view_frames Result Recorded at time: 1703712768.520 map Broadcaster: /amcl Average rate: 7.931 Hz
Most recent transform: 1703712768.855 (-0.335 sec old) Buffer length: 3.657 sec odom Broadcaster: /ekf_se Average rate: 30.266 Hz
Most recent transform: 1703712768.603 (-0.083 sec old) Buffer length: 3.734 sec base_link Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1703712768.520 sec old) Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10.303 Hz
| Most recent transform: 1703712768.559 (-0.039 sec old) Average rate: 10000.000 Hz Most recent transform: 0.000 (1703712768.520 sec old) Most recent transform: 0.000 (1703712768.520 sec old) Buffer length: 0.000 sec Buffer length: 3.300 sec Buffer length: 0.000 sec Buffer length: 0.000 sec laser webcam imu tower Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1703712768.520 sec old) Buffer length: 0.000 sec kinect_rotator Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz

Most recent transform: 0.000 (1703712768.520 sec old) Buffer length: 0.000 sec kinect_base Broadcaster: /kinect aux Average rate: 499.051 Hz Most recent transform: 1703712768.616 (-0.096 sec old) Buffer length: 3.761 sec camera link Broadcaster: /camera_base_link1 Broadcaster: /camera_base_link Average rate: 10000.000 Hz
\Most recent transform: 0.000 (1703712768.520 sec old)

Buffer length: 0.000 sec Average rate: 10000.000 Hz

Most recent transform: 0.000 (1703712768.520 sec old) Buffer length: 0.000 sec camera_rgb_frame camera_depth_frame Broadcaster: /camera_base_link3 Broadcaster: /camera base link2 Average rate: 10000.000 Hz

Most recent transform: 0.000 (1703712768.520 sec old) Average rate: 10000.000 Hz Most recent transform: 0.000 (1703712768.520 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec $camera_depth_optical_frame$ camera_rgb_optical_frame