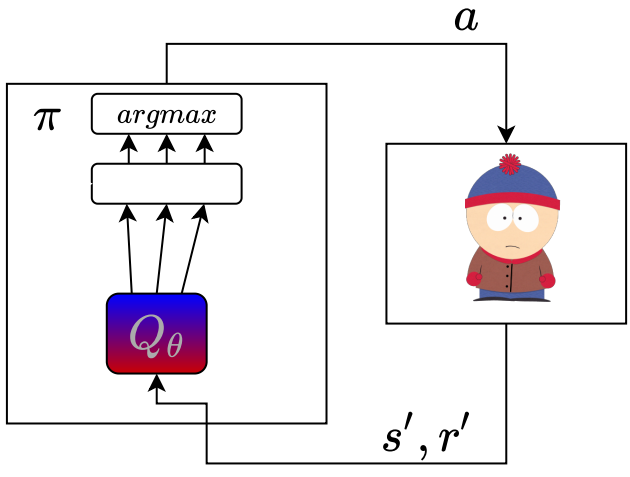
Q_θ $\{(s_i, a_i, r'_i, s'_i)\}_{i\in[0,N]}$



$\{(s_i, a_i, r'_i, s'_i)\}_{i\in[0,L]}$

Q_θ

Q_{θ^-}

AE AE^0 AE^1 AE^2

Q^0 $\{(s_i, a_i, r'_i, s'_i)\}_{i\in[0,N]}$

Q^1 $\{(s_i, a_i, r'_i, s'_i)\}_{i\in[0,N]}$

Q Q^0 Q^1 Q^2

Q^2 $\{(s_i, a_i, r'_i, s'_i)\}_{i\in[0,N]}$