Final Plan

Job 11-1: Now you will need to construct a new plan which does the following

- Feel free to reference your existing plans and previous lessons as it uses elements from them.
- Don't forget to provide values or variable names for event fields

First, the operator should be asked to create a list of locations

When the list of locations is received, Camera tasks should be generated from the list of locations

When the task tokens are received, they should be allocated immediately by the System AI.

When a task is assigned, the robot for the task should move directly to the task's location

When the robot for the task arrives, it should take a panorama

After taking the picture, the robot should wait 5 seconds

After waiting 5 seconds, the task is complete

When there are no unfinished tasks, the mission should end