

Transfer Learning

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graph TD; TL[Transfer Learning] --> Sources; TL --> Target;
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Sources

Source Task 0
 $\langle S_0^s, A_0^s, P_0^s, R_0^s \rangle$

\vdots

Source Task n
 $\langle S_n^s, A_n^s, P_n^s, R_n^s \rangle$

Target

Target Task 0
 $\langle S_0^t, A_0^t, P_0^t, R_0^t \rangle$

\vdots

Target Task m
 $\langle S_m^t, A_m^t, P_m^t, R_m^t \rangle$