

## Theory of computation

Automata theory (also known as **Theory of Computation**) is a theoretical branch of Computer Science and Mathematics

is the branch that deals with how efficiently problems can be solved on a model of computation, using an algorithm

deals with the logic of computation with respect to simple machines, referred to as automata

Automata\* enables the scientists to understand how machines compute the functions and solve problems

*"What are the fundamental capabilities and limitations of computers?*

- **Automaton=an abstract computing device**
  - a device need not even be a physical hardware

## Central Concepts of Automata Theory

- **Symbols** --- a, b, 0, 1, 2 etc
- **Alphabet** --- a set of symbols
- **Strings** --- a sequence of symbols from an alphabet
- **Language** --- a set of strings from the same alphabet

## Alphabets

An alphabet is a finite, nonempty set of symbols.

- Conventional notation ---  $\Sigma$
- The term “symbol” is usually undefined.
- Examples ---
  - Binary alphabet  $\Sigma = \{0, 1\}$ .
  - $\Sigma = \{a, b, \dots, z\} \dots$

## Strings

A string (or word) is a finite sequence of symbols from an alphabet.

- Example ---
- 1011 is a string from alphabet  $\Sigma = \{0, 1\}$
- Empty string  $\varepsilon$  --- a string with zero occurrences of symbols
- Length  $|w|$  of string  $w$  --- the number of positions for symbols in  $w$
- Examples ---  $|0111|=4$ ,  $|\varepsilon|=0$ , ...

## Languages

## Languages

### More examples of languages ---

- The set of all strings of  $n$  0's followed by  $n$  1's for  $n \geq 0$ :  
 $\{\epsilon, 01, 0011, 000111, \dots\}$
  - $\Sigma^*$  is an infinite language for any alphabet  $\Sigma$ .
  - $\emptyset =$  the empty language (not the empty string  $\epsilon$ ) is a language over any alphabet.
- ↳
- $\{\epsilon\}$  is a language over any alphabet (consisting of only one string, the empty string  $\epsilon$ ).

## Extended Transition Function

We describe the effect of a string of inputs on a DFA by extending  $\hat{\delta}$  to a state and a string.

Induction on length of string.

Basis  $\hat{\delta}(q, \epsilon) = q$  X  $\alpha$

Suppose  $w$  is a string where  $w=xa$ .

$w=1101$  is broken into  $x=110$  and  $a=1$ .

Induction:  $\hat{\delta}(q, w) = \hat{\delta}(\hat{\delta}(q, x), a) = r$

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$x \quad a$

	0	1
A	A	B
B	A	C
C	C	C

$$\hat{\delta}(B, 011) = \hat{\delta}(\hat{\delta}(B, 01), 1) = \hat{\delta}(\hat{\delta}(\hat{\delta}(B, 0), 1), 1) =$$

$$\hat{\delta}(\hat{\delta}(A, 1), 1) = \hat{\delta}(B, 1) = C$$

	0	1
A	A	B
B	A	C
C	C	C

$$\omega = 011$$

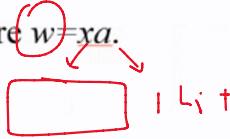
$$\begin{aligned}
 & \hat{\delta} \left( B, \frac{0}{\alpha} \middle| \frac{1}{\alpha} \right) \\
 = & \delta \left( \hat{\delta} \left( B, \underline{0} \right), 1 \right) \\
 = & \delta \left( \delta \left( \delta \left( B, \underline{0} \right), 1 \right), 1 \right) \\
 & \quad \delta(A, 1) \\
 & \quad \delta(B, 1) = C
 \end{aligned}$$

## Extended transition function for NFA

- Basis:  $\hat{\delta}(q, \epsilon) = \{q\}$

Induction: Suppose  $w$  is a string where  $w = xa$ .

- Let  $\hat{\delta}(q, x) = \{p_1, p_2, \dots, p_k\}$

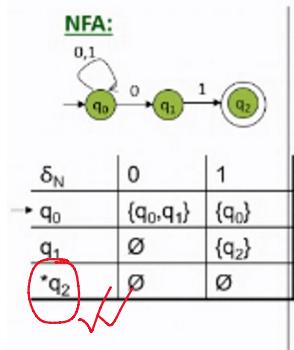


- $\bigcup_{i=1}^k \delta(p_i, a) = \{r_1, r_2, r_3, \dots, r_m\}$

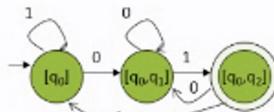
$$\hat{\delta}(q, w) = \{r_1, r_2, r_3, \dots, r_m\}$$

## NFA to DFA: Repeating the example using *LAZY CREATION*

$$L = \{w \mid w \text{ ends in } 01\}$$



DFA:



$\delta_D$	0	1
$[q_0]$	$[q_0, q_1]$	$[q_0]$
$[q_0, q_1]$	$[q_0, q_1]$	$[q_0, q_2]$
$*[q_0, q_2]$	$[q_0, q_1]$	$[q_0]$

Main Idea:

Introduce states as you go  
(on a need basis)

# FA with $\epsilon$ -Transitions

- We can allow explicit  $\epsilon$ -transitions in finite automata
  - i.e., a transition from one state to another state without consuming any additional input symbol
  - Explicit  $\epsilon$ -transitions between different states introduce non-determinism.
  - Makes it easier sometimes to construct NFAs
  - This means that a transition is allowed to occur without reading in a symbol.

**Definition:**  $\epsilon$ -NFAs are those NFAs with at least one explicit  $\epsilon$ -transition defined.

- $\epsilon$ -NFAs have one more column in their transition table

Transition function  $\delta$  is now a function that takes as arguments:

- A state in  $Q$  and
- A member of  $\Sigma \cup \{\epsilon\}$ ; that is, an input symbol or the symbol  $\epsilon$ . We require that  $\epsilon$  not be a symbol of the alphabet  $\Sigma$  to avoid any confusion.

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## $\epsilon$ -Transitions

### Use of $\epsilon$ -transitions

We allow the automaton to accept the empty string  $\epsilon$ .

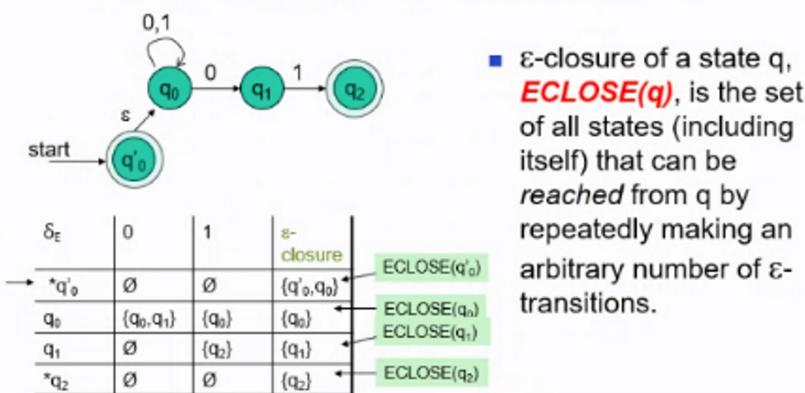
This means that a transition is allowed to occur without reading in a symbol.

The resulting NFA is called  $\epsilon$ -NFA.

It adds “programming (design) convenience” (more intuitive for use in designing FA’s)

## Example #2: $\epsilon$ -NFA..

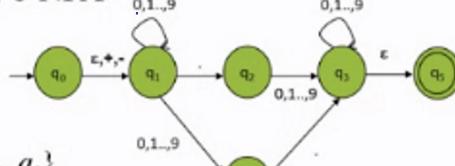
$$L = \{w \mid w \text{ is empty, or if non-empty will end in } 01\}$$



- $\epsilon$ -closure of a state  $q$ ,  $ECLOSE(q)$ , is the set of all states (including itself) that can be reached from  $q$  by repeatedly making an arbitrary number of  $\epsilon$ -transitions.

## FA with $\epsilon$ -transition

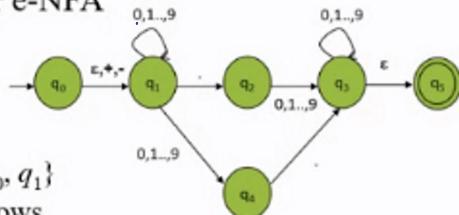
Computing  $\hat{\delta}(q_0, 5.6)$  for e-NFA



$$\hat{\delta}(q_0, \epsilon) = ECLOSE(q_0) = \{q_0, q_4\}$$

## FA with $\epsilon$ -transition

Computing  $\hat{\delta}(q_0, 5.6)$  for e-NFA



- $\hat{\delta}(q_0, \epsilon) = \text{ECLOSE}(q_0) = \{q_0, q_1\}$

- Compute  $\hat{\delta}(q_0, 5)$  as follows

1.  $\hat{\delta}(q_0, 5) = (q_0, 5\epsilon) = \text{ECLOSE}(\delta(q_0, 5) \cup \delta(q_1, 5)) = \{q_1, q_4\}$
2. ECLOSE the result of step (1)

$$= \text{ECLOSE}(\{q_1, q_4\}) = \text{ECLOSE}(\{q_1\}) \cup \text{ECLOSE}(\{q_4\}) \\ = \{q_1, q_4\}$$

- Compute  $\hat{\delta}(q_0, 5.)$

- Compute  $\hat{\delta}(q_0, 5.6)$

$\left\{ \quad \right\}$

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$$\hat{\delta}(q_0, \cdot) = \text{ECLOSE}\left(\delta(q_1, \cdot) \cup \delta(q_4, \cdot)\right)$$

$$= \text{ECLOSE}(q_1, q_4)$$

$$= \{q_2, q_3, q_5\}$$

$$\hat{\delta}(q_0, 5 \cdot 6) = \text{ECLOSE}\left(\delta(q_1, 6) \cup \delta(q_4, 6) \cup \delta(q_5, 6)\right)$$

$$= \text{ECLOSE}(q_3),$$

$$= \{q_3, q_5\}$$

## RE's: Definition

- Basis 1: If  $a$  is any symbol, then  $a$  is a RE, and  $L(a) = \{a\}$ .  
Note:  $\{a\}$  is the language containing one string, and that string is of length 1.  
Basis 2:  $\epsilon$  is a RE, and  $L(\epsilon) = \{\epsilon\}$ .  
Basis 3:  $\emptyset$  is a RE, and  $L(\emptyset) = \emptyset$ .

## RE's: Definition – (2)

**Induction 1:** If  $E_1$  and  $E_2$  are regular expressions, then  $E_1 + E_2$  is a regular expression, and  $L(E_1 + E_2) = L(E_1) \cup L(E_2)$ .

**Induction 2:** If  $E_1$  and  $E_2$  are regular expressions, then  $E_1 E_2$  is a regular expression, and  $L(E_1 E_2) = L(E_1)L(E_2)$ .



**Concatenation**: the set of strings  $wx$  such that  $w$  is in  $L(E_1)$  and  $x$  is in  $L(E_2)$ .

## RE's: Definition – (3)

**Induction 3:** If  $E$  is a RE, then  $E^*$  is a RE, and  $L(E^*) = (L(E))^*$ .

**Closure**, or "Kleene closure" = set of strings  $w_1 w_2 \dots w_n$ , for some  $n \geq 0$ , where each  $w_i$  is in  $L(E)$ .



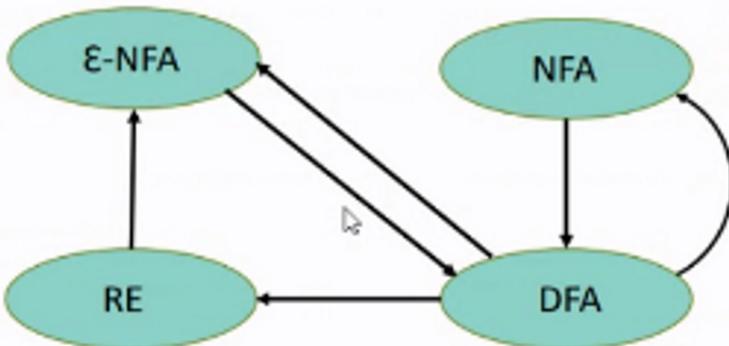
**Note:** when  $n=0$ , the string is  $\epsilon$ .

## Precedence of Operators

Parentheses may be used wherever needed to influence the grouping of operators.

Order of precedence is \* (highest), then concatenation, then + (lowest).

# From DFA to RE



$$R_{i,j}^k$$

Recursive step: for each  $k$ , we can build  $R_{i,j}^k$  as follows:

$$R_{i,j}^k = R_{i,j}^{k-1} + R_{i,k}^{k-1} (R_{k,k}^{k-1})^* R_{k,j}^{k-1}$$

Intuition: since the accepting sequence contains one or more visits to state  $k$ , break the path into pieces that

- first goes from  $i$  to its first  $k$ -visit ( $R_{i,k}^{k-1}$ )
- followed by zero or more revisits to  $k$  ( $(R_{k,k}^{k-1})^*$ )
- followed by a path from  $k$  to  $j$  ( $R_{k,j}^{k-1}$ )

## Pumping Lemma for Regular Languages

Let  $L$  be a regular language

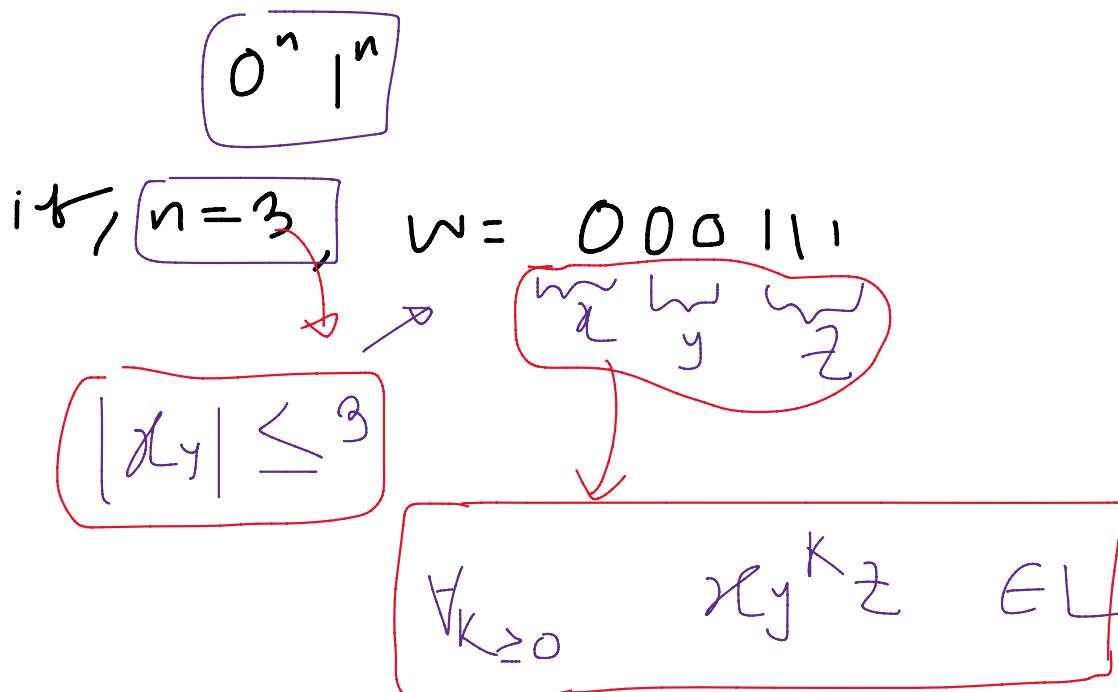
Then **there exists** some constant  $N$  such that **for every** string  $w \in L$  s.t.  $|w| \geq N$ , **there exists** a way to break  $w$  into three parts,  $w = xyz$ , such that:

1.  $y \neq \epsilon$
2.  $|xy| \leq N$
3. For all  $k \geq 0$ , all strings of the form  $xy^kz \in L$

This property should hold for **all** regular languages.

**Definition:**  $N$  is called the "Pumping Lemma Constant"

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$$K=0 \quad w = xy^0z = 0\underline{11} \notin L$$

$$K=1 \quad w = xy^1z = 0\underline{011} \in L$$

$$K=2 \quad w = xy^2z = 0\underline{0011} \notin L$$

$$0^n 1^n \rightarrow w \rightarrow xyz, |xy| \leq n$$

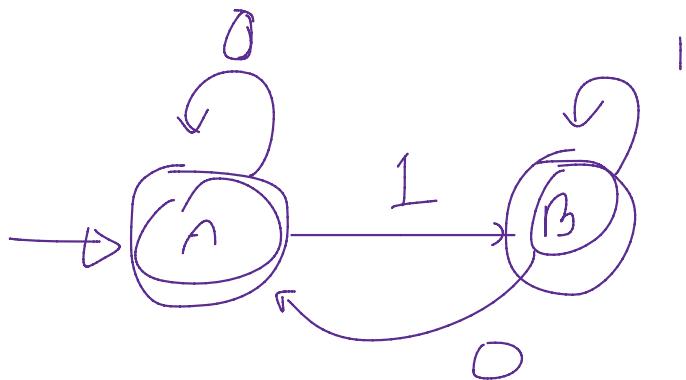
$$\omega = \boxed{0^* \mid ^*} = \frac{0}{n} \mid \frac{111}{z}$$

$|\omega| \leq \boxed{2}$

$$\forall_{k \geq 0} xy^k z \in L$$

$$k=0 \quad w = xyz = 0111 \in L$$

$$k=2 \quad w = xyz = \boxed{000111}$$



$$\omega = 00111$$

$$|\omega| = 5$$

$n=2 \rightarrow$  <sup>n of</sup> states in DFA

$$|w|\geq n$$