



Regression Analyses for Data Synchronization between In-process Monitoring Sensors in Laser Powder Bed Fusion (LBPF) Process

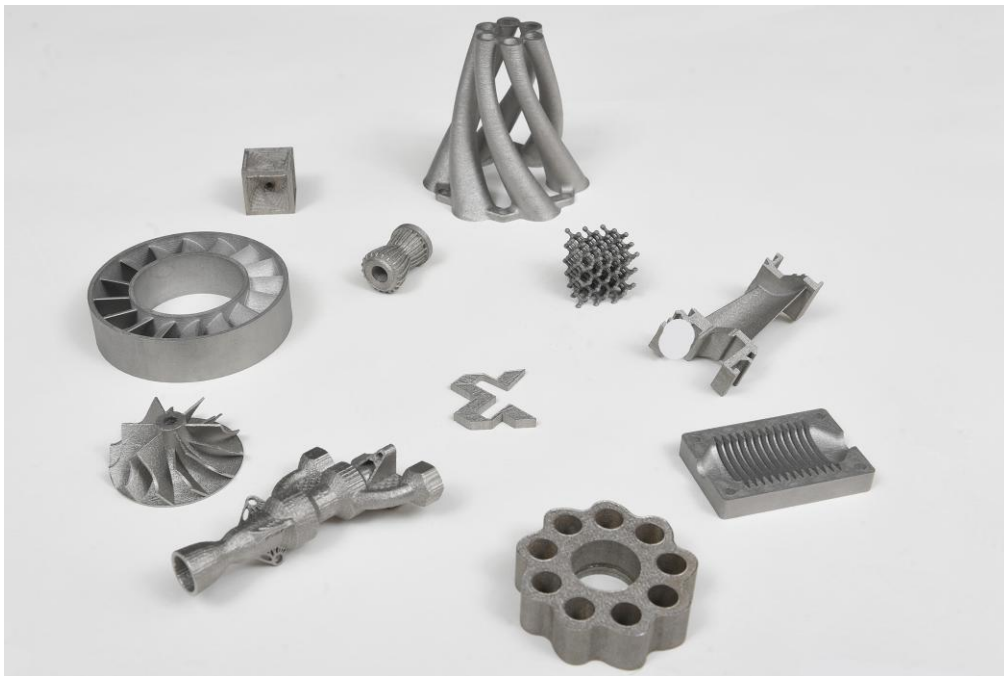
Nazmul Hasan



COLLEGE OF ENGINEERING
Systems & Industrial
Engineering

Background & Motivation

- **Laser Powder Bed Fusion (LPBF) Process:** A metal 3D printing process to fabricate parts based on a digital 3D model by selectively melting fine metal powders layer by layer.



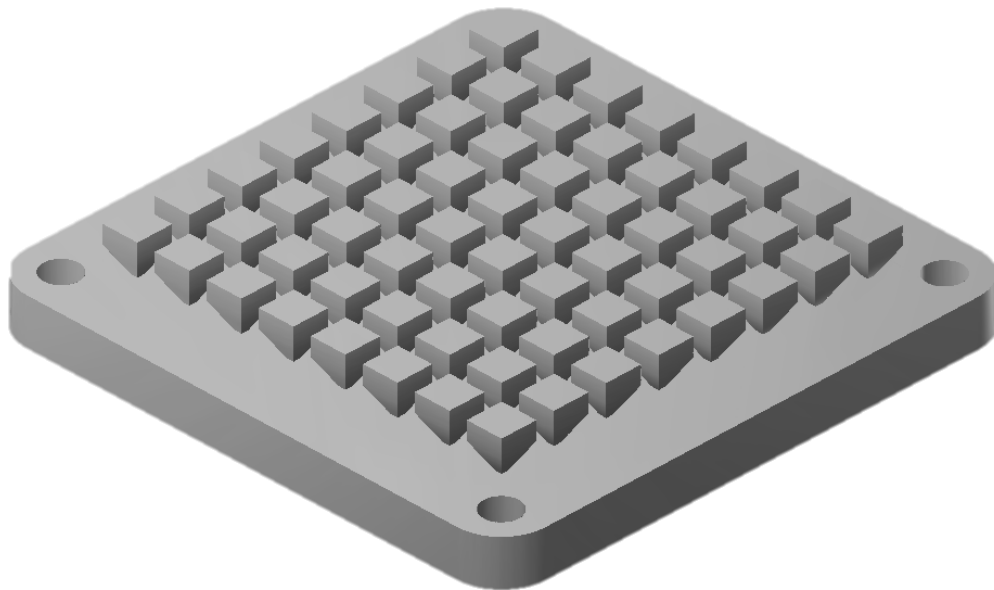
LPBF printed parts ([source link](#))



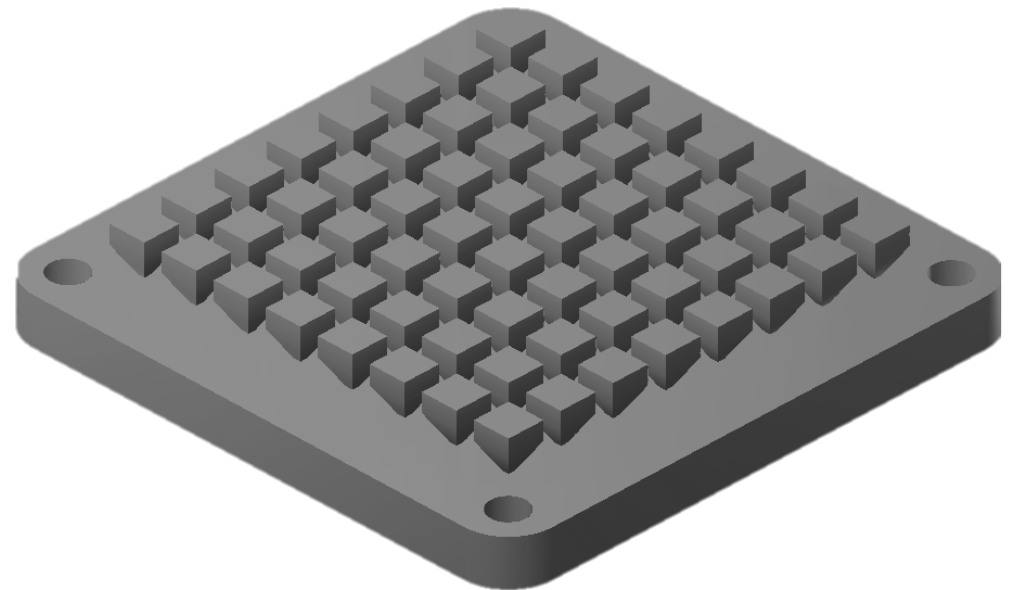
LPBF process in action ([source link](#))

Background & Motivation

- In-process monitoring data was collected during the printing of two following parts using the following:
 - Field-Programmable Gate Array (FPGA) sensor
 - Melt Pool Monitoring (MPM) camera



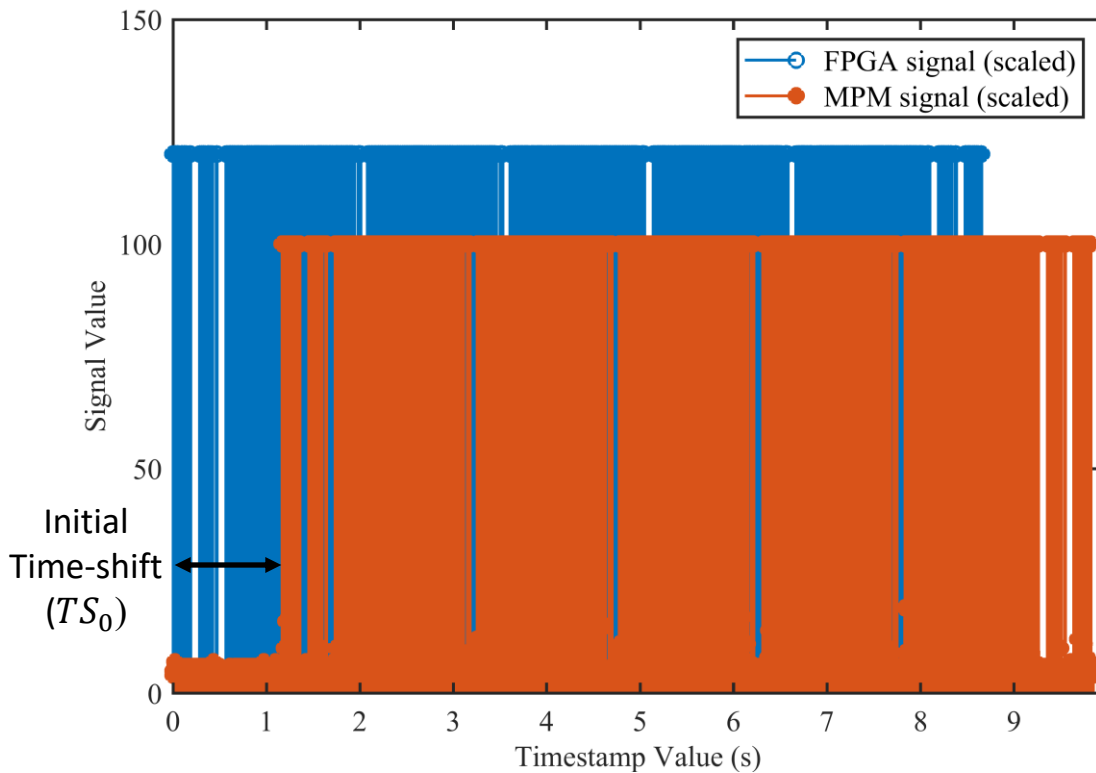
Part 1 - made of In718 alloy with 321 layers



Part 2 - made of H282 alloy with 401 layers

Background & Motivation

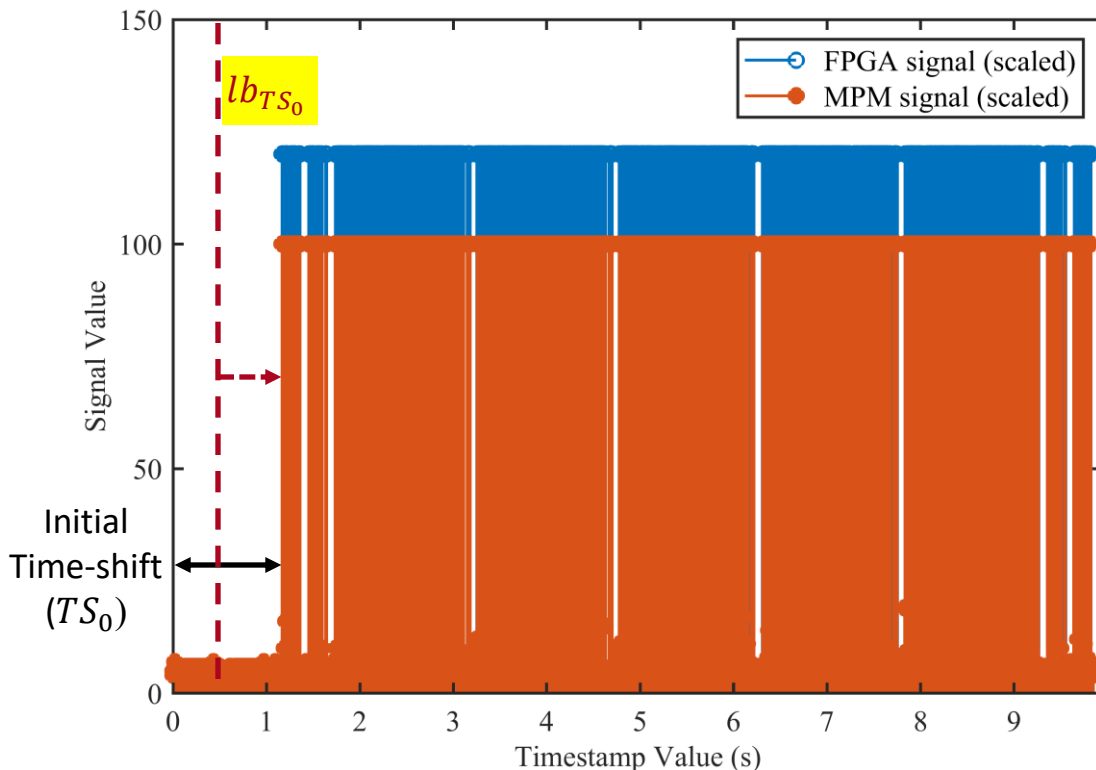
- In-process monitoring sensor and camera under consideration:
 - Field-Programmable Gate Array (FPGA) sensor
 - Melt Pool Monitoring (MPM) camera



FPGA and MPM data for a *single* layer within a part

Background & Motivation

- In-process monitoring sensor and camera under consideration:
 - Field-Programmable Gate Array (FPGA) sensor
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FPGA and MPM data for a **single layer** within a **part**

Research Question 1

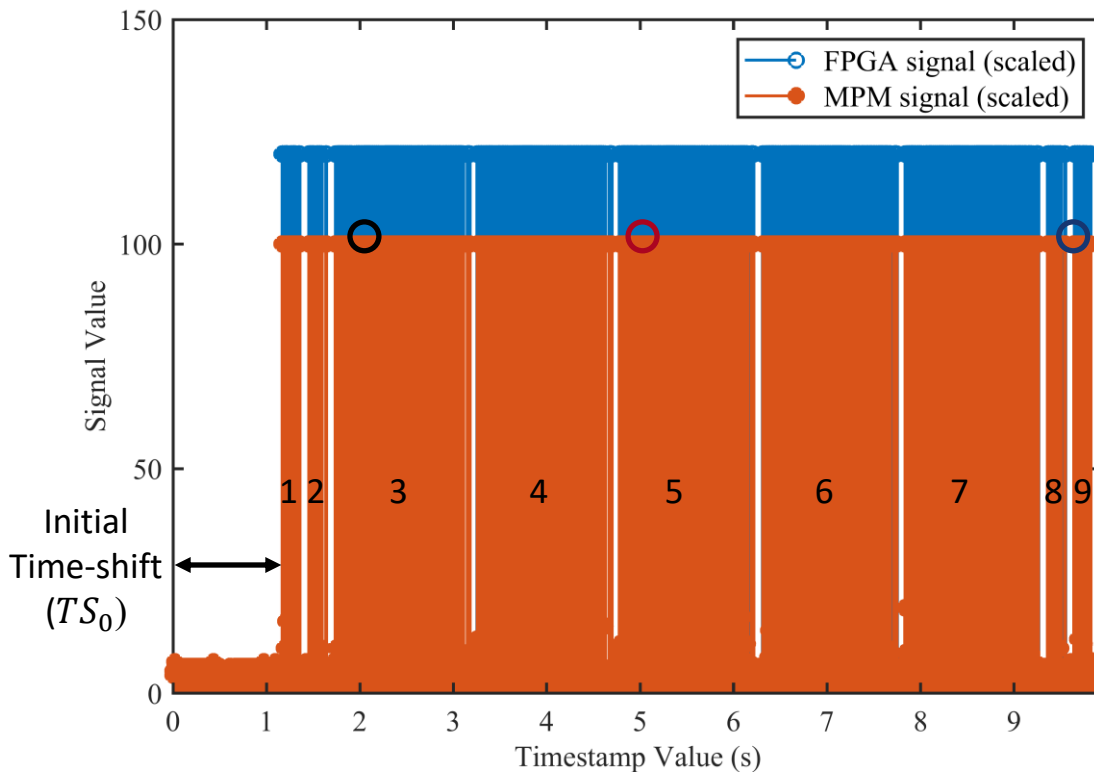
Does a statistical relationship exist among the variables "Initial time-shift, TS_0 ", "Layer index, L ", and "Part index, P "?

Regression analysis 1: $TS_0 \sim f(L, P)$

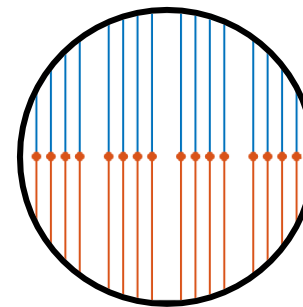
Additionally, determining a **lower bound** on TS_0 can help optimizing computational efficiency.

Background & Motivation

- Does the “Initial Time-shift (TS_0) Adjustment” solve the synchronization problem?
 - Answer: **NO**.
- Additional time-shift adjustment is required: $TS_i = TS_0 + \tau_i$

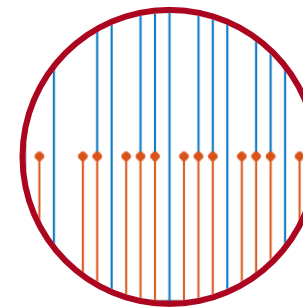


FPGA and MPM data for a *single* layer within a part



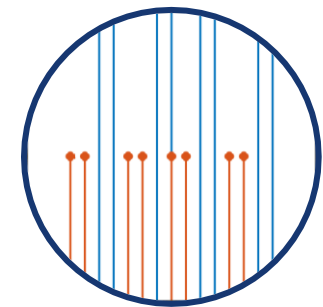
Block 3

$$\tau_i = 0$$



Block 5

$$\tau_i = 1 \times 10^{-3}$$

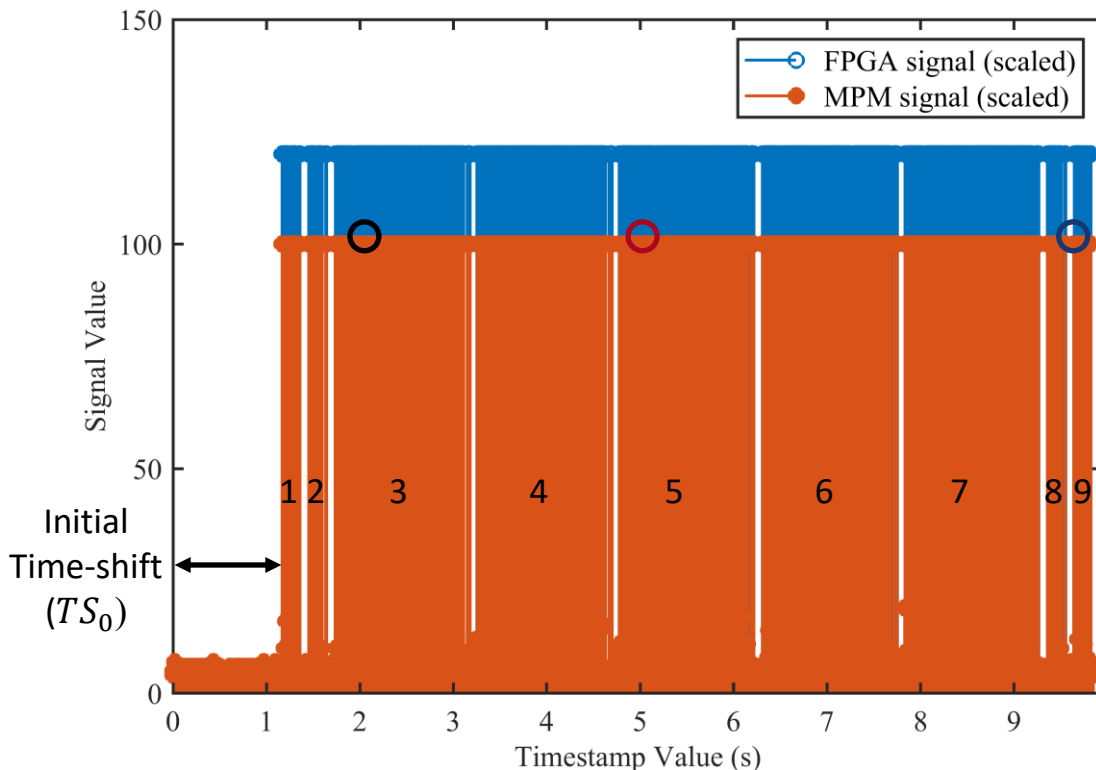


Block 9

$$\tau_i = 2 \times 10^{-3}$$

Background & Motivation

- Does the “Initial Time-shift (TS_0) Adjustment” solve the synchronization problem?
 - Answer: **NO**.
- Additional time-shift adjustment is required: $TS_i = TS_0 + \tau_i$



FPGA and MPM data for a **single layer** within a **part**

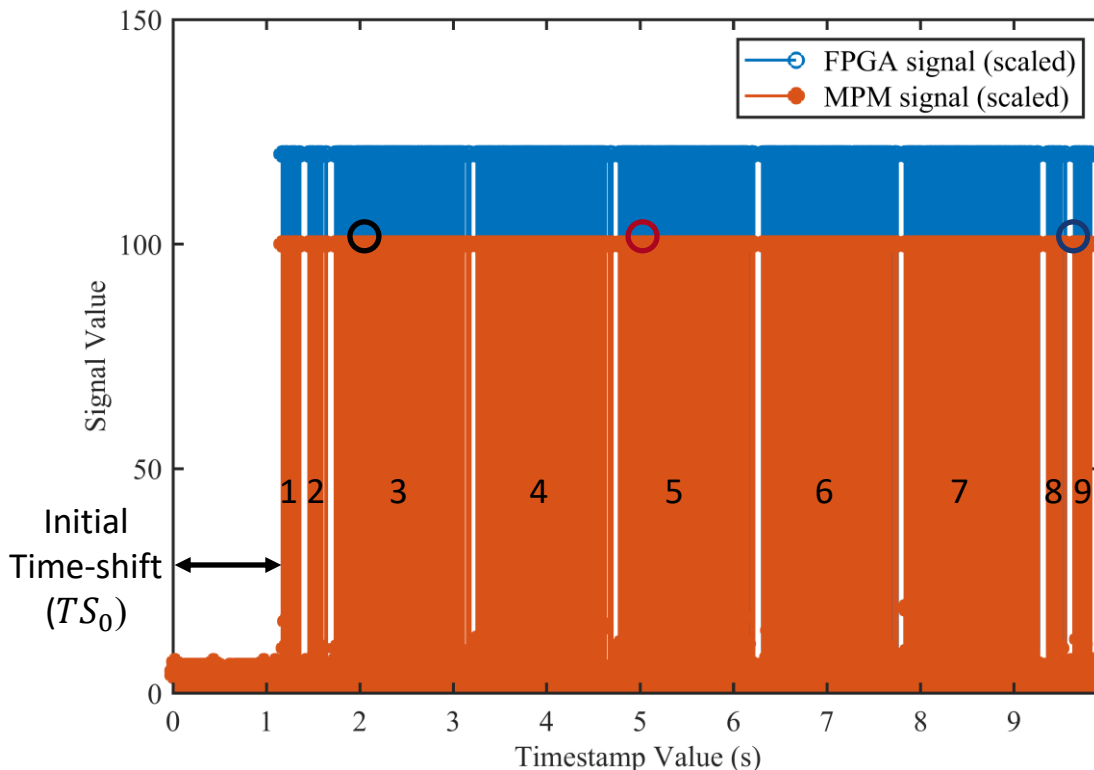
Research Question 2

Does a statistical relationship exist among the variables "Time-shift adjustment, τ ", "FPGA timestamp, T_{FPGA} ", "Initial time-shift, TS_0 ", "Layer index, L ", and "Part index, P "?

Regression analysis 2: $\tau \sim f(T_{FPGA}, TS_0, L, P)$

Background & Motivation

- Does the “Initial Time-shift (TS_0) Adjustment” solve the synchronization problem?
 - Answer: **NO**.
- Additional time-shift adjustment is required: $TS_i = TS_0 + \tau_i$



FPGA and MPM data for a **single** layer within a part

Research Question 3

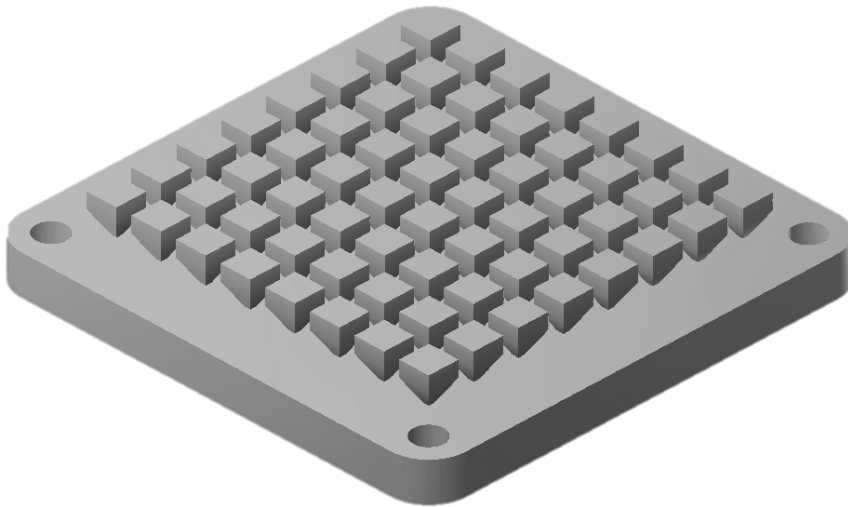
Can "Time-shift adjustment, τ " be predicted by using its statistical relationship with the predictor variables: "FPGA timestamp, T_{FPGA} ", "Initial time-shift, TS_0 ", and "Layer index, L "?

Regression analysis 3: $\tau \sim f(T_{FPGA}, TS_0, L)$

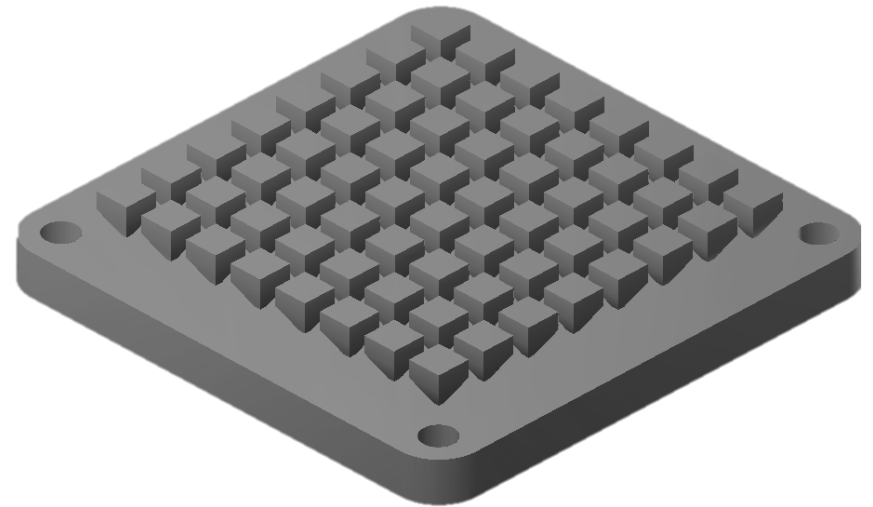
Additionally, determining the **maximum prediction-error magnitude** can help accommodating further adjustment for accurate synchronization.

Data Collection

- For Regression Analysis 1 [$TS_0 \sim f(L, P)$]:
 - *Initial time-shift* (TS_0) values are collected from the two *parts* (P) for **all** *layers* (L) .
- For Regression Analysis 2 [$\tau \sim f(T_{FPGA}, TS_0, L, P)$] & 3 [$\tau \sim f(T_{FPGA}, TS_0, L, P)$]:
 - *Time-shift adjustments* (τ) values across *FPGA timestamps* (T_{FPGA}) are collected from the two *parts* (P) for **selected** *layers* (L) along with associated *initial time-shift* (TS_0) values.



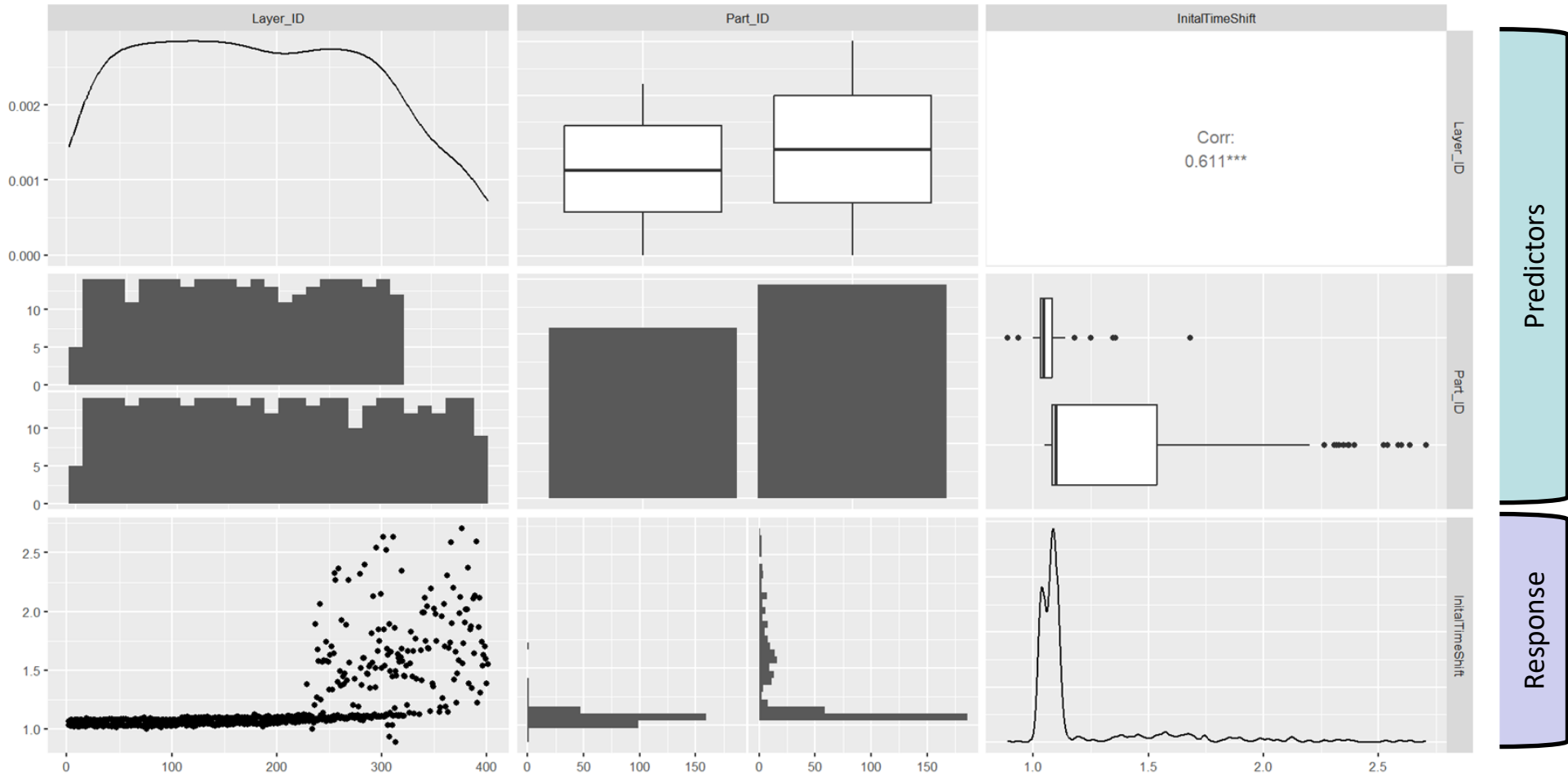
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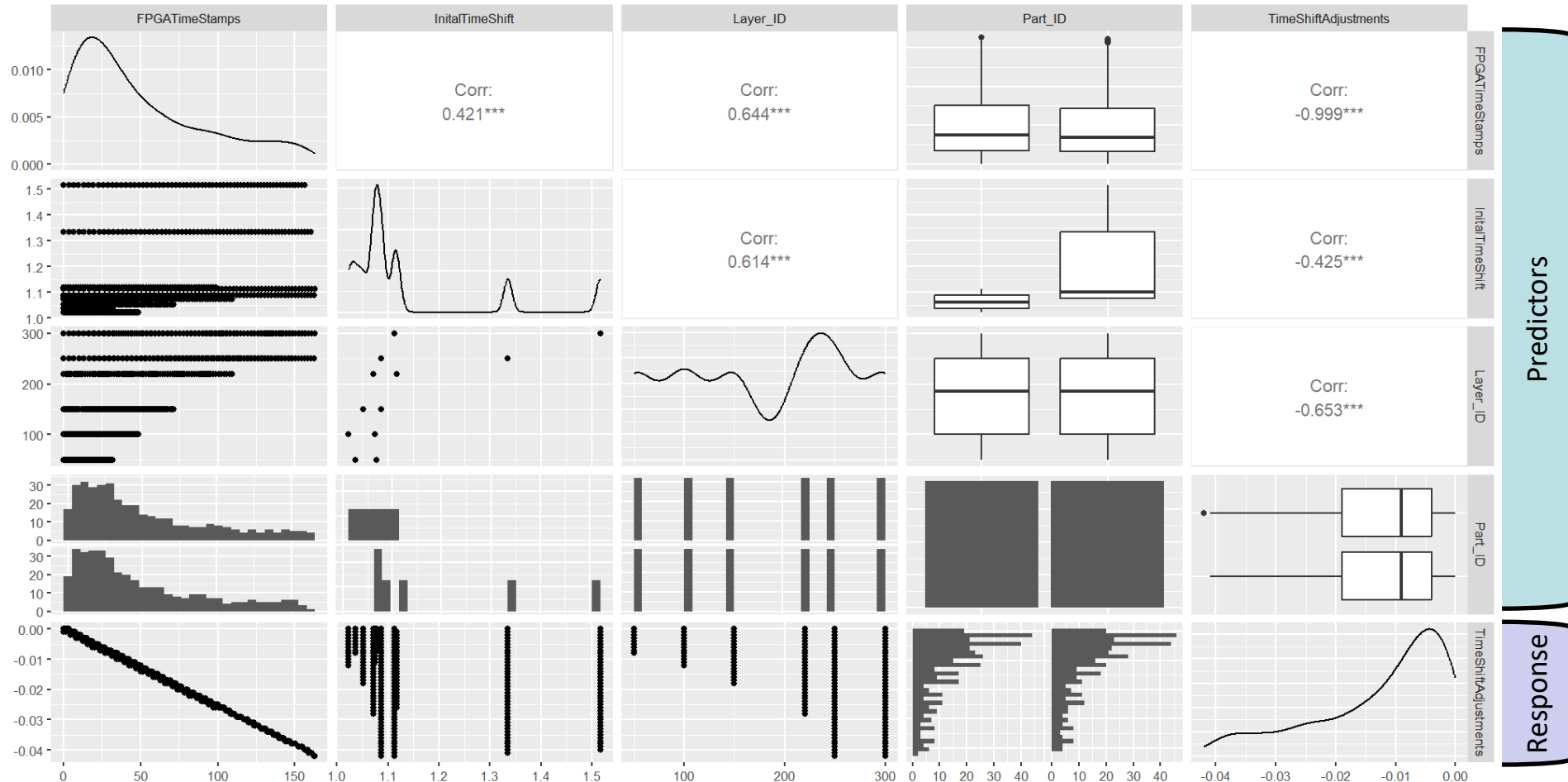
Data Exploration

- For Regression Analysis 1 [$TS_0 \sim f(L, P)$]:



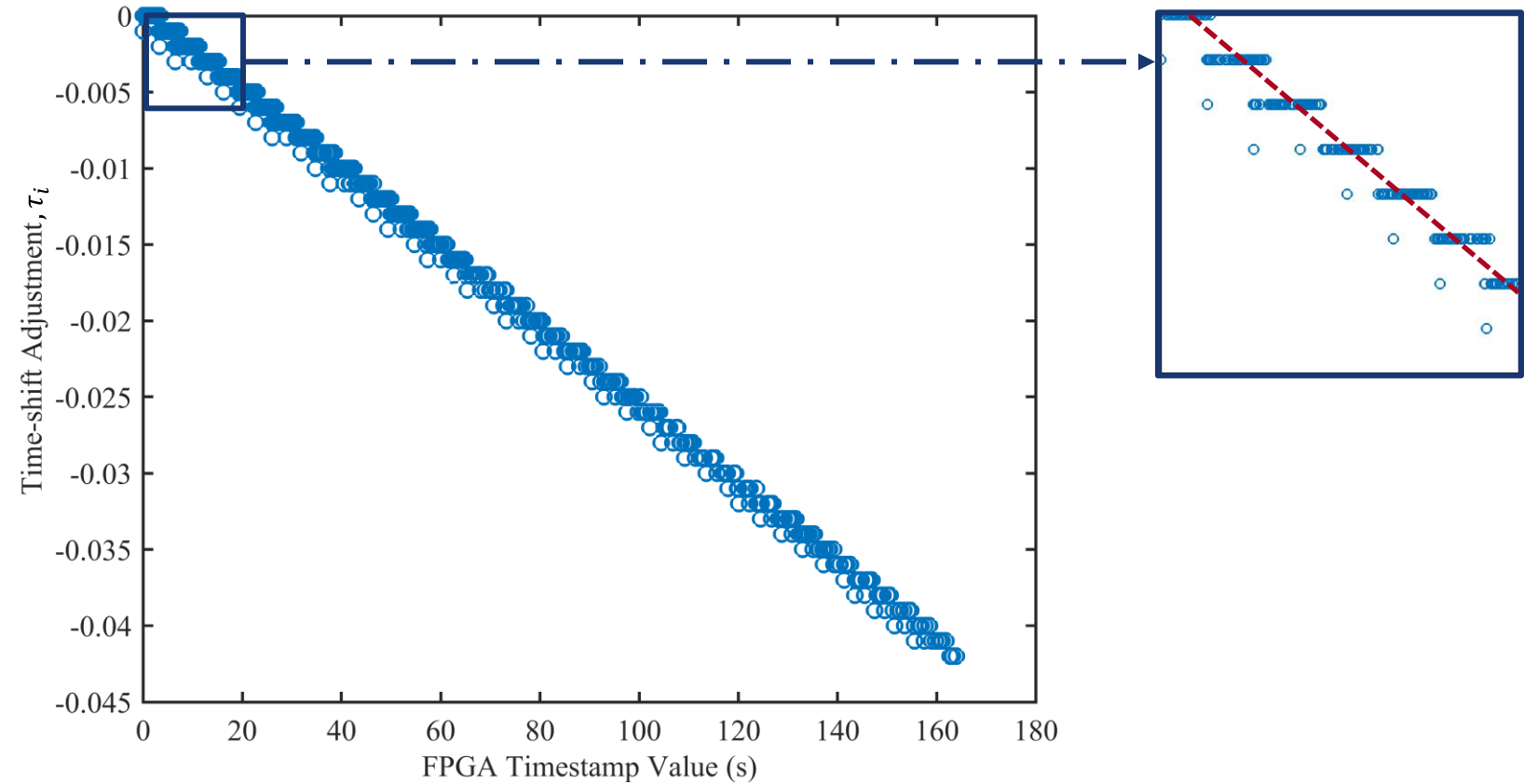
Data Exploration

- For Regression Analysis 2 [$\tau \sim f(T_{FPGA}, TS_0, L, P)$] & 3 [$\tau \sim f(T_{FPGA}, TS_0, L, P)$]:



Data Exploration

- For Regression Analysis 2 [$\tau \sim f(T_{FPGA}, TS_0, L, P)$] & 3 [$\tau \sim f(T_{FPGA}, TS_0, L, P)$]:



Results and Discussion

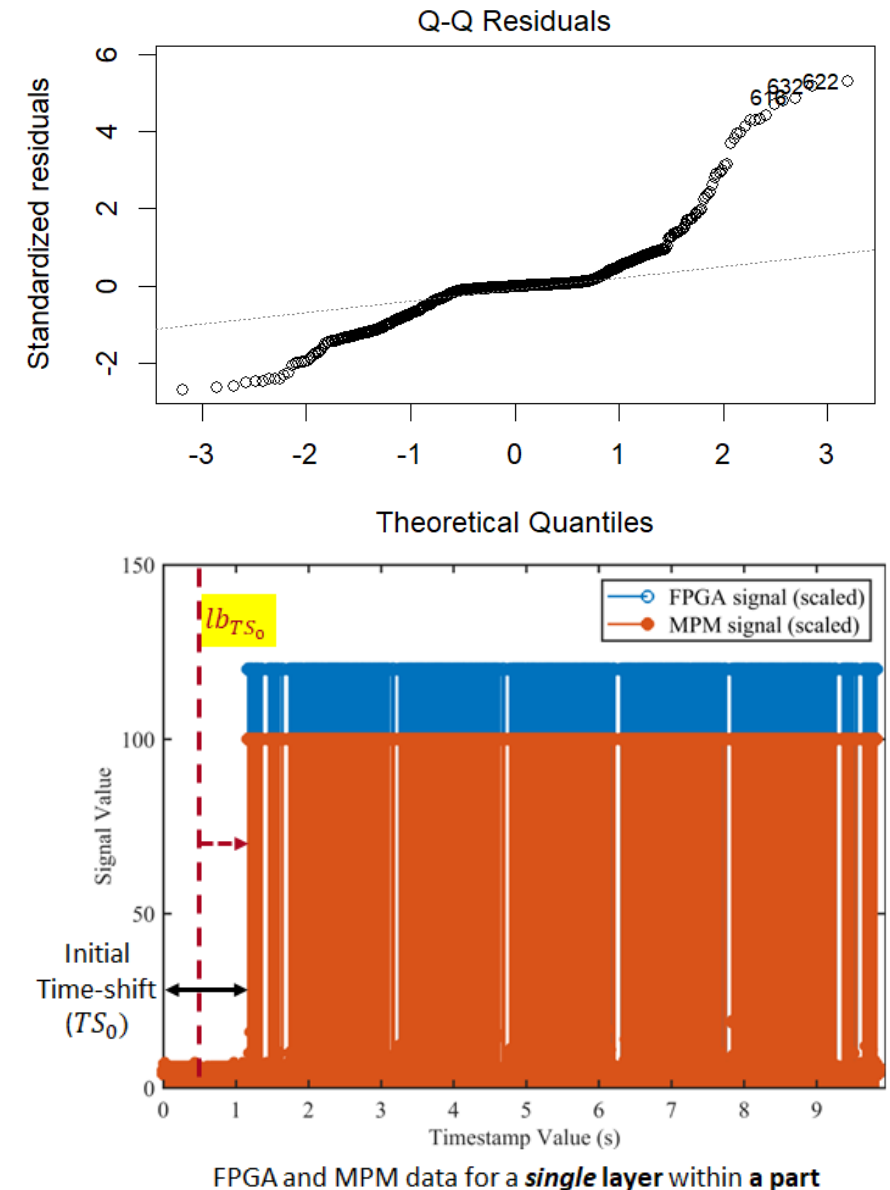
- Regression Analysis 1 [$TS_0 \sim f(L, P)$]
 - **Answer to Research Question 1:** Does a statistical relationship exist among the variables "Initial time-shift, TS_0 ", "Layer index, L ", and "Part index, P "?

```
TS0_formula <- (InitialTimeShift ~ Layer_ID + Part_ID + Layer_ID:Part_ID)
model_TS0_all <- lm(TS0_formula, data = df_TS0)
summary(model_TS0_all)
```

```
##
## Call:
## lm(formula = TS0_formula, data = df_TS0)
##
## Residuals:
##      Min       1Q   Median       3Q      Max
## -0.55106 -0.06097 -0.00399  0.02038  1.08003
##
## Coefficients:
##              Estimate Std. Error t value Pr(>|t|)
## (Intercept)    1.0063053   0.0232055   43.365 < 2e-16 ***
## Layer_ID        0.0003313   0.0001247    2.657  0.00806 **
## Part_IDPart 2   -0.1294588   0.0310462   -4.170 3.43e-05 ***
## Layer_ID:Part_IDPart 2  0.0019283   0.0001535   12.566 < 2e-16 ***
```

Results and Discussion

- Regression Analysis 1 [$TS_0 \sim f(L, P)$]
 - Determination of **lower bound** on TS_0 :
 - Q-Q plot reveals that normality assumption is not valid.
 - “Bootstrapping” is implemented to obtain 99% confidence interval on the predicted values for TS_0 .
 - Obtained *lowest bound*, lb_{TS_0} : **0.881 s**.
 - *Implication*: **881** frames from the MPM camera video (1000 fps) can be skipped and thus the computational burden can be reduced.



Results and Discussion

- Regression Analysis 2
 $[\tau \sim f(T_{FPGA}, TS_0, L, P)]$
 - **Answer to Research Question 2:** Does a statistical relationship exist among the variables "Time-shift adjustment, τ ", "FPGA timestamp, T_{FPGA} ", "Initial time-shift, TS_0 ", "Layer index, L ", and "Part index, P "?

```
tau_formula_initial <- (TimeShiftAdjustments ~ FPGATimeStamps + InitalTimeShift +  
  Layer_ID + Part_ID + FPGATimeStamps:InitalTimeShift +  
  FPGATimeStamps:Layer_ID + FPGATimeStamps:Part_ID +  
  InitalTimeShift:Layer_ID + InitalTimeShift:Part_ID +  
  Layer_ID:Part_ID )  
  
model_initial <- lm(tau_formula_initial, data = df_tau)  
summary(model_initial)
```

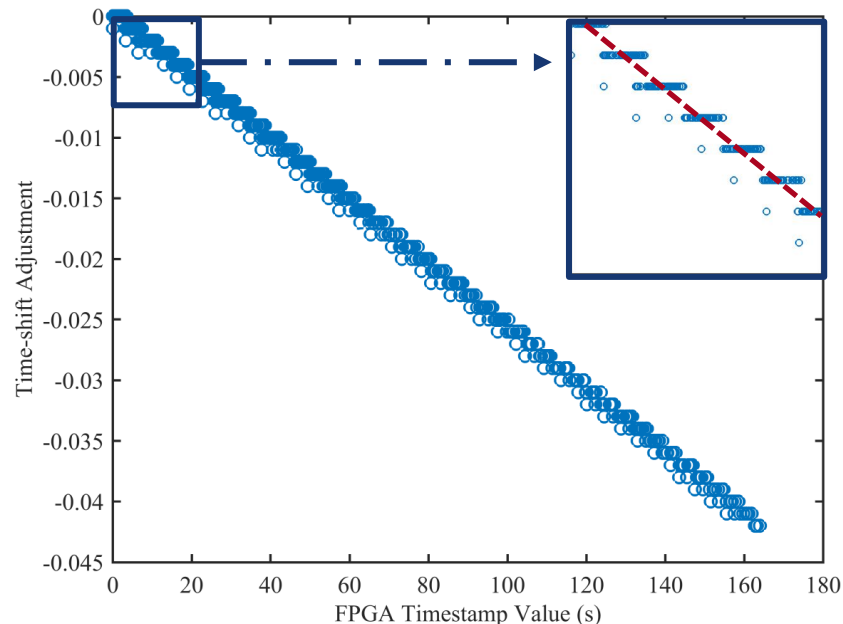
```
##  
## Call:  
## lm(formula = tau_formula_initial, data = df_tau)  
##  
## Residuals:  
##      Min       1Q   Median       3Q      Max   
## -8.031e-04 -2.559e-04 -4.170e-06  2.521e-04  8.370e-04   
##  
## Coefficients:  
##              Estimate Std. Error t value Pr(>|t|)      
## (Intercept)   -2.754e-03  2.197e-03  -1.254  0.210260      
## FPGATimeStamps -2.659e-04  3.829e-06 -69.464 < 2e-16 ***  
## InitalTimeShift  2.981e-03  2.158e-03   1.381  0.167571      
## Layer_ID       9.558e-06  4.283e-06   2.232  0.025931 *     
## Part_IDPart 2  -1.622e-03  2.015e-03  -0.805  0.421068      
## FPGATimeStamps:InitalTimeShift  1.555e-05  4.410e-06   3.527  0.000446 ***  
## FPGATimeStamps:Layer_ID -2.634e-08  8.534e-09  -3.086  0.002100 **    
## FPGATimeStamps:Part_IDPart 2  -3.422e-06  1.326e-06  -2.581  0.010034 *     
## InitalTimeShift:Layer_ID -9.845e-06  4.077e-06  -2.415  0.015990 *     
## InitalTimeShift:Part_IDPart 2  1.898e-03  1.990e-03   0.953  0.340680      
## Layer_ID:Part_IDPart 2  -4.970e-06  7.995e-07  -6.217  8.39e-10 ***
```

Results and Discussion

- Regression Analysis 3 [$\tau \sim f(T_{FPGA}, TS_0, L)$]
 - **Answer to Research Question 3:** Can "Time-shift adjustment, τ " be predicted by using its statistical relationship with the predictor variables: "FPGA timestamp, T_{FPGA} ", "Initial time-shift, TS_0 ", and "Layer index, L "?
 - **3 candidate models** were selected, and their **prediction accuracy** was evaluated using 10-fold cross validation.
 - 1. Full model:** Include all main effects and interaction effects of the predictor variables.
 - 2. Lasso-penalized model:** "cv.glmnet" with LASSO penalty is employed to select the model that corresponds to the minimum mean-squared error across a 10-fold cross-validation.
 - 3. Step-wise regression model:** Step-wise regression in both direction is used to select the model based on AIC (Akaike's information criterion) metric.

Results and Discussion

- Regression Analysis 3 $[\tau \sim f(T_{FPGA}, TS_0, L)]$
 - **Answer to Research Question 3:** Can "Time-shift adjustment, τ " be predicted by using its statistical relationship with the predictor variables: "FPGA timestamp, T_{FPGA} ", "Initial time-shift, TS_0 ", and "Layer index, L "?
 - **Prediction-accuracy calculation:**

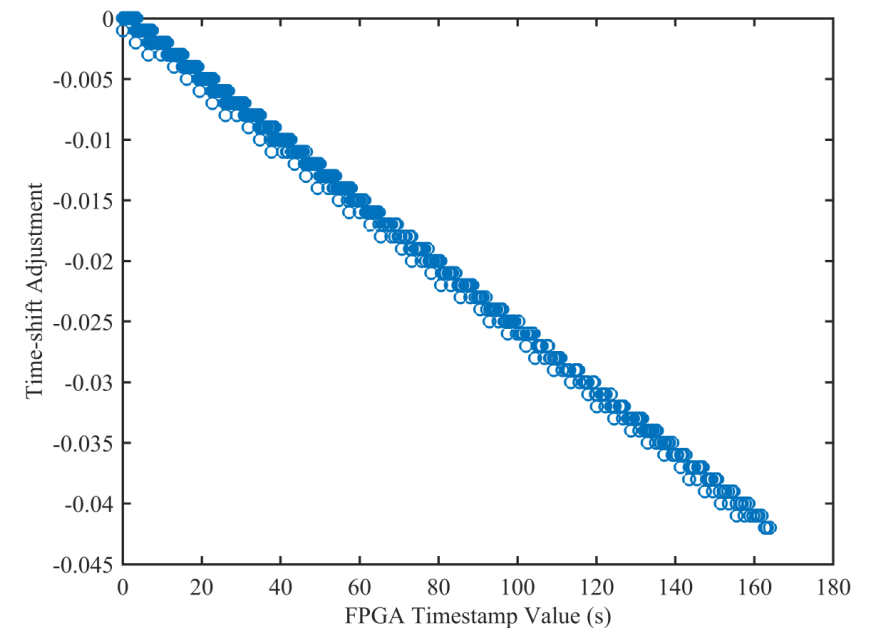


```
for (i in 1:k) {  
  test_indices <- random_indices[fold_indices == i]  
  train_data <- df_tau[-test_indices, ]  
  test_data <- df_tau[test_indices, ]  
  
  # Fit the model_full on the training data  
  model_full <- lm(tau_formula, data = train_data)  
  
  # Make predictions on the test data  
  predictions <- predict(model_full, newdata = test_data)  
  
  # calculate errors (after appropriate rounding), and accuracy %  
  errors <- test_data[,5] - round(predictions,3)  
  pct_accuracy <- length(which(errors==0))/nrow(test_data)*100  
  cv_pct_accuracy[i] <- pct_accuracy  
}
```

Results and Discussion

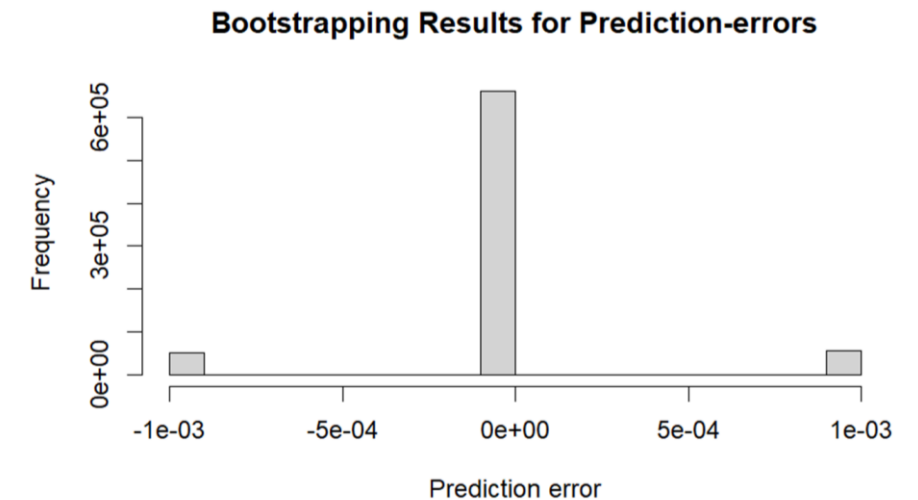
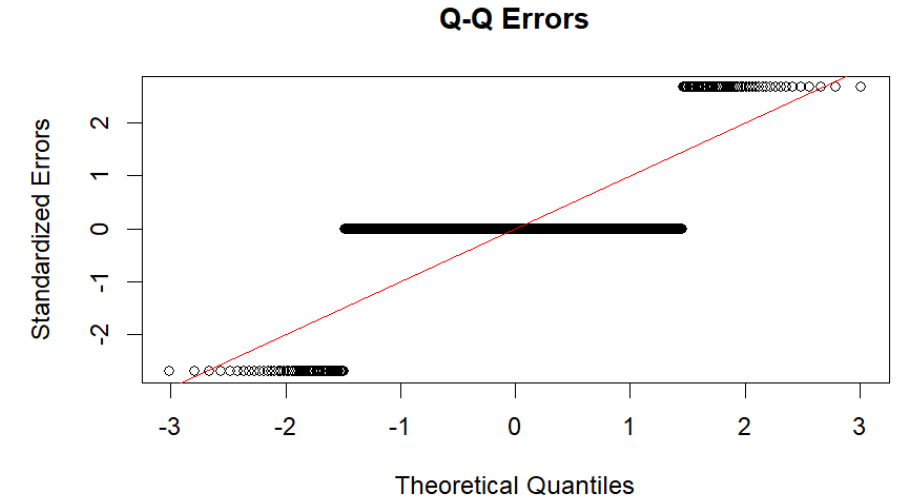
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Model	Average Cross-validation Accuracy
Full model	72.80075%
Lasso-penalized model ($\tau \sim T_{FPGA} + L$)	74.09945%
Step-wise regression model ($\tau \sim T_{FPGA} + TS_0 + L + T_{FPGA} * L + TS_0 * L$)	73.06049%
Base model ($\tau \sim T_{FPGA}$)	70.45455%



Results and Discussion

- Regression Analysis 3 $[\tau \sim f(T_{FPGA}, TS_0, L)]$
 - **Determination of the *maximum prediction-error magnitude*:**
 - Q-Q plot reveals that normality assumption is not valid for the discretized errors or residuals.
 - “Bootstrapping” is implemented to obtain 99% confidence interval on the prediction-errors: $CI_{error} = [-0.001, 0.001]$ s.
 - *Implication*: After obtaining the prediction for τ_i , synchronization results will be checked for τ_i and $(\tau_i \pm 0.001)$ to confirm the accurate synchronization.





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