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nathaniel-burgdorfer

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# Nathaniel Burgdorfer

#### Education

Ph.D. in Computer Science, Stevens Institute of Technology, Hoboken, NJ

2025

 $\circ$  **GPA** -4.00

M.Sc. in Machine Learning, Stevens Institute of Technology, Hoboken, NJ

2020

• **GPA** – 3.95

B.Sc. in Computer Science, Stevens Institute of Technology, Hoboken, NJ

2020

- **GPA** 3.87
- TA: CS-392 Systems Programming, CS-511 Concurrent Programming, CS-284 Data Structures, CS-383 Computer Organization and Programming
- o Upsilon Pi Epsilon, Member of the International Honor Society for the Computing and Information Disciplines
- Honors, Dean's List, Graduated with High Honors

## Professional Experience

Research Intern - 3D Computer Vision, InnoPeak Technology, Palo Alto, CA May 2023 - Aug 2023

- Collaborations with the AR/VR team to perform research in the area of 3D Computer Vision.
- Research topics focused on Multi-View Stereo depth estimation, 3D Implicit Reconstruction, Differentiable Volume Rendering, and Implicit Dense SLAM.

Software Engineer - Embedded Systems, L3Harris Technologies, Clifton, NJ

Jan 2021 – Aug 2021

- Development of core radar systems capabilities. (C++)
- VxWorks kernel modifications and development. (C++)
- Implementation of embedded multicore capabilities. (C++)

Software Engineering Intern - Masters, L3Harris Technologies, Clifton, NJ

Jun 2020 – Aug 2020

- Development on embedded systems algorithms involving Radar technology and signal processing. (C++)
- Integrating automation and data collection into existing unit tests for signal processing algorithms. (C++)

#### Senior Design, Zebra Technologies, Hoboken, NJ

Sep 2019 – May 2020

- Developing a real-time image recognition pipeline for shipping container detection and classification. (C++, Python, TensorFlow)
- Developing a real-time 2D object pose estimation pipeline for shipping container CAD model alignment. (C++, Python)

#### Software Developer, DexterityDB, Hoboken, NJ

Dec 2018 - Jun 2020

- Developing parts of the company's core engine with a small team of systems developers (C++, Rust)
- o Implementing build and test servers utilizing docker containers and cloud services. (Python, Bash, GCP)
- $\circ$  Enhancing and extending plugin features of the database engine. (C++)

### Research Interests

- o Binocular and Multi-View Stereo
- Monocular Depth Estimation from Video
- Surface Reconstruction

## **Publications**

- Burgdorfer, N., Mordohai, P.. V-FUSE: Volumetric Depth Map Fusion with Long-Range Constraints. IEEE/CVF International Conference on Computer Vision (ICCV), 2023.
- Wang, W., Joshi, B., Burgdorfer, N., Batsos, K., Quattrini Li, A., Mordohai, P., Rekleitis, I.. Real-Time Dense 3D Mapping of Underwater Environments. IEEE International Conference on Robotics and Automation (ICRA), 2023.
- o Xanthidis, M., Joshi, B., Roznere, M., Wang, W., **Burgdorfer, N.**, Quattrini Li, A., Mordohai, P., Nelakuditi, S., and Rekleitis, I.. *Towards Mapping of Underwater Structures by a Team of Autonomous Underwater Vehicles*. International Symposium of Robotics Research (ISRR), 2022.
- o Joshi, B., Xanthidis, M., Roznere, M., **Burgdorfer**, N., Mordohai, P., Quattrini Li, A., and Rekleitis, I.. *Underwater Exploration and Mapping*. IEEE/OES Autonomous Underwater Vehicles Symposium (AUV), 2022.

## Teaching Assistantships

o CS 559 - Machine Learning (TA)	Spring 2023
• CS 146 - Intro to Web Programming (TA)	Fall 2022
• CS 392 - Systems Programming (CA)	Spring 2020
• CS 511 - Concurrent Programming (CA)	Fall 2019
• CS 284 - Data Structures (CA)	Spring 2019
• CS 383 - Computer Organization and Programming (CA)	Fall 2018
• CS 284 - Data Structures (CA)	Spring 2018

## Programming Languages & Libraries

- Python, C++, C, C#
- PyTorch, OpenCV, Open3D, TensorFlow