Subspaces, Basis, Dimension & Rank Subspaces are a generalisation of line or plane through the origin Subspace of Rn is a collection of vectors S, such that;
1) the zero vector is in S. 2) if u r v are in s, u+v are in S.
3) if u is in S and c is a scalar, then cu is in S Thrm 3.19 - if v, v2 ... vk are vectors in K" then span(v, v2... vk) is a subspace of K" · span(V_1, V_2, V_k) is the subspace spanned by $(V_1, V_2 ... V_k)$ to determine whether someting is a subspace, check the theorem properties, then \top | counterexample. Row/Column Sogre - Let A be an nxn matrix, the row/col space of A is the subspace (now(A)) spanned by the rows/cols of A * to find the row space, A = w - find the transpose and do the columns.Null Space Let A be an 1xm matrix, the null space of A is the subspace of R consisting of solutions of the homogenious linear system Ax=0 & denoted by null(A) There is no solution in equations Ax = b, exactly one of the following is true; c) There are infinitly many solutions Basis of a subspace describes the direction vectors of the lines/planes Basis for subspace S of R is a set of vectors in S that i) span, S, and, 1) are linearly independent → e,,e,...en is called the standard basis * to find the basis of a subspace;

I) find the REFR of A 1) use the ool vectors of A that correspond to the columns R containing the leading LI variables to form a basis for collA) 3) Solve for leading variables, eg Rx = 0 in terms of free variables (s,t...) 4) set free variables = to parameter, sub back into vector form (to write as linear combination) These vectors form a basis for null A) Thrm 3.23- let of be a subspace of R, any 2 bases have the science number of vectors

