view frames Result Recorded at time: 1703709759.431 map Broadcaster: /amcl Average rate: 7.840 Hz
Most recent transform: 1703709759.792 (-0.361 sec old) Buffer length: 4.337 sec odom Broadcaster: /ekf_se Average rate: 30.223 Hz
Most recent transform: 1703709759.455 (-0.024 sec old) Buffer length: 4.467 sec base_link Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1703709759.431 sec old) Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10.255 Hz
\Most recent transform: 1703709759.412 (0.019 sec old) Average rate: 10000.000 Hz Most recent transform: 0.000 (1703709759.431 sec old) Most recent transform: 0.000 (1703709759.431 sec old) Buffer length: 0.000 sec Buffer length: 3.901 sec Buffer length: 0.000 sec Buffer length: 0.000 sec laser webcam imu tower Buffer length: 0.000 sec kinect_rotator Broadcaster: /robot_state_publisher Average rate: 10.255 Hz Most recent transform: 1703709759.412 (0.019 sec old) Buffer length: 3.901 sec kinect_base Broadcaster: /robot_state_publisher Average rate: 10.255 Hz Most recent transform: 1703709759.412 (0.019 sec old) Buffer length: 3.901 sec camera link Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (1703709759.431 sec old) Buffer length: 0.000 sec camera_depth_frame camera_rgb_frame Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1703709759.431 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec $camera_depth_optical_frame$ camera_rgb_optical_frame