Path

- -_title: String- locations: Array
- _prerecordedRoutesIndex: Array
- + Path(title: String, locations: Array, prerecordedRoutesIndex: Array)
- + get title(): String
 + get locations(): Array
- + get numberOfTurns(): Number + get totalDistance(): Number
- + initialisePathPDO(pathObject:Object): Object

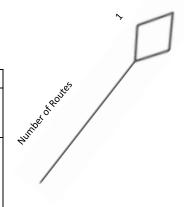


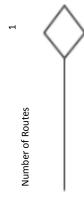
PathList

- -_routeList: Array
- +PathList(routeList: Array)
- + get allPaths(): Array
- + get size(): Number
- + specificPath(index:Number): Array
- + addPath(path): Array
- +initialisePathListPDO(pathObject:Object): Object

PathGyroAccel

- -_directionAngle: Number
- -_speed: Number
- +PathGyroAccel(directionAngle: Number, speed: Number)
- + get directionAngle(): Number
- + get speed (): Number
- + accellerationToSpeed(acceleration:Number): Number
- + directionAngle(acceleration:Number,gyroscope:Number): Number





PathBT

- -_latIng: Array
- -_accuracy: Number
- +get lating(): Array
- +get accuracy(): Number