorithm:

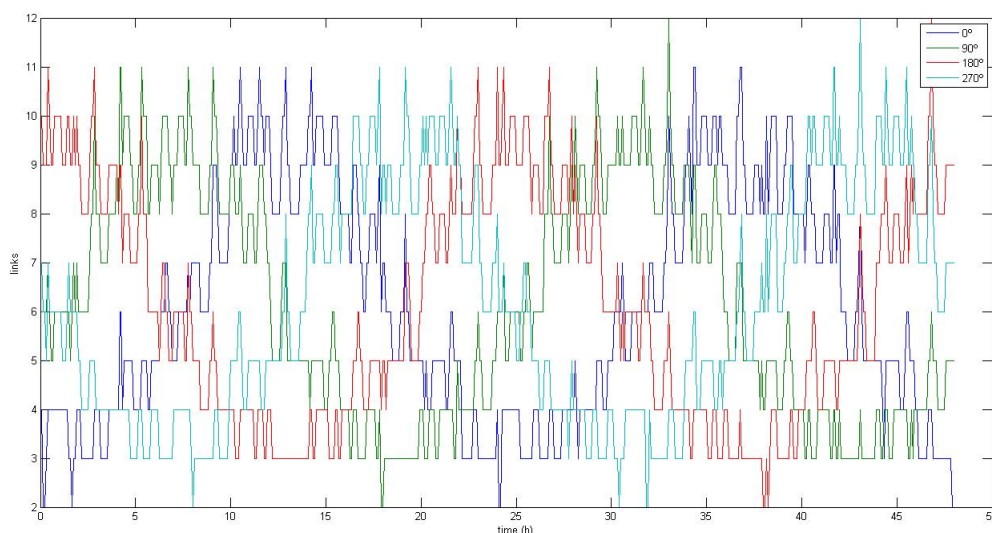


Figure 3.3.9: Links vs time for longitudes from  $0^\circ$  to  $270^\circ$

As it is seen in Figure 1.8 the delay has a reason of 3 hours for every  $45^\circ$  of longitude. This effect can be used in order to optimize the performance of the Ground Stations. During the day every station will have a peak and a valley in the coverage. Placing the stations with a relative longitude of  $120^\circ$  would ensure that when one is at the valley another one is at the peak:



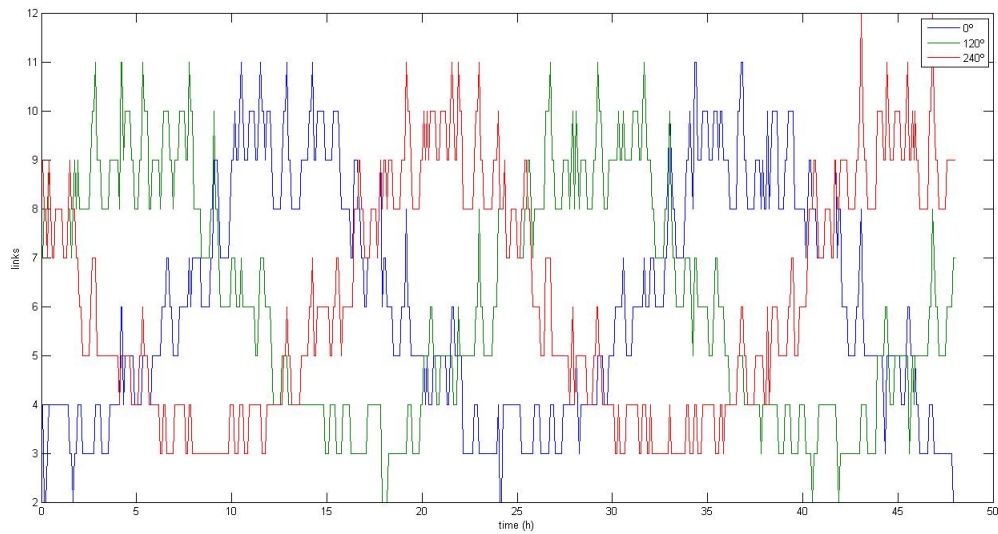


Figure 3.3.10: Links vs time for longitudes of 0°, 120° and 240°

In conclusion, the Ground Stations should be separated 120° longitude between them. It has to be taken into account that this analysis is done for stations at the same latitude. A Ground Station in a given latitude has the same coverage behaviour as an other one at the opposite latitude and 180° of longitude away. To exemplify, in the following table coordinates of equivalent places from the Ground Station point of view are showed.

	GS1		GS2		GS3	
	Latitude	Longitude	Latitude	Longitude	Latitude	Longitude
Option 1	55	0	55	120	55	240
Option 2	-55	180	55	120	55	240
Option 3	55	0	-55	300	55	240
Option 4	55	0	55	120	-55	60
Option 5	-55	180	-55	300	55	240
Option 6	-55	180	55	120	-55	60
Option 7	55	0	-55	300	-55	60
Option 8	-55	180	-55	300	-55	60

Table 3.3.1: Equivalent coordinates

### 3.3.4 Conclusion

Summarizing the results of the analysis, for an optimum performance of every Ground Station, they should be at latitudes between -62.5° and -57.5° or between +5.5° and

## Ground Station localization

+62.5°. For a better performance of the system every Ground Station should be 120° of longitude away of the other GSs if they are at the same latitude or 60° of longitude away if they are at the opposite latitude. Taking in account the topography of the Earth, the following options are proposed (every color represent the options for one Ground Station):



Figure 3.3.11: Options for placing the 3 Ground Stations.

Given this possibilities a study of the legislation of the involved countries has to be done in order to know the viability of placing there the Ground Stations. The candidate countries, as is shown in the map, are: Canada, Argentina, Chile, Falkland Islands (Islas Malvinas), United Kingdom, Denmark, Norway, Sweden and Russia.

## Part III

# Financial and Other Considerations

*"The first rule is to never lose money.  
The second rule is to never forget the  
first one. "*

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Warren Buffett

Over this chapter, the **financial study** is going to be performed. The costs and the profits will be analyzed, and some important figures will be acquired.

Moreover, some other important considerations, such as social and security issues or environmental impact will be studied too.

## Chapter 4

# Financial Study

The different departments have estimated the main costs of the project. It is high time to start performing a deep analysis on the economical solvency of the project.

Up to this point, it is important to determine how this product will be sold, so as to quantify the benefits of the project and be able to determine some figures as the Pay Back Time.

## 4.1 Selling the product: university clients

Firstly, it has been thought that the service offered has great academic interests. In fact, any student could build a satellite with a certain payload, send it to space and then receive data from the satellite at any time thanks to Astrea constellation. However, students usually do have not enough money to afford that kind of project on their own. Consequently, for aerospace students from all over the world to get access to the service, it has been decided to offer a special fare to Universities. Basically, for a reasonable price the universities will have access to our service through an annual subscription. In this way any student of the respective university will have access too.

In order to study the viability of doing a university fare, an estimation of the possible universities that would want to use the services had been done. Fortunately, the list of universities that offer studies in the aerospace field goes back a total of 400 schools approximately. Nevertheless, it is highly improbable that all those colleges become clients because not all universities have the same sources or interests. Therefore, the following list presents the number of existing colleges having an aerospace degree in each continent.

Continent	Number of Universities
Europe	124
Asia	138
North America	97
South America	18
Australia	8
Africa	12

Table 4.1.1: Table. List of Universities with Aerospace Degrees

By analyzing this information, it can be determined that the continents with countries with higher PIB have more colleges interested in the space field. It is noticed that Asia is the continent with more colleges because, even if it is mostly poor, it is so big that it has rich countries such as Japan, Korea or China and the United Arab Emirates. Moreover, Europe and North America are not so extensive but have a higher aerospace culture and interest.

On the basis the service is affordable for many prestigious colleges and it permits to provide their students with the chance to improve their knowledge by doing their own experiments, it has been estimated that about 150 universities will end up contracting

## **Selling the product: university clients**

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our service in the next years. As a result, it is considered that it is suitable to offer an special fare for universities.

## 4.2 Table with financial data

In order to perform the analysis on the economical solvency of the project, following there is a table which contains the main costs of the project, as well as the numerical operations that allow to calculate some important financial parameters, such as the Net Present Value (NPV), the Internal Rate of Return (IRR), the Simple Pay Back Time (PBT), the Updated Pay Back Time (UPBT) and the Breakeven Point (BP). From this data, some conclusions will be drawn.

[TABLA UNA VEZ SEA DEFINITIVA]



### **4.3 Conclusions of the financial study**

As a result of a few iterations of this table, changing some parameters, it has been found that:

[PBT, IRR, NPV, ...]

## Chapter 5

# Environmental Impact Study

This chapter pretends to assess the environmental consequences (positive and negative) of developing the project. The target of this study is to identify, predict, evaluate and mitigate the biophysical and social negative effects that the project could generate during the execution of it.

## 5.1 Ground Stations

At first sight the Ground Stations do not represent any environmental problem. The main factor that has to be taken into account is the placement of the stations. They have to be located in a place where they do not interfere with the ecosystem. The placement of the stations has to be adequate with the environmental legislation of the countries.

## 5.2 Satellites

For analysing the impact of the satellites it has to be studied the possible environmental impact during the fabrication and during the orbital life.

Since the fabrication of the satellites is externalized to other companies, the responsibility of the environmental consequences derived of this manufacturing is over these companies. For commercializing these products they must pass all the controls required.

During the orbital performance of the satellites, it has to be taken into account whether or not they would become orbital waste. The satellites are designed to burn out in the atmosphere at the end of their useful life. This burnt should not leave any solid residue that could precipice over the surface. The deorbit would be forced and controlled by the propulsion system of the satellite. In the case that this system fails, given that they will orbit in a LEO, they will be deorbited and burnt out naturally in a period around 5 years.

### 5.3 Launch system

The most critical part of the entire process, in environmental terms, is the launch of the satellites. For this reason the main relevance in this report is given to the spacecraft that will put the satellites in orbit, the Electron rocket of Rocket-Lab.

The company operate in New Zealand, and for doing it, the Ministry for the Environment make an accurate study of the environmental impact of the Electron launching. The entire document can be seen at [29].

In this document are analysed the critical components of the spacecraft:

- **Structure.** The primary structural material is carbon fibre reinforced polymer. The carbon filaments are chemically inert and do not react to seawater.
- **Propellants.** Liquid oxygen and kerosene (RP-1 analogue) propellants are used on both the first and second stages of the launch vehicle. Liquid oxygen, if released to the atmosphere, rapidly boils and returns to the atmosphere as gaseous oxygen. RP-1 kerosene is a highly refined grade of hydrocarbon with low density, a thin surface film and rapid evaporation.
- **Pneumatics.** All inflight pneumatic systems use stored pressurised cold gases to provide tank pressurisation, cold-gas manoeuvring thrust in space, and for stage separation mechanisms. All gases are non-toxic.
- **Engines.** The launch vehicle uses nine engines for stage 1 and a single engine for stage 2. The engines are constructed of inconel, an inert high performance, corrosion resistant nickel alloy. At stage 1 separation, the thrust section is likely to separate from the stage, return to Earth's surface and land in the Exclusive Economical Zone.
- **Batteries.** The first stage batteries are highly likely to burn-up before returning to Earth's surface. The stage 2 batteries will entirely burn-up downrange, with only the first battery potentially landing in the EEZ. The batteries are lithium-based, and contain no lead, acid, mercury, cadmium, or other toxic heavy metals.

The document also evaluates the following possible risks:

- **Risk of toxic effects.** The toxic effects of the materials comprising stage 1, the fairings and the two stage 2 LithiumIon batteries were assessed as low at all levels of launch activity.
- **Risk of ingestion of materials and provision of floating shelter.** Floating jettisoned materials as shelter for pelagic organisms and the ingestion of jettisoned

materials were both evaluated as having low ecological risk at all levels of launch activity.

- **Environmental effect of the displacement of fishing activities.** For the demersal fish and mobile invertebrate community, marine mammals and seabirds, the effects of fishing displacement would be low because these populations could also be impacted in the areas to which fishing is displaced. In the eastern jettison zone there is less fishing activity so the consequences of fishing displacement on the seabed community, demersal fish and mobile invertebrates, marine mammals and seabirds are negligible, reaching minor impacts after 1000 or more launches.
- **Effect of the provision of hard substrates.** Another potential positive outcome for seafloor biota requiring hard substrates is that the jettisoned materials would provide further attachment sites. However, even after 10,000 launches this would provide only about 50 ha of additional attachment surface, leading to a moderate benefit at most.
- **Disturbance to marine fauna.** Noise and disturbance to marine fauna above and below water is a potential consequence of the jettisoned materials falling into the jettison zone. The chance of repeated disturbance to the same individuals or groups of marine mammals or seabirds increases with the number of launches. This was assessed as a low risk for up to 100 launches over two years, a moderate risk for up to 1000 launches over almost 20 years, and a high risk for up to 10,000 launches over almost 200 years.
- **Risk of direct strikes causing mortality to components of the ecosystem.** Direct strikes causing mortality are a low risk for all components of the ecosystem up to 1000 launches over an almost 20 year period. Direct strikes reach moderate levels of risk for the benthic invertebrate community, sensitive benthic environments, and a rare threatened species, the magenta petrel, after 10,000 launches over a period of almost 200 years.
- **Risk of smothering of sea floor organisms.** Smothering the feeding or respiratory structures of sea floor organisms by jettisoned materials was assessed as a low risk for all levels of launches up to 1000 launches and a moderate risk by 10,000 launches. This is likely to be a factor principally in areas of hard substrate where the jettisoned materials are unlikely to become buried in sediment so will be important principally on the Bounty Platform.

New Zealand legislation does not yet regulate these activities, since Rocket Lab is the first company that pretends to operate rocket launchings in the territory. The study concludes that the environmental effects of the activity may become significant after 10,000 launches, this would take 200 years to reach at one launch per week. The

## **Launch system**

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regulatory regime would have been reviewed well before this number of launches. During this review the Ministry allows the activity of the company.

## Chapter 6

# Social and Security Considerations



## 6.1 Social and security considerations

The potential of the CubeSats is very high and they might be the future of satellites. Their low cost and the easiness to construct them, compared to large satellites, make them accessible to countries with fewer resources, universities and people in general, making them able to explore the space and to pursue different missions. The assembly of a CubeSat is not very complicated but requires a minimum knowledge about the subject; in other words, now "you've got a user manual, a datasheet and a 3D model that you can download, and you've got an online shop where people can buy their power systems, etc with their credit card" (CITA) [1].

This project is based on the design of a satellite constellation dedicated to communications relay between LEO satellites and between LEO satellites and the ground. This project is helping to develop the CubeSat industry and its use and it will demonstrate that these small satellites can carry out different missions that were previously done only by large satellites, as for example the communication.

Currently, the constellations of CubeSats dedicated to the communication are in development and the market is not very extensive, this is why this project, and the global coverage that it provides, could have a privileged place in this industry. The main commitment that this project has with the customers is to ensure that they will be able to communicate with any part of the world without problems.

Another important aspect to consider is that the constellation will provide total privacy to the costumers, ensuring that they make a correct use of it and avoiding that third people interfering in the communication.

In relation to security, it must ensured the proper functioning of the constellation. To do this, it must be considered three main factors, where CubeSats could be in danger: the launch of the payload, the permanence of the CubeSats in space and the ground stations.

The launch stage is one of the most important, because it is where the mission has more probability to fail. In the next figure can be observed the succes rate of orbital launches in the last 57 years. In 2014, there were a total of 92 unmaned launches and only 4 of them were failed. This indicates that the fail rate is only a 4,34 %, which is very low.

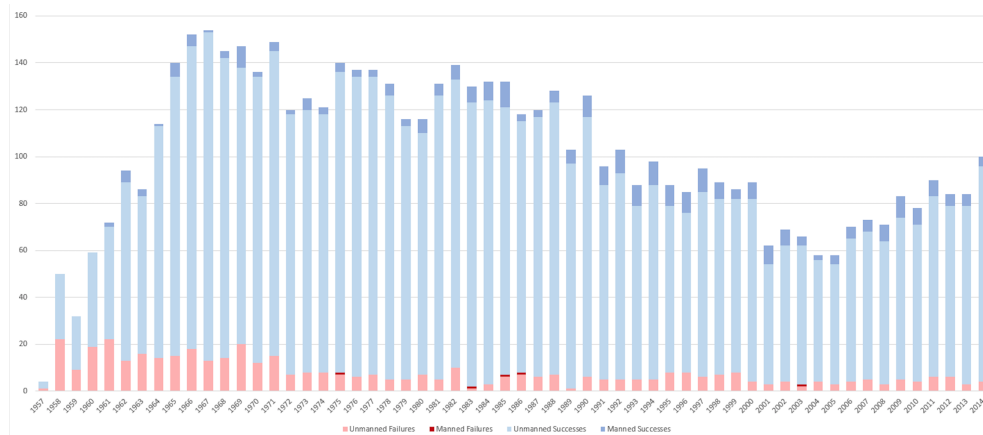


Figure 6.1.1: Orbital Launch Summary by Year

Once the constellation is in orbit, CubeSats can find dangers how colliding with other satellites or with space debris. The distances between most satellites is around hundreds of miles and there is not danger of collision, but the movement of space debris is unpredictable. In order to avoid this space debris, a CubeSat can perform a Debris Avoidance Manoeuvre (DAM). The responsible to control these fragmentation debris is *The United States Space Surveillance Network*. It consists of ground-based radars and optical sensors at 25 sites worldwide and Currently tracks more than 8000 orbiting objects.

Finally, the ground stations are a key element for the correct operation of the constellation and they must prevented from stop working. To do this, each ground station will have its operator, to control the operation of the installation, and a security system, to avoid intrusions.

## 6.2 Legislation

The legislation concerning activities related to space is the Space Law. Space Law is an international law comprised of international treaties and agreements. Its most important rules are the five international treaties, which have been developed under the supervision of the United Nations. The body that promotes these regulations is the United Nations Office for Outer Space Affairs (UNOOSA).

The international law is only applicable to the states that are parties to the treaties. According to the Outer Space Treaty, states are responsible for their national space activities, public or private. For this reason, each state usually adopts its national space regulations.

In the case of the Astrea constellation, since the company is based in Spain (a party of the Space Law), the current legislation is the *Real Decreto 278/1995* of 24 February 1995. According to this Royal Decree, the objects launched from Spain or whose launch has been promoted by Spain, should be registered in the *Registro Español de Objetos Espaciales Lanzados al Espacio Ultraterrestre* (Spanish Registry of Objects Launched into Outer Space). The necessary data to register the satellite must be provided to the *Dirección General de Tecnología Industrial del Ministerio de Industria y Energía* (Department of Industrial Technology of the Ministry of Industry and Energy). This department will notificate the registry to the Secretary-General of the United Nations.

The registration has to contain the following data:

- a) Name of launching State or States;
- b) An appropriate designator of the space object or its registration number;
- c) Date and territory or location of launch;
- d) Basic orbital parameters, including:
  - I) Nodal period;
  - II) Inclination;
  - III) Apogee;
  - IV) Perigee;
- e) General function of the space object.

and any other useful information. For example, in the case of one of the Astrea satellites, the registration will be:

## Legislation

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- a) Spain
- b) AstreaSAT 1
- c) 22 February 2018,
- d) Basic orbital parameters: Low Earth Orbit
  - I) 95,4815 minutes
  - II) 72 degrees
  - III) 6.913,0 km
  - IV) 6.913,0 km
- e) CubeSat 3U, part of the communications constellation Astrea

## Chapter 7

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