view frames Result Recorded at time: 1712066852.072 map Broadcaster: /amcl Average rate: 7.434 Hz
Most recent transform: 1712066851.924 (0.148 sec old) Buffer length: 4.305 sec odom Broadcaster: /teensy_serial_two Average rate: 50.233 Hz
Most recent transform: 1712066852.019 (0.053 sec old) Buffer length: 4.260 sec base link Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
| Most recent transform: 0.000 (1712066852.072 sec old) Most recent transform: 0.000 (1712066852.072 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec webcam laser tower Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 42.741 Hz
Most recent transform: 1712066852.005 (0.068 sec old) Buffer length: 0.000 sec Buffer length: 3.907 sec kinect_rotator scara arm base Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 42.741 Hz
Most recent transform: 1712066852.005 (0.068 sec old) Average rate: 42.741 Hz Most recent transform: 1712066852.005 (0.068 sec old) Buffer length: 3.907 sec Buffer length: 3.907 sec scara_arm_joint kinect_pivot Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: $1\overline{0}000.\overline{00}0$ Hz Average rate: 42.741 Hz Most recent transform: 1712066852.005 (0.068 sec old) Most recent transform: 0.000 (1712066852.072 sec old) Buffer length: 0.000 sec Buffer length: 3.907 sec camera_depth_frame scara_arm_gripper Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1712066852.072 sec old)
Buffer length: 0.000 sec Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz

Most recent transform: 0.000 (1712066852.072 sec old) Buffer length: 0.000 sec camera_depth_optical_frame camera_rgb_frame Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1712066852.072 sec old) Buffer length: 0.000 sec camera_rgb_optical_frame