

Effective diffusivity: a dynamical systems approach

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Abstract

A dynamical systems approach to the effective parameter problem for advection-diffusion is presented.

1 The cell problem as a dynamical system

Consider the cell problem associated with the advection-diffusion equation

$$(\partial_t + \mathbf{u} \cdot \nabla - \varepsilon \Delta) \chi_j(t, \mathbf{x}) = u_j(t, \mathbf{x}) \quad (1)$$

with velocity field

$$\mathbf{u}(t, \mathbf{x}) = (\cos y, \cos x) + \theta \cos t (\sin y, \sin x). \quad (2)$$

The components D_{jk}^* , $j, k = 1, \dots, d$, of the effective diffusivity tensor D^* are given by

$$D_{jk}^* = \varepsilon \delta_{jk} + \langle u_j, \chi_k \rangle_2, \quad (3)$$

where $\langle f, h \rangle = \langle f, \bar{h} \rangle$ denotes the $L^2(\mathcal{T} \times \mathcal{V})$ inner-product over the period cell $\mathcal{T} \times \mathcal{V}$, $\langle \cdot \rangle$ denotes space-time average over $\mathcal{T} \times \mathcal{V}$, and \bar{h} denotes complex conjugation of the function h . We stress that u_j and χ_k are *real-valued*. Inserting the formula for u_j in (1) into equation (3) yields

$$S_{jk}^* = \varepsilon(\delta_{jk} + \langle \chi_j, \chi_k \rangle_1), \quad A_{jk}^* = \langle A \chi_j, \chi_k \rangle_1, \quad A = (-\Delta)^{-1}(\partial_t + \mathbf{u} \cdot \nabla). \quad (4)$$

Here S_{jk}^* and A_{jk}^* are the components of the symmetric S^* and antisymmetric A^* parts of D^* and $\langle f, h \rangle_1 = \langle \nabla f \cdot \nabla h \rangle$.

Since $\chi(t, \cdot) \in \mathcal{H}_{\mathcal{V}}^1$ for each $t \in \mathcal{T}$ and the orthogonal set $\{e^{i(mx+ny)}\}_{m,n \in \mathbb{Z}}$ is complete in $L^2(\mathcal{V}) \supset \mathcal{H}_{\mathcal{V}}^1$, we can represent $\chi_j(t, \mathbf{x})$ by

$$\chi_j(t, \mathbf{x}) = \sum_{m,n} a_{m,n}^j(t) e^{i(mx+ny)}, \quad a_{m,n}^j(t) = \langle \chi_j(t, \mathbf{x}), e^{i(mx+ny)} \rangle_{\mathcal{V}}, \quad a_{m,n}^j(0) = a_{m,n}^j(2\pi), \quad (5)$$

where $\langle \cdot \rangle_{\mathcal{V}}$ denotes spatial averaging over the spatial period \mathcal{V} . Inserting the formula for χ_j in (5) into equation (1) yields

$$\sum_{m,n} e^{i(mx+ny)} [\partial_t + i m u_1 + i n u_2 + \varepsilon(m^2 + n^2)] a_{m,n}^j = u_j, \quad (6)$$

where we have written $\mathbf{u} = (u_1, u_2)$. Writing $\cos x = (e^{ix} + e^{-ix})/2$ and $\sin x = (e^{ix} - e^{-ix})/(2i)$, for example, equation (6) can be written, for $j = 1$, as

$$\begin{aligned} \sum_{m,n} e^{i(mx+ny)} [\partial_t a_{m,n}^1 + \frac{i}{2}(m(a_{m,n-1}^1 + a_{m,n+1}^1) + n(a_{m-1,n}^1 + a_{m+1,n}^1)) \\ + \frac{\theta \cos t}{2}(m(a_{m,n-1}^1 - a_{m,n+1}^1) + n(a_{m-1,n}^1 - a_{m+1,n}^1)) + \varepsilon(m^2 + n^2)a_{m,n}^1 \\ - \frac{1}{2}\delta_{0,m}(\delta_{1,n} + \delta_{-1,n}) - \frac{\theta \cos t}{2i}\delta_{0,m}(\delta_{1,n} - \delta_{-1,n})] = 0, \end{aligned} \quad (7)$$

where $\delta_{l,m}$ is the Kronecker delta. Since $u_2(t, x, y) = u_1(t, y, x)$, the formula for $a_{m,n}^2$ follows from interchanging $\delta_{l,m}$ with $\delta_{l,n}$ in (7), $l = -1, 0, 1$. By the completeness of the orthogonal set $\{e^{i(mx+ny)}\}$, equation (7) and its analogue for $a_{m,n}^2$ can be written as the following two (infinite) linear, coupled dynamical systems

$$\begin{aligned} \partial_t a_{m,n}^1 &+ \frac{i}{2}(m(a_{m,n-1}^1 + a_{m,n+1}^1) + n(a_{m-1,n}^1 + a_{m+1,n}^1)) \\ &+ \frac{\theta \cos t}{2}(m(a_{m,n-1}^1 - a_{m,n+1}^1) + n(a_{m-1,n}^1 - a_{m+1,n}^1)) + \varepsilon(m^2 + n^2)a_{m,n}^1, \\ &= \frac{1}{2}\delta_{0,m}(\delta_{1,n} + \delta_{-1,n}) + \frac{\theta \cos t}{2i}\delta_{0,m}(\delta_{1,n} - \delta_{-1,n}), \\ \partial_t a_{m,n}^2 &+ \frac{i}{2}(m(a_{m,n-1}^2 + a_{m,n+1}^2) + n(a_{m-1,n}^2 + a_{m+1,n}^2)) \\ &+ \frac{\theta \cos t}{2}(m(a_{m,n-1}^2 - a_{m,n+1}^2) + n(a_{m-1,n}^2 - a_{m+1,n}^2)) + \varepsilon(m^2 + n^2)a_{m,n}^2 \\ &= \frac{1}{2}\delta_{0,n}(\delta_{1,m} + \delta_{-1,m}) + \frac{\theta \cos t}{2i}\delta_{0,n}(\delta_{1,m} - \delta_{-1,m}), \end{aligned} \quad (8)$$

with boundary condition $a_{m,n}^j(0) = a_{m,n}^j(2\pi)$, $j = 1, 2$, $m, n \in \mathbb{Z}$. When $\theta = 0$, the velocity field in (2) is time-independent. In this case the function χ_j , hence the Fourier coefficients $a_{m,n}^j$ are also time-independent, and equation (8) reduces to the following algebraic system of equations

$$\begin{aligned} \frac{i}{2}(m(a_{m,n-1}^1 + a_{m,n+1}^1) + n(a_{m-1,n}^1 + a_{m+1,n}^1)) + \varepsilon(m^2 + n^2)a_{m,n}^1 &= \frac{1}{2}\delta_{0,m}(\delta_{1,n} + \delta_{-1,n}) \\ \frac{i}{2}(m(a_{m,n-1}^2 + a_{m,n+1}^2) + n(a_{m-1,n}^2 + a_{m+1,n}^2)) + \varepsilon(m^2 + n^2)a_{m,n}^2 &= \frac{1}{2}\delta_{0,n}(\delta_{1,m} + \delta_{-1,m}). \end{aligned} \quad (9)$$

By restricting the indices, $-M \leq \ell, m, n \leq M$, and imposing the boundary conditions

$$a_{m,n}^l = 0 \quad \text{if} \quad \max(|m|, |n|) > M, \quad (10)$$

the infinite systems of equations in (8) and (9) become finite sets of equations. The bijective mapping

$$\Theta_s(m, n) = (M + m + 1) + (M + n)(2M + 1), \quad (11)$$

maps the finite sets of equations to matrix equations

$$\partial_t \mathbf{a}^j(t) = (A + \theta \cos t B + \varepsilon C) \mathbf{a}^j(t) + \boldsymbol{\xi}_1^j + \theta \cos t \boldsymbol{\xi}_2^j, \quad \mathbf{a}^j(0) = \mathbf{a}^j(2\pi) \quad (12)$$

$$(A + \varepsilon C) \mathbf{a}^j = \boldsymbol{\xi}_1^j \quad (13)$$

Equation (12) is a linear, inhomogeneous dynamical system of equations, while equation (13) is a linear system of algebraic equations. In equation (13), the rows and columns of the matrices A and C corresponding to the $a_{0,0}^j$ component of the unknown vector \mathbf{a}^j , consist entirely of zero elements, and can be removed without loss of generality. Consequently, for each $0 < \varepsilon < \infty$, this algebraic system in (13) can be directly solved using techniques of linear algebra, to determine the Fourier coefficients of χ_j in \mathbf{a}^j . Moreover, the matrix $(A + \varepsilon C)$ is *sparse*, so that iterative methods are applicable.

We now discuss how the symmetric \mathbf{S}^* and antisymmetric \mathbf{A}^* parts of the effective diffusivity tensor \mathbf{D}^* are determined from the Fourier coefficients $a_{m,n}^j$ of χ_j . Inserting the formula for χ_j in (5) into the formula for \mathbf{S}_{jk}^* in equation (4) and using the orthogonality of the set $\{e^{i(mx+ny)}\}$ yields

$$\mathbf{S}_{jk}^*/\varepsilon - \delta_{jk} = \langle \chi_j, \chi_k \rangle_1 = \text{Re} \sum_{m,n} (m^2 + n^2) \langle a_{m,n}^j \overline{a_{m,n}^k} \rangle_{\mathcal{T}}. \quad (14)$$

Here, $\langle \cdot \rangle_{\mathcal{T}}$ denotes time averaging over the temporal period \mathcal{T} and, since χ_j is real-valued, we have $\langle \chi_j, \chi_k \rangle_1 = \text{Re} \langle \chi_j, \chi_k \rangle_1$. As discussed above, when $\theta = 0$, the Fourier coefficients $a_{m,n}^j$ are time-independent, so that $\langle a_{m,n}^j \overline{a_{m,n}^k} \rangle_{\mathcal{T}} = a_{m,n}^j \overline{a_{m,n}^k}$. Note that $\langle A \chi_j, \chi_k \rangle_1 = \langle \nabla(-\Delta)^{-1}(\partial_t + \nabla \cdot \mathbf{u}) \chi_j \cdot \nabla \chi_k \rangle = \langle (\partial_t + \nabla \cdot \mathbf{u}) \chi_j, \chi_k \rangle_2$.

Consequently, inserting the formula for χ_j in (5) into the formula for A_{jk}^* in equation (4) and using the orthogonality of the set $\{e^{i(mx+ny)}\}$ yields

$$\begin{aligned} \langle A\chi_j, \chi_k \rangle_1 = \sum_{m,n} \langle \overline{\gamma_{m,n}^{\theta,j}} a_{m,n}^k \rangle_{\mathcal{T}}, \quad \gamma_{m,n}^{\theta,j} = \partial_t a_{m,n}^j + \frac{\imath}{2} (m(a_{m,n-1}^j + a_{m,n+1}^j) + n(a_{m-1,n}^j + a_{m+1,n}^j)) \\ + \frac{\theta \cos t}{2} (m(a_{m,n-1}^j - a_{m,n+1}^j) + n(a_{m-1,n}^j - a_{m+1,n}^j)). \end{aligned} \quad (15)$$

When $\theta = 0$, the Fourier coefficients $a_{m,n}^j$ are time-independent, so that $\langle \overline{\gamma_{m,n}^{\theta,j}} a_{m,n}^k \rangle_t = \overline{\gamma_{m,n}^{\theta,j}} a_{m,n}^k$ and $\gamma_{m,n}^{\theta,j} = (m(a_{m,n-1}^j + a_{m,n+1}^j) + n(a_{m-1,n}^j + a_{m+1,n}^j))/(-2\imath)$.