

Also can import CAD

- Can import exact governy with exact mass of inertial properties.

- Harder to parameterize

CAn -> Sinescepe

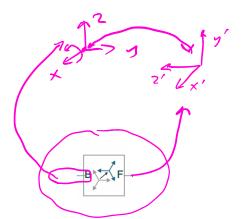
In suscept

1) Parametric control over year.

Allows for "brute force" or optimation exploration exploration of parameters

2) Take advetue of Simulink and control algorithms

CAD -> Sinson



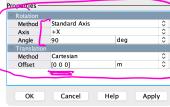
Rigid Transform : Rigid Transform

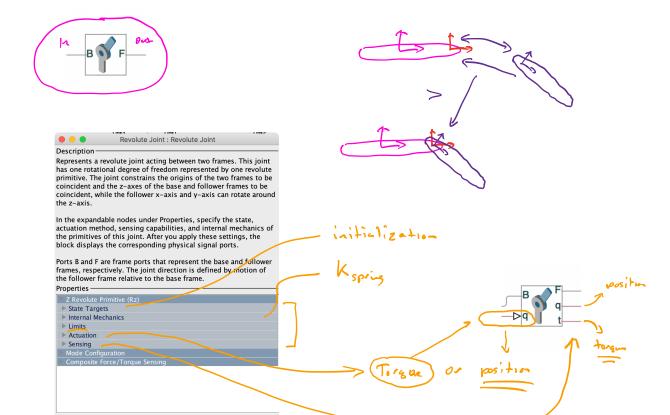
Description

Defines a fixed 3-D rigid transformation between two frames. Two components independently specify the translational and rotational parts of the transformation. Different translations and rotations can be freely combined.

In the expandable nodes under Properties, choose the type and parameters of the two transformation components.

Ports B and F are frame ports that represent the base and follower frames, respectively. The transformation represents the follower frame origin and axis orientation in the base frame.





ОК

Cancel Help Apply