# Lecture 9 →

Spanning a Space

we already know it right? Vectors v1, v2..... Ve span a space means the space consists of all combinations of those vectors.

For example, the columns of a matrix span the column space.

Basis for a space is a sequence of vectors vi, vi, vy .... ve with 2 properties -

1. They are independent

2. They span the space.

Examples

For R3, One basis is [0], [0], [0]. Why?

But this isn't the only basis: Another basis can be [1], [2], [3] NOW if I took only two out of these to three, would that

so, In RM, n vectors give basis if the nxn matrix with those columns

Now, If I took [1] and [2], would they be a basis? Yes!

They would be a basis for a subspace created by the



Basis vectors 50, Basis is not unique. There can be a million possibilities of basis.

But one thing common for all the busis are -Every basis for the space has the same number of vectors.

so, In R6, if we got 7 vectors, that is too many for the basis, we if we got 5 vectors, that would & rot be erough. So, 6 is just the perfect number.

And, this perfect number is the dimension of the space.

Any matrix,  $A = \begin{bmatrix} 1 & 2 & 3 & 1 \\ 1 & 1 & 2 & 1 \\ 1 & 2 & 3 & 1 \end{bmatrix}$ (i) what is the span of these column nectors?  $\rightarrow \underline{c(A)}$ (ii) Are the columns independent ? - No. Because N(A) has a non-zero solution. (iii) what are the basis of the columnspace? - The first two columns columns (column 183 (iv) What is the dimension of the columnspace? > mank(A)=2=# of pivots=dimension dim C(A) = rank (v) What is the dimension of the nullspace? This isn't the dimension (v) What is The special solutions - [-], [-] - And These two are the basis of the mullspace. of the matrix, but only dim N(A) = # of free columns = n-r=2 The four subspaces of R. D. Go to the Last page we are already familiar with 2 subspaces. Columnspace and Nullspace these two spees subspaces come from A. The other two subspaces, namely nowspace and left nullspace comes from AT. Let's know about all the subspaces through a specific example-Let's say we have a 3x5 matrix A and its reduced to its R = 0 3 5 0 7 Prot row
0 0 0 0 0 Privot row
1 0 0 0 0 0 1. The column space (C(A)) As the rank=2, dimension is also 2. The pirot columns 1 & 4 form a basis for C(R). So, The dimension of the column space is nank to, & the pivot columns form a basis.

Example:

2. The NUIL Space (N(A))

First, think about the special solutions of A. that solves Az=0. There are 3 free columns. So, setting the free columns to (1,0,0), (0,1,0), (0,0,1) gives the solution

$$\times_{\text{special}} = \begin{bmatrix} -3 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} -5 \\ 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -7 \\ 0 \\ -2 \\ 1 \end{bmatrix}$$

Su, the dimension is n-r=5-2=3, and these 3 Xspecial ane a basis for the nullspace.

3. The row space (C(AT))

Think about RT. What is the rank? 2. And this is the dimension. And the for first and the second row form a basis. Because the third row doesn't add anything with the rowspace.

The dimension of the row-space is P=2, The non-zero rows form a basis

4. The Left-Nullspace (N(AT))

Let's fay, Ay=0 I special solution

Now, if you transpose the whole their thing -

$$(Ay)^T = 0^T$$

> yTAT=0 1 Rowspace L Null space comes at left.

so, Left Nullspace is busically the nullspace of the rowspace

50, 
$$P^{T} = \begin{bmatrix} 1 & 0 & 0 \\ 3 & 0 & 0 \\ 5 & 0 & 0 \\ 7 & 2 & 0 \end{bmatrix}$$
. So, How many special solution?

Unly 1.

So, the basis would be only one

Free column. vector. Which is?  $\Gamma_{0}$ ? Dimerim

Free column. vector. Which is? [0]. Dimesion = 1.

If A is mxn matrix of rank m, its left nullspace has dimesion m-n

summarizing - of a matrix mxn, In Rn, the now space and null space have dimensions is and n-r. In Rm, the column space and left-nullspace have dimensions is and m-r. so, the big picture would be-The Four Subspaces of A: see, the columnspace has changed!  $C(A) \neq C(R)$ . [] is gone But their dimension is same. and you can't get it back by reversing the operations. But, their rowspace is same! Because, you only charged EA = R → A = E - 'R 1.) A has the same dinension as R and same basis. In fact, A has the same now-space as R. 2. The column space of A has dimension to rank. For Every matrix, the following is the-The number of independent columns equals the number of independent rows. Reason: The same combinations of the columns are zero for both A & R. Ax20 exactly when Rx=0.

3) A has the same nullspace as f. same dimension nor and same basis.

Because nullspace is related to rowspace Does elimination change the rowspace? If you think earefully, you can understand elimination steps actually new vever which rows are dependent. so, as it doesn't charge the rowspace, it wouldn't charge the nullspace as well.

so, the limension would be n-n and the busis would be

1) The left nullspace is refuted to columnspace. Su, it wouldn't be the same as well. The dinersion would be m-r.

Example 1:  $A=\sqrt{1} 2 3$  m=1, n=3, rank=1approx space is a line in  $R^3$ .

From Start with this matrix 
$$\rightarrow A = \begin{bmatrix} 2 & -1 & -3 \\ -4 & 2 & 6 \end{bmatrix}$$

Column Space:

$$Span = \left\{ \begin{bmatrix} 2\\ -4 \end{bmatrix} \right\}$$
,  $Basis = \begin{bmatrix} 2\\ -4 \end{bmatrix}$ , Dimension = 1

Nullspace:

$$R = \begin{bmatrix} 1 & -1/2 & -3/2 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}, Span = \begin{bmatrix} 1/2 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 3/2 \\ 0 \\ 1 \end{bmatrix}$$
, Basis, Dimension=2.

C(AT):

$$A^{T} = \begin{bmatrix} 2 & -4 \\ -1 & 2 \\ -3 & 6 \end{bmatrix}$$
, span =  $\begin{bmatrix} 2 \\ -1 \\ -3 \end{bmatrix}$ , Basis, Dimension = 1.

But this is the row of our original matrix. so, me can also say that this is the span of the now nector of A, or the rowspace of A4! 50, C(AT) is called the rowspace of A!

(TA)N

pref(AT) = 
$$\begin{bmatrix} 1 & -2 \\ 0 & 0 \\ 0 & 0 \end{bmatrix}$$
, span =  $\begin{bmatrix} 2 \\ 1 \end{bmatrix}$ , Basis, Dimension = 1.

NIM, If the nullspace of 
$$A^T$$
 is  $y$ ,
$$A^Ty = 0$$

50, this is also called the left nullspace of A!

$$=) (A^{T}y)^{T} = O^{T}$$

$$=$$
)  $Y^TA = O^T$