

**Names:****Sindhu (MD24S001)****Bhargava Satya Nunna(BT24S007)****Shivam Chaudhari(BT24S003)****Data Augmentation****ImageDataGenerator and Random Cropping**

This part had the biggest challenge. Since we're using a very small set for training, it is imperative to have good image augmentations. Keras' ImageDataGenerator class comes with different functionalities but it lacks an important one: random cropping. Since the images have different sizes, it is not optimal to resize them to a fixed size that would result in deformation and degrading images. I dug into Keras' source code and found that a function called `load_img` referenced `keras.preprocessing.image.image.load_img` takes care of loading images and then immediately resizing them to a specified size. So defined my own function that performs random cropping and overrode it with the original function.

**Requirements**

- Python  $\geq 3.5$
- Keras  $\geq 2.2.4$
- PIL
- Numpy
- Matplotlib
- Jupyter Notebook

**Model Architecture**

The architecture somewhat resembles U-Net, an encoder-decoder network with skip connections between mirrored layers in the encoder and decoder stacks. The network consists of convolutional, dropout and batch normalization layers. LeakyReLU is used as the activation function. One of the notable differences between this model and UNet is that it uses strided convolutions and transposed convolutions instead of pooling and upsampling layers.

The architecture you're looking at is a DnCNN (Denoising Convolutional Neural Network) model, which is specifically designed for image denoising tasks. Here are some resources and key points to help you understand and get more information about the DnCNN architecture:

The foundational work on DnCNN was presented in the paper titled "DnCNN: Beyond a Gaussian Denoiser." You can find it here: [DnCNN Paper](#). This paper explains the architecture, the training process, and various results.

## Key Components of DnCNN:

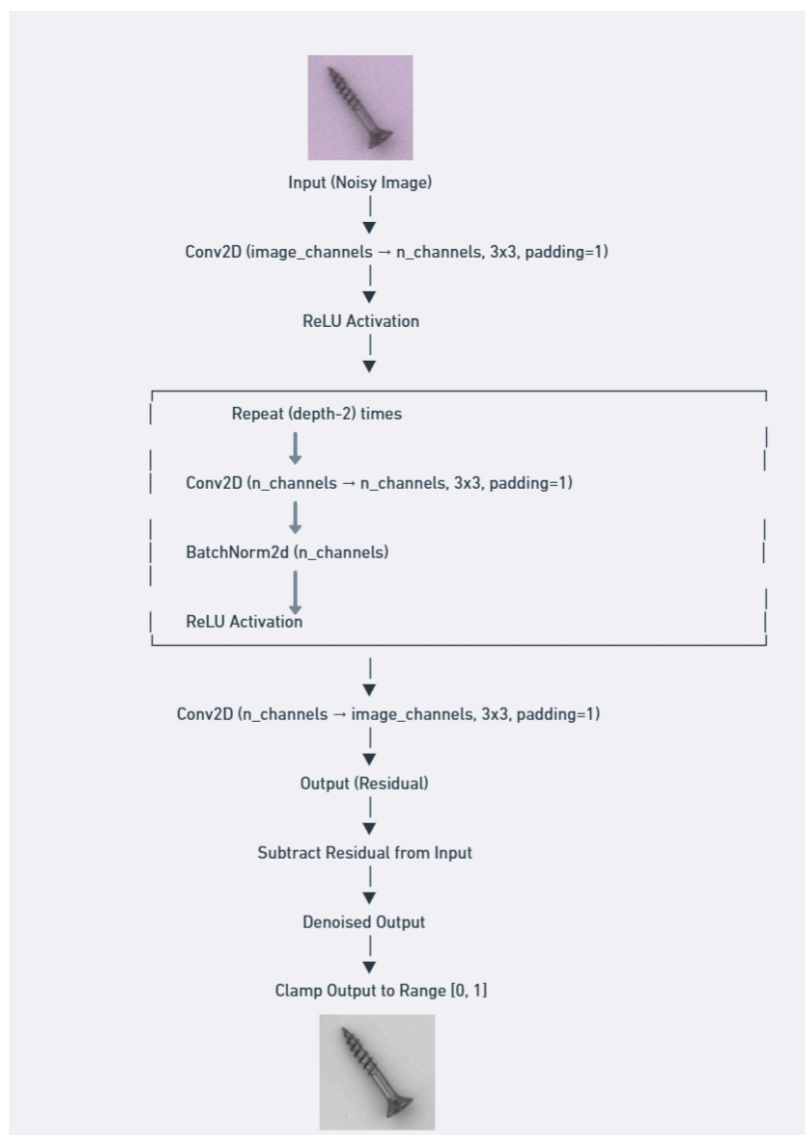
**Convolutional Layers:** The model consists of multiple convolutional layers to learn the mapping from noisy images to clean images.

**Residual Learning:** DnCNN employs residual learning, where the output is the noise that needs to be subtracted from the input image.

**Batch Normalization:** This is used between the convolutional layers to stabilize and accelerate the training process.

**ReLU Activation:** The model uses the ReLU activation function to introduce non-linearity.

**Implementations:** You can find various implementations of DnCNN on GitHub, which can help you understand how the architecture is applied in practice. Here are a few notable repositories:



## Github link

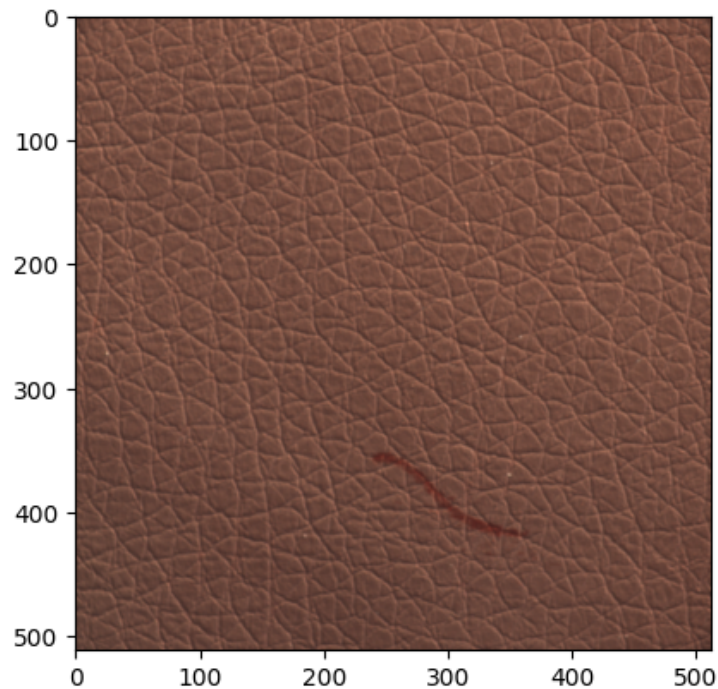
GitHub: [https://github.com/nbs19/AutoAE\\_Denoising/tree/main](https://github.com/nbs19/AutoAE_Denoising/tree/main)



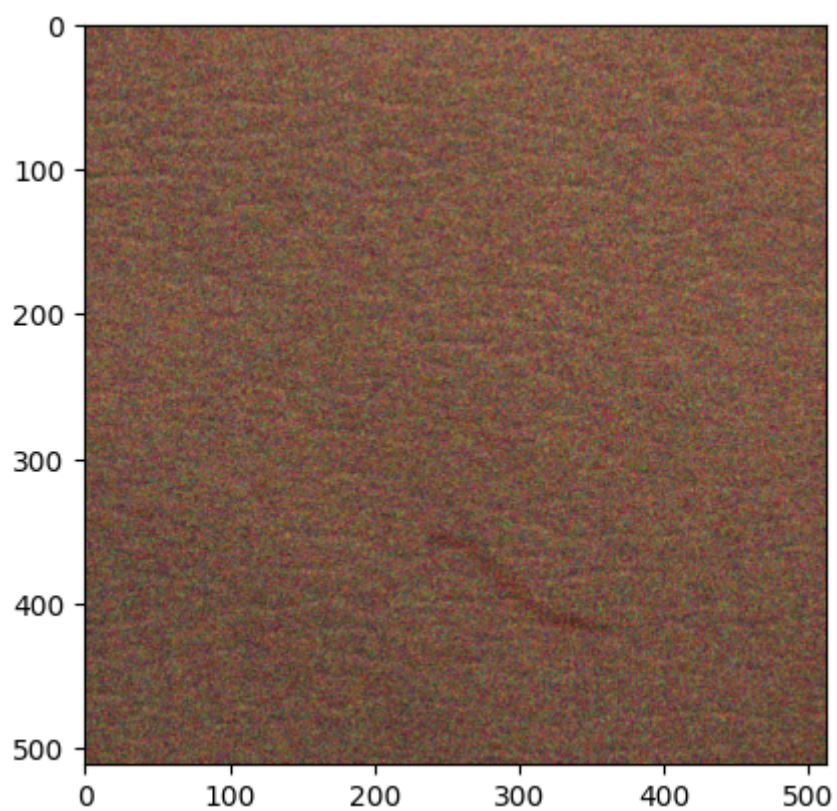
Image architecture generated using Torchviz library

**Sample Image:**

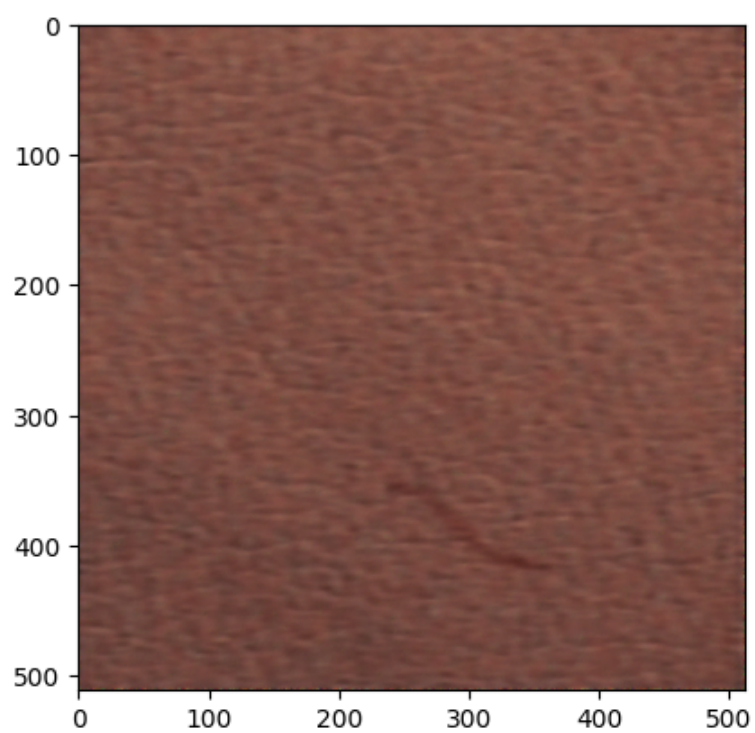
Ground Truth:



Denoised Image:



Denoised generated image:



## Results:

Avg PSNR Value for validation: 28.3

Avg SSIM Value for validations 0.76

## Class Wise PSNR:

psnr for bottle is 26.731958389282227

psnr for cable is 25.60096549987793

psnr for capsule is 27.70871925354004

psnr for carpet is 20.63148307800293

psnr for grid is 24.275985717773438

psnr for hazelnut is 30.310144424438477

psnr for leather is 27.201934814453125

psnr for metal\_nut is 27.034360885620117

psnr for pill is 29.53520965576172

psnr for screw is 26.993492126464844

psnr for tile is 24.234760284423828

psnr for toothbrush is 29.037992477416992

psnr for transistor is 28.25482177734375

psnr for wood is 26.24666976928711

psnr for zipper is 28.36189079284668

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