

Complexity Theory II

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Outline

- 1 Example decision problems
- 2 $P = NP???$
 - NP-Completeness
 - Polynomial time reducibility
 - Proving a problem NP-complete

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1 Example decision problems

2 $P = NP???$

- NP-Completeness
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Some languages in NP

- ❶ $\text{CLIQUE} = \{ \langle G, k \rangle \mid G \text{ is a undirected graph that has a } k\text{-clique} \}$.

$\text{CLIQUE} \in \text{NP}$

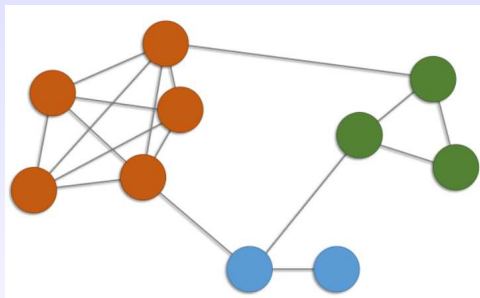
- ❷ $\text{SUBSET-SUM} = \{ \langle S, t \rangle \mid S = \{x_1, \dots, x_k\} \text{ and for some } \{y_1, \dots, y_n\} \subseteq \{x_1, \dots, x_k\}, \text{ we have } \sum y_i = t \}$.

$\text{SUBSET-SUM} \in \text{NP}$

Question: What about $\overline{\text{CLIQUE}}$ and $\overline{\text{SUBSET-SUM}}$??

Clique Example

Suppose G is as follows: [Source: <http://compbio.ucsd.edu/communities-and-cliques/>]



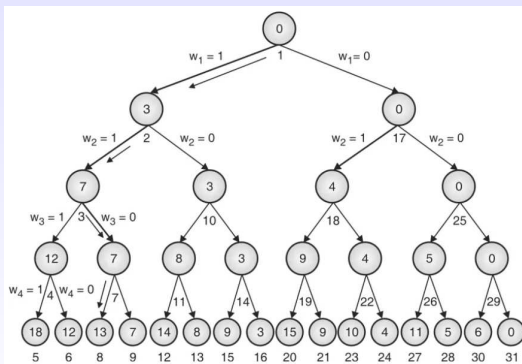
- 1 Is $\langle G, 1 \rangle \in \text{CLIQUE?}$
- 2 Is $\langle G, 2 \rangle \in \text{CLIQUE?}$
- 3 Is $\langle G, 3 \rangle \in \text{CLIQUE?}$
- 4 Is $\langle G, 4 \rangle \in \text{CLIQUE?}$
- 5 Is $\langle G, 5 \rangle \in \text{CLIQUE?}$
- 6 Is $\langle G, 6 \rangle \in \text{CLIQUE?}$

Subset-Sum Example

Suppose $S = \{3, 4, 5, 6\}$.

- ❶ Is $\langle S, 2 \rangle \in \text{SUBSET-SUM}$?
- ❷ Is $\langle S, 3 \rangle \in \text{SUBSET-SUM}$?
- ❸ Is $\langle S, 8 \rangle \in \text{SUBSET-SUM}$?
- ❹ Is $\langle S, 9 \rangle \in \text{SUBSET-SUM}$?
- ❺ Is $\langle S, 12 \rangle \in \text{SUBSET-SUM}$?
- ❻ Is $\langle S, 20 \rangle \in \text{SUBSET-SUM}$?

Suppose $S = \{3, 4, 5, 6\}$.



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More decision problems

We have seen

PATH, RELPRIME, HAMPATH, COMPOSITES, CLIQUE, SUBSET-SUM

There are many more decision problems.

Example

EMPTYREG = $\{E \mid E \text{ is a regular expression and } L(E) = \emptyset\}$

NEREG = $\{E \mid E \text{ is a regular expression and } L(E) \neq \Sigma^*\}$

IS = $\{\langle G, k \rangle \mid G \text{ has an independent set of size } k\}$

VC = $\{\langle G, k \rangle \mid G \text{ has a vertex cover of size } k\}$

HC = $\{\langle G \rangle \mid G \text{ has a hamiltonian cycle}\}$

TSP = $\{\langle G, C, b \rangle \mid G \text{ is a graph, } C \text{ is a cost metrix, } b \text{ is a non-negative integer such that } G \text{ has a hamiltonian cycle of cost at most } b\}$

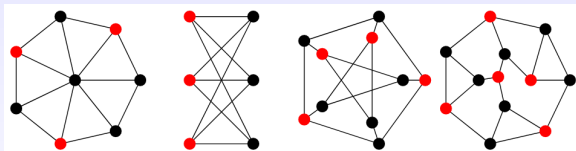
SAT = $\{\langle \phi \rangle \mid \phi \text{ is a satisfiable boolean formula}\}$

Independent Set Examples and Vertex Cover Examples

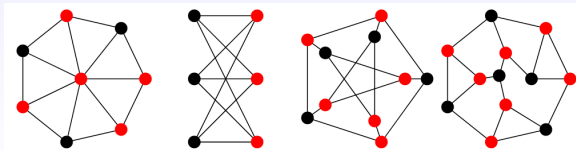
Definitions: Let G be an undirected graph.

- An **independent set** Cof G is a subset of the nodes where no two nodes in C are connected by an edge.
- A **vertex cover** Cof G is a subset of the nodes where every edge of G touches one of the nodes in C .

IS:



VC:



[Source: <https://mathworld.wolfram.com/IndependentSet.html>]

[Source: <https://mathworld.wolfram.com/VertexCover.html>]

Boolean logic

- A **formula** is an expression made up of boolean variables (e.g. x_1, x_2, y, z) connected via boolean operators (e.g. \vee, \wedge, \neg).

Example (Formula)

$$\phi = x_1 \vee x_2 \vee (\neg x_3 \wedge x_1)$$

- A **truth assignment** is a function specifying the truth values for the variables in a formula.

Example (Truth assignment)

$$T = \{(x_1, 1), (x_2, 0), (x_3, 1)\}$$

- A truth assignment T **satisfies** a formula ϕ iff T makes ϕ true. We write this as $T \models \phi$.

SAT

$$\text{SAT} = \{ \langle \phi \rangle \mid \phi \text{ is a satisfiable boolean formula} \}$$

The SAT problem is this:

Input: A boolean formula ϕ

Output: Yes if ϕ is satisfiable. No, otherwise.

Boolean logic (cont.)

- A **literal** is either a boolean variable x or its negation $\neg x$.
- A **clause** is a boolean formula of the form $l_1 \vee \dots \vee l_k$ where $k \in \mathbb{Z}^+$ and l_i is a literal.
- A formula is in **conjunctive normal form (CNF)** if it is of the form $c_1 \wedge \dots \wedge c_k$ where $k \in \mathbb{Z}^+$ and c_i is a clause.
- A formula is in **3CNF** if it is in conjunctive normal form and if each clause has exactly 3 pairwise unrelated literals.
- Two literals are **related** if they are identical or one is the complement of the other.

Example

- $(x_1 \vee x_2 \vee \neg x_3) \wedge (x_2 \vee x_3) \wedge x_4$ is in CNF
- $(x_1 \vee x_2 \vee \neg x_3) \wedge (x_2 \vee x_3 \vee \neg x_1) \wedge (x_4 \vee \neg x_1 \vee x_2)$ is in 3CNF

Problems related to boolean logic

Example

$$\text{EVAL} = \{ \langle \phi, T \rangle \mid T \models \phi \}$$

$$\text{3CNF} = \{ \langle \phi \rangle \mid \phi \text{ is in 3-conjunctive normal form} \}$$

$$\text{3SAT} = \{ \langle \phi \rangle \mid \phi \text{ is a satisfiable formula in 3CNF} \}$$

$$\text{2SAT} = \{ \langle \phi \rangle \mid \phi \text{ is a satisfiable formula in 2CNF} \}$$

Which ones are in P?

Which ones seem harder? Are they easy to verify?

There are many problems that appear to be “difficult” to solve, i.e. it seems to be hard to find solutions that take polynomial time to solve them.

Moreover, some of these hard problems have related counterparts that are easy to solve.

Easy (solvable in polynomial time)	Hard
shortest path between 2 nodes in a graph	longest path between 2 nodes in a graph
traversing a graph using each edge exactly once	traversing a graph using each vertex exactly once
figuring out if a 2-CNF formula is satisfiable	figuring out if a 3-CNF formula is satisfiable

But some of the hard problems can be easily verified, i.e. verifiable in polynomial time.

Example

- 1 HAMPATH
- 2 COMPOSITES

In contrast, some hard problems do not seem to be easily verifiable, e.g. HAMPATH. What would be a certificate???

Summary

- P = class of languages where membership can be decided quickly
- NP = class of languages where membership can be decided quickly by a nondeterministic Turing machine
- NP = class of languages where membership can be verified quickly

Some problems, e.g. HAMPATH and CLIQUE, are in NP but are not known to be in P .

The big open question:

$$P = NP???$$

[e.g. can problems like HAMPATH and CLIQUE be solved in deterministic polynomial time?]

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P = NP??

For now, we only know that

$$\begin{aligned} P &\subseteq NP \\ NP &\subseteq \text{EXP} = \bigcup_k \text{TIME}(2^{n^k}). \end{aligned}$$

But we do **not** know whether

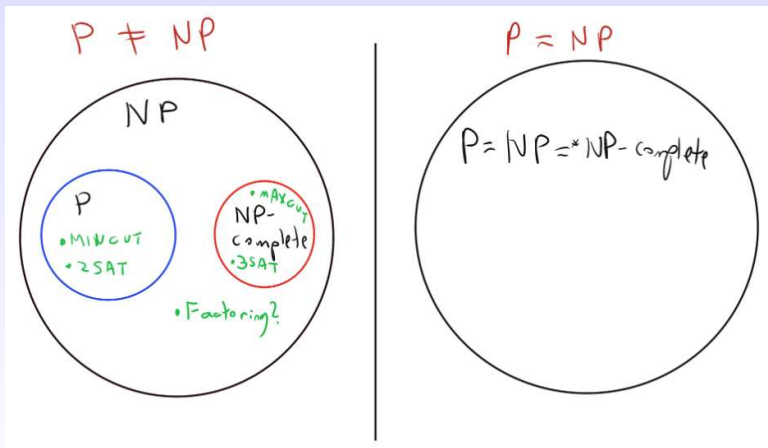
$$NP \subseteq P = \bigcup_k \text{TIME}(n^k) ???$$

Surprisingly, Cook and Levin found that SAT is among the hardest problems in NP

in the sense that, if we can solve SAT in deterministic polynomial time, then we can solve all of the problems in NP!

i.e. if $\text{SAT} \in P$, then $NP \subseteq P$, which means that $NP = P$.

Two possible worlds



[Source: https://files.boazbarak.org/introtcs/lec_13_Cook_Levin.pdf]

SAT is among the hardest problems in NP

Theorem (Cook-Levin)

SAT is NP-complete.

And we can show that the following theorem is true.

Theorem

Suppose A is NP-complete. Then, we have that

$$\text{if } A \in P \text{ then } P = NP .$$

It turns out that there are many other **NP-complete problems**.

If **theoreticians** can solve any one of these NP-complete problems in deterministic polynomial time, then we would have $P = NP$.

If a **practitioner** working on a problem cannot solve the problem in deterministic polynomial time, then he can instead try to show that the problem is NP-complete.

NP-Completeness: Definition

Definition

A language L is **NP-complete** iff it satisfies two conditions:

- 1 $L \in NP$
- 2 L is NP-hard.

Definition

A language L **NP-hard** iff every $L' \in NP$ is polynomial time reducible to L .

If we can solve L in a short time, we can solve all the problems in NP in a short time. So P would be equal to NP!

Polynomial time reducibility: Definitions

The reduction that we saw can be formalized explicitly as a **polynomial time reduction**.

Definition

Language A is **polynomial time reducible** to language B , written $A \leq_P B$ **iff** there is a polynomial time reduction of A to B .

Definition

A function $f : \Sigma^* \rightarrow \Sigma^*$ is a **polynomial reduction** of a language A to a language B **iff** f is polynomial computable and, for every $w \in \Sigma^*$,

- If $w \in A$, then $f(w) \in B$, and
- If $w \notin A$, then $f(w) \notin B$.

Properties we get from polynomial time reducibility

Let A, B be languages. Suppose $A \leq_P B$.

- 1 If $B \in P$, then so is A .
- 2 If $A \notin P$, then neither is B .

Also, these statements are true:

- $A \leq_P B$ iff $\overline{A} \leq_P \overline{B}$
- If $A \leq_P B$ and $B \leq_P C$, then $A \leq_P C$.
(i.e. \leq_P is a transitive relation.)

Questions: Is \leq_P reflexive? Is it symmetric?

NP-complete problems are the hardest ones in NP

The theorem we saw earlier follows directly from polynomial time reducibility.

Theorem

Suppose A is NP-complete. Then, we have that

if $A \in P$ then $P = NP$.

The theorem says that, if there is an NP-complete problem that ends up being easily solvable (i.e. solvable in polynomial time), then **all** the problems in NP become easily solvable.

So there are no problems in NP harder than NP-complete problems.

How to prove a problem NP-complete?

We reduce an NP-complete problem to L .

Theorem

Let $L \in \text{NP}$. If C is NP-complete and $C \leq_P L$, then L is NP-complete.

This theorem is true because polynomial reducibility is transitive.

So to prove that a problem L is NP-complete, we prove that

- 1 $L \in \text{NP}$, and that
- 2 there is a **reduction** from an NP-complete problem to L .

The first NP-complete problem

The problem that gets everything started is SAT.

In particular, Cook and Levin proved that any language in NP reduces to SAT.

Theorem (Cook-Levin)

SAT is NP-complete.

[As you might expect, the proof is somewhat complicated.]

So we “grow” our list of NP-complete problems starting from SAT.

SAT is NP-complete: Proof

- It is easy to see that $SAT \in NP$.
- Let L be an NP language. We show $L \leq_P SAT$. Let $w = w_1, \dots, w_n$. Let N be an NTM deciding L in time n^k for some constant $k \in \mathbb{Z}^+$.
- We record the sequence of configurations resulting from running N on w and use it to construct ϕ such that

N accepts w iff ϕ is satisfiable.

- The table is of size $n^k \times n^k$. Let the first and the last column contain $\#$.

We define ϕ as follows:

$$\phi = \phi_{\text{cell}} \wedge \phi_{\text{start}} \wedge \phi_{\text{accept}} \wedge \phi_{\text{move}} .$$

SAT is NP-complete: Proof (cont.)

Let Q be the set of states of N . The formula ϕ contains the following variables:

$$x_{i,j,s}$$

for $1 \leq i, j \leq n^k$ and $s \in C = \Sigma \cup \Gamma \cup \{\#\} \cup Q$.

We want to write ϕ so that, for every cell $[i, j]$, any satisfying assignment assigns

$$x_{i,j,s} = 1 \iff \text{cell}[i, j] \text{ contains } s.$$

SAT is NP-complete: Proof (cont.)

$$\phi_{\text{cell}} = \bigwedge_{1 \leq i, j \leq n^k} \left[\left(\bigvee_{s \in C} x_{i,j,s} \right) \wedge \bigwedge_{s, t \in C, s \neq t} (\overline{x_{i,j,s}} \vee \overline{x_{i,j,t}}) \right]$$

- At least one variable associated with each cell is turned on.
- For each pair of variables, at least one is turned off. So, no more than one variable is turned on in each cell.

Thus, any satisfying assignment must have exactly one variable on for every cell.

SAT is NP-complete: Proof (cont.)

$$\begin{aligned} \phi_{\text{start}} = & x_{1,1,\#} \wedge x_{1,2,q_0} \wedge x_{1,3,w_1} \wedge x_{1,4,w_2} \wedge \dots \wedge \\ & x_{1,n+2,w_n} \wedge x_{1,n+3,\sqcup} \wedge \dots \wedge \\ & x_{1,n^k-1,\sqcup} \wedge x_{1,n^k,\#} . \end{aligned}$$

- The first row contains the initial configuration.

SAT is NP-complete: Proof (cont.)

$$\phi_{\text{accept}} = \bigvee_{1 \leq i, j \leq n^k} x_{i,j,q_{\text{accept}}}$$

- There is an accepting configuration in the table.

SAT is NP-complete: Proof (cont.)

$$\phi_{\text{move}} = \bigwedge_{1 \leq i, j < n^k} \text{legal-window}(i, j)$$

where

$$\begin{aligned} \text{legal-window}(i, j) = \bigvee_{a, b, c, d, e, f \in LW} & x_{i, j-1, a} \wedge x_{i, j, b} \wedge x_{i, j+1, c} \wedge \\ & x_{i+1, j-1, d} \wedge x_{i+1, j, e} \wedge x_{i+1, j+1, f} \text{ and} \end{aligned}$$

LW denotes the set of all legal windows.

- Every window in the table is legal.

3SAT is NP-complete

Theorem

3SAT is NP-complete.

To prove this theorem, we modify the Cook-Levin proof.

Specifically, we convert ϕ in the Cook-Levin proof to an equivalent formula in 3CNF.

CLIQUE is NP-complete

Theorem

CLIQUE *is NP-complete.*

To prove this theorem, we proceed as follows:

- ➊ Show that $\text{CLIQUE} \in \text{NP}$
- ➋ Show that $3\text{SAT} \leq_P \text{CLIQUE}$
 - ➊ Specify a reduction f
 - ➋ Prove that f is polynomial time computable
 - ➌ Prove that $\forall \phi, \phi \in 3\text{SAT}$ if and only if $f(\phi) \in \text{CLIQUE}$.

Proving other languages NP-complete

Usually, it is easy to show that a language is in NP. The tough part is often in showing that it is NP-hard.

- ❶ $3SAT \leq_P VC$
- ❷ $VC \leq_P IS$
- ❸ $3SAT \leq_P HAMPATH$

Summary

