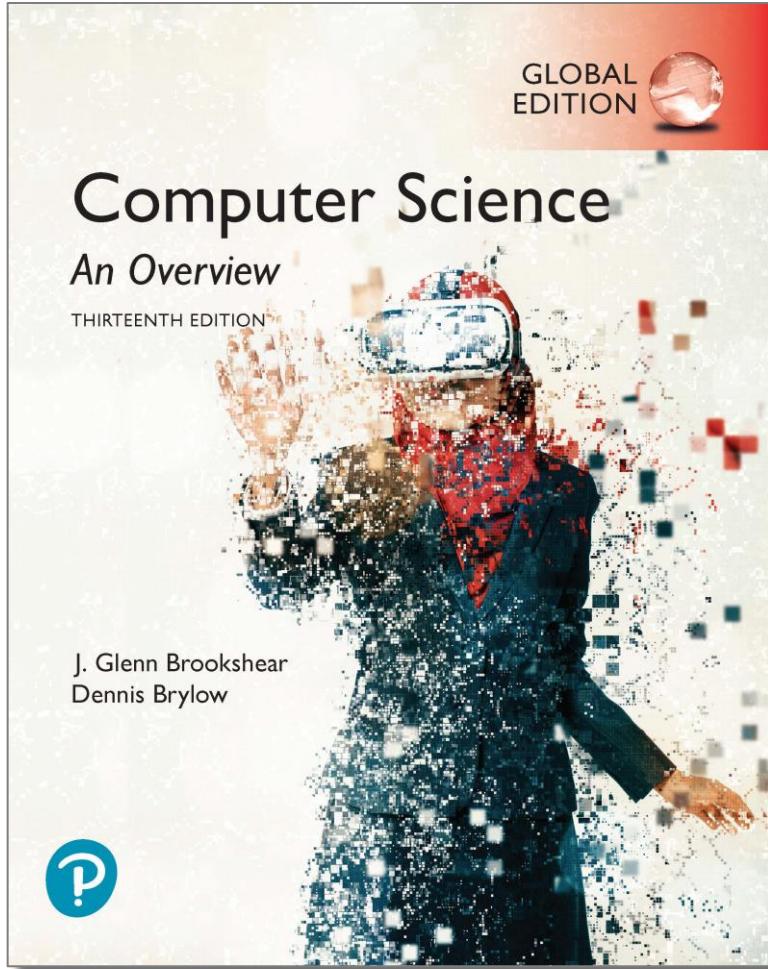


Computer Science An Overview

13th Edition, Global Edition



Chapter 6

Programming Languages

Chapter 6: Programming Languages

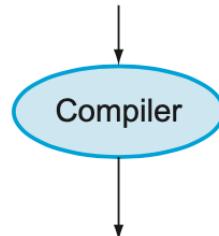
- 6.1 Historical Perspective
- 6.2 Traditional Programming Concepts
- 6.3 Procedural Units
- 6.4 Language Implementation
- 6.5 Object Oriented Programming
- 6.6 Programming Concurrent Activities
- 6.7 Declarative Programming

6.1 Historical Perspective

- Early Generations
 - Machine Language (e.g. Vole)
 - Assembly Language
- Machine Independent Language
- Beyond – more powerful abstractions

High-level
language
program
(in C)

```
swap(int v[], int k)
{int temp;
    temp = v[k];
    v[k] = v[k+1];
    v[k+1] = temp;
}
```

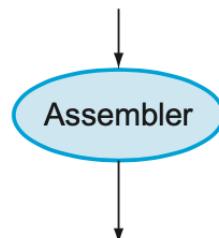


Assembly language program (for MIPS)

```

swap:
    multi $2, $5,4
    add   $2, $4,$2
    lw    $15, 0($2)
    lw    $16, 4($2)
    sw    $16, 0($2)
    sw    $15, 4($2)
    jr

```

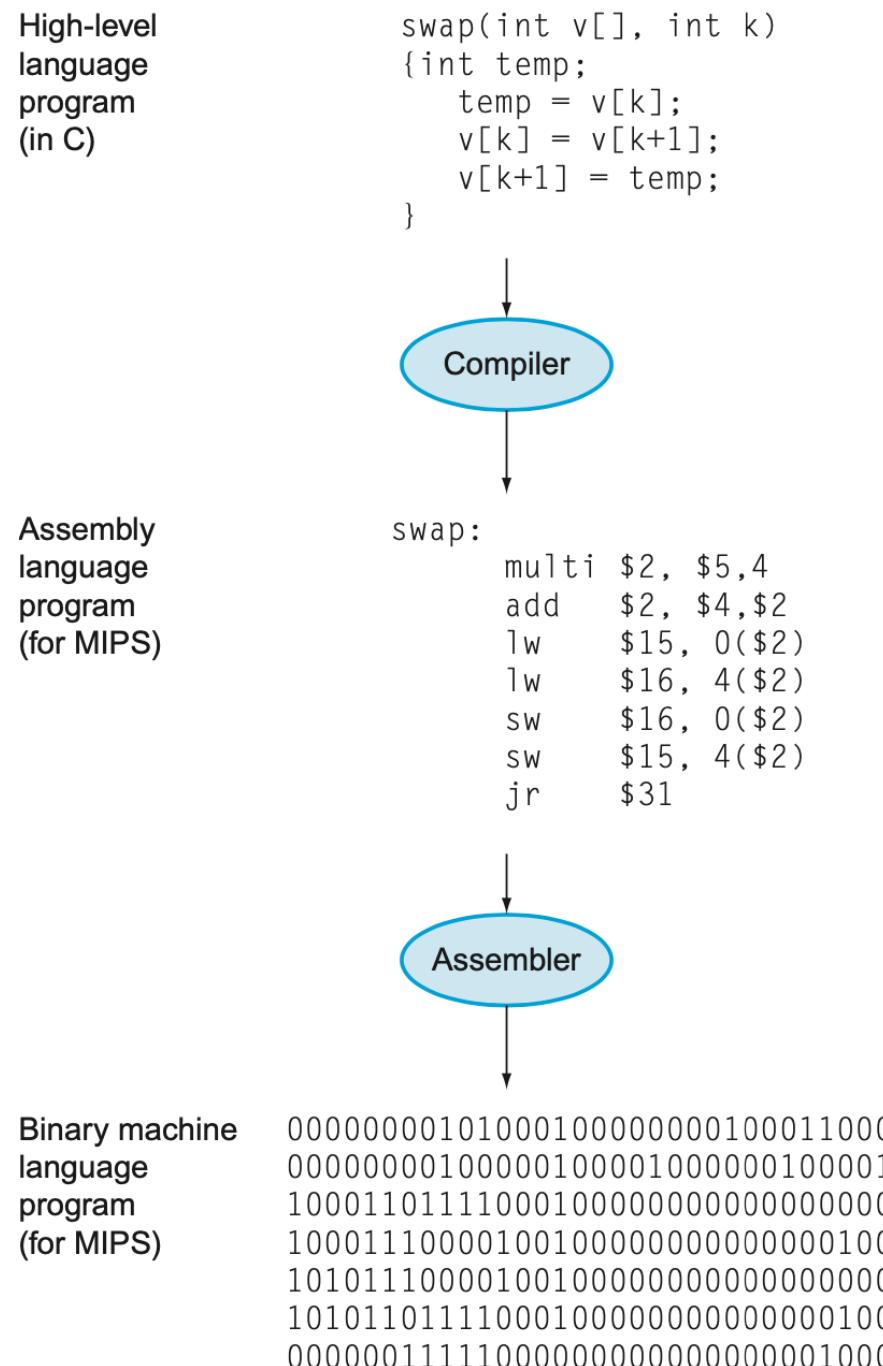


Binary machine language program (for MIPS)

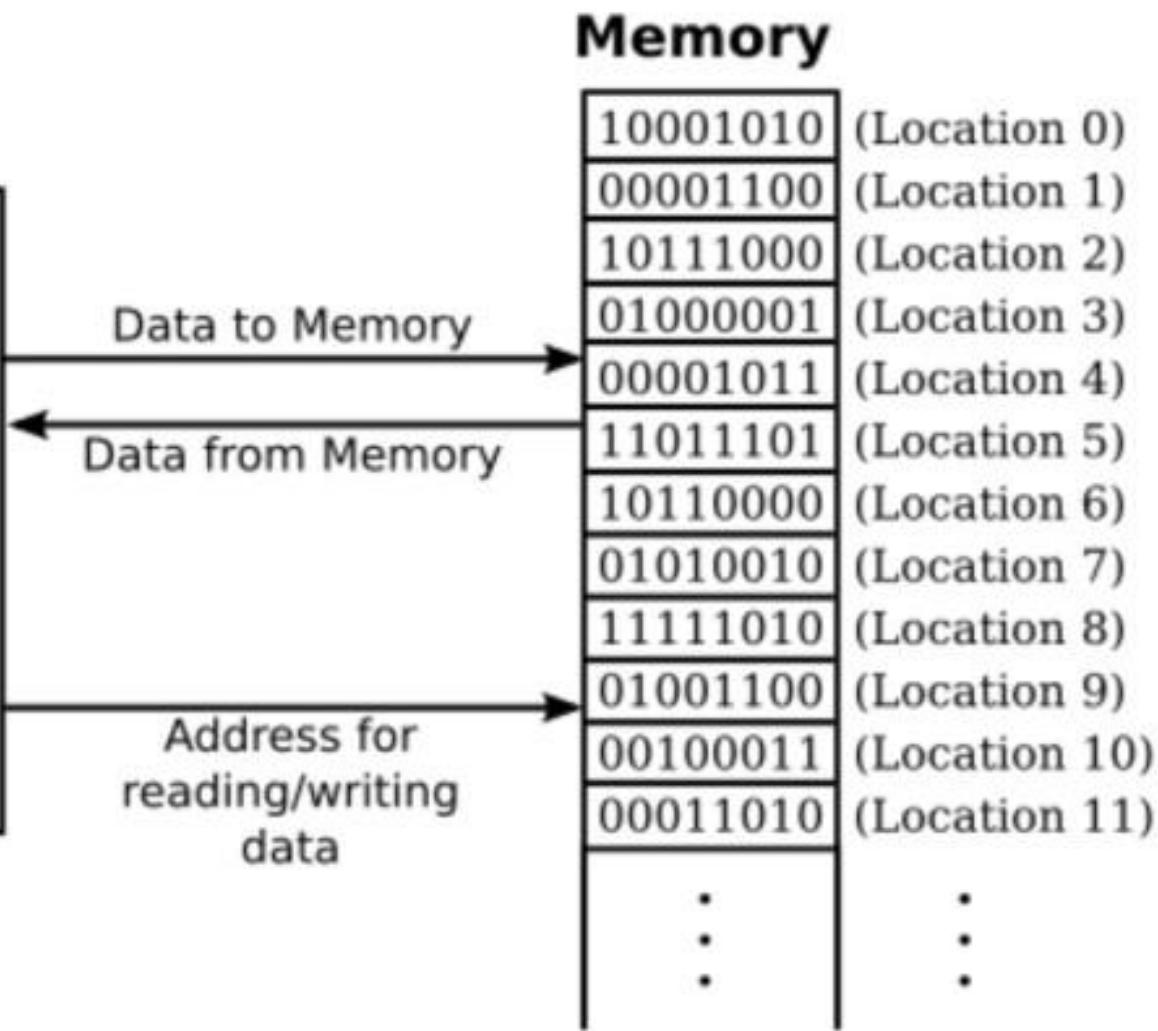
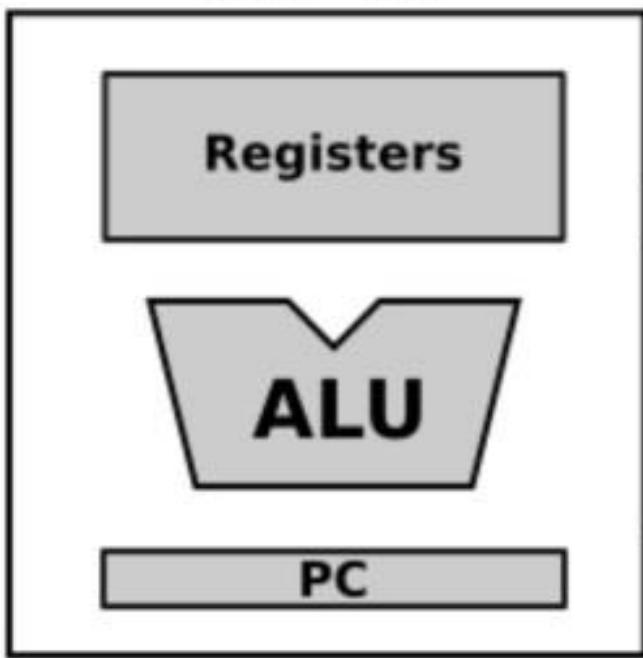
```
00000000101000100000000100011000  
00000000100000100001000000100001  
1000110111100010000000000000000000  
1000111000010010000000000000000100  
10101110000100100000000000000000000  
10101101111000100000000000000000000  
000000111110000000000000000000000000
```

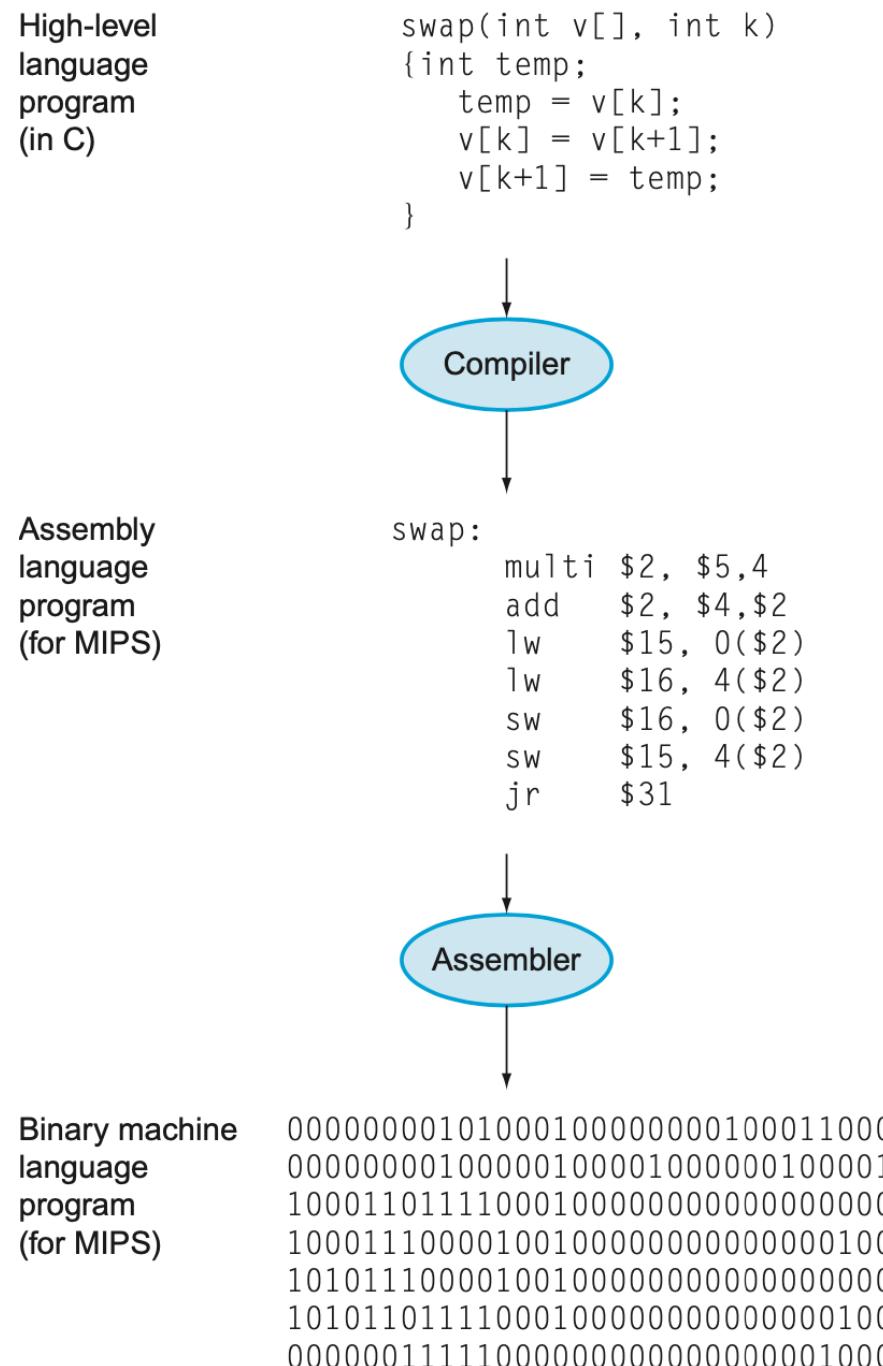
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 - Assembly Language
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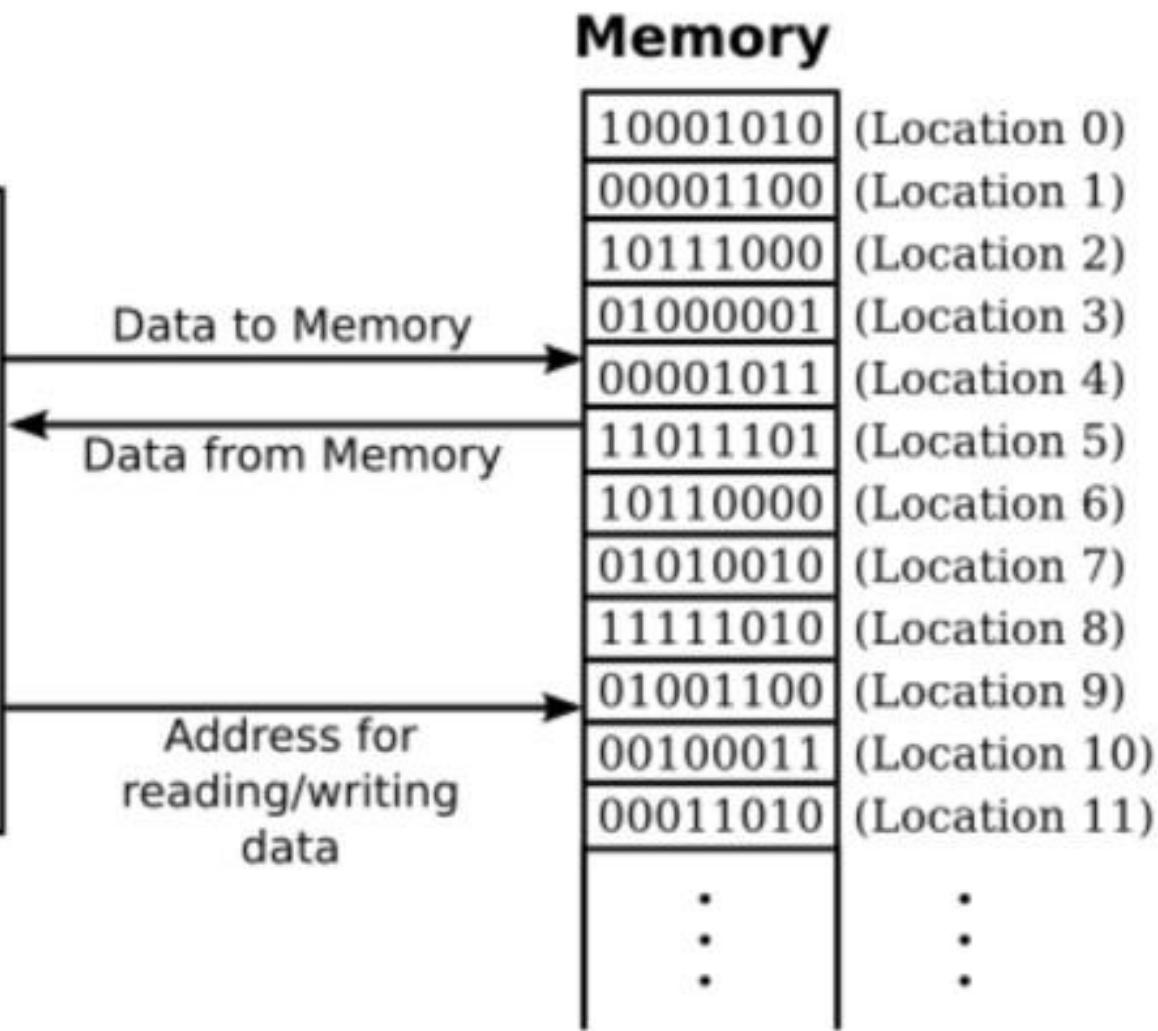
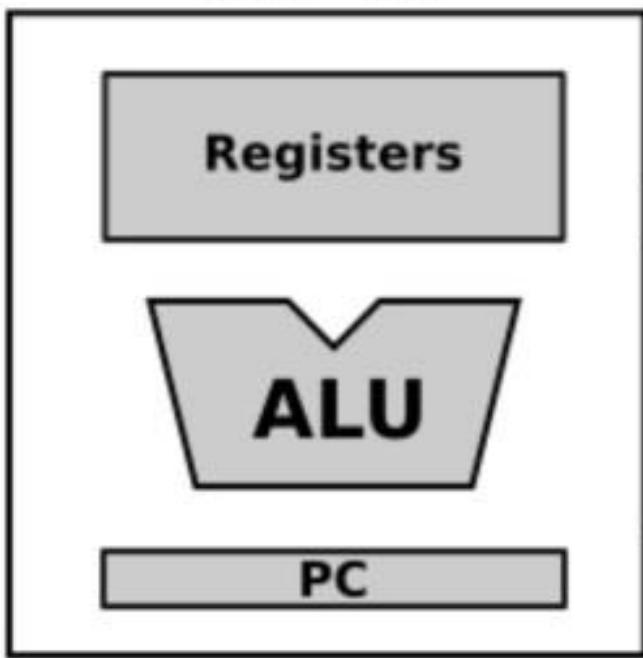


CPU



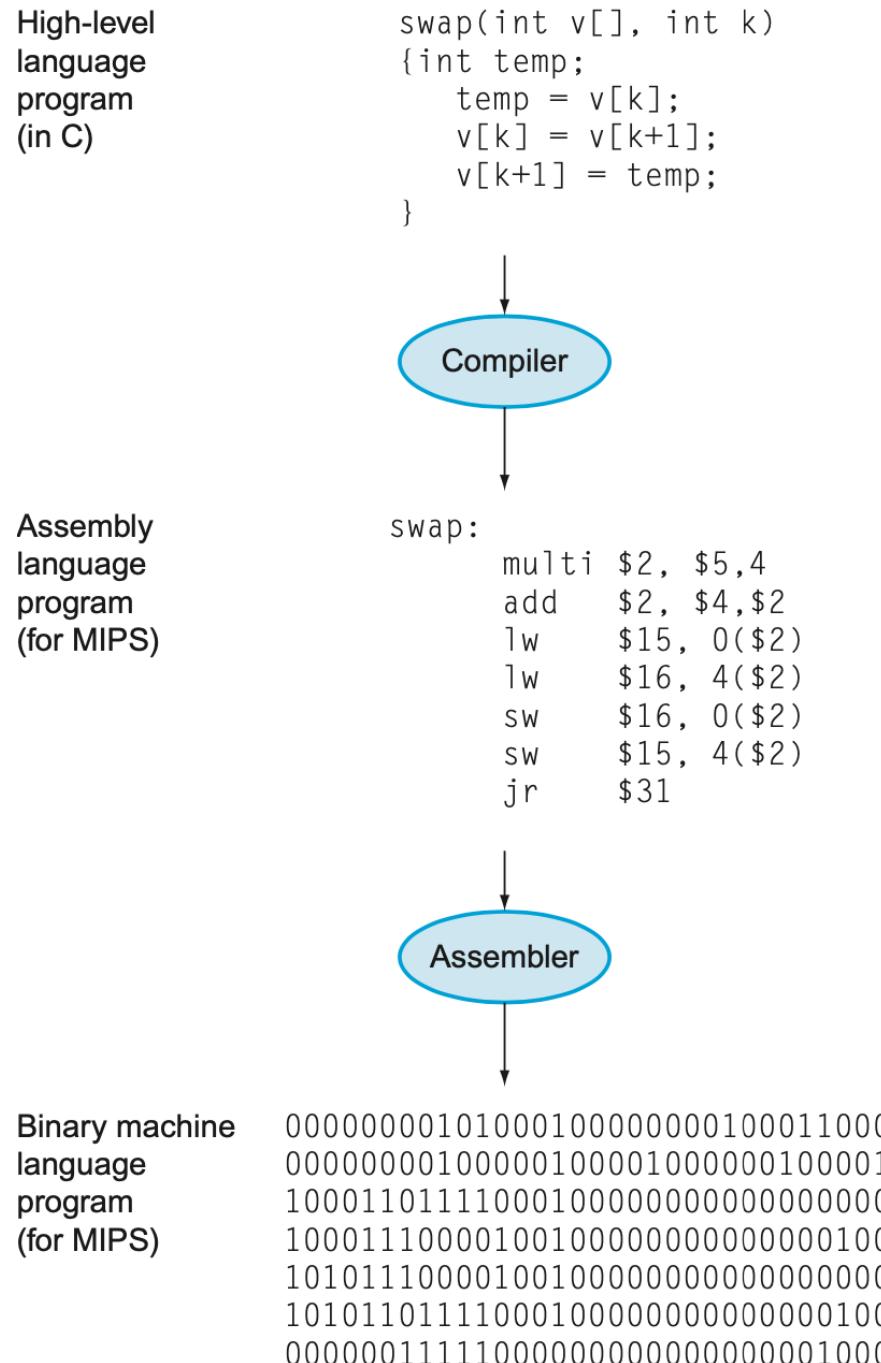


CPU



6.1 Historical Perspective

- Early Generations
 - Machine Language (e.g. Vole)
 - Assembly Language
- Machine Independent Language
- Beyond – more powerful abstractions



Second-generation: Assembly language

- A mnemonic system for representing machine instructions
 - Mnemonic names for op-codes
 - Program **variables** or **identifiers**: Descriptive names for memory locations, chosen by the programmer

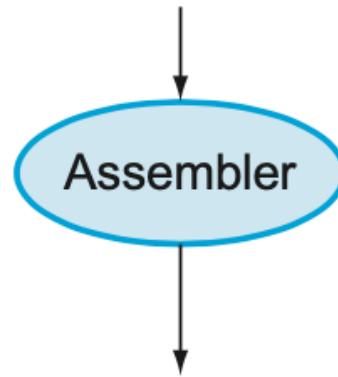
BASIC INSTRUCTION FORMATS

R	opcode	rs	rt	rd	shamt	funct	
	31	26 25	21 20	16 15	11 10	6 5	0
I	opcode	rs	rt		immediate		
	31	26 25	21 20	16 15			0
J	opcode			address			
	31	26 25					0

**Assembly
language
program
(for MIPS)**

swap:

```
multi $2, $5,4
add   $2, $4,$2
lw    $15, 0($2)
lw    $16, 4($2)
sw    $16, 0($2)
sw    $15, 4($2)
jr    $31
```



**Binary machine
language
program
(for MIPS)**

```
0000000101000100000000100011000
000000010000010001000000100001
10001101110001000000000000000000
100011100001001000000000000000000
1010111000010010000000000000000000
1010110111000100000000000000000000
0000001111000000000000000000000000
```



Pe

erved.

Second-generation: Assembly language

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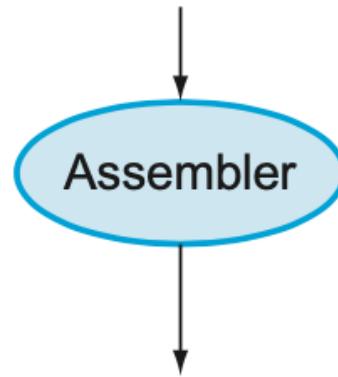
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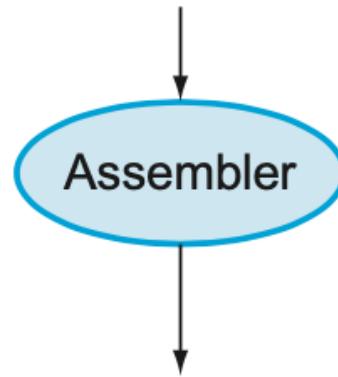
Assembly Language Characteristics

- One-to-one correspondence between machine instructions and assembly instructions
 - Programmer must think like the machine
- Inherently machine-dependent
- Converted to machine language by a program called an **assembler**

**Assembly
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(for MIPS)**

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```



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```



Pe

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I	opcode	rs	rt		immediate		
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J	opcode				address		
	31	26 25					0

<https://stackoverflow.com/questions/42392369/why-are-opcode-field-and-funct-field-apart-in-mips>

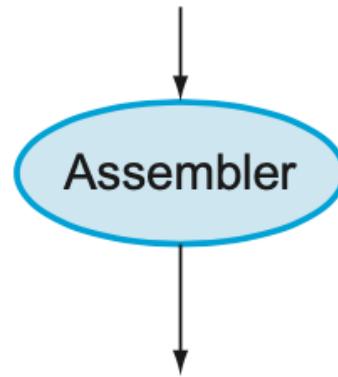
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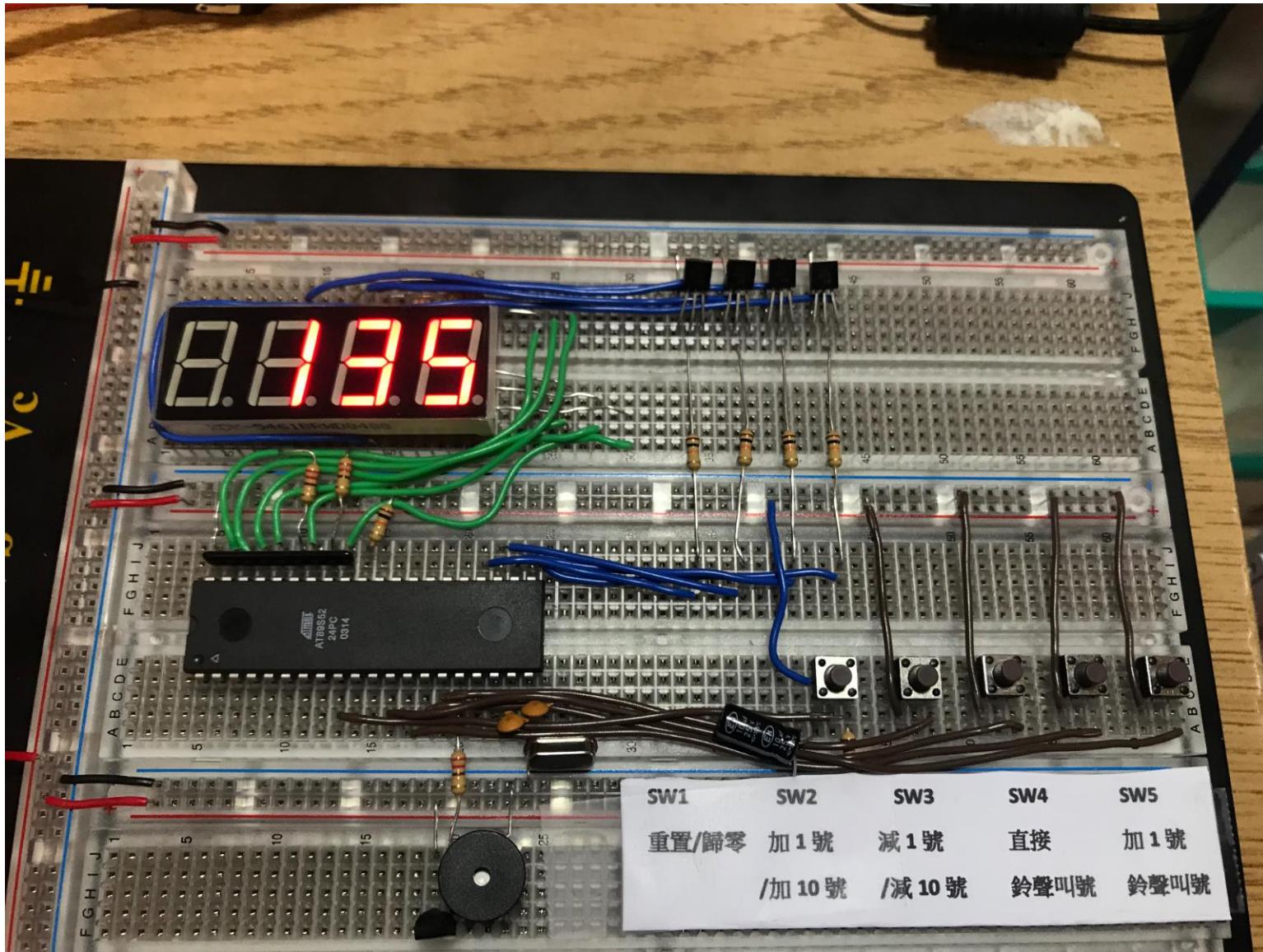
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```
0000000101000100000000100011000
000000010000010001000000100001
10001101110001000000000000000000
10001110000100100000000000000000
101011100001001000000000000000000
101011011100010000000000000000000
0000001111000000000000000000000000
```



Pe

erved.



<https://www.cakeresume.com/portfolios/8051?locale=zh-TW>

Third Generation Language

- Uses high-level primitives
 - Similar to our pseudocode in Chapter 5
- Machine independent (mostly)
- Examples: FORTRAN, COBOL
- Each primitive corresponds to a sequence of machine language instructions
- Converted to machine language by a program called a **compiler**

Algorithm 1 Consensus-Based FA

```
1: procedure CFA( $\mathcal{N}_{\bar{k}}$ ,  $\epsilon_t$ ,  $\alpha_{t,i}$ )
2:   initialize  $\mathbf{W}_{0,k} \leftarrow$  device  $k$ 
3:   for each round  $t = 1, 2, \dots$ , do                                ▷ Main loop
4:     receive  $\{\mathbf{W}_{t,i}\}_{i \in \mathcal{N}_{\bar{k}}}$                                ▷ RX from neighbors
5:      $\psi_{t,k} \leftarrow \mathbf{W}_{t,k}$ 
6:     for all devices  $i \in \mathcal{N}_{\bar{k}}$  do
7:        $\psi_{t,k} \leftarrow \psi_{t,k} + \epsilon_t \alpha_{t,i} (\mathbf{W}_{t,i} - \mathbf{W}_{t,k})$ 
8:     end for
9:      $\mathbf{W}_{t+1,k} = \text{ModelUpdate}(\psi_{t,k})$ 
10:    send( $\mathbf{W}_{t+1,k}$ )                                         ▷ TX to neighbors
11:  end for
12: end procedure
13: procedure MODELUPDATE( $\psi_{t,k}$ )                                ▷ Local SGD
14:    $\mathcal{B} \leftarrow$  mini-batches of size  $B$ 
15:   for batch  $b \in \mathcal{B}$  do                                     ▷ Local model update
16:      $\psi_{t,k} \leftarrow \psi_{t,k} - \mu_t \nabla L_{t,k}(\psi_{t,k})$ 
17:   end for
18:    $\mathbf{W}_{t,k} \leftarrow \psi_{t,k}$ 
19:   return( $\mathbf{W}_{t,k}$ )
20: end procedure
```

Third Generation Language

- Uses high-level primitives
 - Similar to our pseudocode in Chapter 5
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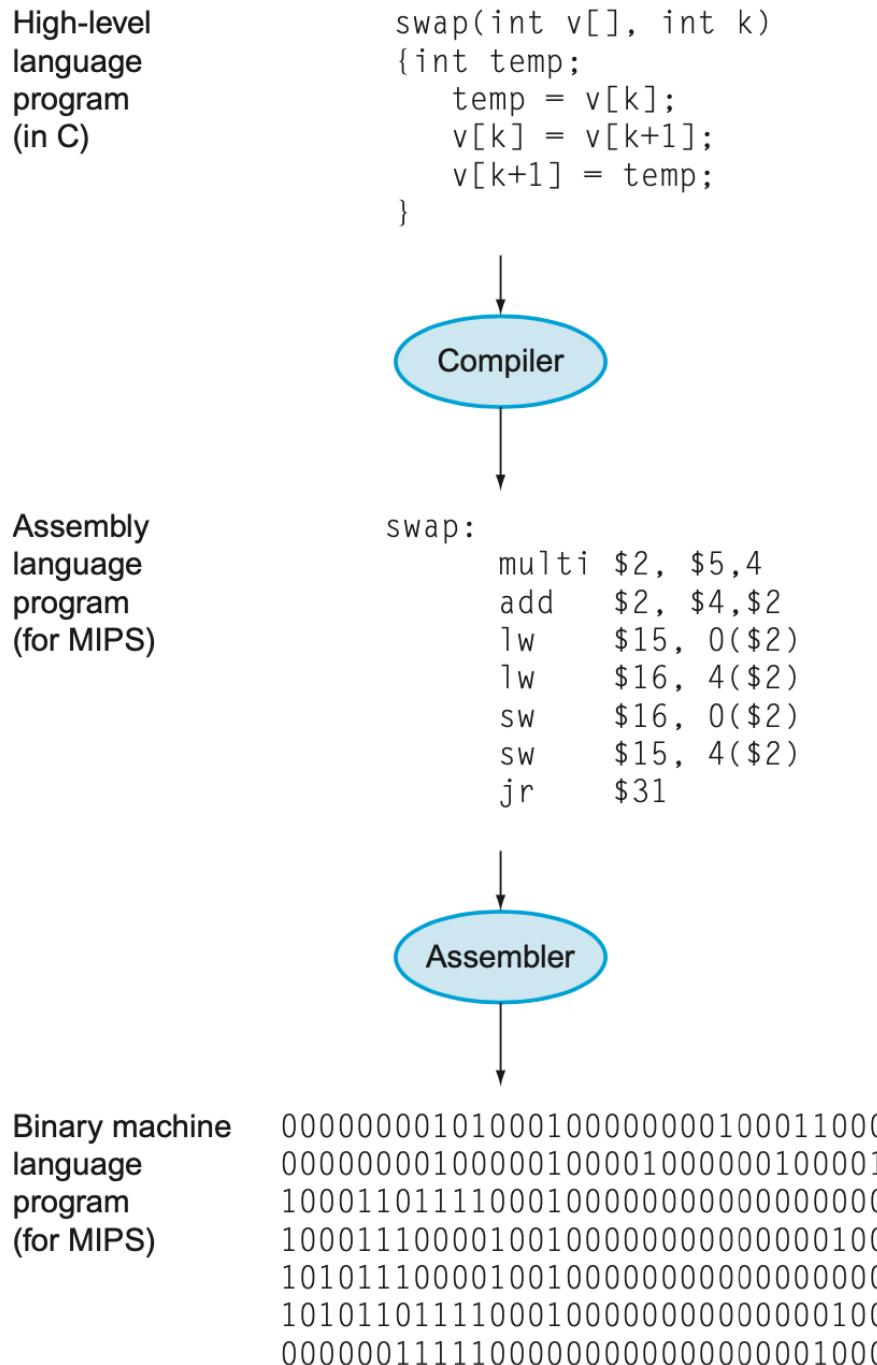
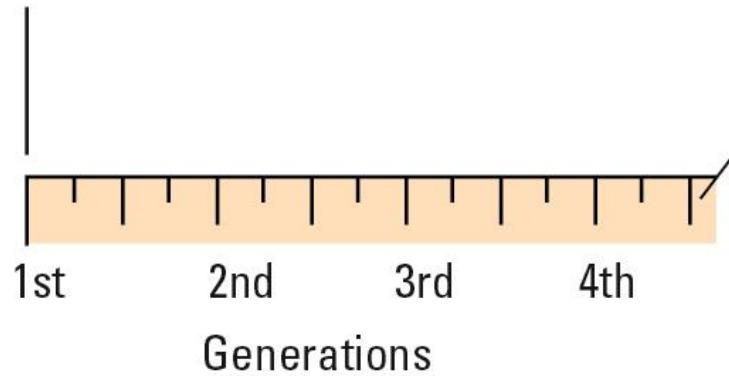


Figure 6.1 Generations of programming languages

Problems solved in an environment in which the human must conform to the machine's characteristics.



Problems solved in an environment in which the machine conforms to the human's characteristics.

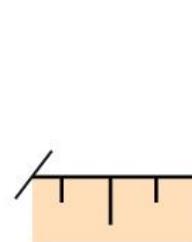
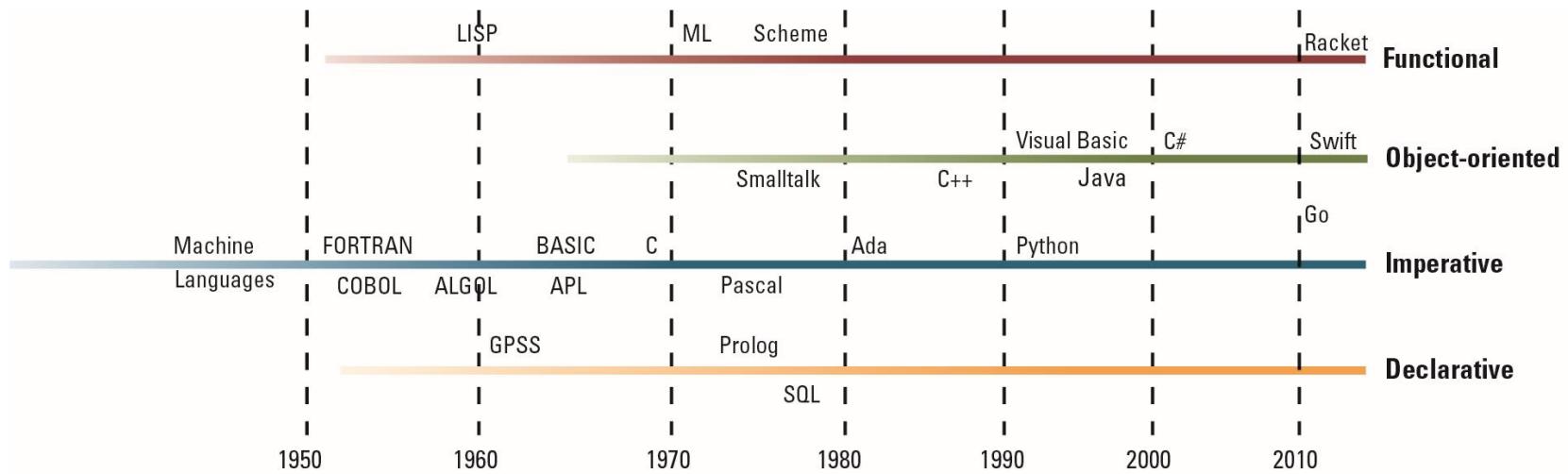


Figure 6.2 The evolution of programming paradigms



例子 [編輯]

彈簧 [編輯]

把質量為 M 的物體懸掛在勁度係數為 k 的彈簧的底端，則物體將進行簡諧運動，其方程式為：

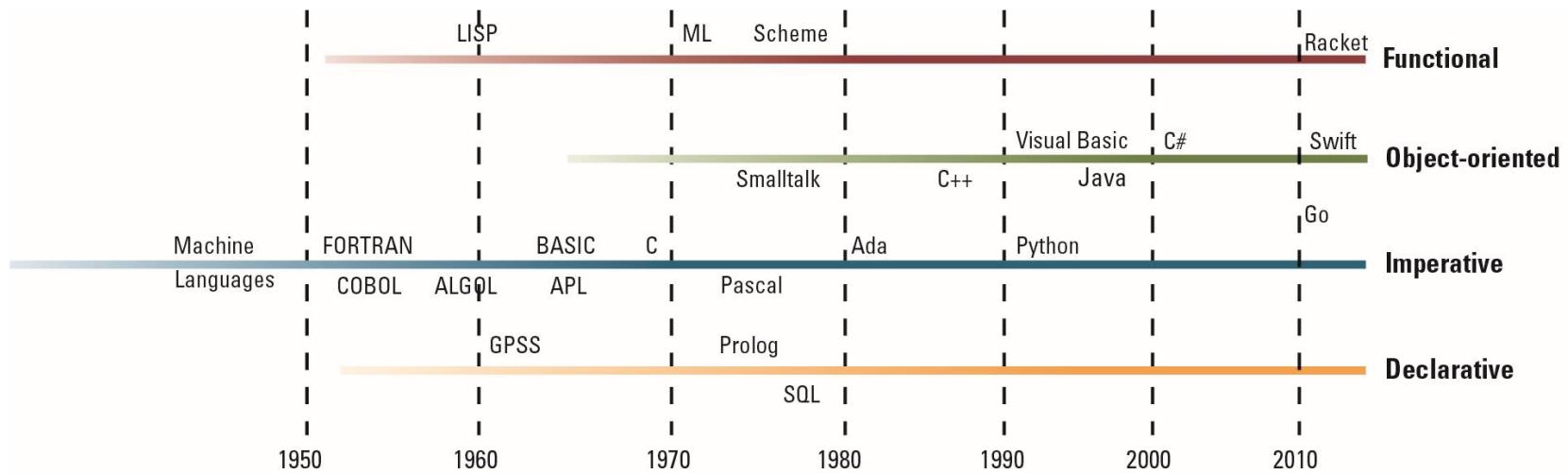
$$\omega = 2\pi f = \sqrt{\frac{k}{M}}.$$

如果要計算它的週期，可以用以下的公式：

$$T = \frac{1}{f} = 2\pi \sqrt{\frac{M}{k}}.$$

<https://zh.wikipedia.org/zh-tw/%E7%B0%A1%E8%AB%A7%E9%81%8B%E5%8B%95>

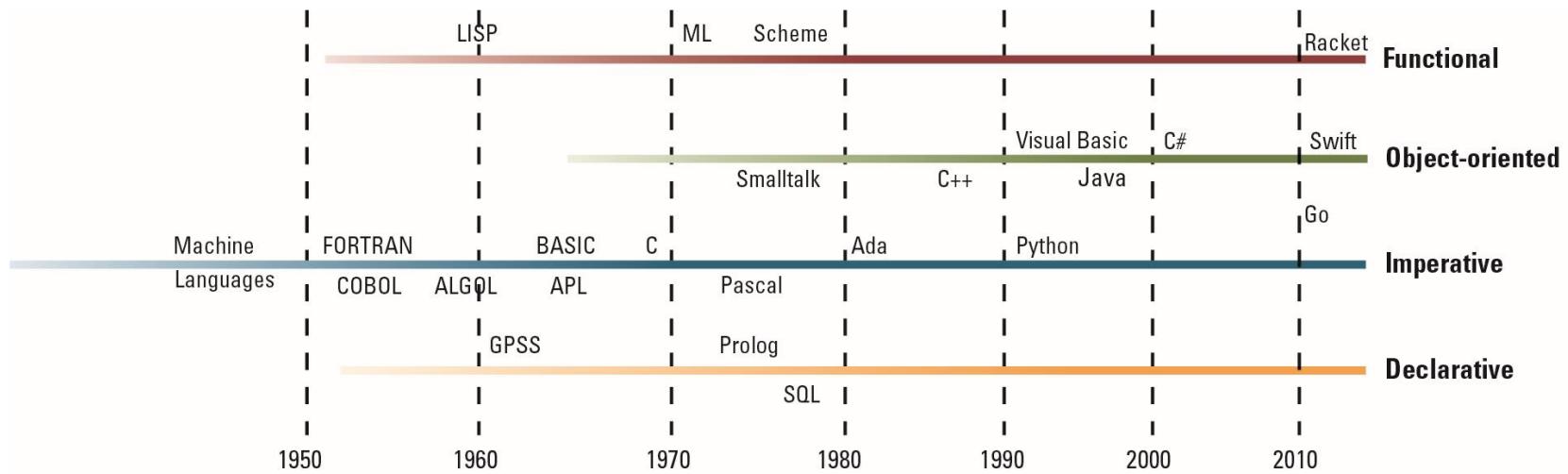
Figure 6.2 The evolution of programming paradigms



Chapter 6: Programming Languages

- 6.1 Historical Perspective
- 6.2 Traditional Programming Concepts
- 6.3 Procedural Units
- 6.4 Language Implementation
- 6.5 Object Oriented Programming
- 6.6 Programming Concurrent Activities
- 6.7 Declarative Programming

Figure 6.2 The evolution of programming paradigms



<https://www.youtube.com/watch?v=pSoDUFdqVOU&t=479s>

<https://www.youtube.com/watch?v=3EkaxkNGXD8>

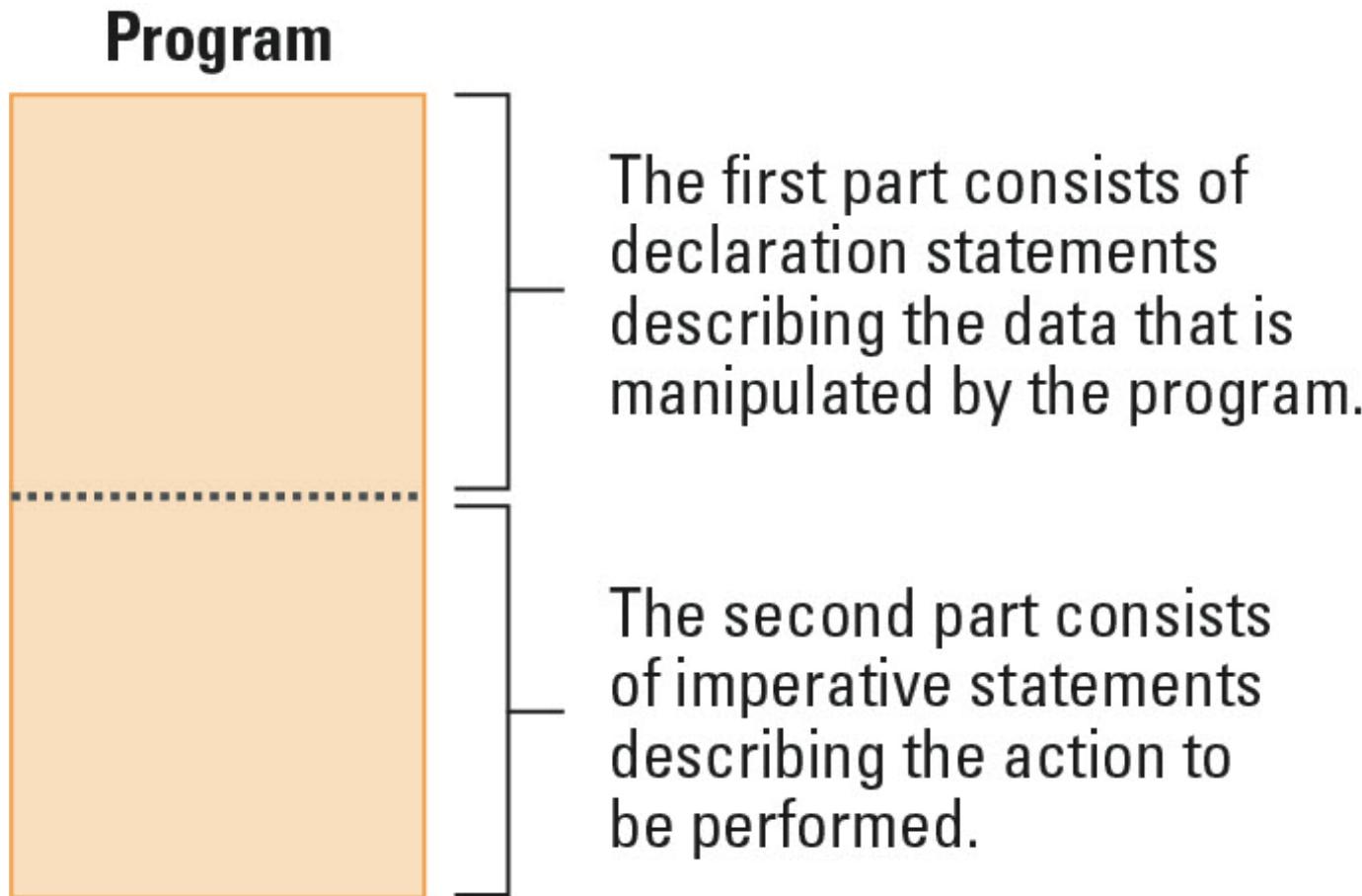
6.2 Traditional Programming Concepts

- Variables and Data Types
- Data Structure
- Constants and Literals
- Assignment Statements
- Control Statements
- Comments

6.2 Traditional Programming Concepts

- High-level languages (C, C++, Java, C#, FORTRAN) include many kinds of abstractions
 - Simple: constants, literals, variables
 - Complex: statements, expressions, control
 - Esoteric: procedures, modules, libraries

Figure 6.4 The composition of a typical imperative program or program unit



Process (其他版本 = jobs = task (Linux))

(-) Def:

A program in execution, 即執行中的程式

當 Process 被建立後, Process 的主要組成包含下列:

1. Code section (or Text section), 即 program code
2. Data section: containing the global variables
3. Stack: 包含 temporary data
(e.g. Function parameters, Local variables, return address)
4. Heap: 包含 memory dynamically allocated during run time)
(e.g. pointer 變數之要求空間)
5. Programming Counter and other register
內放下一條指令之所在位址

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5. Programming Counter and other register
內放下一條指令之所在位址

(=) Process V.S. Program

Process	Program
A program in execution	Just a file stored in storage device
"Active" entity	"Passive" entity

圖示：

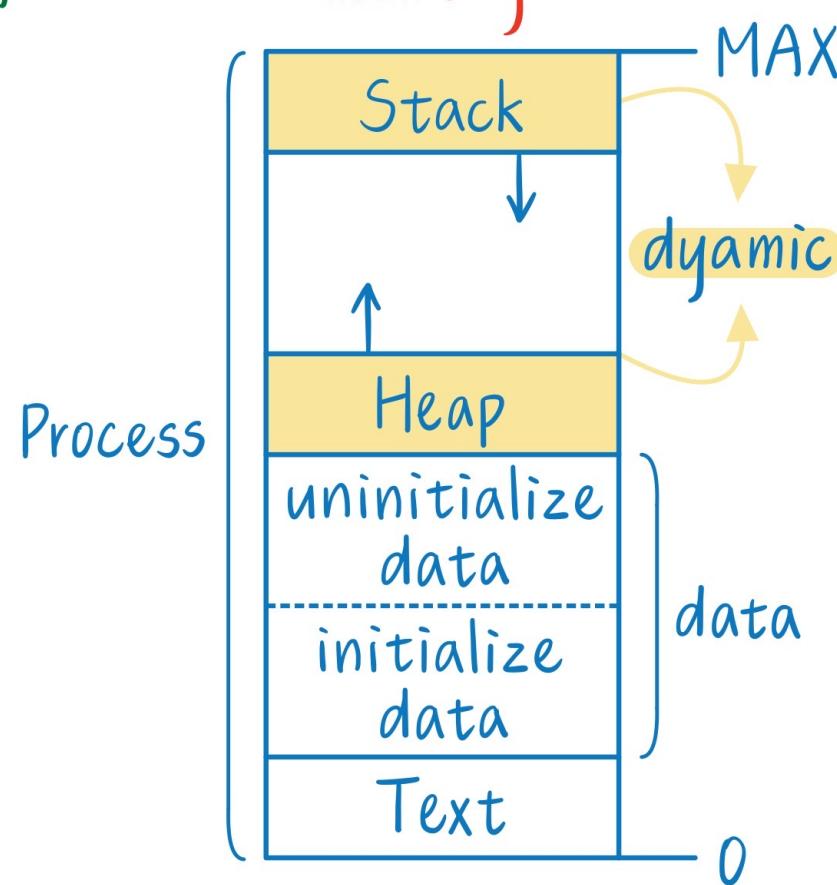
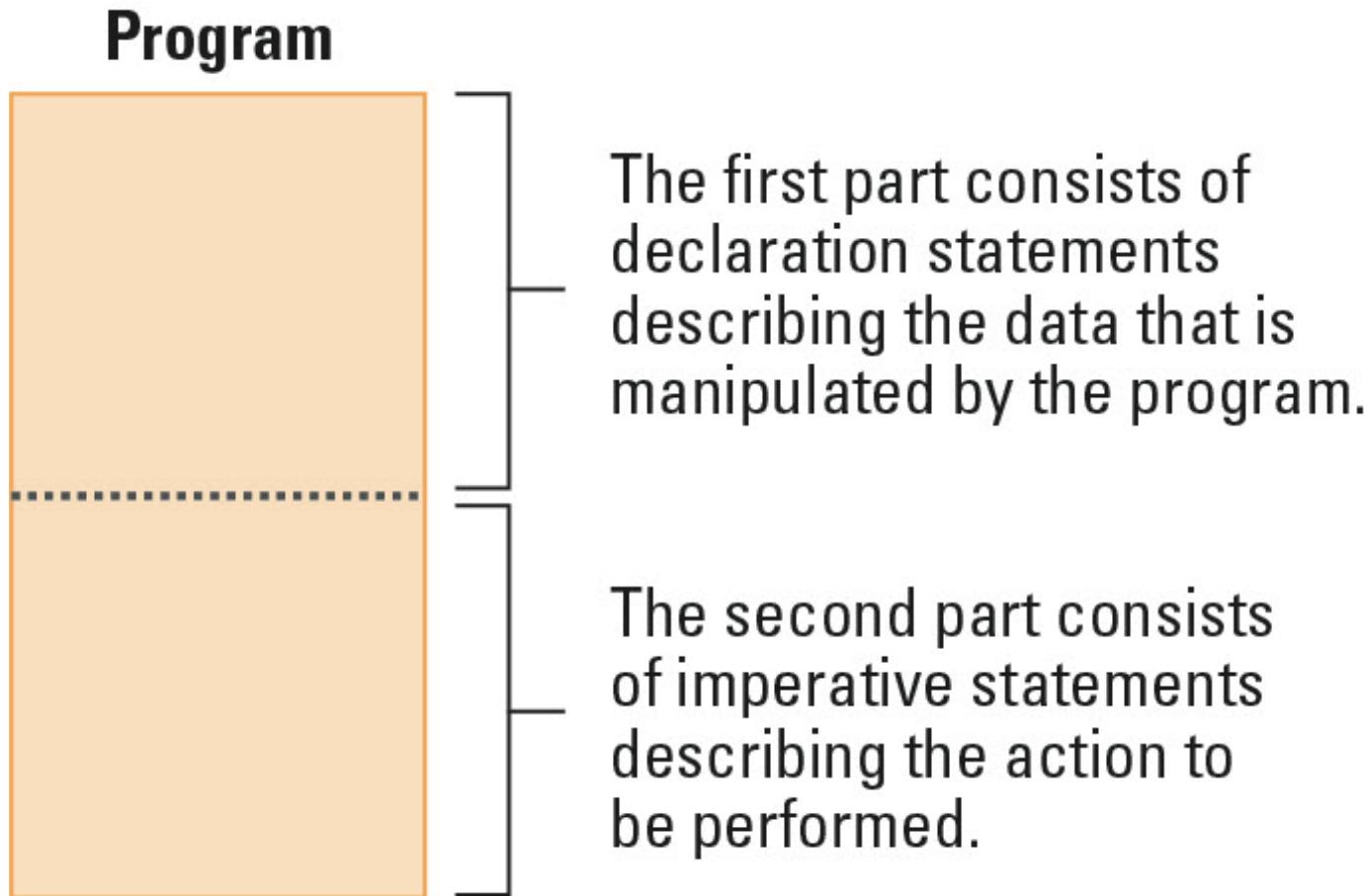


Figure 6.4 The composition of a typical imperative program or program unit



Data Types

- Integer: Whole numbers
- Real (float): Numbers with fractions
- Character: Symbols
- Boolean: True/false

Variables and Data types

```
float Length, Width;  
int Price, Total, Tax;  
char Symbol;  
  
int WeightLimit = 100;
```

6.2 Traditional Programming Concepts

- High-level languages (C, C++, Java, C#, FORTRAN) include many kinds of abstractions
 - Simple: constants, literals, variables
 - Complex: statements, expressions, control
 - Esoteric: procedures, modules, libraries

Variables and Data types

```
float Length, Width;  
int Price, Total, Tax;  
char Symbol;  
  
int WeightLimit = 100;
```

Data Structure

- Conceptual shape or arrangement of data
- A common data structure is the **array**

- In C

```
int Scores[2][9];
```

- In FORTRAN

```
INTEGER Scores(2,9)
```

Figure 6.5 A two-dimensional array with two rows and nine columns

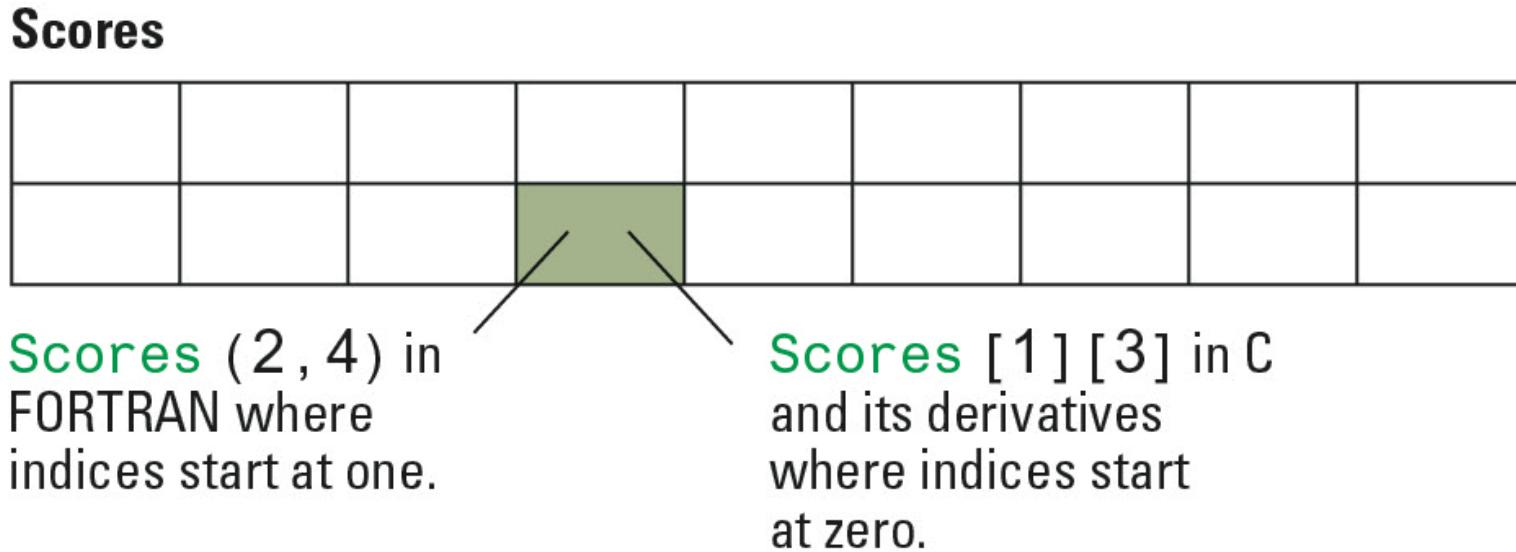
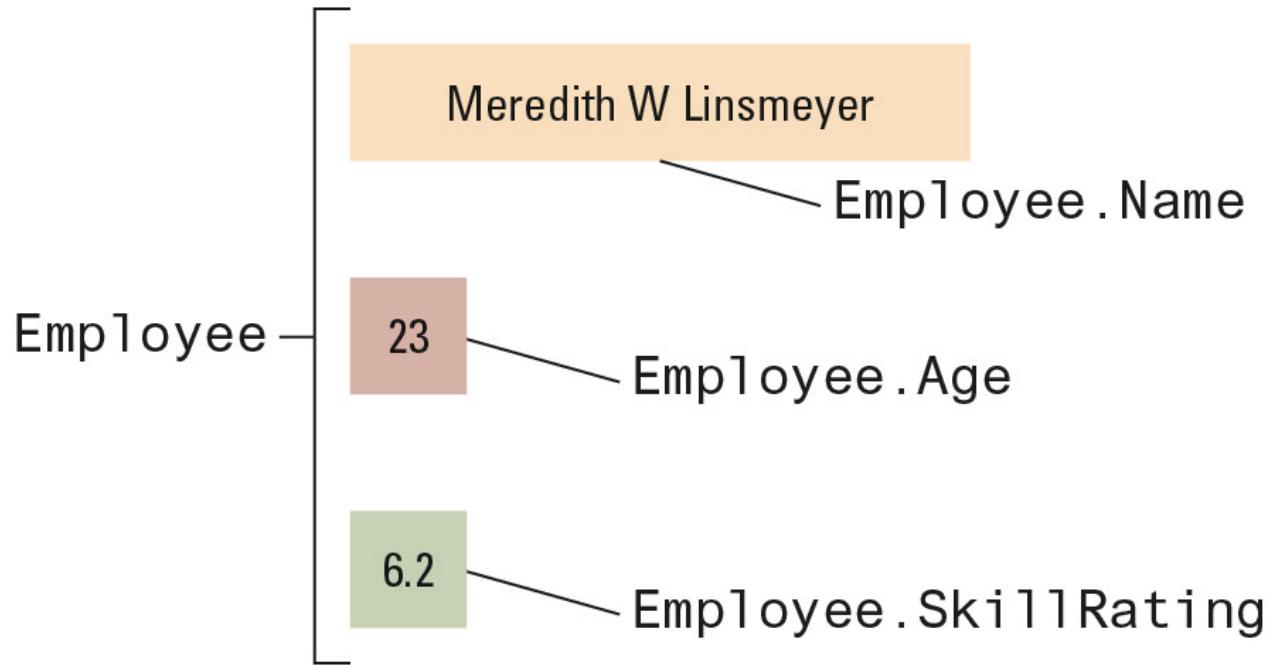


Figure 6.6 The conceptual structure of the aggregate type Employee



```
struct {    char  Name[25];
            int   Age;
            float SkillRating;
} Employee;
```

Assignment Statements

- In C, C++, C#, Java

$\text{Z} = \text{X} + \text{y};$

- In Ada

$\text{Z} := \text{X} + \text{y};$

- In APL (A Programming Language)

$\text{Z} \leftarrow \text{X} + \text{y}$

Control Statements

- Go to statement

```
        goto 40
20    Evade()
        goto 70
40    if (KryptoniteLevel < LethalDose) then goto
60
        goto 20
60    RescueDamsel()
70    ...
```

- As a single statement

```
if (KryptoniteLevel < LethalDose):
    RescueDamsel()
else:
```

Control Statements (continued)

- If in Python

```
if (condition):  
    statementA  
else:  
    statementB
```

- In C, C++, C#, and Java

```
if (condition) statementA; else statementB;
```

- In Ada

```
IF condition THEN  
    statementA;  
ELSE  
    statementB;  
END IF;
```

Control Statements (continued)

- While in Python

```
while (condition):  
    body
```

- In C, C++, C#, and Java

```
while (condition)  
{ body }
```

- In Ada

```
WHILE condition LOOP  
    body  
END LOOP;
```

Control Statements (continued)

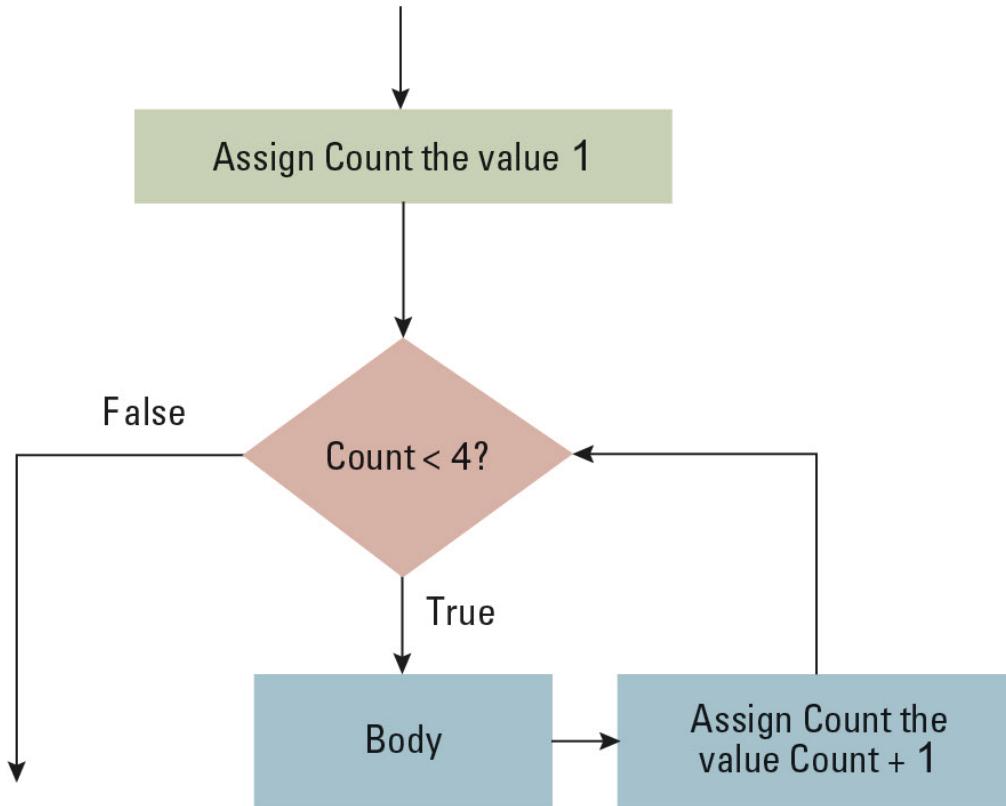
- Switch statement in C, C++, C#, and Java

```
switch (variable) {  
    case 'A': statementA; break;  
    case 'B': statementB; break;  
    case 'C': statementC; break;  
    default: statementD; }
```

- In Ada

```
CASE variable IS  
    WHEN 'A'=> statementA;  
    WHEN 'B'=> statementB;  
    WHEN 'C'=> statementC;  
    WHEN OTHERS=> statementD;  
END CASE;
```

Figure 6.7 The for loop structure and its representation in C++, C#, and Java



```
for (int Count = 1; Count < 4; Count++)  
    body;
```

Comments

- Explanatory statements within a program
- Helpful when a human reads a program
- Ignored by the compiler

```
/* This is a comment in C/C++/Java. */
```

```
// This is a comment in C/C++/Java.
```

6.3 Procedural Units

- Many terms for this concept:
 - Subprogram, subroutine, procedure, method, function
- Unit begins with the function's **header**
- Local versus Global Variables
- Formal versus Actual Parameters
- Passing parameters by value versus reference

```
1 # A同學  
2 v0_A = 10  
3 a_A = 20  
4 t_A = 200  
5 s_A = v0_A * t_A + (0.5) * a_A * (t_A^2)  
6  
7 # B同學  
8 v0_B = 5  
9 a_B = 200  
10 t_B = 100  
11 s_B = v0_B * t_B + (0.5) * a_B * (t_B^2)  
12  
13 # C同學  
14 v0_C = 50  
15 a_C = 20  
16 t_C = 1  
17 s_C = v0_C * t_C + (0.5) * a_C * (t_C^2)
```



```
1 # 距離公式
2 def vt_func(v0, a, t):
3     s = v0 * t + (0.5) * a * (t^2)
4     return s
5
6 # A同學
7 v0_A = 10
8 a_A = 20
9 t_A = 200
10 s_A = vt_func(v0_A, a_A, t_A)
11
12 # B同學
13 v0_B = 5
14 a_B = 200
15 t_B = 100
16 s_A = vt_func(v0_B, a_B, t_B)
17
18 # C同學
19 v0_C = 50
20 a_C = 20
21 t_C = 1
22 s_A = vt_func(v0_C, a_C, t_C)
```

```
1 # A同學  
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15 t_B = 100
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18 # C同學
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Creating a Function

To create a function, you would have to first write a function header. A function header looks like this:

```
def function_name(args):  
    #code in function
```

Let's break it down:

The diagram shows a function header with five numbered callouts pointing to specific parts of the code:

- 1: The `def` keyword.
- 2: The function name `function_name`.
- 3: The argument `(args)`.
- 4: The colon `:`.
- 5: The code inside the function, which is `#code in function`.

1. The `def` keyword just indicates that we are starting to write a function header
2. The name of the function goes here. You can name a function in the same ways you can name a variable.
3. Arguments go here. This is covered in the next lesson, so here you would usually leave it as blank parentheses
4. Colon is required! Don't forget!
5. The code underneath that is tabbed is the code inside the function.

<https://teach'en.info/cspp/unit4/u0401-functions.html>

6.3 Procedural Units

- Many terms for this concept:
 - Subprogram, subroutine, procedure, method, function
- Unit begins with the function's **header**
- Local versus Global Variables
- Formal versus Actual Parameters
- Passing parameters by value versus reference

```
1 # 距離公式
2 def vt_func(v0, a, t):
3     s = v0 * t + (0.5) * a * (t^2)
4     return s
5
6 # A同學
7 v0_A = 10
8 a_A = 20
9 t_A = 200
10 s_A = vt_func(v0_A, a_A, t_A)
11
12 # B同學
13 v0_B = 5
14 a_B = 200
15 t_B = 100
16 s_A = vt_func(v0_B, a_B, t_B)
17
18 # C同學
19 v0_C = 50
20 a_C = 20
21 t_C = 1
22 s_A = vt_func(v0_C, a_C, t_C)
```

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Figure 6.8 The flow of control involving a function

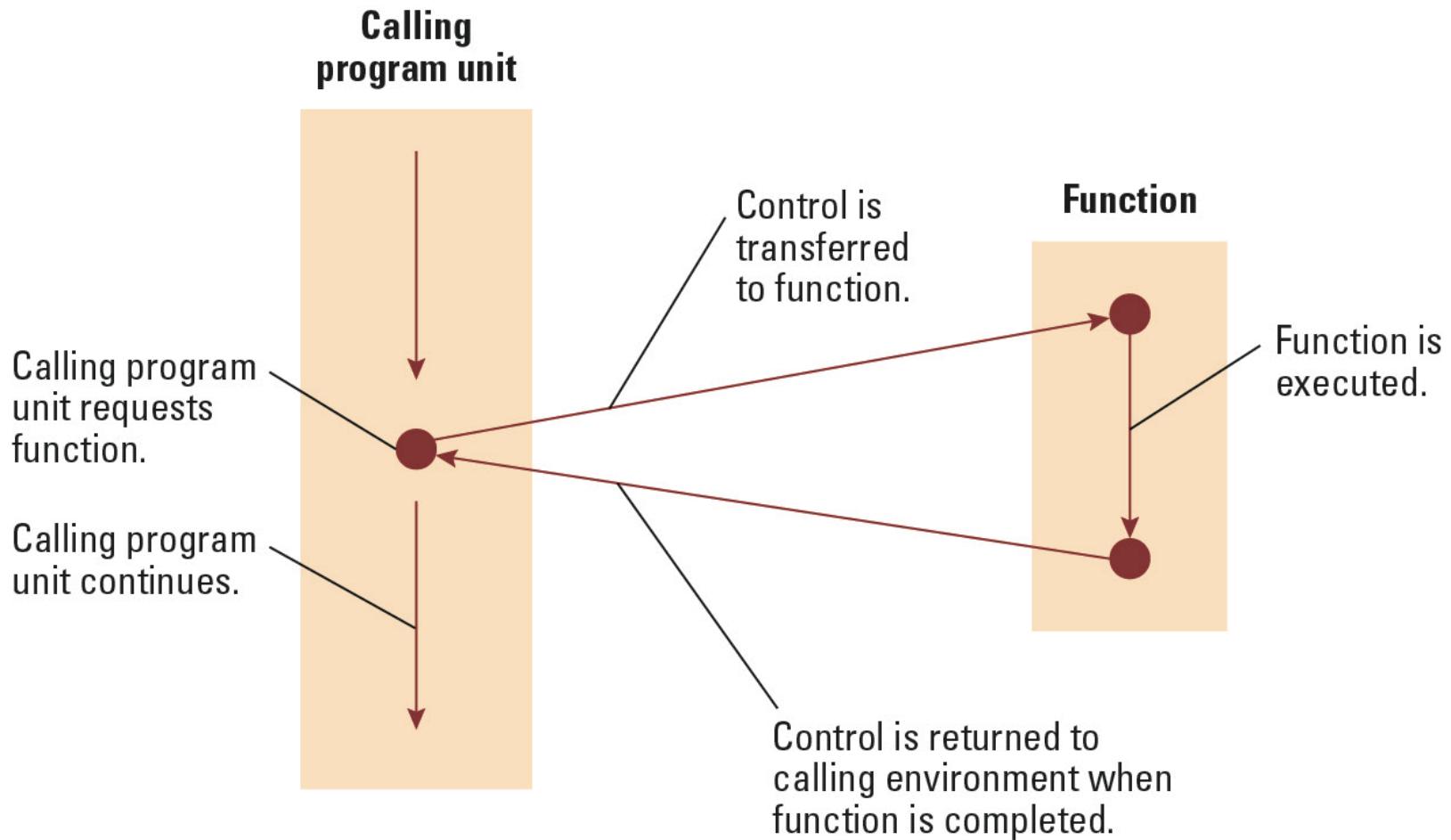


Figure 6.9 The function ProjectPopulation written in the programming language C

Starting the header with the term “void” is the way that a C programmer specifies that the program unit returns no value. We will learn about return values shortly.

The formal parameter list. Note that C, as with many programming languages, requires that the data type of each parameter be specified.

```
void ProjectPopulation (float GrowthRate)
{
    int Year; // This declares a local variable named Year.

    Population[0] = 100.0;
    for (Year = 0; Year <= 10; Year++)
        Population[Year+1] = Population[Year] + (Population[Year] * GrowthRate);
}
```

These statements describe how the populations are to be computed and stored in the global array named Population.

Figure 6.12 The fruitful function CylinderVolume written in the programming language C

```
float CylinderVolume (float Radius, float Height)
{
    float Volume;
    Volume = 3.14 * Radius * Radius * Height;
    return Volume;
}
```

The function header begins with the type of the data that will be returned.

Declare a local variable named Volume.

Compute the volume of the cylinder.

Terminate the function and return the value of the variable Volume.

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6.3 Procedural Units

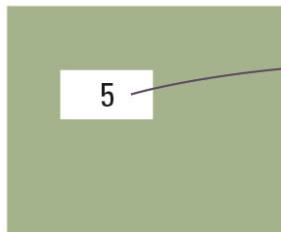
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Figure 6.10

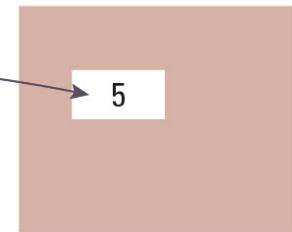
Executing the function Demo and passing parameters by value

- a. When the function is called, a copy of the data is given to the function

Calling environment

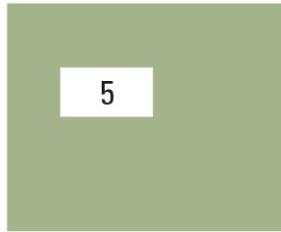


Function's environment

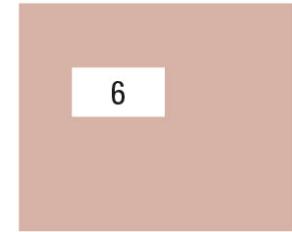


- b. and the function manipulates its copy.

Calling environment



Function's environment



- c. Thus, when the function has terminated, the calling environment has not been changed.

Calling environment

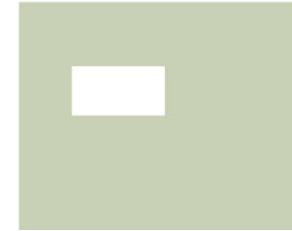
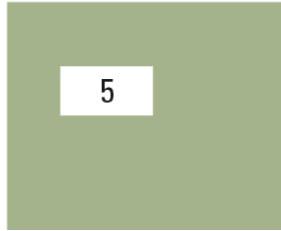
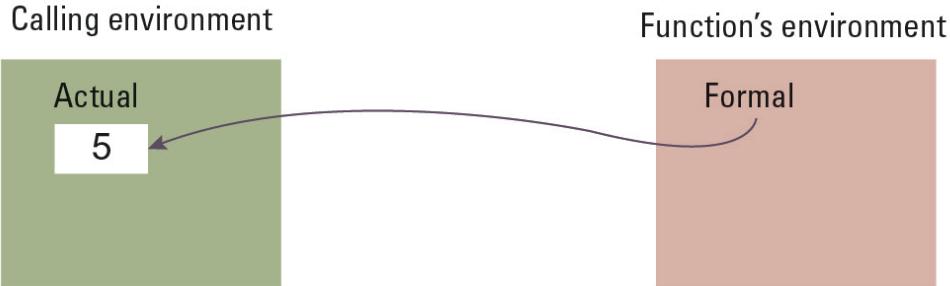


Figure 6.11

Executing the function Demo and passing parameters by reference

- a. When the function is called, the formal parameter becomes a reference to the actual parameter.



- b. Thus, changes directed by the function are made to the actual parameter



- c. and are, therefore, preserved after the function has terminated.



6.4 Language Implementation

- The process of converting a program written in a high-level language into a machine-executable form.
 - The Lexical Analyzer recognizes which strings of symbols represent a single entity, or token.
 - The Parser groups tokens into statements, using syntax diagrams to make parse trees.
 - The Code Generator constructs machine-language instructions to implement the statements.

Figure 6.13 The translation process

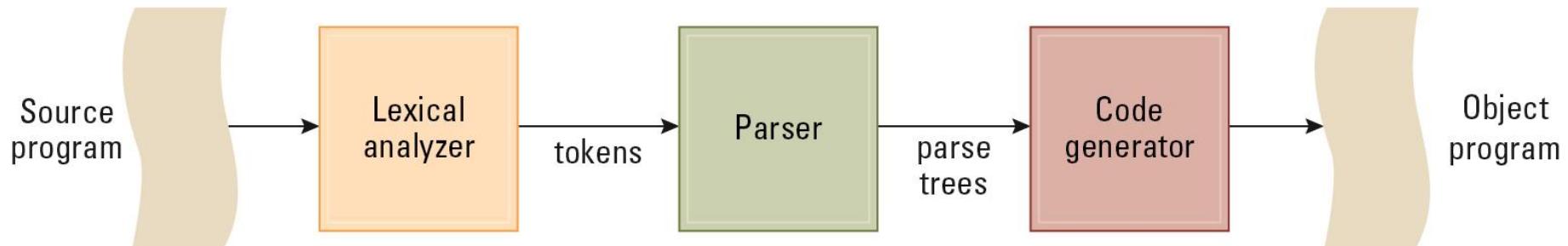


Figure 6.14 A syntax diagram of Python's if-then-else statement

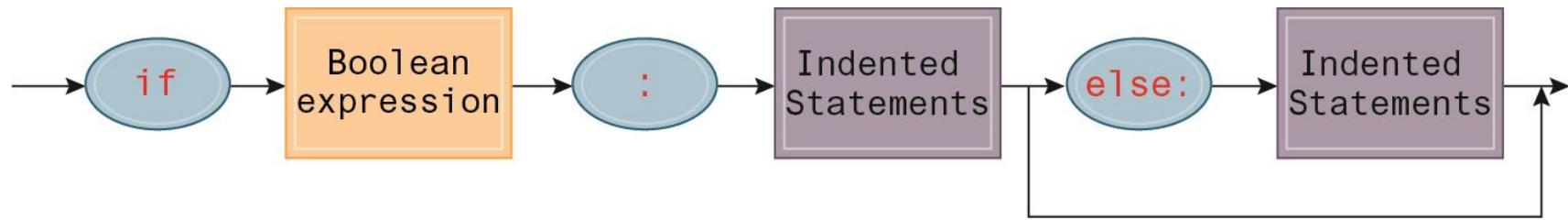


Figure 6.15 Syntax diagrams describing the structure of a simple algebraic expression

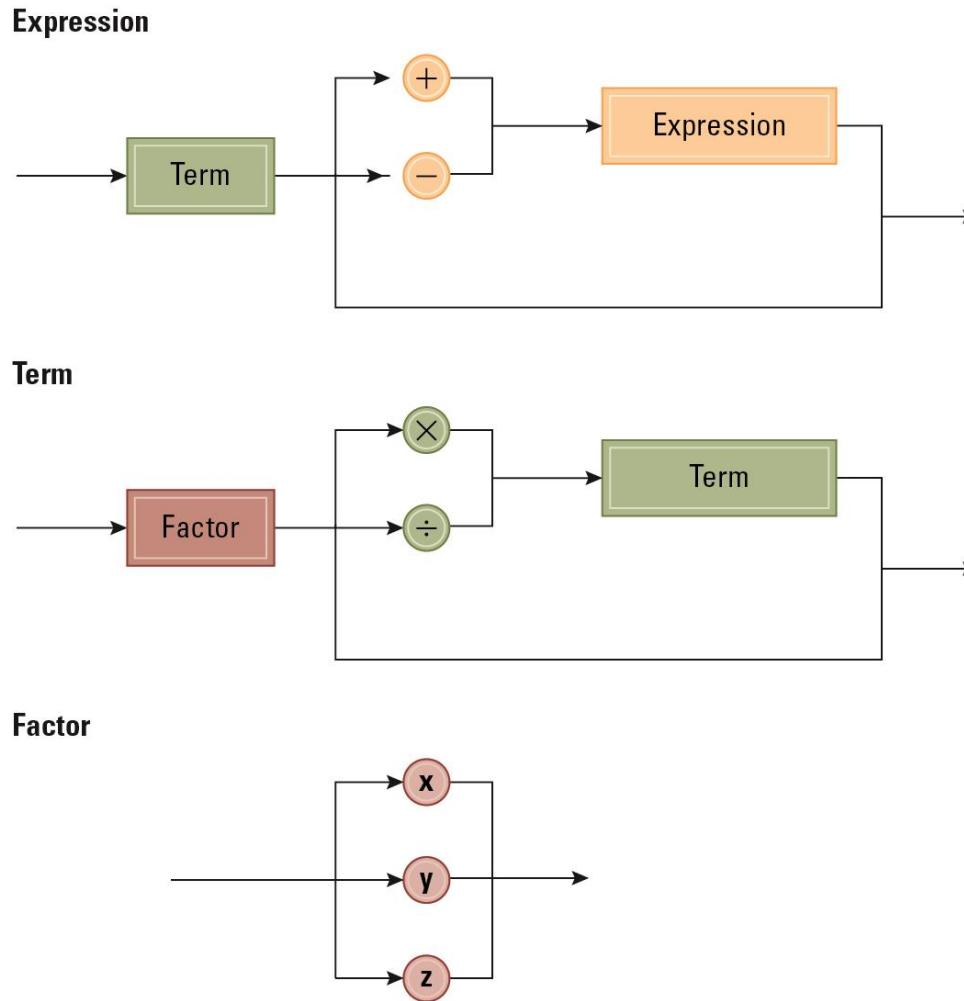
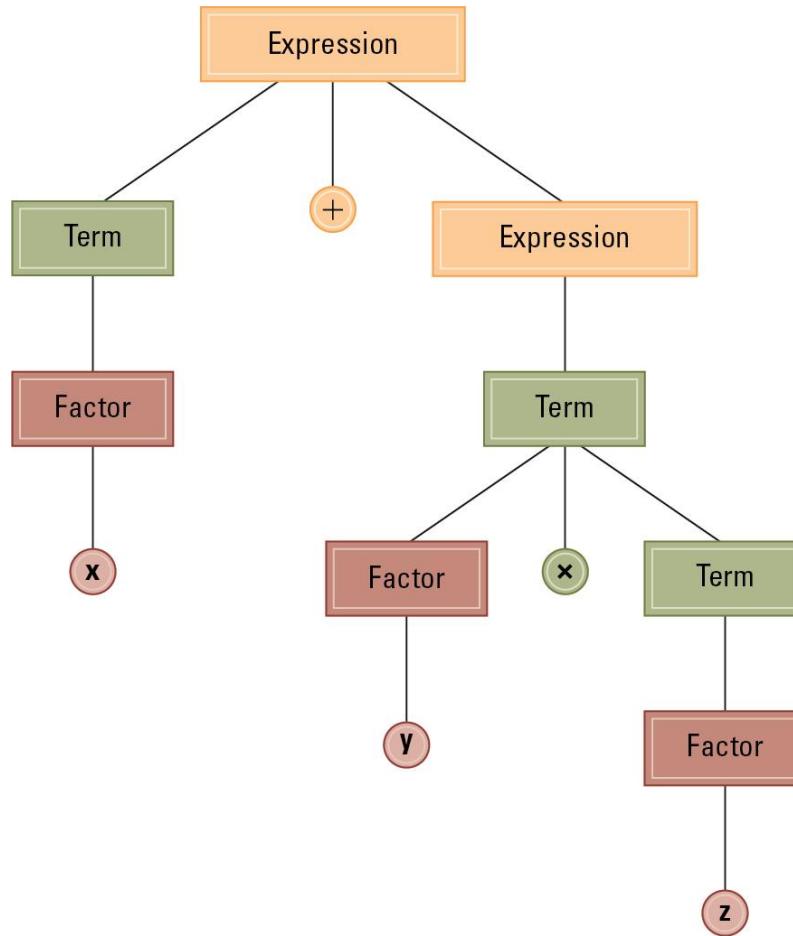


Figure 6.16 The parse tree for the string $x + y * z$ based on the syntax diagrams in Figure 6.17



**Figure 6.17 Two distinct parse trees for the statement
if B1 then if B2 then
S1 else S2**

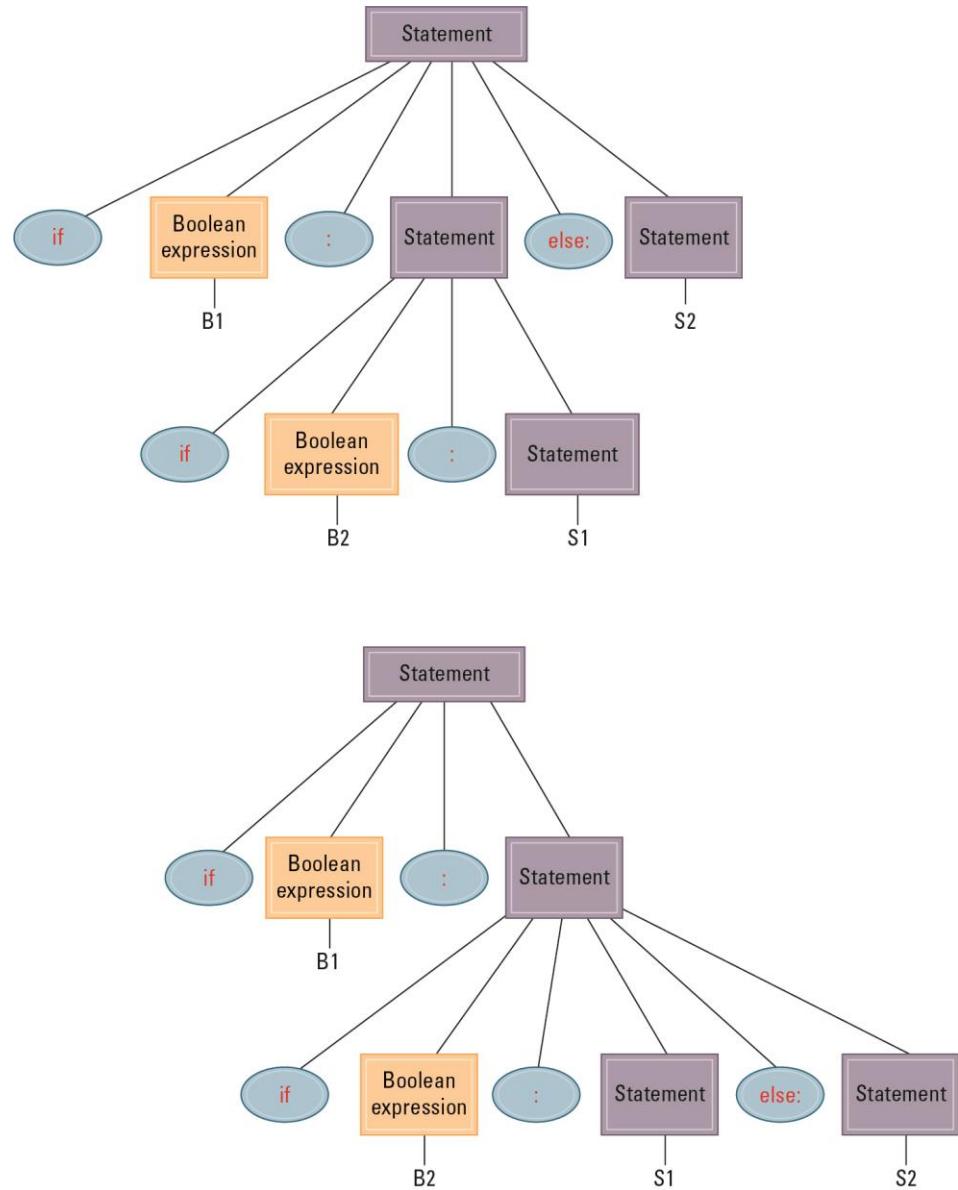
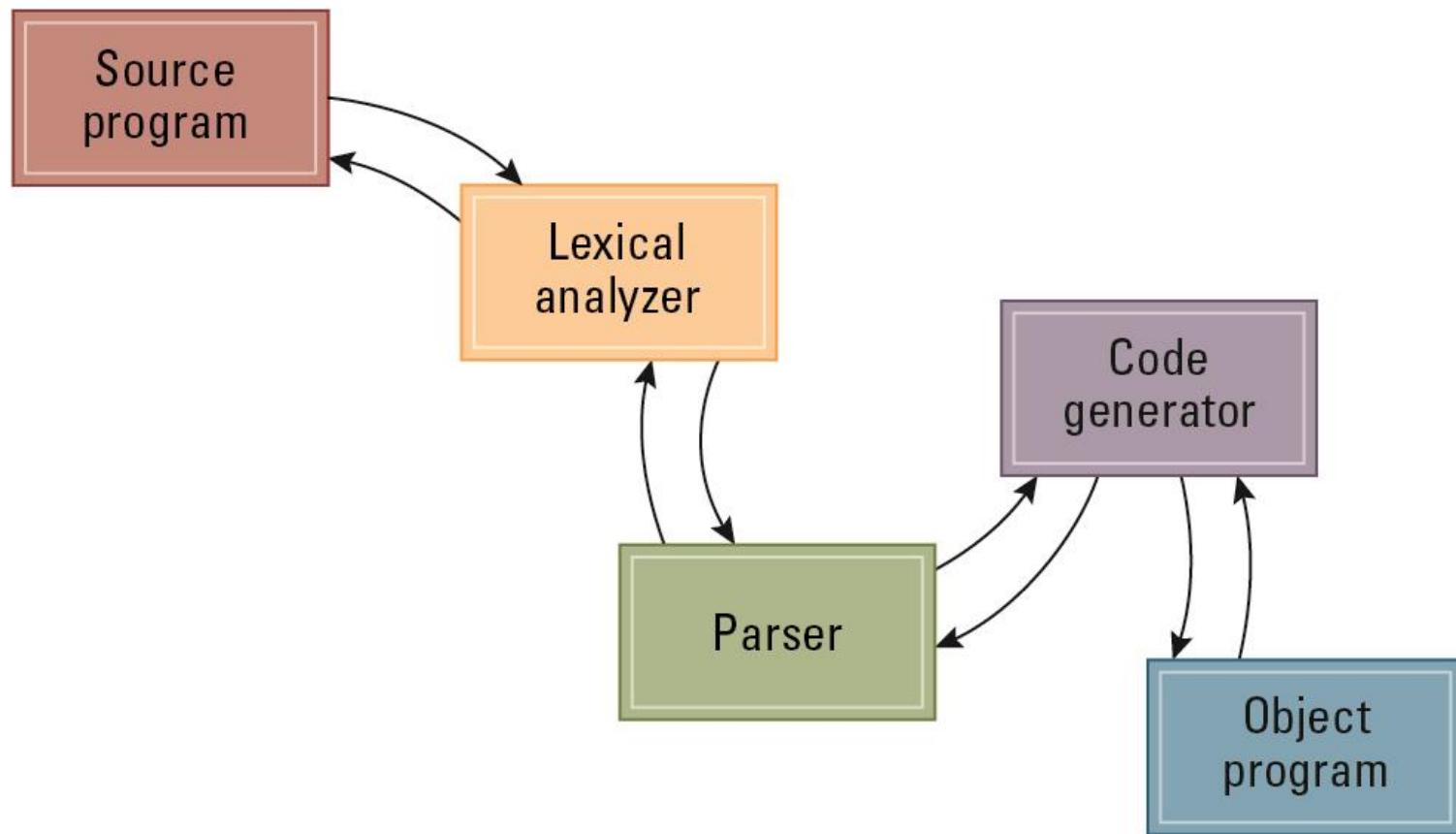


Figure 6.18 An object-oriented approach to the translation process



6.5 Object-Oriented Programming

- **Object:** Active program unit containing both data and procedures
- **Class:** A template from which objects are constructed

An object is called an **instance** of the class.

Figure 6.19 The structure of a class describing a laser weapon in a computer game

```
class LaserClass
{
    int RemainingPower = 100;           Description of the data
                                         that will reside inside of
                                         each object of this “type”.
    void turnRight()                  Methods describing how an
    { ... }                           object of this “type” should
                                         respond to various messages.
    void turnLeft()                  Methods describing how an
    { ... }                           object of this “type” should
                                         respond to various messages.
    void fire()
    { ... }
}
```

Components of an Object

- **Instance Variable:** Variable within an object
 - Holds information within the object
- **Method:** Procedure within an object
 - Describes the actions that the object can perform
- **Constructor:** Special method used to initialize a new object when it is first constructed

Figure 6.21 A class with a constructor

```
class LaserClass
{ int RemainingPower;
LaserClass(InitialPower)
{ RemainingPower = InitialPower;
}
void turnRight()
{ . . . }
void turnLeft()
{ . . . }
void fire()
{ . . . }
}
```

Constructor assigns a value to RemainingPower when an object is created.

Object Integrity

- **Encapsulation:** A way of restricting access to the internal components of an object
 - Private
 - Public

Figure 6.22 Our LaserClass definition using encapsulation as it would appear in a Java or C# program

Components in the class are designated public or private depending on whether they should be accessible from other program units.

```
class LaserClass
{private int RemainingPower;
public LaserClass (InitialPower)
{RemainingPower = InitialPower;
}
public void turnRight ( )
{...}
public void turnLeft ( )
{...}
public void fire ( )
{...}
}
```

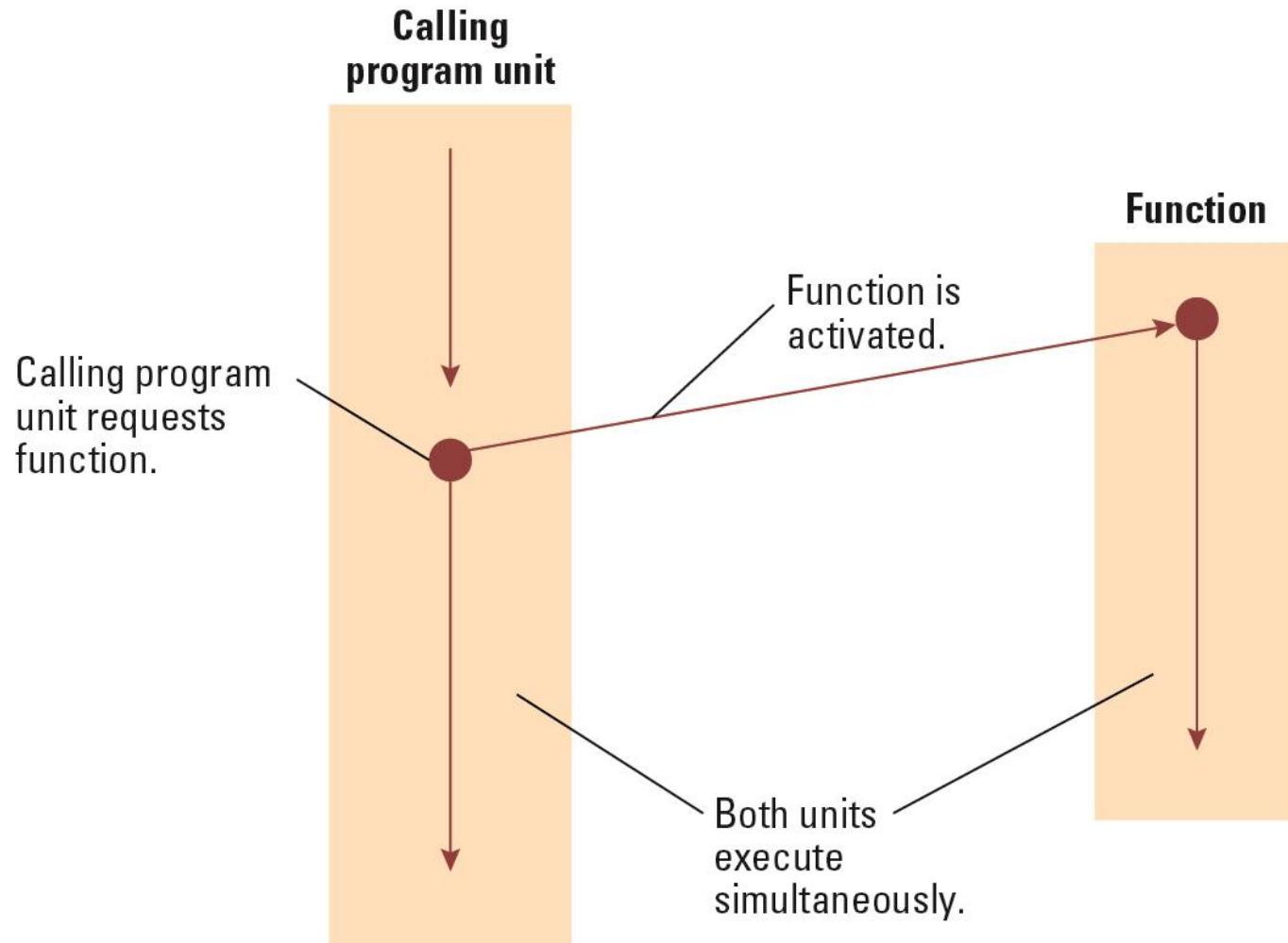
Additional Object-oriented Concepts

- **Inheritance:** Allows new classes to be defined in terms of previously defined classes
- **Polymorphism:** Allows method calls to be interpreted by the object that receives the call

6.6 Programming Concurrent Activities

- **Parallel (or concurrent) processing:** simultaneous execution of multiple processes
 - True concurrent processing requires multiple CPUs
 - Can be simulated using time-sharing with a single CPU

Figure 6.23 Spawning threads



Controlling Access to Data

- **Mutual Exclusion:** A method for ensuring that data can be accessed by only one process at a time
- **Monitor:** A data item augmented with the ability to control access to itself

6.7 Declarative Programming

- **Resolution:** Combining two or more statements to produce a new statement (that is a logical consequence of the originals).
 - Example: $(P \text{ OR } Q) \text{ AND } (R \text{ OR } \neg Q)$ resolves to $(P \text{ OR } R)$
 - **Resolvent:** A new statement deduced by resolution
 - **Clause form:** A statement whose elementary components are connected by the Boolean operation OR
- **Unification:** Assigning a value to a variable so that two statements become “compatible.”

Figure 6.24 Resolving the statements $(P \text{ OR } Q)$ and $(R \text{ OR } \neg Q)$ to produce $(P \text{ OR } R)$

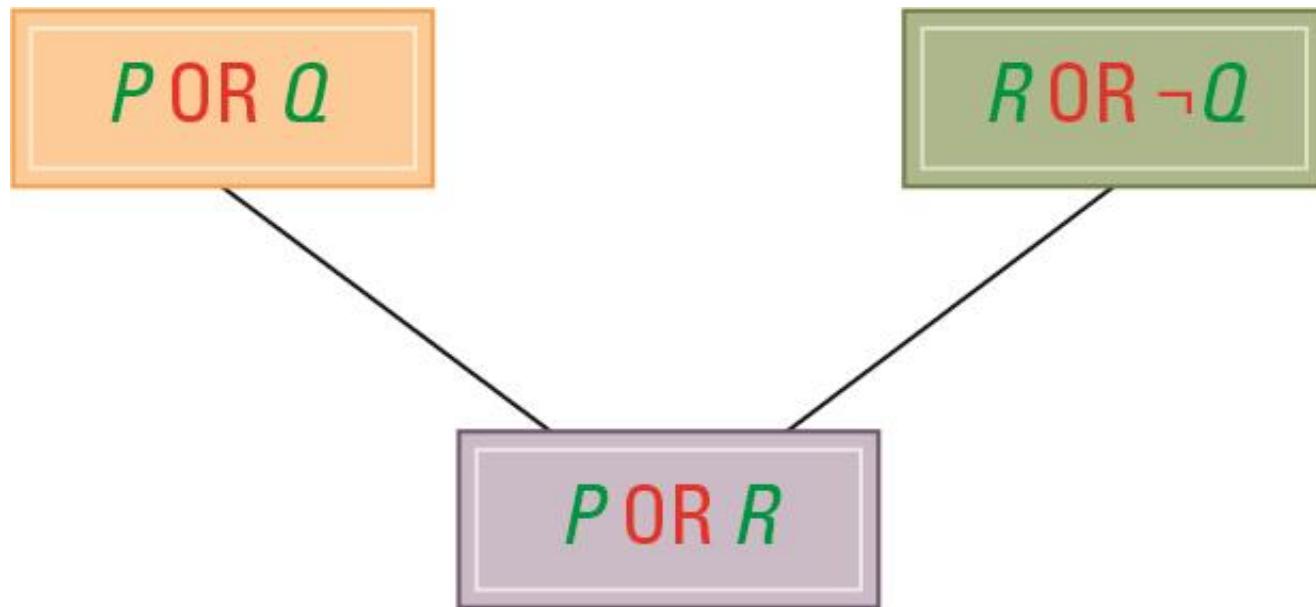
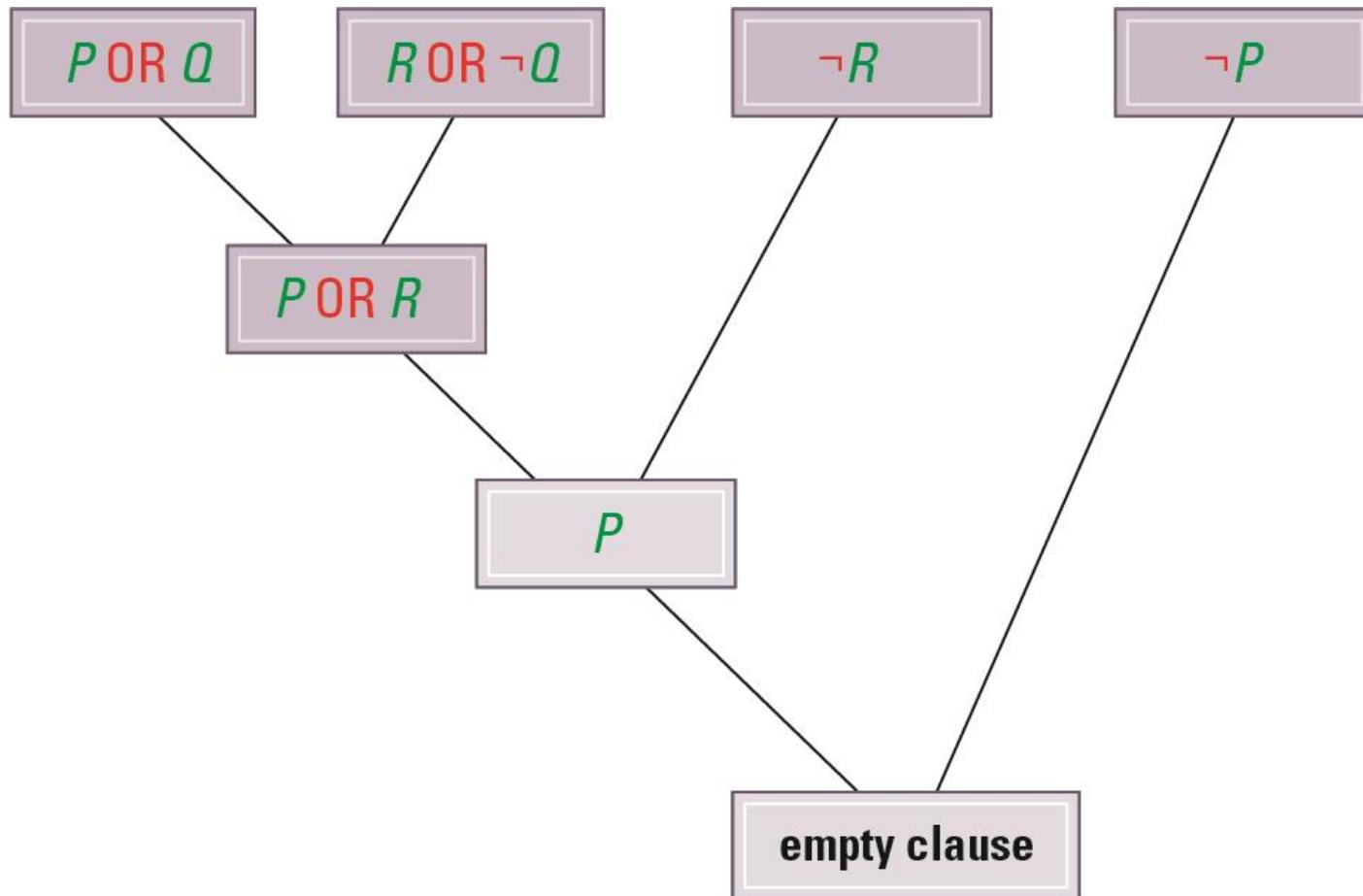


Figure 6.25 Resolving the statements $(P \text{ OR } Q)$, $(R \text{ OR } \neg Q)$, $\neg R$, and $\neg P$



Prolog

- **Fact:** A Prolog statement establishing a fact
 - Consists of a single predicate
 - Form: *predicateName(arguments)*.
 - Example: `parent(bill, mary) .`
- **Rule:** A Prolog statement establishing a general rule
 - Form: *conclusion :- premise.*
 - `:-` means “if”
 - Example: `wise(X) :- old(X) .`
 - Example: `faster(X, Z) :- faster(X, Y), faster(Y, Z) .`