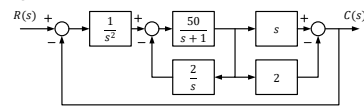


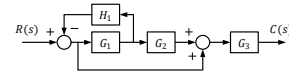
5.1 Reduce the block diagram to a single TF, $T(s) = C(s)/R(s)$. Use the following methods

a. Block diagram reduction

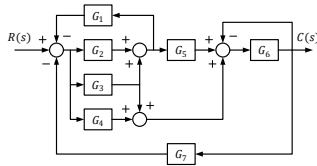
b. Matlab



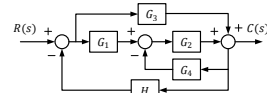
5.2 Find the equivalent TF, $T(s) = C(s)/R(s)$ for the system using block diagram reduction TF



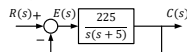
5.3 Find the closed-loop TF, $T(s) = C(s)/R(s)$ for the system



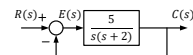
5.4 Reduce the system to a single TF $T(s) = C(s)/R(s)$



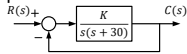
5.11 For the given system, find the percent overshoot, settling time, and peak time for a step input if the system's response is underdamped. (Is it? Why?)



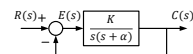
5.12 For the given system, find the output $c(t)$ if the input $r(t)$ is a unit step



5.14 For the given system, find the value of K that yields 10% overshoot for a step input



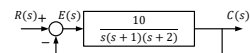
5.15 For the given system, find K and a to yield a settling time of $0.15s$ and a 30% overshoot



5.31 Represent the systems below in state space in phase-variable form. Draw the signal-flow graphs

- $G(s) = \frac{s+3}{s^2+2s+7}$
- $G(s) = \frac{s^2+2s+6}{3s^3+5s^2+2s+1}$
- $G(s) = \frac{s^3+2s^2+7s+1}{s^4+3s^3+5s^2+6s+4}$

5.34 You are given the system shown in the figure



- Represent the system in state space in phase variable form
- Represent the system in state space in any other form besides phase-variable

5.39 Given a unity feedback system with the forward-path TF

$$G(s) = \frac{7}{s(s+9)(s+12)}$$

use matlab to represent the closed loop system in state space in

- phase-variable form
- parallel form

5.45 Diagonalize the following system

$$\dot{x} = \begin{bmatrix} -5 & -5 & 4 \\ 2 & 0 & -2 \\ 0 & -2 & -1 \end{bmatrix} x + \begin{bmatrix} -1 \\ 2 \\ -2 \end{bmatrix} r, y = [-1 \quad 1 \quad 2]x$$