

ENGR-E 533 “Deep Learning Systems”

Lecture 04: The First Layer

Minje Kim

Department of Intelligent Systems Engineering

Email: minje@indiana.edu

Website: <http://minjekim.com>

Research Group: <http://saige.sice.indiana.edu>

Meeting Request: <http://doodle.com/minje>



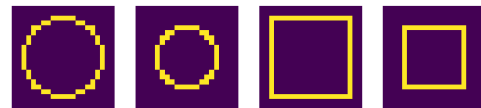
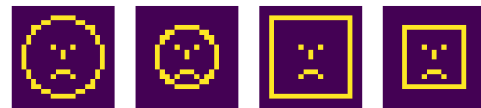
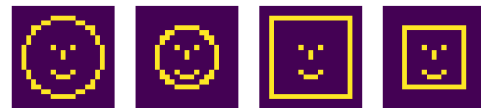
INDIANA UNIVERSITY

**SCHOOL OF INFORMATICS,
COMPUTING, AND ENGINEERING**

Unsupervised Feature Learning

- What do we do in the first layer?

- Before deep learning, a common practice was to extract features and then learn a supervised model
 - Source separation
 - Convert the time domain audio signals into matrices by using Short-Time Fourier Transform (STFT) and then learn dictionaries
 - Object recognition
 - Extract a bunch of different features (e.g. HoG, SIFT, etc) and then build a classifier
 - Sentiment analysis
 - Preprocess the text, learn topics, and then build a classifier
 - Speech recognition
 - Extract Mel-Frequency Cepstrum Coefficients (MFCC) and then learn Hidden Markov Models
- YALT
 - In our baby facial expression recognition problem we manually extracted the features first
 - And then built a softmax classifier



Unsupervised Feature Learning

- What do we do in the first layer?

- Today we will learn how to systematically learn those features from raw data
 - We call this procedure **unsupervised feature learning**
 - Don't worry, we're not getting away from neural networks
- Why unsupervised?
 - Supervision here means human intervention to solve the problem
 - e.g. When you train a classifier, you need a bunch of pairs: a data sample (facial image) and its label (happy or sad)
 - You let the model know how you think of the problem
 - Mathematically, this can be done by either learning the mapping function between the data sample and its label
$$\mathbf{y} = \mathcal{F}(\mathbf{x}) \quad \hat{\mathbf{y}} = \mathcal{G}(\mathbf{x} ; \mathbb{W})$$
 - Or, finding the parameters that maximize the *a posteriori* probability
$$P(\mathbf{y}|\mathbf{x}; \Theta)$$
 - Unsupervised learning
 - You don't have the human intervention, or the labels
 - Then, what are we learning?
 - A model that best describes the data



Unsupervised Feature Learning

- What do we do in the first layer?

o Modeling the data

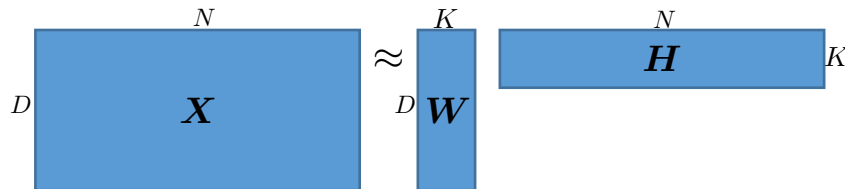
- If we use a probabilistic distribution it's to find out the maximum likelihood solution

$$P(\mathbf{x}; \Theta)$$

- Often, this can be viewed as a latent variable analysis with K latent variables, too

The data matrix $\rightarrow \mathbf{X} \approx \mathbf{W}\mathbf{H} \leftarrow$ The activation of the latent variable

The representative vectors of the latent variable



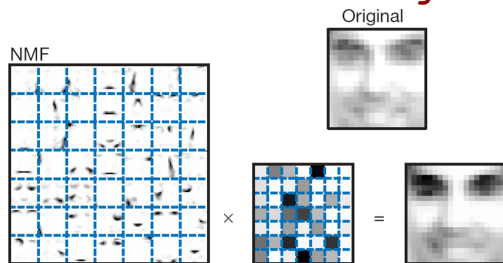
o For example

- If you find the eigenvectors of $\mathbf{X}\mathbf{X}^T$, that will correspond to \mathbf{W}
 - $\mathbf{W}^T\mathbf{W} = \mathbf{I}$ and, therefore, $\mathbf{W}^T\mathbf{X} = \mathbf{H}$. Also, rows of \mathbf{H} are ordered in their variances
 - Principal Component Analysis
 - \mathbf{H} is a set of lower dimensional features that can still describe the original distribution
- If $\mathbf{X}_{:,n} \sim \sum_k \mathbf{H}_{k,n} \mathcal{N}(\mathbf{W}_{:,k}, \Sigma_{:,k})$ and $\mathbf{H}_{:,n}$ is a one hot vector
 - Gaussian Mixture Model (a.k.a. Vector Quantization)
- If you find \mathbf{W} and \mathbf{H} that minimize the approximation error, but are nonnegative at the same time
 - Nonnegative Matrix Factorization
 - \mathbf{H} gives you the parts-based representation

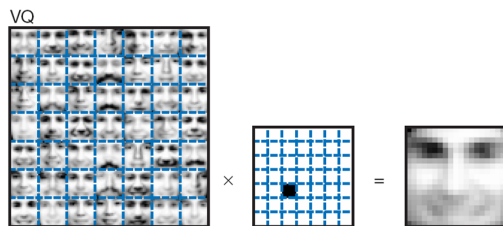


Unsupervised Feature Learning

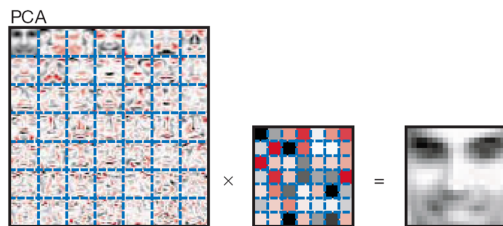
- What do we do in the first layer?



NMF estimates parts-based representations, something like Lego blocks. Reconstruction is a linear combination of them, but subtraction is not allowed.



VQ finds a bunch of cluster means. Reconstruction is choosing the most similar mean.



PCA finds the holistic eigenfaces. From the important one down to the subtle ones.

Unsupervised Feature Learning

- What do we do in the first layer?

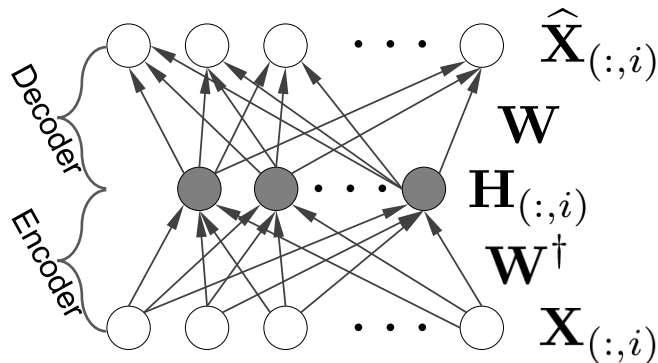
- There are so many different ways to solve the linear approximation $\mathbf{X} \approx \mathbf{W}\mathbf{H}$
- So, eventually it's all about how to constrain the problem

$$\arg \min_{\mathbf{W}, \mathbf{H}} \mathcal{D}(\mathbf{X} || \mathbf{W}\mathbf{H}) + \lambda_{\mathbf{W}} f(\mathbf{W}) + \lambda_{\mathbf{H}} g(\mathbf{H})$$

- For clustering, you want a super sparse column vectors in \mathbf{H} so that the data sample is one of the cluster means, deviated accordingly
- For PCA, you want the after-projection-samples are with maximal variances
- For NMF, you constrain \mathbf{W}, \mathbf{H} to be nonnegative (element-wise)
- ...
- It is convenient to assume that there exists some kind of pseudo inverse of \mathbf{W}
 - For PCA, $\mathbf{W}^\dagger = \mathbf{W}^\top$
 - For NMF, $\mathbf{W}^\dagger = \mathbf{W}^\top$ depending on the choice of the error function $\mathbf{H} \leftarrow \mathbf{H} \odot \frac{\mathbf{W}^\top \mathbf{X}}{\mathbf{W}^\top \mathbf{W} \mathbf{H}}$
- If you assume this pseudo inverse of the basis vectors, you can think of the projection as a way to convert your data into features $\mathbf{W}^\dagger \mathbf{X} \approx \mathbf{W}^\dagger \mathbf{W} \mathbf{H} \approx \mathbf{H}$

The Autoencoders

- A unified neural network-based representation of unsupervised learning



$$\arg \min_{\mathbf{W}, \mathbf{W}^\dagger, \mathbf{H}} \mathcal{D}(\mathbf{X} || \mathbf{W} \mathbf{W}^\dagger \mathbf{X}) + \lambda_{\mathbf{W}} f(\mathbf{W}) + \lambda_{\mathbf{W}^\dagger} f(\mathbf{W}^\dagger) + \lambda_{\mathbf{H}} g(\mathbf{H})$$

- Once the objective function is setup in this way, you can estimate the parameters using SGD
 - TF or PT will take care of this part using automatic gradient calculation

The Autoencoders

- A unified neural network-based representation of unsupervised learning

- Demo

- Sparse coding
- NMF



Nonlinearity in Neural Networks

- Stacked linear models form another linear model

- So far I haven't said anything about nonlinearity in the lower layers (at least officially)
- Why do we need it?
 - Because stacked linear models form yet another linear model

○ Stacked linear models

$$x_1^{(2)} = w_{11}^{(1)} x_1^{(1)} + w_{12}^{(1)} x_2^{(1)} + b_1^{(1)}$$

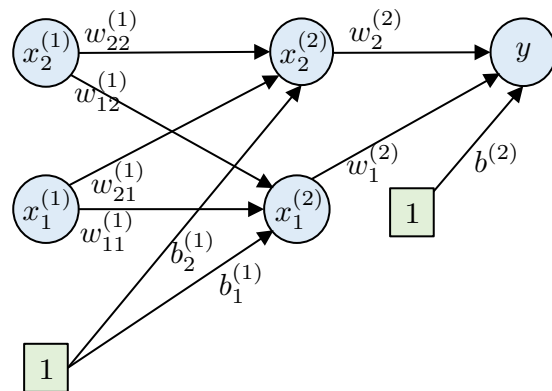
$$x_2^{(2)} = w_{21}^{(1)} x_1^{(1)} + w_{22}^{(1)} x_2^{(1)} + b_2^{(1)}$$

$$y = w_1^{(2)} x_1^{(2)} + w_2^{(2)} x_2^{(2)} + b^{(2)}$$

○ Form another linear model

$$\begin{aligned} y &= w_1^{(2)} w_{11}^{(1)} x_1^{(1)} + w_1^{(2)} w_{12}^{(1)} x_2^{(1)} + w_1^{(2)} b_1^{(1)} \\ &\quad + w_2^{(2)} w_{21}^{(1)} x_1^{(1)} + w_2^{(2)} w_{22}^{(1)} x_2^{(1)} + w_2^{(2)} b_2^{(1)} + b^{(2)} \\ &= (w_1^{(2)} w_{11}^{(1)} + w_2^{(2)} w_{21}^{(1)}) x_1^{(1)} + (w_1^{(2)} w_{12}^{(1)} + w_2^{(2)} w_{22}^{(1)}) x_2^{(1)} + w_1^{(2)} b_1^{(1)} + w_2^{(2)} b_2^{(1)} + b^{(2)} \end{aligned}$$

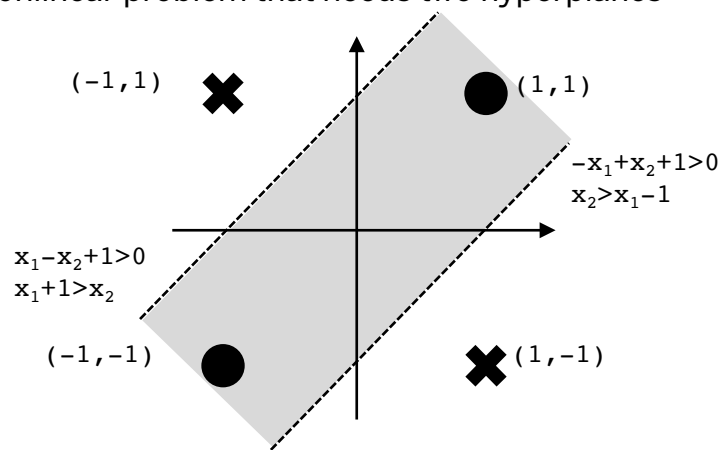
- Or $y = \mathbf{w}^{(2)} (\mathbf{W}^{(1)} \mathbf{x} + \mathbf{b}^{(1)}) + b^{(2)}$
 $= \mathbf{w}^{(2)} \mathbf{W}^{(1)} \mathbf{x} + \mathbf{w}^{(2)} \mathbf{b}^{(1)} + b^{(2)}$



Nonlinearity in Neural Networks

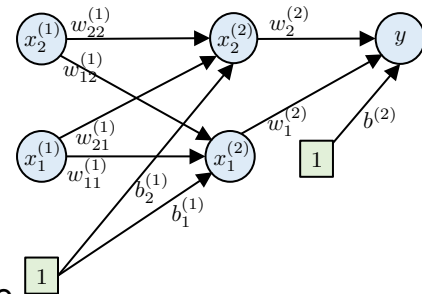
- Stacked linear models form another linear model

- What can we do then?
- The XOR problem
 - A nonlinear problem that needs two hyperplanes

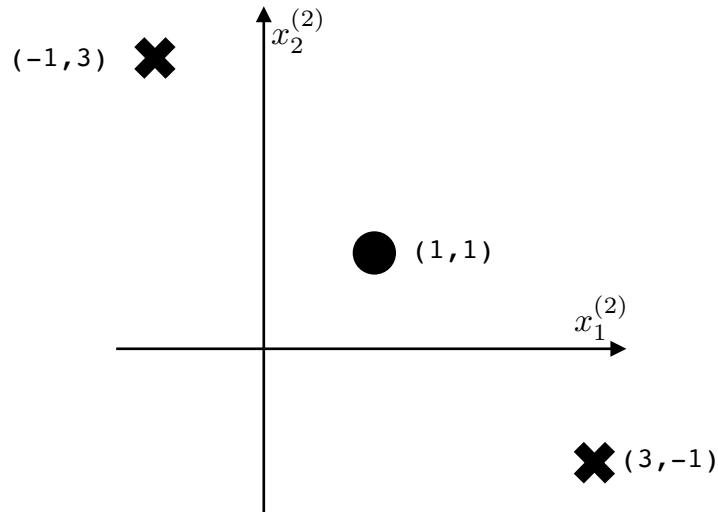


- How do you transform the data into features?
 - It must have something to do with hyperplanes

$$W^{(1)} = \begin{bmatrix} +1 & -1 & 1 \\ -1 & +1 & 1 \end{bmatrix}$$



- The new feature space



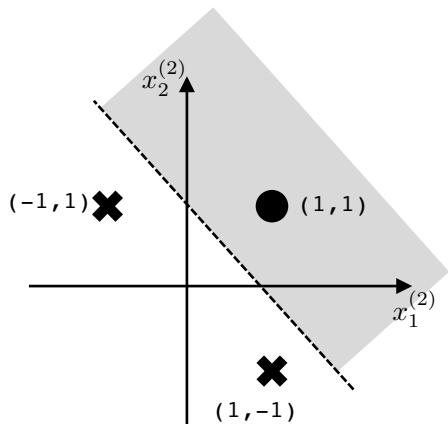
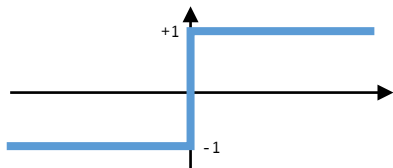
- What happens in the feature space?
 - If it were not for the help from the nonlinearity
 - Still NOT linearly solvable!

Nonlinearity in Neural Networks

- Adding nonlinearity

- With a sign function

$$x_i^{(2)} = \text{sign}(\mathbf{W}_{i,:}^{(1)} \mathbf{x} + b_i^{(1)})$$

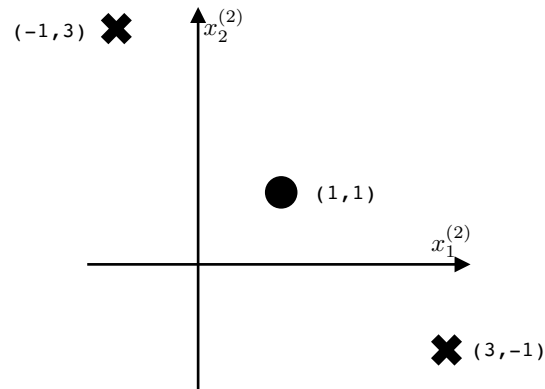
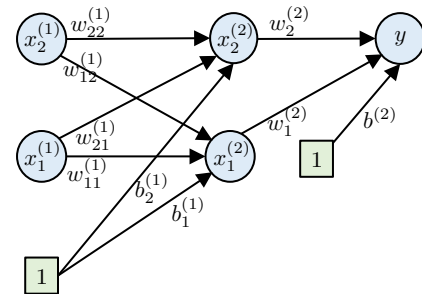
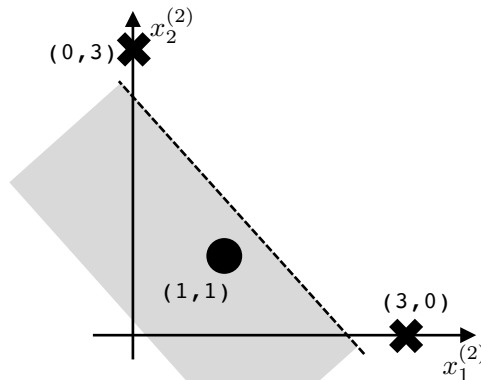
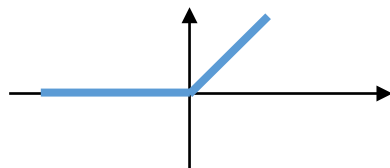


Now they are linearly solvable!

New hyperplane corresponds to the last layer weights

- With a Rectified Linear Unit (ReLU)

$$x_i^{(2)} = \max(\mathbf{W}_{i,:}^{(1)} \mathbf{x} + b_i^{(1)}, 0)$$



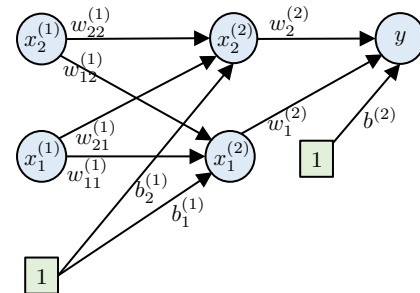
Nonlinearity for AEs?

- What does the XOR example mean for unsupervised learning?

- You can replace the final layer binary output with the input vector
 - Classifier turns into an AE
- Suppose you can estimate these weights of the XOR network by using BP
- Can you also estimate these weights with the AE setup?
- You just saw that nonlinearity can help producing better features
- AE might benefit from it to

$$\arg \min_{\mathbf{W}, \mathbf{W}^\dagger, \mathbf{H}} \mathcal{D}(\mathbf{X} || \mathbf{W} \sigma(\mathbf{W}^\dagger \mathbf{X})) + \lambda_{\mathbf{W}} f(\mathbf{W}) + \lambda_{\mathbf{W}^\dagger} f(\mathbf{W}^\dagger) + \lambda_{\mathbf{H}} g(\mathbf{H})$$

- But it's not clear if the encoder weights are going to be actually create useful features for the following classification
- We will cover this part in the next time



The Pipeline for Supervised Learning

- What people have done so far before deep learning

- Feature engineering
 - Tries to come up with a set of features that best describe the data and the problem
 - There can be many different ways (as you've seen)
 - You never know the quality until you actually test out those features for your problem
- Supervised learning (classification/regression)
 - Tries to come up with the best model to best predict the output variable
 - Even if you use a very nice set of features, nonlinearity can be still involved (e.g. kernel methods for SVM)
 - If you don't like the performance, you never know what to blame
 - It could be because of either bad feature engineering or classifier
- A holistic approach
 - In a multilayer perceptron, you have the first layer dedicated to the feature extraction
 - And the last layer as your supervised learning part
 - What if you just optimize the weights of both layers all together?
 - Then, you can skip the feature engineering part
 - Does this work? When does this approach not work? Why?





Thank You!

