

5.3 Gram Schmit Process

Constructing an orthonormal basis for any subspace

The Gram-Schmidt process - begin with an arbitrary basis & orthogonalise 1 vector at a time

* GS Process (Thm 5.15)

Let $\{x_1, \dots, x_k\}$ be a subspace W of \mathbb{R}^n and define the following;

$$v_1 = x_1 \quad \left| \quad v_2 = x_2 - \left(\frac{v_1 \cdot x_2}{v_1 \cdot v_1} \right) v_1 \quad \left| \quad v_3 = x_3 - \left(\frac{v_1 \cdot x_3}{v_1 \cdot v_1} \right) v_1 - \left(\frac{v_2 \cdot x_3}{v_2 \cdot v_2} \right) v_2 \quad \left| \quad v_k = x_k - \left(\frac{v_1 \cdot x_k}{v_1 \cdot v_1} \right) v_1 - \dots - \left(\frac{v_{k-1} \cdot x_k}{v_{k-1} \cdot v_{k-1}} \right) v_{k-1}$$

5.4 Orthogonal Diagonalisation of Symmetric Matrices

• **Orthogonally Diagonalisable** - if there exists an orthogonal matrix Q and diagonal matrix D ; such that: $Q^T A Q = D$

• Thm 5.17 - If A is orthogonally diagonalisable then A is symmetric

• Thm 5.19 - If A is a symmetric matrix then any two eigenvectors (of distinct Eigenvalues) are or

• Thm 5.20 - Spectral Theorem - Every real symmetric square matrix can be diagonal

5.5 Applications: Graphing Quadratics

We can represent quadratic forms using matrices;

$$x^2 + by^2 + cxy = [x \ y] \begin{bmatrix} a & c/2 \\ c/2 & b \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} \text{ and; } ax^2 + by^2 + cz^2 + dxy + exz + fyz = [x \ y \ z] \begin{bmatrix} a & d/2 & e/2 \\ d/2 & b & f/2 \\ e/2 & f/2 & c \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix}$$

→ these are symmetric, making; $f(x) = x^T A x$, where A is the matrix associated with f .

• **general form** of a quadratic equation in two variables x and y ;

$$ax^2 + by^2 + cxy + dx + ey + f = 0$$

• the graphs of such equations are called 'conic sections' or conics

• **Non degenerate conics**; ellipses (circles), hyperbolas & parabolas

• **Standard position** represented in the following forms;



Circle



Ellipse



Parabola



Hyperbola

Ellipse or Circle

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1$$



