

## Lagrange Interpolation Polynomial

Let  $x_0, x_1, \dots, x_n$  denote  $n$  distinct real numbers and  $f_0, f_1, \dots, f_n$  be arbitrary real numbers. The points  $(x_0, f_0), (x_1, f_1), \dots, (x_n, f_n)$  can be imagined to be data values connected by a curve. Any function  $P(x)$  satisfying the condition

$$P(x_k) = f_k \text{ for } k=0, 1, \dots, \dots, n$$

is called interpolation function. Let us consider a second order polynomial of the form,

$$P_2(x) = b_0(x-x_1)(x-x_2) + b_1(x-x_0)(x-x_2) + b_2(x-x_0)(x-x_1) \dots \dots \dots \quad (i)$$

If  $(x_0, f_0), (x_1, f_1)$  and  $(x_2, f_2)$  are three interpolating points then we have,

$$P_2(x_0) = f_0 = b_0(x_0-x_1)(x_0-x_2)$$

$$\therefore b_0 = \frac{f_0}{(x_0-x_1)(x_0-x_2)}$$

$$P_2(x_1) = f_1 = b_1 (x_1 - x_0)(x_1 - x_2)$$

$$\therefore b_1 = \frac{f_1}{(x_1 - x_0)(x_1 - x_2)}$$

$$P_2(x_2) = f_2 = b_2 (x_2 - x_0)(x_2 - x_1)$$

$$\therefore b_2 = \frac{f_2}{(x_2 - x_0)(x_2 - x_1)}$$

①  $\Rightarrow$

$$P_2(x) = b_0 \frac{(x - x_1)(x - x_2)}{(x_0 - x_1)(x_0 - x_2)} + b_1 \frac{(x - x_2)(x - x_0)}{(x_1 - x_0)(x_1 - x_2)}$$

$$+ b_2 \frac{(x - x_0)(x - x_1)}{(x_2 - x_0)(x_2 - x_1)}$$

$$= b_0 l_0(x) + b_1 l_1(x) + b_2 l_2(x)$$

$$= \sum_{i=0}^2 b_i l_i(x) \dots \dots \dots (2)$$

$$\text{Where, } l_i(x) = \prod_{j=0, j \neq i}^n \frac{x - x_j}{x_i - x_j} \dots \dots \dots (3)$$

$$P_n(x) = \sum_{i=0}^n b_i \prod_{j=0, j \neq i}^n \frac{(x - x_j)}{(x_i - x_j)} \rightarrow n \text{ degree polynomial}$$

$$P_n(x) = \sum_{i=0}^n b_i l_i(x) \text{ in general} \dots \dots \dots (4)$$

$$\text{where } l_i(x) = \prod_{j=0, j \neq i}^n \frac{x - x_j}{x_i - x_j} \quad (5)$$

Eq<sup>n</sup> ④ is called Lagrange Interpolation polynomial

Eq<sup>n</sup> (5) is called Lagrange Basis polynomial.

For  $n=1$

$$\begin{aligned} P_1(x) &= f_0 l_0(x) + f_1 l_1(x) \\ &= f_0 \frac{x - x_1}{x_0 - x_1} + f_1 \frac{x - x_0}{x_1 - x_0} \\ &= f_0 + \frac{f_1 - f_0}{x_1 - x_0} (x - x_0) \dots \dots \dots \quad (6) \end{aligned}$$

Eq<sup>n</sup> (6) is called Linear Interpolation Formula.

$$\begin{aligned} &\rightarrow f_1 x - f_1 x_0 - f_0 x + f_0 x_1 \\ &= \frac{x_1 - x_0}{x_1 - x_0} \rightarrow f_0 x_0 \text{ and } f_1 x_0 \\ &= \frac{f_1 x - f_1 x_0 - f_0 x + f_0 x_1 - \overbrace{f_0 x_0 + f_0 x_0}}{x_1 - x_0} \rightarrow f_0 x_0 \text{ and } f_1 x_0 \text{ (extra)} \\ &= \frac{(x_1 - x_0) f_0 + x (f_1 - f_0) + x_0 (f_0 - f_1)}{x_1 - x_0} \\ &= f_0 + \frac{(f_1 - f_0)(x - x_0)}{x_1 - x_0} \\ &= f_0 + \frac{f_1 - f_0}{x_1 - x_0} (x - x_0) \end{aligned}$$

Oct 23, 2017  
Mahmud Sir

Eg - 9.3

$x$	1	2	3	4	5
$f(x)$	1	1.4142	1.7321	2	2.2361

Well defined for your square root table. अमर्त्यनानी विद्या विज्ञान एवं तकनीकी संस्कृत विश्वविद्यालय

Determine the square root of 2.5 using linear interpolation polynomial.

Soln:

$$x_1 = 2, f(x_1) = 1.4142$$

$$x_2 = 3, f(x_2) = 1.7321$$

$$\therefore f(x) = f(x_1) + (x - x_1) * \frac{f(x_2) - f(x_1)}{x_2 - x_1}$$

straight line eqn  
 $y = mx + c$

$$\therefore f(2.5) = 1.4142 + (2.5 - 2) * \frac{1.7321 - 1.4142}{3 - 2}$$

$$= 1.5732$$

Correct Answer 1.5811 // exactly

error calculate गणित एवं विज्ञान just actual उत्तर (प्र०) प्र० का उत्तर बिल्कुल भला होगा। आरू % ए प्र० का उत्तर एवं 100 विलेन उत्तर % ज्ञात होगा। आरू  
relative error calc. नहीं लगाएगा original द्वारा दिए गए उत्तर का उत्तर।

→ Interval एवं gap (प्र०) रखे accuracy बनाएँ।

Or<sup>2</sup> error কোণৰ ফলে তাজেকোনী point (x<sub>n+1</sub>)  
পুনৰ অথবা higher order এর interpolation

use কোণৰ

// 1<sup>o</sup> polynomial  $\rightarrow$  linear  $\rightarrow$  order  $\rightarrow 1$  so  $1+1 = 2^{\text{point}}$   
নোট:-

// 2<sup>o</sup> order এই ক্ষেত্রে (x<sub>n</sub>, x<sub>n+1</sub>) অঞ্চলৰ point থাকে। (পুনৰ  
1<sup>o</sup> order use কোণৰ)

Eg 9.4 □ <Same dataset>

Determine the square root of 2.5 using second order Lagrange interpolation polynomial

Sol<sup>n</sup>:  $\rightarrow$  নোট:- Interpolate কৰে 5<sup>th</sup> datapoint কৰে মাত্ৰ এবং  $P_0 - P_4$  পুনৰ পুনৰ  
ৰাখা হৈছে।  $(x_{n-1})^{\text{th}}$  এবং  $x_n$

$$P_n = \sum_{i=0}^n f_i l_i(x) \quad // \text{Lag. interpolation polynomial (2<sup>o</sup> formula)}$$

$$\text{where } l_i(x) = \prod_{j=0, j \neq i}^n \frac{(x-x_j)}{(x_i-x_j)}, \text{ lag. basis polynomial}$$

$$\text{Sol}^n: P_2(x) = \sum_{i=0}^2 f_i l_i(x)$$

$$= f_0 l_0(x) + f_1 l_1(x) + f_2 l_2(x) \quad ... (i)$$

$$l_0(x) = \frac{(x-x_1)(x-x_2)}{(x_0-x_1)(x_0-x_2)}$$

$$l_0(2.5) = \frac{(2.5-3)(2.5-4)}{(2-3)(2-4)} = 0.3750$$

(25 point 20-45) value (0) നിന്റെ രണ്ട് പോയിന്റുകൾ  
ഒരു ബഹു (order = 2 എന്ന് ചാലു)

point choose ചേരാൻ (data table (2.5 x 25 value) ചുണ്ട്  
അടുത്ത രണ്ട് range 2, 3 (2) പോയിന്റ് (2.5) ചുണ്ട്,  
ഒരു ഏ തിരി പോയിന്റ് പശ്ചാത്യം  $x_0$ , പുതിയ  $x_1$   
(3) അതാണും  $x_2$ ! വിശദിച്ച  $x_0 = 2, x_1 = 3, x_2 = 4$   
(3) 2.5 എൽഡർ കോറോറ്റേഷൻ രീതി! വസ്തു formula  
രൂപം!

$$\text{Now } x_1 = 2 \quad f(x_1) = 1.4142$$

$$x_2 = 4 \quad f(x_2) = 2$$

$$f(x) = \text{Then } f(x) + \frac{(x - x_1)}{(x_2 - x_1)} * \frac{f(x_2) - f(x_1)}{x_2 - x_1}$$

$$\therefore f(2.5) = 1.4142 + (2.5 - 2) * \left( \frac{2 - 1.4142}{4 - 2} \right)$$

$$= 1.5607$$

$$l_1(x) = \frac{(x - x_0)(x - x_2)}{(x_1 - x_0)(x_1 - x_2)}$$

$$\therefore l_1(2.5) = \frac{(2.5 - 2)(2.5 - 4)}{(3 - 2)(3 - 4)}$$

$$= 0.7500$$

$$l_2(x) = \frac{(x-x_0)(x-x_1)}{(x_2-x_0)(x_2-x_1)}$$

$$\therefore l_2(2.5) = \frac{(2.5-2)(2.5-3)}{(4-2)(4-3)}$$

$$= -0.125$$

①  $\Rightarrow$

$$P_2(2.5) = 1.4142 \times 0.3750 + 1.7321 \times 0.7500 \\ + 2 \times (-0.125) \\ = 1.5794$$

Eg 9.5

i	0	1	2	3
$x_i$	0	1	2	3
$e^{x_i}$	0	1.7138	6.3891	19.0855

find  $e^{1.5} = ?$

Since well defined function  
( $e^x$ )

Soln:

$$P_3(x) = f_0 l_0(x) + f_1 l_1(x) + f_2 l_2(x) + f_3 l_3(x) \quad \dots \dots \dots \dots \quad (i)$$

$$l_0(x) = \frac{(x-x_1)(x-x_2)(x-x_3)}{(x_0-x_1)(x_0-x_2)(x_0-x_3)}$$

$$\begin{aligned}
 &= \frac{(x-1)(x-2)(x-3)}{(0-1)(0-2)(0-3)} \\
 &= \frac{x^3 - 6x^2 + 11x - 6}{-3} \\
 &= \cancel{x^3} / \cancel{-3} \\
 l_1(x) &= \frac{(x-x_0)(x-x_1)(x-x_2)}{(x_1-x_0)(x_1-x_2)(x_1-x_3)} \\
 &= \frac{(x-0)(x-2)(x-3)}{(1-0)(1-2)(1-3)} \\
 &= \frac{x^3 - 5x^2 + 6x}{2}
 \end{aligned}$$

$$l_2(x) = \frac{(x-x_0)(x-x_1)(x-x_3)}{(x_2-x_0)(x_2-x_1)(x_2-x_3)}$$

→ ପତ୍ର ନାମ୍ବୁର୍ଜିନ୍ - ଟିଫାର ଲେଖିଥିଲେ  $x$  ପ୍ରିଣ୍ଡିକ୍ସ୍  
 ଲେଖିଥିଲେ  $x$  ଏହିବେ ନିଯମ ରୁହି କିମ୍ବା କିମ୍ବା  $x$  ପ୍ରିଣ୍ଡିକ୍ସ୍  
 ନିଯମ ରୁହି ଏହି ଉଦୟାଳୁ (first term କୁଳରେ ଶୁଣୁ ଯାଇଥିଲା)  
 ଯାଇଥିଲା

$$= \frac{(x-0)(x-1)(x-3)}{(2-0)(2-1)(2-3)}$$

$$= \frac{x^3 - 4x^2 + 3x}{-2}$$

$$l_3(x) = \frac{(x-x_0)(x-x_1)(x-x_2)}{(x_3-x_0)(x_3-x_1)(x_3-x_2)}$$

$$= \frac{(x-0)(x-1)(x-2)}{(3-0)(3-1)(3-2)}$$

$$= \frac{x^3 - 3x^2 + 2x}{6}$$

①  $\Rightarrow$

$P_3(x) = 0 + \frac{1.7138(x^3 - 5x^2 + 6x)}{2} +$

$$\frac{6.3891(x^3 - 4x^2 + 3x)}{-2} + \frac{19.0856(x^3 - 5x^2 + 2x)}{6}$$

$$= \frac{5.0732x^3 - 6.3621x^2 + 11.5987x}{6}$$

$$= 0.8455x^3 - 1.0604x^2 + 1.9331x$$

$$\therefore P_3(1.5) = 3.3677$$

$$\Rightarrow e^{1.5} - 1 = 3.3677$$

$$\therefore e^{1.5} = 4.3677$$

Limitations/Drawbacks:

→ ଅନ୍ତର୍ଗତ ପରିମାଣିକ ମୁଲିପଲେସନ୍ ଓ ଡିଭିଜନ୍

→ ନେତ୍ରନ ଏବଂ ପଞ୍ଚମୀ ପଞ୍ଜି ପଦ୍ଧତି ଆବଶ୍ୟକ

ଅନ୍ତର୍ଗତ ମୂଳ୍ୟ ବେଳେ ଏବଂ ପରିମାଣିକ ମୁଲିପଲେସନ୍

ପରିମାଣିକ ବାର୍ଷିକ ପଦ୍ଧତି ପରିବର୍ତ୍ତନ କରିବାକୁ ଆବଶ୍ୟକ

প্রথম (2)’s calculation করুন।

→ ২ মন্তব্য করুন। Newton interpolation use ২০—।

Oct 25, 2017

Rocky Sir

## Newton Interpolation Polynomial

The Newton form of polynomial is —

$$P_n(x) = a_0 + a_1(x-x_0) + a_2(x-x_0)(x-x_1) + \dots \dots \dots \\ + a_n(x-x_0)(x-x_1)\dots\cdots(x-x_{n-1})$$

" air polynomial A shifted power form. " (i)

To construct the interpolation polynomial, we need to determine the coefficient  $a_0, a_1, \dots, a_n$ . Let us assume that  $(x_0, f_0), (x_1, f_1), \dots, (x_{n-1}, f_{n-1})$  are interpolating points. That is,

$$P_n(x_k) = f_k, \quad k=0, 1, \dots, n-1 \quad \text{(ii)}$$

" interpolating function.

Now at  $x=x_0$ , we have from eqn (i),

$$P_n(x_0) = a_0 = f_0 \quad \text{(iii)}$$

"  $x_0$  পরিষেবক  $x_0$  যাওয়া

Similarly at  $x=x_1$ ,

$$P_n(x_1) = a_0 + a_1(x_1-x_0) = f_1$$

"  $x_1$  পরিষেবক ① রেখা  $x_1$  যাওয়া

// Ansara target: in terms of functional value  
 // co-efficient  $a_0, a_1, a_2, \dots$  এর মানের ক্ষেত্রে

$$\therefore f_0 + a_1(x_1 - x_0) = f_1$$

$$\therefore a_1 = \frac{f_1 - f_0}{x_1 - x_0} \dots \dots \dots \text{(iv)}$$

AT  $x=x_2$

$$P_n(x_2) = a_0 + a_1(x_2 - x_0) + a_2(x_2 - x_0)(x_2 - x_1) \\ = f_2 \dots \dots \dots \text{(v)}$$

Substituting the value of  $a_0$  and  $a_1$  in

eqn (v) we get,

$$f_0 + \frac{(f_1 - f_0)}{x_1 - x_0}(x_2 - x_0) + a_2(x_2 - x_0)(x_2 - x_1) = f_2 \\ \therefore a_2 = \frac{[(f_2 - f_1)(x_2 - x_1)] - [(f_1 - f_0)/(x_1 - x_0)]}{x_2 - x_1} \dots \dots \dots \text{(vi)}$$

$\square a_0 + a_1x + a_2x^2 + a_3x^3 + \dots$  // polynomial

// গো power form

Let us define a notation

$$f[x_k] = f_k$$

$$f[x_k, x_{k+1}] = \frac{f[x_{k+1}] - f[x_k]}{x_{k+1} - x_k}$$

$$f[x_k, x_{k+1}, x_{k+2}] = \frac{f[x_{k+1}, x_{k+2}] - f[x_k, x_{k+1}]}{x_{k+2} - x_k}$$

(প্রথম স্তর উন্নয়ন পদ্ধতি  
 on f'val - (নির্বাচিত পদ্ধতি)

উন্নয়ন (নির্বাচিত পদ্ধতি f'val) / (নির্বাচিত - আবশ্যিক

$$f[x_k, x_{k+1}, \dots, x_i, x_{i+1}] = \frac{f[x_{k+1}, \dots, x_{i+1}] - f[x_k, \dots, x_i]}{x_{i+1} - x_k}$$

These quantities are called divided differences.  
Now we can express the co-efficients  $a_i$  in terms of these divided differences.

$$a_0 = f_0 = f[x_0]$$

$$a_1 = \frac{f_1 - f_0}{x_1 - x_0} = f[x_0, x_1]$$

$$a_2 = \frac{\left(\frac{f_2 - f_1}{x_2 - x_1}\right) - \left(\frac{f_1 - f_0}{x_1 - x_0}\right)}{x_2 - x_1} = \frac{f[x_1, x_2] - f[x_0, x_1]}{x_2 - x_0}$$

$$= f[x_0, x_1, x_2]$$

$$\text{Thus, } a_n = f[x_0, x_1, \dots, x_n]$$

$$\textcircled{1} \Rightarrow P_n(x) = f[x_0] + f[x_0, x_1](x - x_0) + f[x_0, x_1, x_2](x - x_0)(x - x_1) + \dots + f[x_0, x_1, \dots, x_n](x - x_0)(x - x_1) \dots (x - x_{n-1}) \quad (\text{vii})$$

$\downarrow$   
order

// 2nd order till 3rd data point तक

// 4th , , , 4th , , , ,

// तिसरी तक 2nd data point तक

In compact form,

$$P_n(x) = \sum_{i=0}^n f[x_0, \dots, x_i] \prod_{j=0}^{i-1} (x - x_j)$$

eg. 9.6 : 2<sup>nd</sup> order Newt. Int. pol. use  $\log x$

i	0	1	2	3
$x_i$	1	2	3	4
$\log x_i$	0	0.3010	0.4771	0.6021

$\log 2.5 = ?$  using 2<sup>nd</sup> order Newton Interpolation polynomial

$$\text{Soln: } P_2(x) = a_0 + a_1(x - x_0) + a_2(x - x_0)(x - x_1)$$

$$a_0 = f[x_0] = 0$$

$$a_1 = \frac{f[x_0, x_1] - f[x_0]}{x_1 - x_0} = \frac{0.3010 - 0}{2 - 1}$$

$$= 0.3010$$

$$a_2 = \frac{f[x_0, x_1, x_2] - f[x_0, x_1]}{x_2 - x_0} = \frac{f[x_1, x_2] - f[x_0, x_1]}{x_2 - x_0}$$
$$= \frac{0.4771 - 0.3010}{3 - 0}$$

$$f[x_1, x_2] = \frac{b_2 - b_1}{x_2 - x_1} = \frac{0.4771 - 0.3010}{3-2} = 0.1761$$

$$\alpha_2 = \frac{0.1761 - 0.3010}{3-1} = -0.06245$$

$$P_2(x) = 0 + 0.3010(x-1) - 0.06245(x-1)(x-2)$$

$$P(2.5) = 0 + 0.3010(2.5-1) - 0.06245(2.5-1)(2.5-2)$$

$$= 0.4047$$

## 1 Exercise (Q1)

Oct 29, 2017  
Moon Mam

### Jacobi Iterative Method

$$\underline{n} \quad a_{11}x_1 + a_{12}x_2 + a_{13}x_3 + \dots + a_{1n}x_n = 0 \quad x_1 = \frac{b_1 - (a_{12}x_2 - a_{13}x_3 - \dots - a_{1n}x_n)}{a_{11}}$$

$$a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n = 0$$

$$a_{31}x_1 + a_{32}x_2 + \dots + a_{3n}x_n = 0$$

→ 1st iteration  $\Rightarrow$  1st value of  $x_1$  calc.

$$|x_1^{(3)} - x_1^{(2)}| & \& |x_2^{(3)} - x_2^{(2)}|$$

$$\epsilon = 0.01$$

$x_1, x_2$  satisfy tolerance

∴  $x_1 = 0.8$ ,  $x_2 = 0.2$

Oct 30, 2017  
Mahmud Sir

□ Newton Raphson Interpolation Polynomial:

$$P_n(x) = a_0 + a_1(x - x_0) + a_2(x - x_0)(x - x_1) + \dots +$$

*shifted power form*  $a_n(x - x_0)(x - x_1) \dots (x - x_{n-1})$

$$= f[x_0] + f[x_0, x_1](x - x_0) + f[x_0, x_1, x_2]$$

$$(x - x_0)(x - x_1) + \dots + f[x_0, x_1, \dots, x_n]$$

$$(x - x_0)(x - x_1) \dots (x - x_{n-1})$$

□ Divided Difference Table:

$$a_2 = f[x_0, x_1, x_2]$$

$$= \frac{f[x_1, x_2] - f[x_0, x_1]}{x_2 - x_0}$$

$f[x_1, x_2] = \frac{f(x_2) - f(x_1)}{x_2 - x_1} = \frac{f_2 - f_1}{x_2 - x_1}$
$f[x_0, x_1] = \frac{f(x_1) - f(x_0)}{x_1 - x_0} = \frac{f_1 - f_0}{x_1 - x_0}$

Similarly  $f[x_1, x_2, x_3, x_4] = \frac{f[x_2, x_3, x_4] - f[x_1, x_2, x_3]}{x_4 - x_1}$

$$\therefore f[x_2, x_3, x_4] = \frac{f[x_3, x_4] - f[x_2, x_3]}{x_4 - x_2}$$

$$f[x_3, x_4] = \frac{f_4 - f_3}{x_4 - x_3}$$

$$f[x_2, x_3] = \frac{f_3 - f_2}{x_3 - x_2}$$

$$f[x_1, x_2, x_3] = \frac{f[x_2, x_3] - f[x_1, x_2]}{x_3 - x_1}$$

$$f[x_2, x_3] = \frac{f_3 - f_2}{x_3 - x_2}$$

$$f[x_1, x_2] = \frac{f_2 - f_1}{x_2 - x_1}$$

$i$	$x_i$	$f[x_i]$	First Difference	Second Difference	Third Difference	Forth Difference
0	$x_0$	$f[x_0]$	$a_0$	$a_1$		
1	$x_1$	$f[x_1]$	$f[x_0, x_1]$	$a_2$		
2	$x_2$	$f[x_2]$	$f[x_1, x_2]$	$f[x_0, x_1, x_2]$	$a_3$	
3	$x_3$	$f[x_3]$	$f[x_2, x_3]$	$f[x_0, x_1, x_2, x_3]$	$f[x_1, x_2, x_3]$	$a_4$
4	$x_4$	$f[x_4]$				

Given points  
P(4)

Divided difference table

↑ Amalgam stepwise calculation use for  
calculation effort, कम करता

1/2<sup>2</sup>(x के लिए वन्दी)

eg - 9.7

$x^0$	0	1	2	3	4
$x^1$	1	2	3	4	5
$f(x^0)$	0	7	26	63	124

$$f(1 \cdot 5) = ?$$

here,

$$f[x_0] = 0$$

$$f[x_1] = 7$$

$$f[x_0, x_1] = \frac{f[x_1] - f[x_0]}{x_1 - x_0} = \frac{7 - 0}{2 - 1} = 7$$

$$f[x_1, x_2] = \frac{f[x_2] - f[x_1]}{x_2 - x_1} = \frac{26 - 7}{3 - 2} = 19$$

$$f[x_0, x_1, x_2] = \frac{f[x_2] - f[x_0]}{x_2 - x_0} = \frac{19 - 0}{3 - 1} = \frac{19}{2} = 6$$

$$f[x_2, x_3] = \frac{f[x_3] - f[x_2]}{x_3 - x_2} = \frac{63 - 26}{4 - 3} = 37$$

$$f[x_1, x_2, x_3] = \frac{f[x_3] - f[x_1]}{x_3 - x_1}$$

$$= \frac{37 - 0}{4 - 1} = \frac{37}{3} = 12.33$$

$$= 9$$

$$f[x_0, x_1, x_2, x_3] = \frac{9 - 0}{4 - 0} = 0.75$$

$$f[x_1, x_2, x_3, x_4] =$$

$$f[x_2, x_3, x_4] =$$

$$f(x) = x^3 - 3$$

$$f'(x) = 3x^2$$

$$f''(x) = 6x$$

$$f'''(x) = 6$$

$$\therefore f''''(x) = 0$$



$$= f[x_0, x_1, x_2, x_3, x_4]$$

इति उपर्युक्त

Exercise (4)(b) fitted form 3 linear, Newton, Lagrange  
to data point use  $f(x)$  or  $f(x)$  -  $f(x_0)$  to compare error

$$f[x_2, x_3] = \frac{63 - 26}{4 - 3} = 37$$

$$f[x_3, x_4] = \frac{124 - 63}{5 - 4} = 61$$

$$\therefore f[x_2, x_3, x_4] = \frac{61 - 37}{5 - 3} = 12$$

$$\therefore f[x_1, x_2, x_3, x_4] = \frac{12 - 9}{124 - 7} = 0.028641$$

$P_4(x=2.5)$

$$\begin{aligned} \therefore P_4(x) &= f[x_0] + f[x_0, x_1](x-x_0) + f[x_0, x_1, x_2] \\ &\quad (x-x_0)(x-x_1) + f[x_0, x_1, x_2, x_3] \\ &\quad (x-x_0)(x-x_1)(x-x_2) + f[x_0, x_1, x_2, x_3, \\ &\quad x_4] \\ &\quad (x-x_0)(x-x_1)(x-x_2)(x-x_3) \end{aligned}$$

$$\begin{aligned} P_4(1.5) &= 0 + 7(1.5 - 1) + 6(1.5 - 1)(1.5 - 2) + \\ &\quad 0.75(1.5 - 1)(1.5 - 2)(1.5 - 3) + 0.028641 \\ &\quad (1.5 - 1)(1.5 - 2)(1.5 - 3)(1.5 - 4) \\ &= 2.375 \end{aligned}$$

Newton is better  
to compare /  
Comments to  
std. func. 16)  
error = ?

# INTERPOLATION WITH EQUIDISTANT POINTS

ଅଗ୍ରାହୀ ପୁଣ୍ୟକ୍ଷେତ୍ର—ମର୍ଦ୍ଦ ସ୍ଥାନୀୟ equidistant ଠିକ୍ ମଧ୍ୟ

$\chi$  value କୁଳର ଏକଟି-factor କାହାରେ ପରିବର୍ତ୍ତନ କରିବାକୁ ଆବଶ୍ୟକ ହେଲାମାତ୍ରା

$x = 10, 20, 30, \dots$ ;  $y = 10, 20, 30, \dots$  Newton Gregory Interpolation (3) - 1

Let us assume that,

$x_k = x_0 + kh$ , where  $x_0$  is the reference point and  $h$  is the step size. The integer  $k$  may take either positive/negative values.

अग्र विधि method एवं divided difference quantities (or simple difference) ए निम्न आवश्यक, इसमें किसी notation define करते हैं-

The first forward difference  $\Delta f_1$  is defined as,

$\Delta f_i = f_{i+1} - f_i$  // base case | recursive way (G solve approach)

The second forward difference is defined as,

$$\Delta f_i = f_{i+1} - f_i$$

In general  $\Delta^j z_i = \Delta^{j-1} f_{i+1} - \Delta^{j-1} f_i$

We know that  $f[x_0, x_1] = \frac{f(x_1) - f(x_0)}{x_1 - x_0}$

$$\therefore f_1 - f_0 = h f [x_0, x_1]$$

$$\Rightarrow \Delta f_0 = h f [x_0, x_1]$$

Similarly,

$$\Delta f_1 = h f [x_1, x_2]$$

$$\text{Now, } \Delta^2 f_0 = \Delta f_1 - \Delta f_0$$

$$= \{ f[x_1, x_2] - f[x_0, x_1] \}$$

$$\therefore \Delta^2 f_0 = h \cdot 2h \cdot f [x_0, x_1, x_2]$$

$$\text{or } f[x_0, x_1, x_2] = \frac{f[x_1, x_2] - f[x_0, x_1]}{x_2 - x_0} \leftarrow \begin{array}{l} \text{point 20} \\ \text{and 02} \\ h+h=2h \end{array}$$

$$\text{or } f[x_0, x_1, x_2] = \frac{f[x_1, x_2] - f[x_0, x_1]}{2h}$$

$$\therefore f[x_1, x_2] - f[x_0, x_1] = 2h f [x_0, x_1, x_2]$$

In general by induction,

$$\Delta^j f_i = j! h f [x_i, x_{i+1}, \dots, x_{i+j}]$$

$$\therefore \Delta^j f_0 = j! h^j f [x_0, x_1, \dots, x_j]$$

" (i.e., value of topmost term 1st, 2nd, 3rd, ...)

(difference of 2nd) 2nd value का मान ज्ञात करें

(column of topmost value टो कल्पना करें (कल्पना करें-

मान) 1. . . . एवं इसके दो दूसरे मान,

$$\Rightarrow f[x_0, x_1, \dots, x_j] = \frac{\Delta^j f_0}{j! h^j}$$

From Newton interpolation,

$$P_n(x) = \sum_{j=0}^n f[x_0, x_1, \dots, x_j] \prod_{k=0}^{j-1} (x - x_k) \quad \dots \dots \dots \text{... (i)}$$

(गणित क्लास वर्ष १९८५-८६ में)

$$\textcircled{i} \Rightarrow P_n(x) = \sum_{j=0}^n \frac{\Delta^j f_0}{j! h^j} \prod_{k=0}^{j-1} (x - x_k) \quad // \text{putting value} \quad \dots \dots \dots \text{... (ii)}$$

Let us set

$$x = x_0 + sh \quad \text{and} \quad P_n(s) = P_n(x)$$

We know that,  $x_k = x_0 + kh \quad // \text{initially वर्ष १९८५-८६}$

$$\therefore x - x_k = (s - k)h$$

Putting this in Eq.  $\text{Eq. } \textcircled{ii}$ ,

$$\begin{aligned} \textcircled{ii} \Rightarrow P_n(s) &= \sum_{j=0}^n \frac{\Delta^j f_0}{j! h^j} \prod_{k=0}^{j-1} \underbrace{(s - k)h}_{\substack{0-(j-1) \rightarrow j \text{ शब्दों के टर्म्स} \\ h \text{ का गुणांक है} \\ \text{or } h^j}} \\ &= \sum_{j=0}^n \frac{\Delta^j f_0}{j! h^j} \underbrace{[s(s-1)(s-2) \dots (s-j+1)] h^j}_{\substack{\text{or } h^j}} \end{aligned}$$

$$= \sum_{j=0}^n \frac{s(s-1)(s-2) \dots (s-j+1)}{j!} \Delta^j f_0$$

$$= \sum_{j=0}^n \frac{s}{j} \Delta^j f_0 \quad \dots \dots \dots \text{... (iii)}$$

$$sC_j = \frac{s!}{(s-j)! j!}$$

$$\text{where } \binom{s}{j} = \frac{s(s-1)(s-2)\cdots(s-j+1)}{j!}$$

Equations (III) and (II) are known as Gregory-Newton forward difference formula (or forward difference interpolation / interpolation with equidistance point).

### Forward difference table:

general case for  $\Delta^i f_i = f_{i+1} - \Delta^{i-1} f_i$

$x$	$f$	$\Delta f$	$\Delta^2 f$
$x_0$	$f_0$		$\Delta^2 f_0$
$x_1$	$f_1$	$\Delta f_1$	$\Delta^2 f_1$
$x_2$	$f_2$		

• (NOT) നിലവ് പ്രസ്തര  
അനുസരിച്ച് കാണാം  
( $\Delta^2 f_0$  ഉപരി പാഠ)

divided difference (last - first) point നിലവ് ആണ്  
അതായും വ്യക്ത അനാഗ്രഹിത

→ Backward difference table → self study  
 (just reversely calculate  $\Delta f$ )

Example 9.8

0	10	20	30	40	50
$\sin \theta$	0.1736	0.3420	0.5000	0.6428	0.7660

// Using Gragory interpolation for  $\theta = 25^\circ$  from data table

// (v) Newton's method for Grag.-Newton Interpolation

// 0 is value factor  $\Delta f_0 = 0.1736$ , step factor = 10

// Now 1 step change value (or change  $\Delta f$ ) for grag-newt.

// 1 step change But 1 step change for Newton Int. use  $\Delta f_1 = 0.3420$

$$\theta = 25^\circ = ?$$

Soln:

$$x_0 = \theta_0 = 10$$

$$h = 10$$

$$s = \frac{x - x_0}{h} = \frac{25 - 10}{10} = 1.5$$

$$= 1.5$$

$$\begin{aligned}
 P_4(s) &= \sum_{j=0}^4 \frac{\Delta^j f_0}{j!} [s(s-1)(s-2)\dots(s-j+1)] \\
 &= f_0 + \frac{\Delta f_0 s}{L_1} + \frac{\Delta^2 f_0}{L_2} s(s-1) \\
 &\quad + \frac{\Delta^3 f_0}{L_3} s(s-1)(s-2) + \\
 &\quad \left( \frac{\Delta^4 f_0}{L_4} s(s-1)(s-2)(s-3) \right)
 \end{aligned}$$

value for equidistant table

(2) (iii) 1st (just) 2nd (just) 3rd (just)

$x_i$	$f$	$\Delta f$	$\Delta^2 f$	$\Delta^3 f$	$\Delta^4 f$	just simple interpolation method
$x_0$	$f_0$					
		$\Delta f_0$				
$x_1$			$\Delta^2 f_0$			
$\vdots$						
$x_4$ and so on						

// just not suffix  $\Delta^4 f$  (top most row)