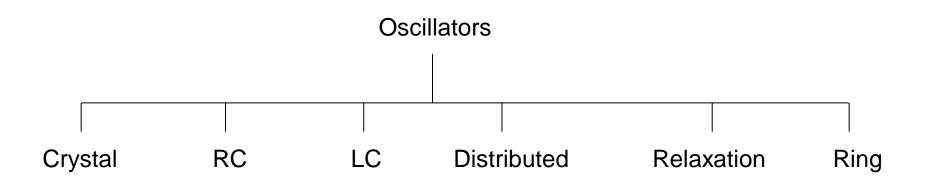
## Chapter 6

**Microwave Oscillators** 

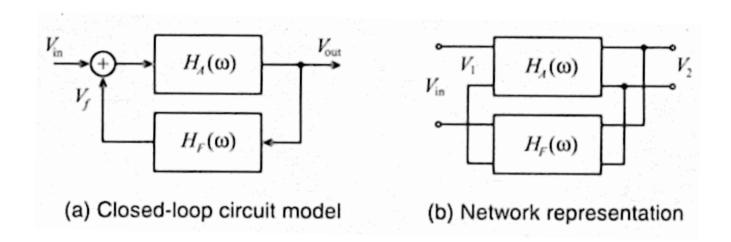
## **SOME THEORY**

#### **DEFINITION AND CLASSIFICATION**

An oscillator is a network that is able to generate an output periodic signal without using a periodic input excitation. In other words, it can be viewed as a dc-to-ac converter and can be explained in terms of feedback circuit. Oscillators can be classified as crystal, RC, LC, relaxation, ring, and distributed oscillators.



An oscillator can be viewed as a loop that causes a positive feedback.



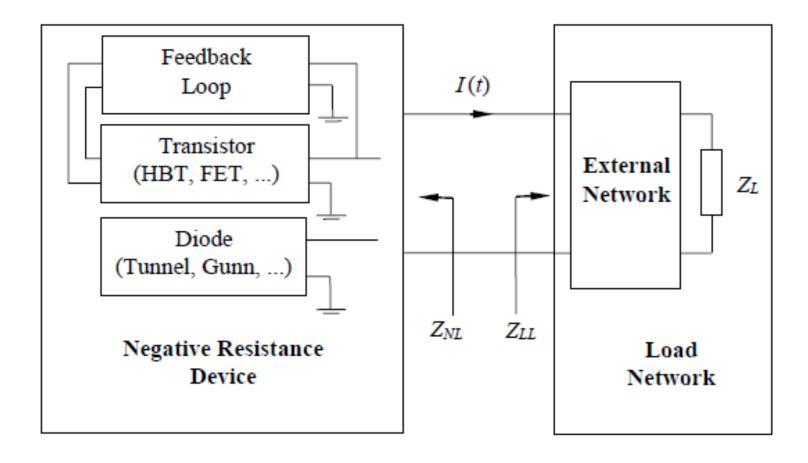
For steady oscillation, two conditions must be simultaneously met for the closed-loop gain

$$H(\omega_o) = \frac{V_{out}}{V_{in}} = \frac{H_A(\omega_o)}{1 - H_F(\omega_o)H_A(\omega_o)}$$

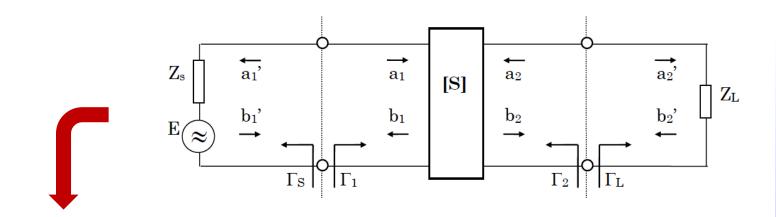
- The loop gain,  $|H(j\omega_o)|$  must be equal to unity (condition of oscillation) at the frequency  $\omega_o$ ,
- The total phase shift around the loop,  $/\_H(j\omega_o)\_$  must be equal to zero or 180° at the frequency  $\omega_o$  if the dc feedback is negative (condition of stability).

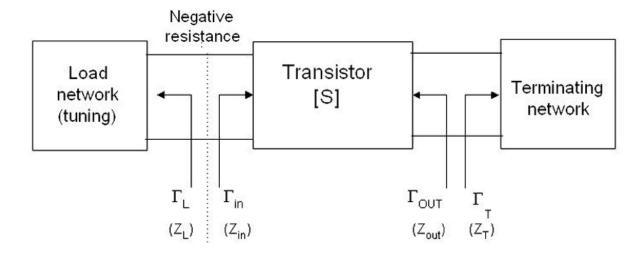
These oscillation criteria can be expressed in terms of negative resistance provided by a diode (e.g., Tunnel diode) or an unstable transistor.

$$R_{NL} = -R_{LL}$$
 and  $j(X_{NL} + X_{LL}) = 0$   $\Rightarrow$   $\Gamma_{NL} \cdot \Gamma_{LL} = 1$ 

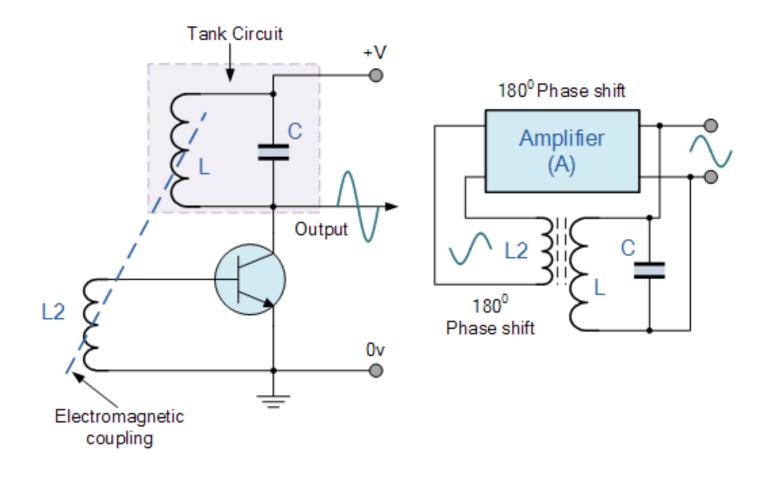


# ANALYSIS BY THE TRANSISTOR S-PARAMETERS (FROM AMPLIFIER TO OSCILLATOR)





## **WORKING PRINCIPLE OF TRANSISTOR BASED OSCILLATORS**



## ANALYSIS BY THE TRANSISTOR S-PARAMETERS (FROM AMPLIFIER TO OSCILLATOR)

The unknown incident power  $a_2$  must be minimized to assure an optimum efficiency.

Let A be the gain defined as

$$A = \frac{b_2}{a_1} \qquad \Rightarrow \qquad a_2 = \frac{A - S_{21}}{S_{22}} a_1$$

$$A_{opt} = \frac{1}{|S_{22}|^2 + |S_{12}|^2 - 1} (|S_{12}|^2 S_{21} - S_{21} - S_{22} S_{11} S_{12}^*)$$

## ANALYSIS BY THE TRANSISTOR S-PARAMETERS (FROM AMPLIFIER TO OSCILLATOR)

The following steps can summarize this process (mainly experimental):

- Choose a convenient range for  $a_1$ .
- Fix a value for  $a_1$  and measure  $S_{11}$  and  $S_{21}$ . Then, estimate  $a_2$  to obtain  $S_{12}$  and  $S_{22}$ .
- Determine  $A_{opt}$ , deduce the ratio  $a_2/a_1$ , then  $a_2$  (these two quantities are independent of the reference planes). Therefore, the output parameters  $S_{12}$  and  $S_{22}$  can be obtained as well as the optimum output power.

**(6)** 

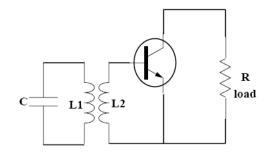
- Vary  $a_1$ . A curve of the optimum output power versus the incident power can be plotted.
- Select  $a_1$  that gives the highest output power. Note the corresponding  $a_2$ .

The main limitation is in the assumption that  $S_{11}$  and  $S_{21}$  depend only of the incident **power**  $a_1$  (and similarly for  $S_{22}$  and  $S_{12}$  versus  $a_2$ ). This could lead to significant errors for some power devices.

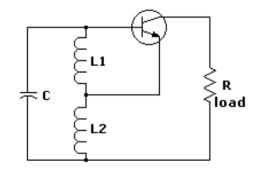
### **ANALYSIS BY Z OR Y PARAMETERS**

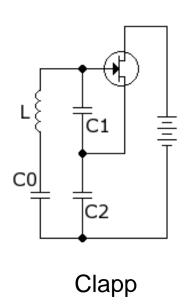
## **Main types of LC Oscillators Circuits**

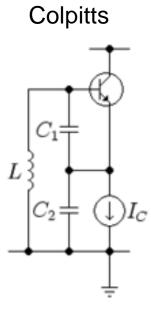
## Armstrong



Hartley







### **ANALYSIS BY Z OR Y PARAMETERS**

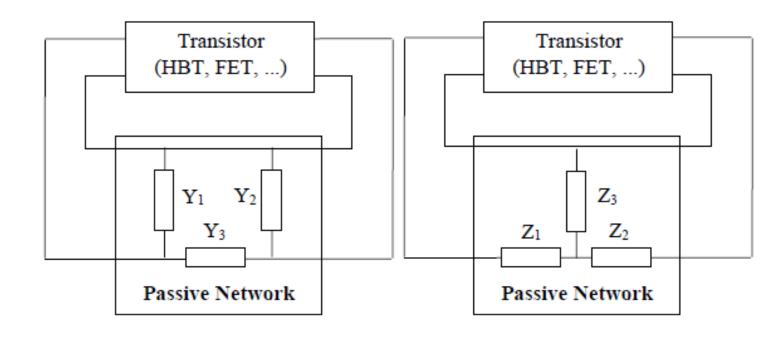
Usually, the oscillator configuration highlights unknown impedances or admittances

$$\{Z_1, Z_2, Z_3\}$$
 or  $\{Y_1, Y_2, Y_3\}$ 

with

$$Z_i = R_i + j X_i$$
 and  $Y_i = G_i + j B_i$ 

## Why considering T or $\pi$ networks?



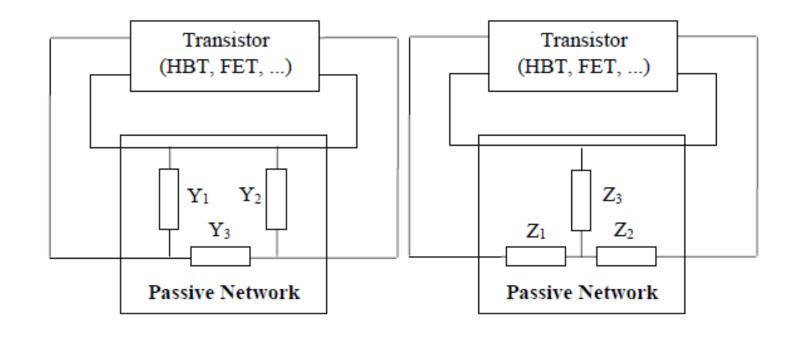
#### **ANALYSIS BY Z OR Y PARAMETERS**

We have in total 6 unknown variables:  $\{Z_1, Z_2, Z_3\}$  or  $\{Y_1, Y_2, Y_3\}$ 

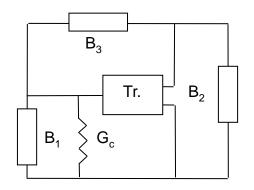
However, we have 2 ports so 2 equations.

#### Therefore:

- we set two of the impedances/admittances as purely reactive and
- the real part of the third impedance/admittance is set as the oscillator load  $R_c$  or  $G_c$ .



#### ANALYSIS BY Z OR Y PARAMETERS **π NETWORKS**

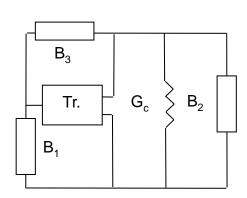


$$G_c = C_1 + A_r C_3 + A_i C_4$$

$$B_1 = C_2 + (1 - A_r)(C_4 + C_3 A_r / A_i)$$

$$B_2 = C_3(A_r - 1)/A_i + C_4$$

$$B_3 = -C_3 A_r / A_i - C_4$$



$$G_c = (C_1 + A_r C_3 + A_i C_4)/|A|^2$$

$$B_1 = C_1(A_r - 1)/A_i + C_2$$

$$B_2 = (C_1(A_r - |A|^2)/A_i + A_rC_4 - A_iC_3)/|A|^2$$

$$B_3 = C_1/A_i$$

$$C_1 = -\operatorname{Re} \ (Y_{11} + AY_{12})$$

**(6)** 

$$C_2 = -\operatorname{Im} (Y_{11} + AY_{12})$$

$$G_c = (C_1 + A_r C_3 + A_i C_4)/|A - 1|^2$$

$$C_3 = -\text{Re} \ (Y_{21} + AY_{22})$$

$$B_1 = (C_1 + C_3)A_r/A_i + C_2 + C_4$$

$$C_4 = -\operatorname{Im} (Y_{21} + AY_{22})$$

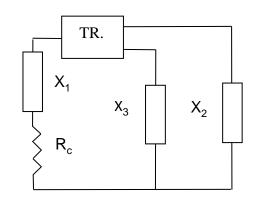
$$B_2 = -(C_1 + C_3)/A_i$$

$$B_3 = (C_1 - (1 - A_r)G_c)/A_i$$

$$A = A_r + jA_i = -(Y_{21} + Y_{12}^*)/2 \operatorname{Re}(Y_{22})$$

$$B_3$$
 $G_c$ 
 $B_1$ 
 $B_2$ 

#### ANALYSIS BY Z OR Y PARAMETERS - T NETWORKS

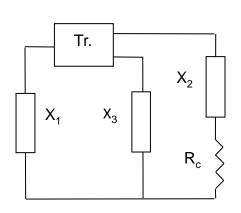


$$R_c = D_1 + F_r D_3 + F_i D_4$$

$$X_1 = D_2 - (1 + F_r)(D_4 + D_3F_r/F_i)$$

$$X_2 = -D_3(1 + F_r)/F_i - D_4$$

$$X_3 = D_3 F_r / F_i + D_4$$

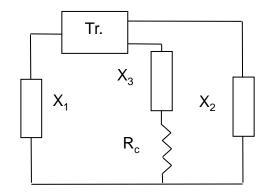


$$R_c = (D_1 + F_r D_3 + F_i D_4)/|F|^2$$

$$X_1 = D_1(1 + F_r)/F_i + D_2$$

$$X_2 = (D_1(F_r + |F|^2)/F_i + F_rD_4 - F_iD_3)/|F|^2$$

$$X_3 = -D_1/F_i$$



$$R_c = (D_1 + F_r D_3 + F_i D_4)/|1 + F|^2$$

$$X_1 = (D_1 - D_3)F_r/F_i + D_2 - D_4$$

$$X_2 = (D_1 - D_3)/F_i$$

$$X_3 = \frac{\left((1+F_r)(D_4-(D_1-D_3)F_r/F_i)-F_iD_1\right)}{|1+F|^2}$$

$$D_1 = - \operatorname{Re} \ (Z_{11} + F Z_{12})$$

$$D_2 = -\operatorname{Im} \ (Z_{11} + FZ_{12})$$

$$D_3 = -\operatorname{Re} \ (Z_{21} + FZ_{22})$$

$$D_4 = -\operatorname{Im} \ (Z_{21} + FZ_{22})$$

$$F = F_r + jF_i = (Z_{21} - AZ_{11})/(AZ_{12} - Z_{22})$$

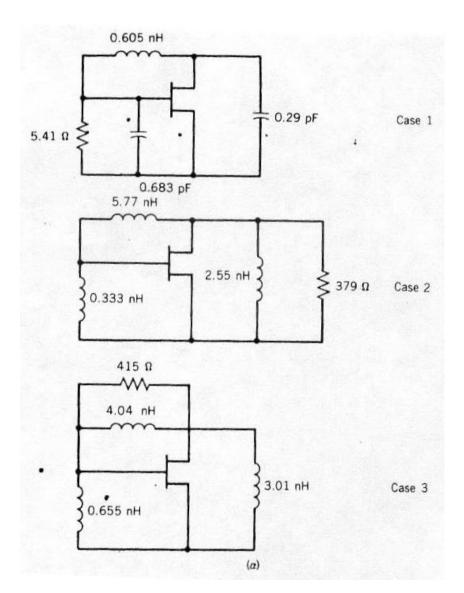
## An example of this calculation for a 500 µm DXL-3501A GaAs MESFET is given at 10 GHz

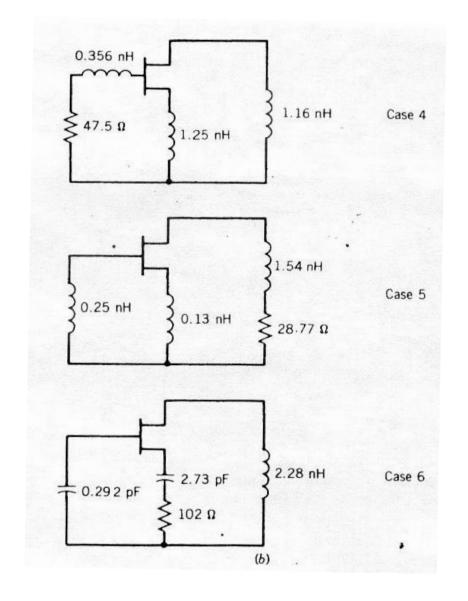
$$S_{11} = 0.66 \ \angle -143^o$$

$$S_{12} = 0.071 \angle + 117^{o}$$

$$S_{21} = 1.26 \angle + 46^{o}$$

$$S_{22} = 0.74 \ \angle - 59^o$$





## Which one is the most suitable?

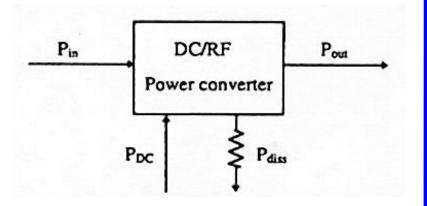
## HARMONIC OSCILLATORS

#### HARMONIC OSCILLATORS

Harmonic oscillators function both as a fundamental frequency oscillator and as a harmonic generator. These components deserve special attention due to their capability of generating RF power above the frequencies usually obtained from fundamental frequency oscillators.

One can start by considering the dynamic balance of power in a microwave amplifier (with G the gain and  $P_{ad}$  the RF power added by the amplifier):

$$P_{in} + P_{dc} = P_{out} + P_{diss}$$
 
$$P_{diss} = P_{dc} - (P_{out} - P_{in}) = P_{dc} - (G - 1)P_{in}$$
 
$$P_{ad} = P_{out} - P_{in}$$



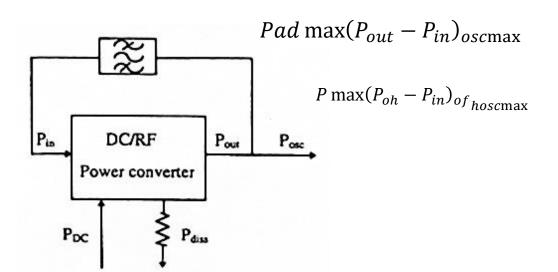
#### HARMONIC OSCILLATORS

The power balance for the oscillator is also similar to the amplifier case: Conventional oscillator theory states that the maximum available power  $P_{osc}$  from an oscillator is equal to the added power from an amplifier at the point of maximum efficiency (i.e., when the difference between  $P_{out}$  and  $P_{in}$  is maximum).

For a harmonic oscillator, the output power comprises the fundamental frequency power,  $P_{of}$ plus the harmonic power  $P_{oh}$ .

$$P_{osc} = P_{out} - P_{in} = P_{dc} - P_{diss}$$

$$P_{hosc} = (P_{of} - P_{in}) + P_{oh} = (P_{oh} - P_{in}) + P_{of}$$

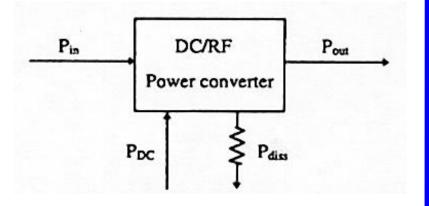


$$P_{in} + P_{dc} = P_{out} + P_{diss}$$

**(6)** 

$$P_{diss} = P_{dc} - (P_{out} - P_{in}) = P_{dc} - (G - 1)P_{in}$$

$$P_{ad} = P_{out} - P_{in}$$



#### HARMONIC OSCILLATORS - DESIGN APPROACH

The design of harmonic oscillators starts with the design of a frequency multiplier

"The harmonic amplifier"

The objectives of a frequency multiplier are a maximum output power at the desired harmonic, a matched input for maximum efficiency, and a reasonable frequency bandwidth.

For harmonic oscillation operation, the multiplier's saturation characteristics are also required:

$$P_{oh}(P_{in}, n\omega_o) - P_{in}(\omega_o) = f[P_{in}(\omega_o)]$$

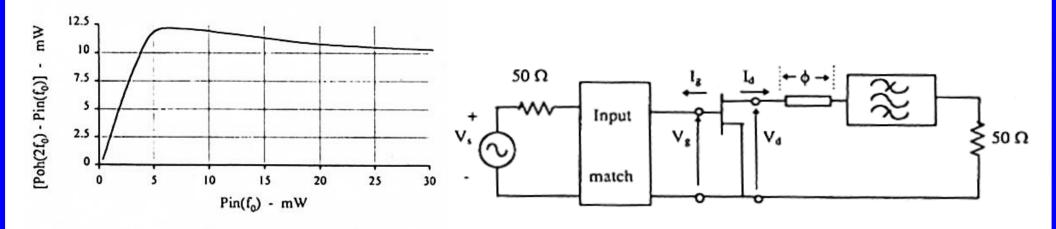
#### HARMONIC OSCILLATORS - DESIGN APPROACH

As illustration of such characteristics, let us consider a 5-10 GHz frequency doubler.

One can observe a nonlinear relation between input and output powers at low levels, and a saturation of the second harmonic output power after a certain input drive level.

The added power is maximized at the peak of the curve obtained for

- A matched input that maximize the gate voltage swing, a shorted load,
- A shorted load for the fundamental frequency maximizing the drain current,
- A matched second harmonic drain impedance.



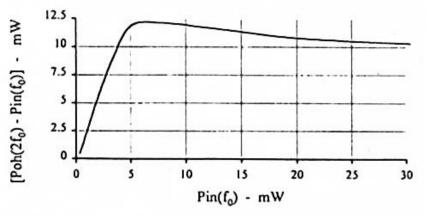
## HARMONIC OSCILLATORS - DESIGN APPROACH : 5-10 GHz frequency doubler

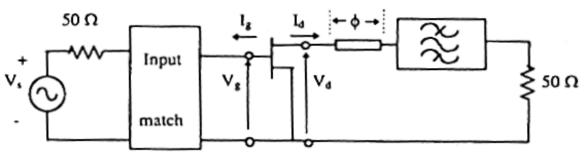
Network elements for the T topology:

Fundamental Frequency Impedances	Output Harmonic Frequency Impedances
$Z_{\mathcal{D}}(\omega_{o}) = R_{\mathcal{D}1} + jX_{\mathcal{D}1}$	$Z_{D}(n\omega_{o})=R_{Dn}+jX_{Dn}$
$Z_S(\omega_0) = jX_{S1}$	$Z_S(n\omega_o)=0$
$Z_G(\omega_0) = jX_{G1}$	$Z_G(n\omega_o) = R_{Gn} + jX_{Gn}$

Case	Z <sub>G</sub>	Zs	Z <sub>0</sub>
$Re\{Z_G\} = Re\{Z_S\} = 0$	$\frac{jRe\{V_G(I_G^* + I_D^*)\}}{Im\{I_G^*I_D\}}$	$\frac{jRe\{V_GI_{G^*}\}}{Im\{I_GI_{D^*}\}}$	$\frac{V_D}{I_D} - Z_s \left[ 1 + \frac{I_G}{I_D} \right]$
$Re\{Z_G\} = Re\{Z_O\} = 0$	$\frac{jRe\{I_{D}(V_{D}^{*}-V_{G}^{*})\}}{Im\{I_{G}I_{D}^{*}\}}$	$\frac{V_G - Z_G I_G}{I_G + I_O}$	$\frac{jRe\{I_G(V_G^*-V_D^*)\}}{Im\{I_GI_D^*\}}$
$Re\{Z_0\} = Re\{Z_S\} = 0$	$\frac{V_G}{I_G} - Z_s \left[ 1 + \frac{I_D}{I_G} \right]$	$\frac{jRe\{V_{D}I_{D}^{*}\}}{Im\{I_{G}^{*}I_{D}\}}$	$\frac{jRe\{V_{0}(I_{0}^{*}+I_{G}^{*})\}}{Im\{I_{G}I_{D}^{*}\}}$

T configuration: Network elements as a function of terminal current-voltage at the fundamental frequency.





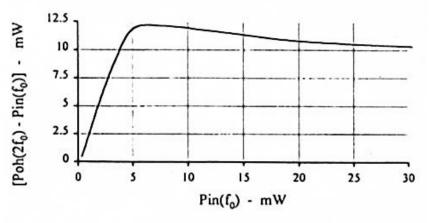
## HARMONIC OSCILLATORS - DESIGN APPROACH : 5-10 GHz frequency doubler

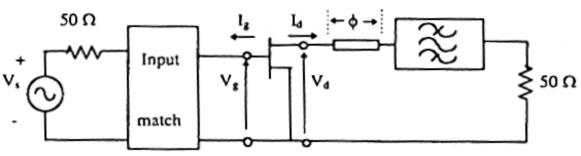
Network elements for the  $\pi$  topology:

Fundamental Frequency Admittance	Output Harmonic Frequency Admittance	
$Y_{DS}(\omega_0) = G_{DS1} + jB_{DS1}$	$Y_{DS}(n\omega_0) = G_{DSn} + jB_{DSn}$	
$Y_{GS}(\omega_0) = jB_{GS1}$	$Y_{GS}(n\omega_0) = G_{GSn} + jB_{GSn}$	
$Y_{OG}(\omega_0) = jB_{OG1}$	$Y_{OG}(n\omega_0)=0$	

Case	Y <sub>GS</sub>	Y <sub>GD</sub>	Yos
$Re\{Y_{GS}\} = Re\{Y_{GO}\} = 0$	$\frac{jRe\{I_{G}(V_{O}^{*}-V_{G}^{*})\}}{Im\{V_{O}V_{G}^{*}\}}$	$\frac{jRe\{V_G^*I_G\}}{Im\{V_G^*V_O\}}$	$\frac{I_0}{V_0} + Y_{G0} \left[ \frac{V_0}{V_0 - 1} \right]$
$Re\{Y_{GS}\} = Re\{Y_{OS}\} = 0$	$\frac{jRe\{V_{D}(I_{D}^{*}+I_{G}^{*})\}}{Im\{V_{D}V_{G}^{*}\}}$	$\frac{Y_{GS}V_G - I_G}{V_O - V_G}$	$\frac{jRe\{V_G(I_{G}^* + I_{D}^*)\}}{Im\{V_{D}^*V_G\}}$
$Re\{Y_{GS}\} = Re\{Y_{DS}\} = 0$	$\frac{I_G}{V_G} - Y_{GD} \left[ \frac{V_D}{V_G} - 1 \right]$	$\frac{jRe\{V_0^*I_0\}}{Im\{V_0^*V_G\}}$	$\frac{jRe\{I_{D}(V_{G}^{*}-V_{D}^{*})\}}{Im\{V_{D}^{*}V_{G}\}}$

π configuration: Network elements as a function of terminal current-voltage at the fundamental frequency.





Fundamental Frequency Admittance	Output Harmonic Frequency Admittance
$Y_{DS}(\omega_0) = G_{DS1} + jB_{DS1}$	$Y_{DS}(n\omega_0) = G_{DSn} + jB_{DSn}$
$Y_{GS}(\omega_0) = jB_{GS1}$	$Y_{GS}(n\omega_0) = G_{GSn} + jB_{GSn}$
$Y_{OG}(\omega_0) = jB_{OG1}$	$Y_{OG}(n\omega_0)=0$

*Note*: Although both topologies are possible, the T configuration is more adequate to harmonic oscillators, due to the difficulty of building a circuit where the feedback element  $Y_{DG}$ , is an open circuit at the output harmonic.

Fundamental Frequency Impedances	Output Harmonic Frequency Impedances
$Z_{\mathcal{O}}(\omega_o) = R_{\mathcal{O}1} + jX_{\mathcal{O}1}$ $Z_{\mathcal{S}}(\omega_o) = jX_{\mathcal{S}1}$ $Z_{\mathcal{G}}(\omega_o) = jX_{\mathcal{G}1}$	$Z_D(n\omega_o) = R_{Dn} + jX_{Dn}$
$Z_S(\omega_0) = jX_{S1}$	$Z_S(n\omega_o)=0$
$Z_G(\omega_0) = jX_{G1}$	$Z_G(n\omega_0) = R_{Gn} + jX_{Gn}$

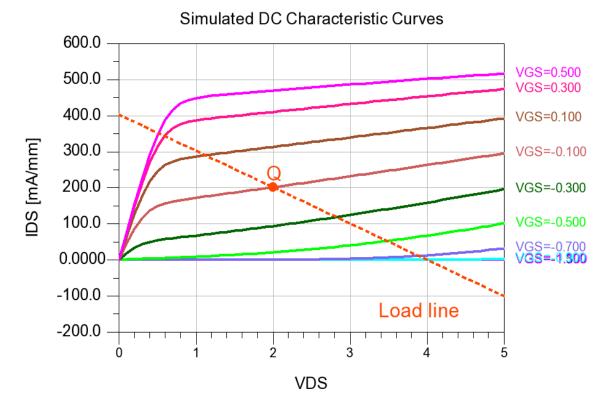
## FIRST DESIGN: SINGLE FREQUENCY OSCILLATOR

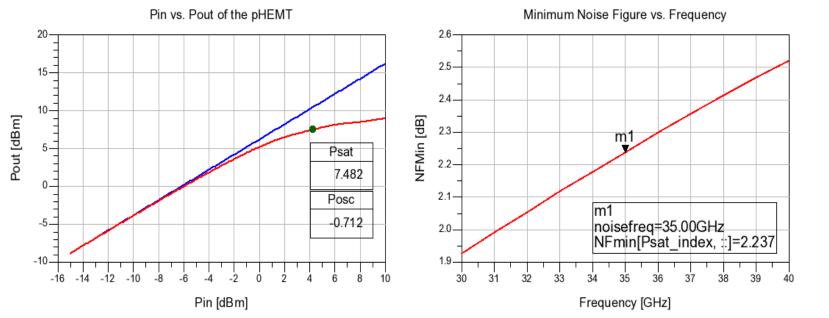
(35 GHz oscillator for radiolocation applications)

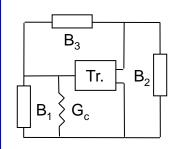
## **Design Requirements**

Parameter	Units	Specs
Frequency	GHz	35
Output Power	dBm	> 6.0
Phase Noise	dBc/Hz (@1MHz offset)	> 110
DC Power Consumption	W	< 50 mW
DC-to-RF Efficiency	%	> 10

## 0.15µm pHEMT device

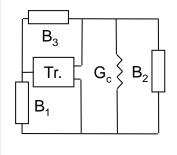




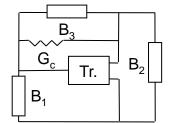


## Component values to implement a shunt oscillator

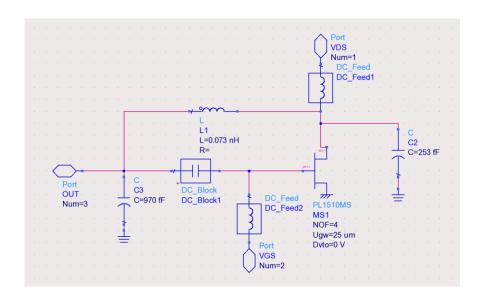
Y <sub>11</sub> [mΩ]	Y <sub>12</sub> [mΩ]	Y <sub>21</sub> [mΩ]	Y <sub>22</sub> [mΩ]
1.09 + j 28.55	0.225 – j 5.05	41.8 – j 23.2	6.67 + j 21.9



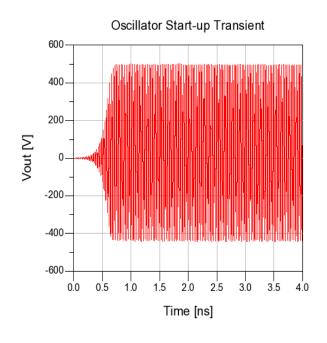
We selected the first : Why?

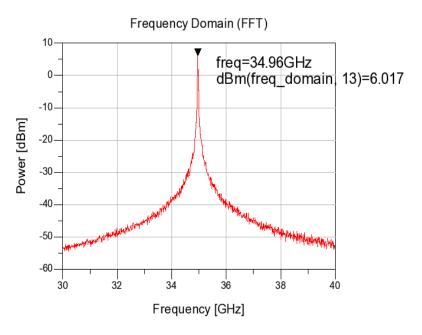


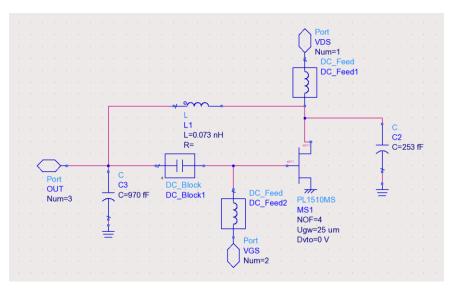
Extracted large-signal Y-parameters

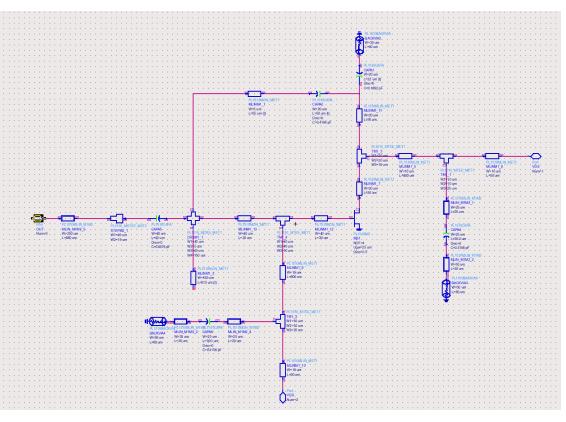


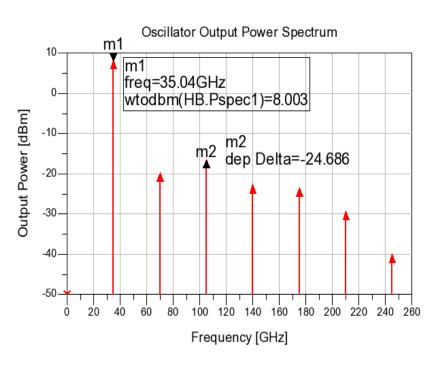
G <sub>L</sub> connected		B <sub>1</sub>		B <sub>2</sub>		B <sub>3</sub>	$G_L$
between:	C [fF]	L [μH]	C [fF]	L [μH]	C [fF]	L [pH]	
Gate & Source	971		253			73	12.9
Drain & Source		200		275		852	152
Gate & Drain	156			3480		256	246

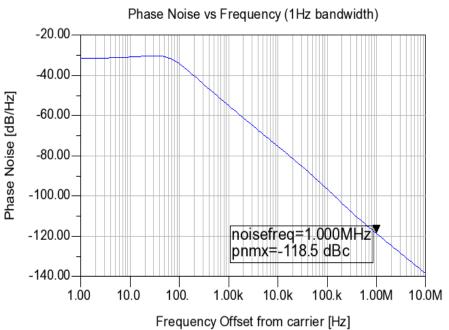












DC Power Consumption

P_DC efficiency		P_RF
0.040	0.158	0.006

Note: phase noise is in dBc/Hz = phase noise density with a BW of 1Hz

- dBc: decibels relative to carrier, a common measurement in RF engineering to specify the power of a sideband in a modulated signal relative to the carrier.
- Since noise has infinite BW, wider the application bandwidth, higher the noise. Therefore, the industry has settled on a bandwidth of 1Hz as a standard – this is considered as the normalized bandwidth

## Comparison of simulated and specified values for the designed oscillator

Parameter	Units	Specs	Simulated
Frequency	GHz	35	35.04
Output Power	dBm	> 6.0	8.0
Phase Noise	dBc/Hz (@1MHz offset)	> 110	-118
DC Power Consumption	W	< 50 mW	40mW
DC-to-RF Efficiency	%	> 10	15.8

Dr. M.C.E. Yagoub

## SECOND DESIGN: SINGLE FREQUENCY OSCILLATOR

(20 GHz OSCILLATOR FOR TEST & MEASUREMENT EQUIPMENT)

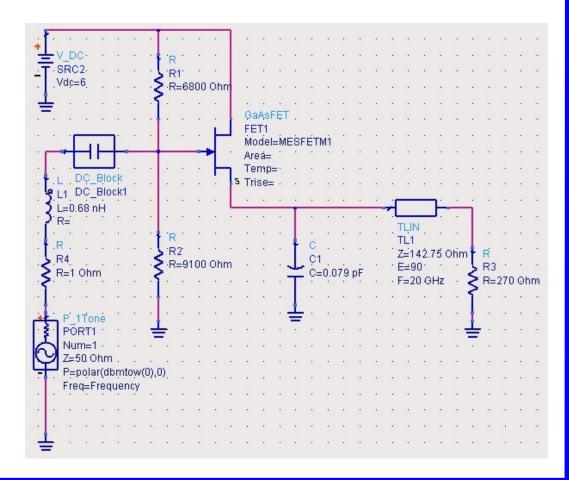
### **Design Requirements**

Output Frequency 20 GHz

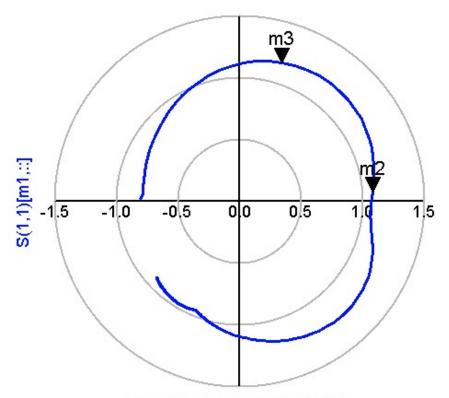
Output Power > 10 dB

Phase Noise > 150 dBc/Hz

- Selected the common drain configuration since it was more likely to be unstable than common source.
- Also simpler to design



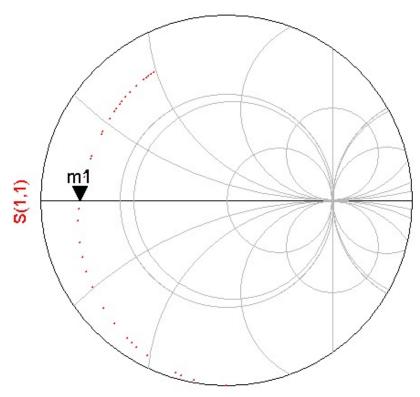
• After canceling the device capacitive impedance with an inductor and capacitor in the resonator, we should have oscillations.



freq (10.00MHz to 100.0GHz)

m2 freq=20.01GHz S(1,1)[m1,::]=1.083 / 3.933

m3 freq=11.51GHz S(1,1)[m1,::]=1.179 / 72.986

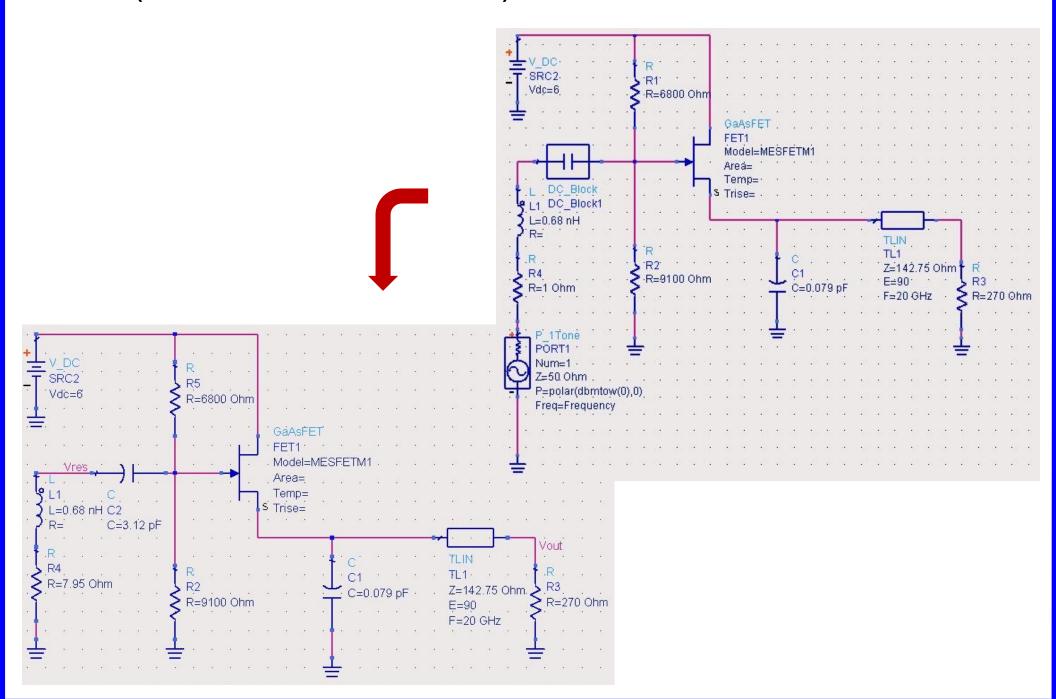


m1 indep(m1)=0 S(1,1)=1.378 / -179.959 Frequency=2.000000E10 impedance = Z0 \* (-0.159 - j3.448E-4)

Nyquist Plot

33

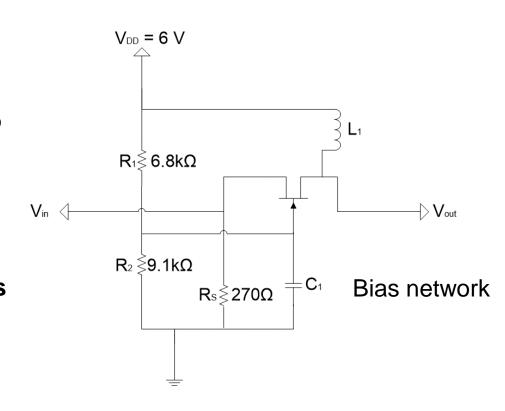
## **ANALYSIS BY THE TRANSISTOR S-PARAMETERS** (FROM AMPLIFIER TO OSCILLATOR)

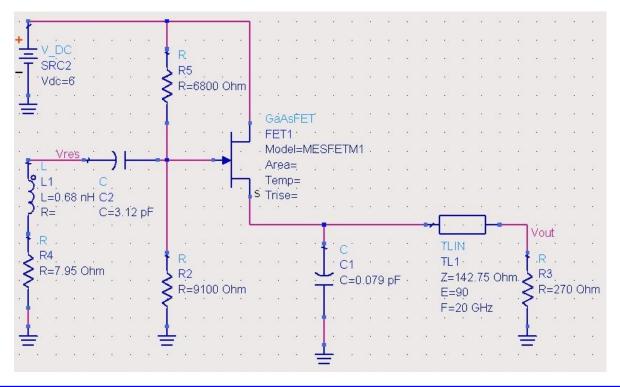


Found the maximized negative input resistance by altering values of L<sub>G</sub> and C<sub>D</sub> (1 nH, 0.05 pF)

#### **PROBLEM 1:**

The gate inductor L<sub>G</sub> effectively shorts out the DC bias at the gate!!





Attempted various solutions:

λ/4 transformer

 $\lambda/4$  transformer with single stub matching

Inductive shorted transmission line coupled with capacitor

Both solutions proved unreliable as they were prone to drive the oscillator into stability. (influenced both gain and phase)

→ Reverted to LC planar elements instead.

#### **PROBLEM 2:**

The negative resistance values are too close, thereby increasing the likely hood of stability later on !

Power Level	Normalized Impedance
-20 dBm	-1.599 – j2.240
+20 dBm	-1.601 – j2.216

## **Solution:**

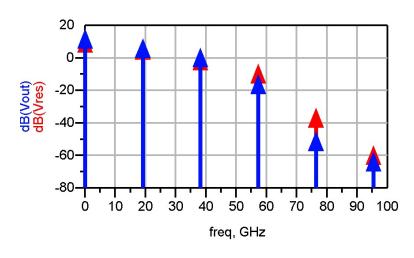
Drive the transistor into mild saturation ≈ 5 dBm

But this will increase phase noise and distort the output!

## **PROBLEM 2:**

The negative resistance values are too close, thereby increasing the likely hood of stability later on !

Power Level	Normalized Impedance
-20 dBm	-1.599 — j2.240
+20 dBm	-1.601 – j2.216



### **Solution:**

Add a filter



# THIRD DESIGN: VOLTAGE CONTROLLED OSCILLATOR (VCO)

# **Design Requirements**

Output Frequency 0.92 GHz

Output Power - 6 dB

Phase Noise - 60 dBc/10 Hz

### **Voltage controlled oscillator (VCO)**

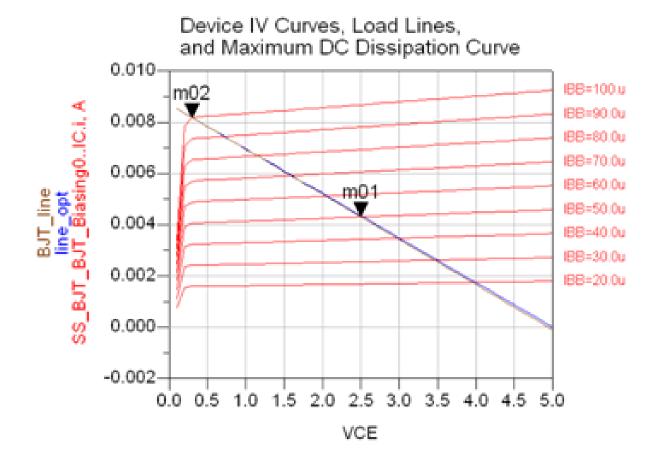
A voltage controlled oscillator or VCO is a circuit element that adjusts its oscillation frequency in response to an input DC voltage (it usually uses a varactor to tune a capacitor value which, in turn, will tune the resonant frequency).

Transistor must operate within power specifications

Low Power Dissipation

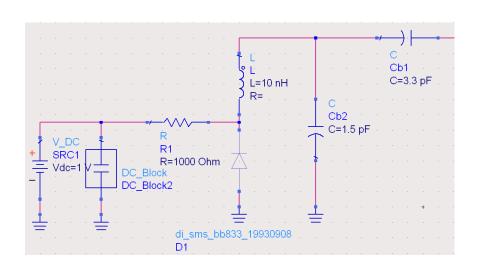
Low Power Consumption

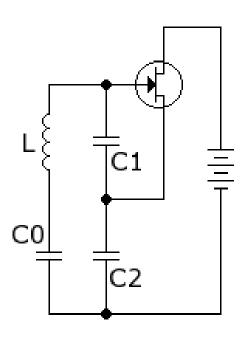
m01 VCE=2.500 SS\_BJT\_BJT\_Biasing0..IC.i=4.304m IBB=0.000050 m02 VCE=300.0m SS\_BJT\_BJT\_Biasing0..IC.i=8.177m IBB=0.000100



### Clapp circuit retained:

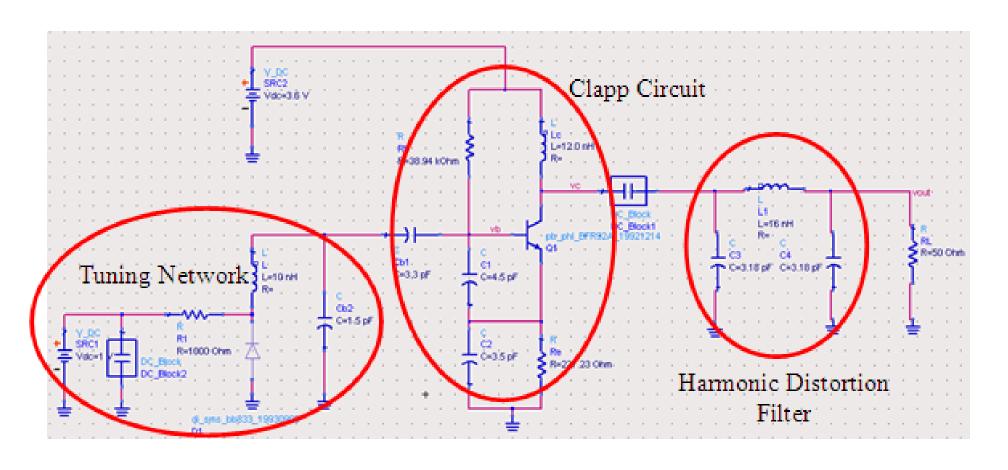
- A resonant circuit allows achieving the required frequency.
  - Here C<sub>0</sub> encompasses Cb1, Cb2, and the varactor diode capacitance
  - Cb2 is used to tune the resonant frequency and helps limit the junction capacitance of the diode.
  - The varactor diode capacitance changes as the voltage is changed. Increased voltage leads to increase in frequency.

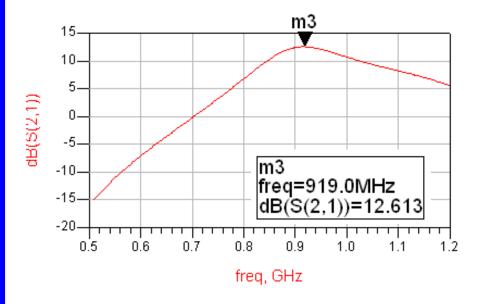




This schematic was used to find the frequency of operation and was used to show the range of frequency values for which this VCO operates. This was achieved by adjusting the voltage across the varactor diode.

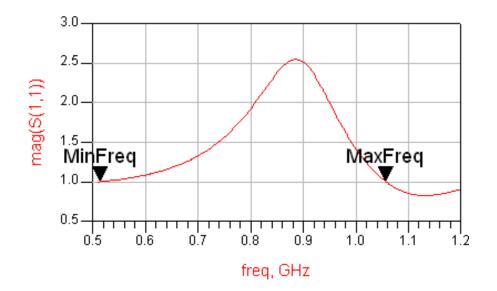
Input is taken at the beginning of the Clapp circuit, not the resonant circuit.



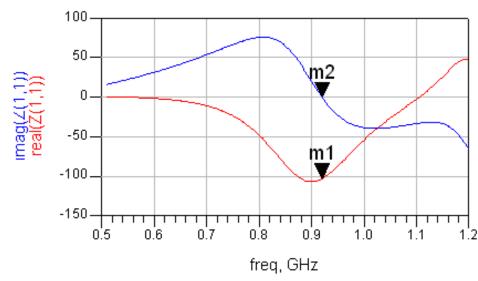


MinFreq freq=514.0MHz mag(S(1,1))=1.002

MaxFreq freq=1.056GHz mag(S(1,1))=1.005



- S<sub>21</sub> shows the resonant frequency where gain is the highest
- $S_{11}$  shows the "maximum" range of frequency the oscillator could cover (with  $S_{11} > 1$ )
- Z<sub>11</sub> shows the resonant frequency (with phase equals to 0)

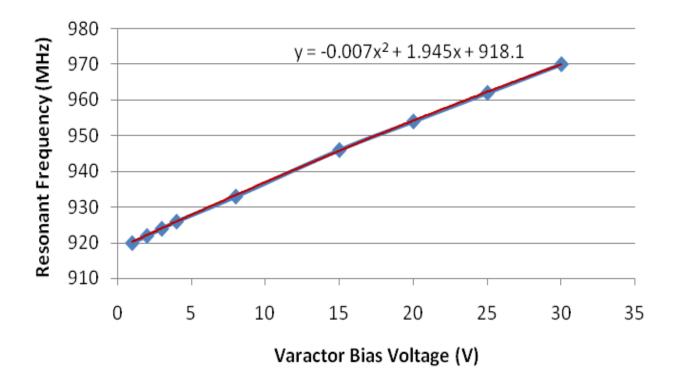


**Z-Parameter** 

m1 freq=920.0MHz real(Z(1,1))=-102.885

m2 freq=920.0MHz imag(Z(1,1))=-0.010

# Resonant frequency vs. Varactor bias voltage



$$f_o = \frac{1}{2\pi} \sqrt{\frac{1}{L} \left(\frac{1}{C_0} + \frac{1}{C_1} + \frac{1}{C_2}\right)^{-1}}$$

#### We added a harmonic filter.

### Why?

Harmonic distortion is due to the high alternating voltage in the tuning circuit due to:

- The nonlinearity of the capacitance that may produce harmonics
  - In order to reduce the effects of this, the voltage across the diode should be kept small. A resistor can be placed in series to reduce the voltage.
- The diode nonlinearities
- The varactor diode which does not follow the sine law. Thus, the resonator frequency may change when a sinusoidal voltage is applied to it.
  - Under certain conditions they may even lead to **squegging**, which can cause an oscillator to start and stop at frequencies much lower than the desired frequency

**Squegging** is a radio engineering term. It is a contraction of **self-quenching**. A squegging or *self-blocking* oscillator produces an intermittent or changing output signal.

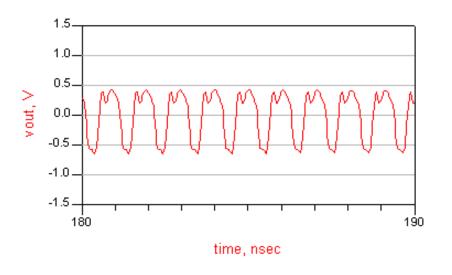
Wildlife tags for birds and little mammals use squegging oscillators.

The receiver sensitivity rises while the oscillation builds up. The oscillation stops when the operation point no longer fulfills the Barkhausen stability criterion. The blocking oscillator recovers to the initial state and the cycle starts again.

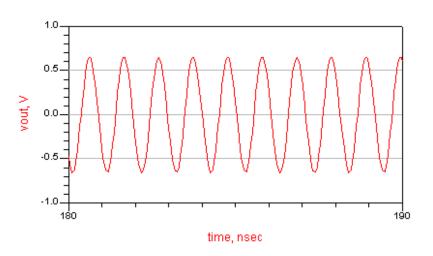
Squegging is an oscillation that builds up and dies down with a much longer time constant than the fundamental frequency of the oscillation.

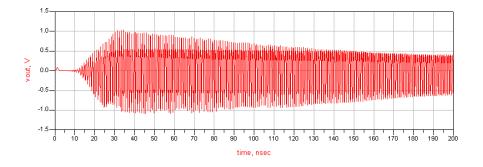
A self-quenching oscillator circuit oscillates at two or more frequencies at the same time.

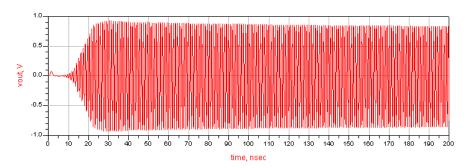
## Without Filter



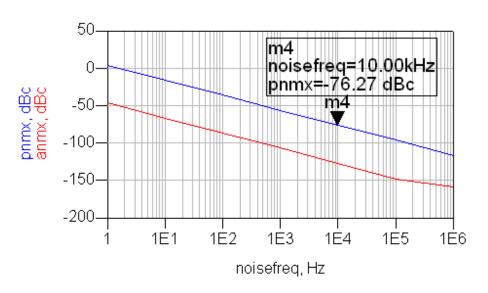
# With Filter







### **Phase Noise**

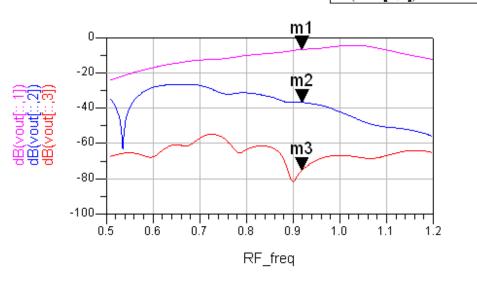


m1 RF\_freq=0.919 dB(vout[::,1])=-6.566

(6)

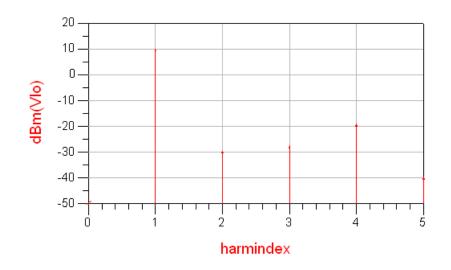
m2 RF\_freq=0.919 dB(vout[::,2])=-36.670

m3 RF\_freq=0.919 dB(vout[::,3])=-75.320

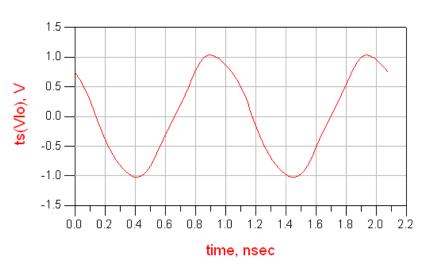


Harmonic Level

## Harmonic Spectrum



# Time Signal Output



Thank you!

**End of Chapter 6**