

9. Ideal gas and indistinguishability

Indistinguishability



- Let us review the arguments of key point 13.
- Identification of a microstate as a specification of the state of each and every particle, $i_1...i_N$ of particles 1...N.
- Reorganisation of the partition function as

$$Z = \sum_{r} e^{-\beta E_r} = \left[\sum_{i_1} e^{-\beta \epsilon_{i_1}} \right] \cdots \left[\sum_{i_N} e^{-\beta \epsilon_{i_N}} \right]$$

• We must now recognise that these steps presuppose that the constituent particles are at least, in principle, **distinguishable** from one another, so that each may be thought of as carrying a personal identifying label.

Indistinguishability



- In the context of models of solids or crystalline magnets, there is nothing for us to worry about: the atoms in a solid are **localised** (nailed down!) in space; their 'addresses' in space provide, in principle, the ingredients of a labelling scheme.
- In the case of a gas, within a classical world view, there is also no problem. We may envisage 'christening' the atoms at some point and, with the aid of an army of willing assistants, keeping track of their identities.
- But quantum physics tells us that particles should not be thought of as having 'trajectories'; they are at best characterised by wave functions whose overlap makes it impossible to 'keep track of' which particle is which.
- We reach a profound conclusion:
- Key point 14: Identical non-localised particles must be treated as indistinguishable.

Accounting for indistinguishability



- We seek to modify in a simple way the Boltzmann theory to take into account indistinguishability that arises from non-localisation.
- Roughly speaking (see Blundell-Blundell for full argument), the number of microstates of a system of non-localised particles is less by a factor of 1/N! compared to the case where the particles are treated distinguishably.
- Thus to correct for the overcounting due to indistinguishability, we divide the partition function by N!

$$Z_{\text{indist.}} = \frac{1}{N!} \sum_{i_1 = i_2 \dots = i_N} \exp(-\beta [\epsilon_{i_1} + \epsilon_{i_2} + \dots + \epsilon_{i_N}]) = \frac{1}{N!} [Z(1)]^N$$

where i_n is the state of particle n.

This simple correction for non-localisation is only valid at low densities

Calculation of Z(1)



- The single particle partition function Z(1) for a free particle in a cubic box of side L.
- $_{\bullet}$ Schrödinger's equation for a free particle: $\bigg(-\frac{\hbar^2}{2M}\nabla^2 \epsilon \hspace{0.1cm}\bigg)\psi = 0$
- In 1d: $\psi'' = -k^2 \psi$ where $k^2 = \frac{2M\epsilon}{k^2} = 0$

$$\psi = A \sin kx$$
 with $k = \frac{n\pi}{I}$ and $n = 1,2,3,...$ • ψ vanishes at $x = 0,L$

• In 3d: $\psi = A \sin k_x x \sin k_y y \sin k_z z$ with $k_x = \frac{n_x \pi}{I}$, $k_y = \frac{n_y \pi}{I}$, $k_z = \frac{n_z \pi}{I}$

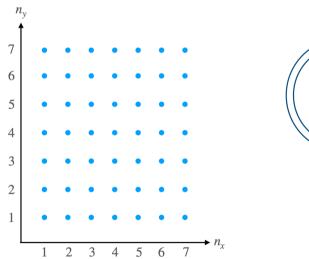
$$\epsilon = \frac{\hbar^2}{2M}(k_x^2 + k_y^2 + k_z^2) = \frac{\hbar^2 \pi^2}{2ML^2}(n_x^2 + n_y^2 + n_z^2)$$

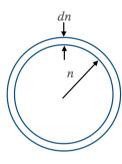
Calculation of Z(1)



• The task now is to sum over all allowed values of n_x , n_y , n_z :

$$Z(1) = \sum_{n_x, n_y, n_z} \exp(-\beta \epsilon(n_x, n_y, n_z)) = \exp(-\beta \epsilon(1, 1, 1)) + \exp(-\beta \epsilon(2, 1, 1)) + \dots$$





• Approach: convert the sum into an integral in *n*-space.

$$n = (n_x^2 + n_y^2 + n_z^2)^{1/2}$$

$$\sum_{n_{\nu},n_{\nu},n_{\tau}} [\cdots] \to \frac{1}{8} \int [\cdots] 4\pi n^2 dn$$

$$Z(1) \to \frac{\pi}{2} \int_0^\infty \exp\left(-\beta \frac{\hbar^2 \pi^2 n^2}{2ML^2}\right) n^2 dn$$

• This is of course an approximation. It is a good approximation when $\frac{\hbar^2\pi^2}{2ML^2}\ll kT$