# Nicholas Carr



T: 604.822.9677 | F: 604.822.9676 | science.coop@ubc.ca | www.sciencecoop.ubc.ca

https://nicholascarr.ca — https://github.com/ncarr — https://linkedin.com/in/nicholas-carr +1 (416) 456-4319 — nicholas.carr@alumni.ubc.ca

### Skills

Programming Node.js, TypeScript, Vue, Python, Java, HTML, JavaScript, CSS, C, Arduino

Engineering SolidWorks, Altium, MATLAB, Jupyter

Certifications Standard First Aid, AED, CPR Level C, WHMIS, G Suite

## Work Experience

### Software Developer Co-op - <u>TickTrade Systems</u>

Jan - Apr 2021

- Built dropdown list component with autocomplete and performant support for thousands of items using Angular Material
- Created interactive documentation on components and webpages for design stakeholders and developers using Storybook
- Migrated a currency trading page from Angular.js 1.x to Angular 11, checking in with design stakeholders weekly
- Created strong type definitions for all datatypes used in the application using TypeScript

### QA Testing Co-op - Edsby

Feb - Jun 2018

- Tested preview versions of the web app, used a ticketing system to report bugs before they were sent to customers
- Participated in and edited an interview video describing the benefits of the product for parents
- Created demo posts and assignments to show potential customers what a classroom could look like if they were using the product
- Wrote a Python script to combine datasets from two CSV files, migrating data to a new format

### Full-Stack WordPress Developer - Zoom Digital

**Jul - Aug 2017** 

- Built a website for a client using HTML/CSS starting from a Bootstrap template
- Used Gulp to automate responsive image resizing and insert the responsive image set onto the site
- Wrote blog posts and product information pages for another client, uploaded it to WordPress
- Used PHP to modify a WordPress template to the client's specifications



# Nicholas Carr

## **Technical Projects**

#### The Revolver Robot - ENPH 253

May - Aug 2021

- Designed an autonomous robot to collect and drop off soda cans as part of a team of
  4 in a design course
- Created electrical schematics and designed perfboard circuit using EasyEDA
- Contributed to mechanical design using OnShape CAD software
- Contributed to PID line-following algorithm and robot controller code, written in C
- Fabricated one copy of robot design by hand at home using corrugated plastic and hand-soldered components to a set of perfboards

### Comms Sub-Team Member - UBC Orbit

Sep 2019 - Aug 2021

- Using software-defined radio to test prototype radio hardware
- Working on a Python-based serial test client for satellite-mounted radio hardware
- Writing unit tests for the test client using the Python unittest module

### Video Doorbell Project

Aug 2020

- Wrote firmware using Arduino IDE to stream video from an off the shelf ESP32 camera module
- Implemented MJPEG video streaming and MQTT telemetry and control
- Integrated camera into Home Assistant home automation platform

#### Co-founder - Cursor

Sep 2017 - Jun 2019

- Managed 9 volunteers and hosted 2 technology-related events
- Co-lead a 3-hour React Native workshop for 20 attendees aged 12-16

Jul 2018

Organized a 12-hour hackathon for 18 participants

Feb 2019

### Thinq - THacks 2

Oct 2017

- Used Node.js and Twilio to create a service that would return weather, directions, and other info if requested via text message, so people without mobile data could still get information
- Integrated features in a fast-paced environment; built service within 36-hour time limit
- Won first place at THacks 2

### Education

Third-year Engineering Physics student at the University of British Columbia

2019-2024