

# Monte Carlo parameter estimation in the Lorenz 63 system

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## 1 Introduction

Operational and theoretical climate and weather prediction use a host of approximations known as *parameterizations* to account for sub-grid scale dynamics. Frequently these parameters are physically well motivated, but just as frequently these parameters are chosen in an *ad hoc* manner.

As a proof of concept, the point of this final project is to learn parameters in a simple chaotic dynamical system using Markov Chain Monte Carlo (MCMC) techniques. The approach used is to minimize the sum of squares of the *dynamic residuals* as proposed by Prof. Goodman in a conversation. As a simple prototype chaotic system, we use the 3 dimensional ODE introduced in (Lorenz, 1963).

This system is one of the earliest examples of what would later become known as *chaotic* dynamical systems. It is obtained by projection of the Rayleigh-Benard equations for convection of a thin layer onto three orthogonal modes. The system is given by

$$\dot{X} = \sigma(Y - X) \tag{1}$$

$$\dot{Y} = -XZ + rX - Y \tag{2}$$

$$\dot{Z} = XY - bZ. \tag{3}$$

The parameters used by Lorenz are  $\sigma = 10$ ,  $b = 8/3$  and  $r = 28$ . The objective of this project is estimate these three parameters using Monte Carlo. This problem is the simplest prototype of parameter fitting in chaotic dynamical systems.

## 2 Parameter fitting procedure

The general outline here is to define a dynamics based loss function, and then samples from the associated Gibbs distribution. The loss function was proposed by Prof. Goodman in a meeting is sum of squares of the so-called *dynamic residuals*.

Let  $U$  be given by the dynamics

$$\dot{U} = F(U; \theta) + \epsilon \dot{W}$$

where  $\theta$  is some set of parameters.

Let  $T > 0$ ,  $N$ , and define  $\tau = T/(N + 1)$ . Then, a temporal grid  $t_j = j\tau$  can be defined for  $j = 0 \dots N$ . Let  $\Psi_t^\theta$  be the pushforward operator for deterministic part of the dynamics. Given a set of point estimates  $U_j$  and parameters, define the dynamic residual for a time  $t_j$  to be

$$e_j(\theta) := e(U_{j-1}, U_j, \theta) := \Psi_\tau^\theta U_{j-1} - U_j.$$

Then, a sensible way to choose the parameters is so that they minimize

$$H(\theta) = \frac{1}{N} \sum_{j=1}^N |e_j(\theta)|^2.$$

The corresponding Gibbs distribution is  $f(\theta) \propto \exp(-\beta H(\theta))$ .

This Gibbs distribution is sampled using a Metropolis-Hastings algorithm with a proposal distribution that is independent in each direction. In other words,

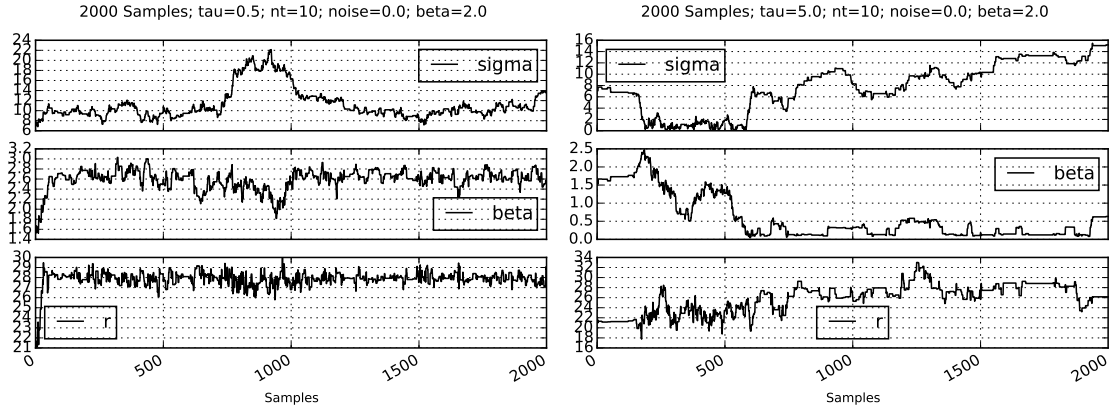
$$P(\theta_0, \theta_1) \propto \exp\left(-\frac{1}{2}(\theta_1 - \theta_0)^T C^{-1}(\theta_1 - \theta_0)\right),$$

where the covariance matrix is given by  $C_{11} = .5^2$ ,  $C_{22} = .1^2$ , and  $C_{33} = 1.0^2$ ,  $C_{ij} = 0$  if  $i \neq j$ .

A reference value of  $\beta = 2.0$  is used.

### 3 Results and Discussion

The traces of the sampler are shown here for short and long observation intervals of  $\tau = .5$  and 5.0, respectively:



The performance of the method is strongly dependent on the observation time interval  $\tau$ . Using the dynamic residuals method to find parameters works well for short observations times  $\tau \leq .5$ , but MCMC performance is very poor for larger  $\tau$  regardless of the  $\beta$  parameter used. This makes sense if  $\tau$  is approaching the predictability limit of the system. Making a model error by introducing gaussian noise  $\epsilon > 0$ , can regularize the fit somewhat, but does not work miracles. Of all the parameters in Lorenz63, the exchange parameter  $\sigma$  is the most difficult to estimate and shows very long autocorrelation times compared to  $r$  and  $b$ .

Future directions include using the dynamics residuals approach for the state estimation problem, which might be more tractable given the simpler dependence of the  $H(\theta)$  on the state estimates  $U_j$ . Since the parameters determine the shape of the Lorenz attractor, it probably makes more sense to pose the parameter-finding problem in terms of equilibrium statistics. The *dynamic residuals* approach is subject to the inherent predictability limit of the system and essentially misses the forest through the trees.

The code for this project is available on github at [https://github.com/nbren12/mc2015\\_final](https://github.com/nbren12/mc2015_final).

## References

- [1] Edward N. Lorenz. “Deterministic Nonperiodic Flow”. In: *Journal of the Atmospheric Sciences* 20.2 (Mar. 1963), pp. 130–141. DOI: 10.1175/1520-0469(1963)020<0130:dnf>2.0.co;2. URL: [http://dx.doi.org/10.1175/1520-0469\(1963\)020%3C0130:DNF%3E2.0.CO;2](http://dx.doi.org/10.1175/1520-0469(1963)020%3C0130:DNF%3E2.0.CO;2).