



南方科技大学

SOUTHERN UNIVERSITY OF SCIENCE AND TECHNOLOGY

Machine Learning and NeuroEngineering

机器学习与神经工程

Lecture 9 – Bayesian Parameter Estimation

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Lecture 9 – Bayesian Parameter Estimation

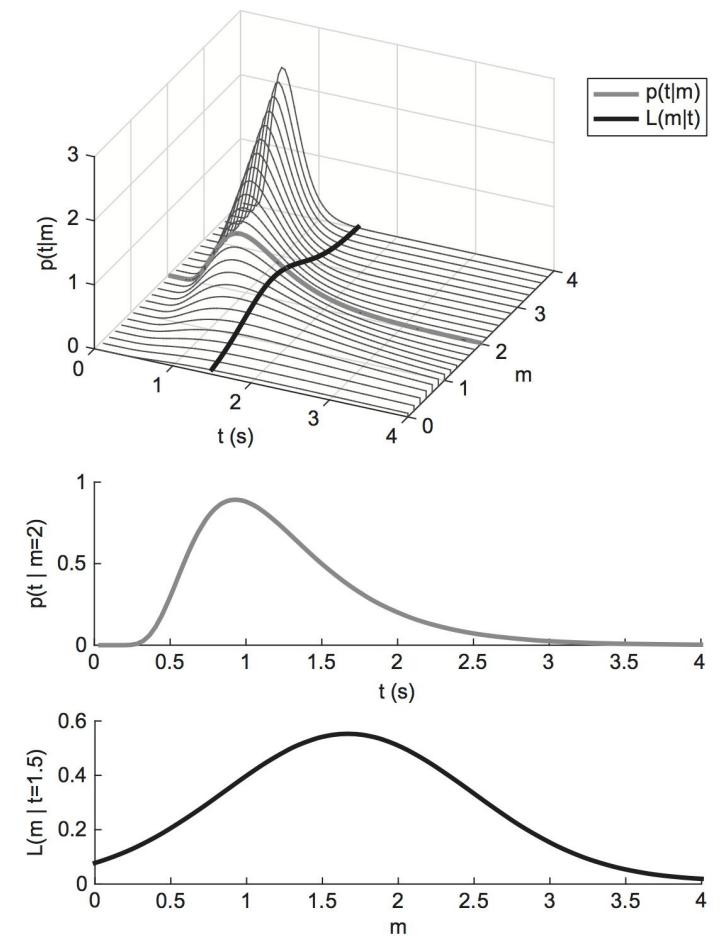
- What is Bayesian Inference?
 - Motivations
 - Bayes Theorem: prior, likelihood, evidence, posterior
- Analytic Methods for Obtaining Posteriors
 - The likelihood function
 - The Prior Distribution
 - The Posterior Distribution
 - An example: Estimating the bias of a coin
- Determining the Prior Distributions of Parameters
 - Non-Informative Priors
 - Reference Priors
- LSE vs MLE vs MAP
- Tutorial of MNE-python for EEG analysis (thanks to 林沛阳)

Motivations

- We have learned Maximum Likelihood Estimation (**MLE**) in Lecture 5.
- Recall **MLE**: Probability distribution $f(y|\theta, M)$
- It permits to estimate parameter value by **relative** comparisons between different parameter values. But it is not suited for estimating **absolute** probabilities.
- It did **not** combine our prior knowledge of the parameters.

Motivations for Bayesian Parameter Estimation:

- We want to know is the likely range of the “true” parameter value that we can infer from our measurements (information about the probability distribution of the parameters)
- We want to incorporate our prior knowledge of the parameters into the consideration.



Bayes Theorem

Prior – what we know about θ
BEFORE collecting data y

Likelihood – propensity for observing a certain value of y given a certain value of θ

$$p(\theta|y) = \frac{p(\theta)p(y|\theta)}{p(y)} = \frac{p(\theta)p(y|\theta)}{\sum_{\theta} p(\theta)p(y|\theta)}$$

Posterior – what we know about y **AFTER** seeing x

Evidence – a **constant** to ensure that the left hand side is a valid distribution

$$p(\theta|y) \propto p(\theta)p(y|\theta)$$

4 components

$$p(\theta|y) = \frac{p(\theta)p(y|\theta)}{p(y)} = \frac{p(\theta)p(y|\theta)}{\sum_{\theta} p(\theta)p(y|\theta)}$$

Prior $p(\theta)$

Our knowledge of our model's parameters **before** we collect data in an experiment.

θ is the probability of *head* for a coin

an example of discrete prior θ is $p(\theta = 0.5) = 0.8, p(\theta = 1) = 0.2$

an example of continuous prior θ is $\text{Unif}(0,1)$

Likelihood $p(y|\theta)$ or $L(\theta|y)$

Having collected data y in an experiment, we can now examine the probability of having obtained **a particular outcome** in light of the prior values of the parameters, θ .

An example: $\text{Bin}(y=5 | n=10, \theta)$

Evidence $p(y)$

The overall probability of the data, irrespective of the values of parameters.

$$\sum_{\theta} p(\theta)p(y|\theta) = p(\theta = 0.5)\text{Bin}(y=5 | n=10, \theta = 0.5) + p(\theta = 1)\text{Bin}(y=5 | n=10, \theta = 1)$$

Posterior $p(\theta|y)$

The posterior probability of θ , is a result of the application of Bayes theorem.

It can answer all sorts of interesting questions: the mode/mean of θ

The likelihood function

- Bernoulli $f(x = k|\theta) = \theta^k(1 - \theta)^{1-k}$
- Categorical $f(x = e_k|\boldsymbol{\theta}) = \theta_k$
- Binomial $f(x = k|n, \theta) = \binom{n}{k} \theta^k(1 - \theta)^{n-k}$
- Poisson $f(x = k|\theta) = e^{-\theta} \frac{\theta^k}{k!}$
- Gaussian $f(x|\mu, \sigma^2) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(x-\mu)^2}{2\sigma^2}}, \quad \boldsymbol{\theta} = [\mu, \sigma^2]$

The prior distribution

- The assumption of parameters θ is captured by prior distribution. The parameters of the prior are called **hyper-parameters**.
- In Bayesian probability theory, if the **posterior** distributions $p(\theta | x)$ are in **the same probability distribution family** as the **prior** probability distribution $p(\theta)$, the prior and posterior are then called *conjugate distributions*, and the prior is called *a conjugate prior* for the likelihood function $p(x | \theta)$.
- Bernoulli and binomial likelihood has Beta conjugate prior

$$\text{Beta}(\theta|a, b) \propto \theta^{a-1}(1-\theta)^{b-1}$$

$$\text{mode} = \frac{a-1}{a+b-2} \quad \text{mean} = \frac{a}{a+b} \quad \text{var} = \frac{ab}{(a+b)^2(a+b+1)}$$

```
1 curve(dbeta(x, 2, 4), ylim=c(0,6), ylab="Probability ←  
      Density", las=1)  
2 curve(dbeta(x, 8, 16), add=TRUE, lty="dashed")  
3 legend("topright", c("Johnnie", "Jane"),  
       inset=.05, lty=c("solid", "dashed"))
```

The Posterior distribution

- The posterior distribution is proportional to prior times likelihood

$$p(\theta|y) \propto p(\theta)p(y|\theta)$$

- Beta prior

$$\text{Beta}(\theta|a, b) \propto \theta^{a-1}(1-\theta)^{b-1}$$

- Binomial likelihood $\text{Bin}(y = k|n, \theta) = \binom{n}{k} \theta^k (1-\theta)^{n-k}$

- Posterior distribution

$$\begin{aligned} p(\theta|y) &\propto p(\theta)p(y|\theta) = \text{Beta}(\theta|a, b)\text{Bin}(y = k|n, \theta) \\ &\propto \theta^{a-1}(1-\theta)^{b-1} \theta^k (1-\theta)^{n-k} \\ &\propto \theta^{a+k-1}(1-\theta)^{b+n-k-1} \\ &= \text{Beta}(\theta|a+k, b+n-k) \end{aligned}$$

Example: Estimating the bias of a coin

- Beta prior $\text{Beta}(\theta|a, b) \propto \theta^{a-1}(1-\theta)^{b-1}$
- Binomial likelihood $\text{Bin}(y=k|n, \theta) = \binom{n}{k} \theta^k (1-\theta)^{n-k}$
- Posterior distribution $p(\theta|y=k) = \text{Beta}(\theta|a+k, b+n-k)$

- We do an experiment, and toss a coin **10** times

- We observe **6** heads, **4** tails.

- (θ is probability of head) What is the MLE of θ ?

$$\underset{\theta}{\operatorname{argmax}} \text{Bin}(y=6|10, \theta)$$

- What is the posterior distribution of θ ?

- 1) Assuming the prior distribution of θ as $\text{Beta}(\theta|1,1)$
- 2) Assuming the prior distribution of θ as $\text{Beta}(\theta|12,12)$

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$$\underset{\theta}{\operatorname{argmax}} \text{Bin}(y=6|10, \theta)$$
- What is the posterior distribution of θ ?
 - 1) Assuming the prior distribution of θ as $\text{Beta}(\theta|1,1)$, the posterior is $\text{Beta}(\theta|7,5)$
 - 2) Assuming the prior distribution of θ as $\text{Beta}(\theta|12,12)$, the posterior is $\text{Beta}(\theta|19,16)$

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 - 2) Assuming the prior distribution of θ as $\text{Beta}(\theta|12,12)$, the posterior is $\text{Beta}(\theta|19,16)$
 - 3) Assuming the prior distribution of θ as $\text{Beta}(\theta|1,4)$
 - 4) Assuming the prior distribution of θ as $\text{Beta}(\theta|4,1)$
 - 5) Assuming the prior distribution of θ as $\text{Beta}(\theta|100,100)$

Plotting the posterior

- Assuming the prior distribution of θ as $\text{Beta}(\theta|12,12)$
- We do experiments.
- We observe:
 - 1) 14 heads out of 26 tosses
 - 2) 113 heads out of 213 tosses
 - 3) 1130 heads our of 2130 tosses
- What is the posterior distribution of θ for each experiment?
- SEE CODE: Lecture9_plotBeta.r
- How Biased Is the Coin?
- **qbeta(c(0.025,0.975),1130,1000)** returns the upper and lower bounds of a 95% *credible* interval for θ

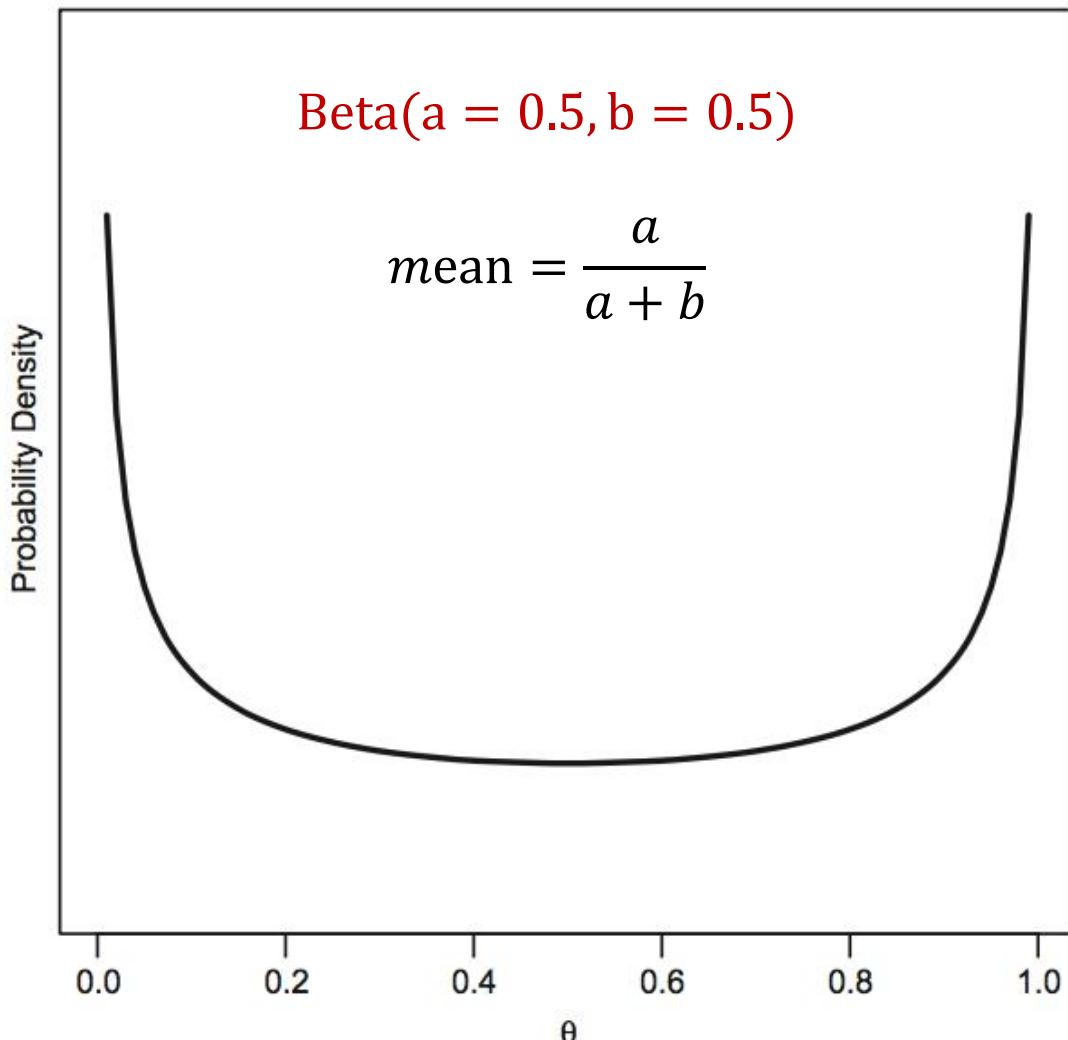
Determining the Prior Distribution

- The combining of prior knowledge with new evidence to revise one's knowledge is at the heart of Bayesian reasoning, statistics, and modeling.
- How to determine the prior distribution of parameters?

1) Non-Informative Priors (to be completely ignorant)

- If we mean “all values of θ are equally likely”, then a **uniform prior over θ**
- if we mean that “all orders of magnitude of θ are equally likely”, then a logarithmic prior – that is, a distribution that is **uniform over $\log(\theta)$** instead of over θ
- If we mean the prior distribution is not invariant across different parameterizations of the same problem or model, then **Beta($a = 0.5, b = 0.5$)**

Jeffreys Prior (a non-informative prior)



See derivation in Zhu and Lu, 2004

This is a bit counter-intuitive.
It seems a strong prior expectation of
the outcome being at 0 or 1.

Let's do some comparisons.

Jeffreys prior: beta(0.5, 0.5)

Uniform prior: beta(1,1)

(1) **k=0, n=10, MLE=0**

Beta(0.5, 10.5), mean=0.045

Beta(1, 11), mean=0.083

(2) **k=10, n=10, MLE=1.0**

Beta(10.5, 0.5), mean=0.95

Beta(2, 10), mean=0.92

Determining the Prior Distribution

1) Jeffreys Prior (to be completely ignorant)

- If we mean the prior distribution is not invariant across different parameterizations of the same problem or model, then **Beta($a = 0.5, b = 0.5$)**

2) Reference Priors

- An noninformative prior maximizes the dominance of the data over our prior knowledge
- Reference priors formalize this idea by seeking to maximize some measure of divergence between the posterior and the prior distribution in light of the data.
- The **greater** this divergence, the **less** the prior distribution has mattered.
- Difficulty: it is defined with respect to the data.

LSE vs MLE vs MAP

- Least Square Estimation (LSE): $\operatorname{argmin} \mathcal{L}(\boldsymbol{\theta})$
- Maximum Likelihood Estimation (MLE): $\operatorname{argmax} P(X|\boldsymbol{\theta})$
- Maximum A Posterior (MAP): $\operatorname{argmax} P(\boldsymbol{\theta}|X)$

Take **linear regression** as an example...

$$\mathbf{y} = \mathbf{w}^T \mathbf{x} + \varepsilon$$

LSE = MLE (when noise is Gaussian)

LSE + L2-norm regularization = MAP (when noise is Gaussian and prior is Gaussian)

Reading materials

Textbooks

- Chapter 6 (Bayesian Parameter Estimation)

Extra reading

- MLaPP– chapter 3 (Generative models for discrete data)

Video

1. 机器学习 - 白板推导 P2: 频率学派vs贝叶斯学派
2. 机器学习 - 白板推导 P9-P12: regression and ridge regression

<https://www.bilibili.com/video/BV1aE411o7qd?p=2>

Summary – Bayesian Parameter Estimation

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Homework 2

EEG data processing with MNE-python

DDL: March 29, 2021

Tips:

- Watch the tutorial video
<https://www.bilibili.com/video/BV1YK411T7H8>
- Read the official website of MNE-python
<https://mne.tools/stable/index.html>

Requirements

1. Read the paper <https://www.nature.com/articles/s41597-020-0535-2>
2. Download the raw EEG data from [26] in the paper (<https://doi.org/10.7910/DVN/RBN3XG>)
学生ID为奇数的同学下载sub-001； 学生ID为偶数的同学下载sub-002
3. Plot the **time course** of raw EEG signals with 10-second window (as Figure 4 in the paper).
4. Data preprocessing, artifacts removal
5. Plot the **time course** of preprocessed EEG signals
6. Plot the **time-frequency maps** of the subject (as Figure 6 in the paper)
7. Plot the **topographical distribution** of power of the subject (as Figure 7 in the paper)
8. **Comparison** of power (in dB) changes with time (in s) during hand, elbow motor imagery, and resting state for electrode **C3**, and electrode **C4** (as Figure 8 in the paper)