

# Elliptic parametrization of the Zamolodchikov model

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Collaboration:

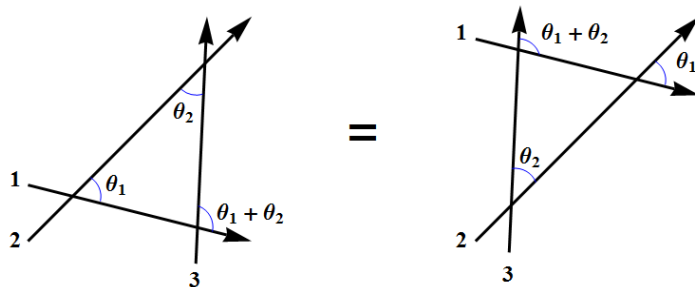
V.Bazhanov, Y. Okada (ANU, Canberra) and S.Sergeev (UC, Canberra)

The tetrahedron equation is a 3D generalization of the YBE equation.

- 3D Zamolodchikov model of straight strings (1981,1982)
  - A “static limit” solution of the TE (1981)
  - A “full” solution of the TE (1982)
- Baxter’s results
  - Proof of the TE for the Zamolodchikov model (1983)
  - Criticality of the Zamolodchikov model (Baxter, Forrester, 1985)
  - Formulation as the 3D IRC statistical model, partition function (1986)
  - Hamiltonian limit (Baxter, Quispel, 1989)
- ZBB IRC  $N$ -state model (Bazhanov, Baxter (1992)
- First vertex results:
  - Korepanov’s results (1993): tetrahedral Zamolodchikov algebra and its realization, the “static” vertex solution of the TE
  - Hietarinta’s “planar” vertex solution of the TE
- A full vertex solution of the TE (Sergeev, M, Stroganov, 1995)
- Vertex-IRC duality of the SMS model and Zamolodchikov model (BMSS, 1996)

# Vertex versions of the YBE and TE

The Yang-Baxter equation with a “difference” property

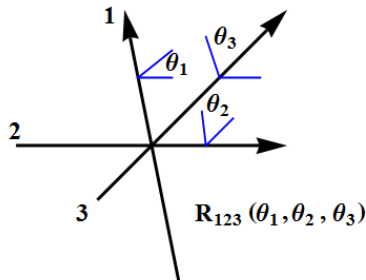
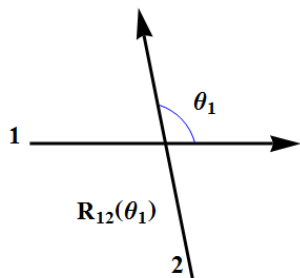


$$R_{12}(\theta_1)R_{13}(\theta_1 + \theta_3)R_{23}(\theta_3) = R_{23}(\theta_3)R_{13}(\theta_1 + \theta_3)R_{12}(\theta_1)$$

where for our case  $R_{12}(\theta)$  is a linear operator acting in  $\mathbb{C}^2 \times \mathbb{C}^2$ .

# Vertex versions of the YBE and TE

The most natural way to generalize to 3D is to replace  $R_{12}$  acting in  $\mathbb{C}^2 \times \mathbb{C}^2$  by  $R_{123}$  acting in  $\mathbb{C}^2 \times \mathbb{C}^2 \times \mathbb{C}^2$



# Vertex versions of the YBE and TE

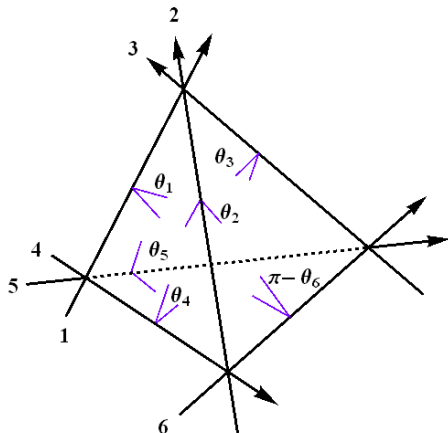
$$R \rightarrow R(\theta_1, \theta_2, \theta_3)$$

$$R' \rightarrow R(\theta_1, \theta_4, \theta_5)$$

$$R'' \rightarrow R(\pi - \theta_2, \theta_4, \theta_6)$$

$$R''' \rightarrow R(\theta_3, \pi - \theta_5, \theta_6)$$

+A quadrilateral constraint



$$R_{123} R'_{145} R''_{246} R'''_{356} = R'''_{356} R''_{246} R'_{145} R_{123}$$

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$$\begin{array}{cccc}
R_{0,0,0}^{0,0,0} = & R_{0,1,1}^{0,1,1} = & R_{1,0,1}^{1,0,1} = & R_{1,1,0}^{1,1,0} = & 1 \\
R_{1,1,1}^{1,1,1} = & R_{1,0,0}^{1,0,0} = & R_{0,1,0}^{0,1,0} = & R_{0,0,1}^{0,0,1} = & t_0 t_1 t_2 t_3 \\
R_{0,0,1}^{0,1,0} = & R_{0,1,0}^{0,0,1} = & -R_{1,1,1}^{1,0,0} = & -R_{1,0,0}^{1,1,1} = & t_2 t_3 \\
R_{1,1,0}^{1,0,1} = & R_{1,0,1}^{1,1,0} = & -R_{0,0,0}^{0,1,1} = & -R_{0,1,1}^{0,0,0} = & t_0 t_1 \\
R_{0,1,0}^{1,1,1} = & R_{0,0,1}^{1,0,0} = & -R_{1,0,0}^{0,0,1} = & -R_{1,1,1}^{0,1,0} = & -i t_1 t_3 \\
R_{1,0,1}^{0,0,0} = & R_{1,1,0}^{0,1,1} = & -R_{0,1,1}^{1,1,0} = & -R_{0,0,0}^{1,0,1} = & i t_0 t_2 \\
R_{1,1,1}^{0,0,1} = & R_{0,0,1}^{1,1,1} = & R_{0,1,0}^{1,0,0} = & R_{1,0,0}^{0,1,0} = & t_1 t_2 \\
R_{0,0,0}^{1,1,0} = & R_{1,1,0}^{0,0,0} = & R_{1,0,1}^{0,1,1} = & R_{0,1,1}^{1,0,1} = & t_0 t_3
\end{array}$$


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where

$$\alpha_0 = \frac{\theta_1 + \theta_2 + \theta_3 - \pi}{2}, \quad \alpha_i = \theta_i - \alpha_0$$

and

$$t_i = \sqrt{\tan \frac{\alpha_i}{2}}.$$

# Degenerate cases

- Korepanov's Static limit  
 $S_{123}(\theta_1, \theta_2, \theta_3) = R(\theta_1, \theta_2, \theta_3)$  provided  $\theta_1 + \theta_2 + \theta_3 = \pi$ . One can consistently satisfy this condition for all 4 weights leaving 4 independent parameters. Each weight depends on 2 angles.
- Hietarinta's Planar limit  
4 vertices of the tetrahedron belong to the same plane. Each vertex depends on 2 angles, there are 4 parameters in total.
- A new “infinite prizm” limit

$$\theta_1 + \theta_2 + \theta_3 = \pi, \quad \theta_4, \theta_5, \theta_6 \quad \text{are arbitrary}$$

Quadrilateral constraint is still nontirival and “kills” another parameter, say,  $\theta_2$ . Independent parameters are  $\theta_4, \theta_5, \theta_6$  and the angle between the vertical direction and the “bottom” (elliptic modulus).

# Parametrization

$$e^{i\theta_1} = \frac{\operatorname{cd}(2\lambda_2)}{\operatorname{cd}(2\lambda_1)}, \quad e^{i\theta_2} = -\frac{\operatorname{cd}(2\lambda_1)}{\operatorname{cd}(2\lambda_3)}, \quad e^{i\theta_3} = \frac{\operatorname{cd}(2\lambda_3)}{\operatorname{cd}(2\lambda_2)}, \quad \operatorname{cd}(x) = \frac{\operatorname{cn}(x)}{\operatorname{dn}(x)}$$

$$e^{-i\theta_4} = -\frac{(1 + \operatorname{sn}(2\lambda_1))(1 - k \operatorname{sn}(2\lambda_1))}{\operatorname{cn}(2\lambda_1)\operatorname{dn}(2\lambda_1)}, \quad e^{i\theta_5} = \frac{(1 + \operatorname{sn}(2\lambda_2))(1 - k \operatorname{sn}(2\lambda_2))}{\operatorname{cn}(2\lambda_2)\operatorname{dn}(2\lambda_2)},$$

$$e^{i\theta_6} = \frac{(1 + \operatorname{sn}(2\lambda_3))(1 - k \operatorname{sn}(2\lambda_3))}{\operatorname{cn}(2\lambda_3)\operatorname{dn}(2\lambda_3)}$$

$$\alpha_0 = \frac{\theta_1 + \theta_2 + \theta_3 - \pi}{2}, \quad \alpha_i = \theta_i - \alpha_0 \quad t_i = \sqrt{\tan \frac{\alpha_i}{2}}.$$

$$\phi(\lambda) = \frac{k'^2 \operatorname{sn} \lambda}{(\operatorname{cn} \lambda + \operatorname{dn} \lambda)(k \operatorname{cn} \lambda + \operatorname{dn} \lambda)}$$

$$t_0 = \sqrt{-i\phi(\lambda_-)/\phi(K - \lambda_+)}, \quad t_1 = \sqrt{i\phi(\lambda_-)\phi(K - \lambda_+)},$$

$$t_2 = \sqrt{-i\phi(K - \lambda_-)\phi(\lambda_+)}, \quad t_3 = \sqrt{i\phi(K - \lambda_-)/\phi(\lambda_+)}$$

where

$$\lambda_{\pm} = \lambda_1 \pm \lambda_2.$$



# The weights

$$L_{i,i_2,i_3}^{j,j_2,j_3} = \frac{1}{2} \sum_{n_2,n_3,m_2,m_3=0}^1 (-)^{i_2 n_2 + i_3 n_3 + j_2 m_2 + j_3 m_3} R_{i,n_2,n_3}^{j,m_2,m_3}$$

Collection of matrices  $L$ :

$$(L_0^0)_{2,3} = \begin{pmatrix} a & 0 & 0 & d \\ 0 & b & c & 0 \\ 0 & c & b & 0 \\ d & 0 & 0 & a \end{pmatrix}, \quad (L_1^1)_{2,3} = \begin{pmatrix} b & 0 & 0 & -c \\ 0 & a & -d & 0 \\ 0 & -d & a & 0 \\ -c & 0 & 0 & b \end{pmatrix}, \quad (1)$$

$$a = 1 - t_0 t_1 + t_2 t_3 + t_0 t_1 t_2 t_3, \quad b = 1 + t_0 t_1 - t_2 t_3 + t_0 t_1 t_2 t_3,$$

$$c = 1 + t_0 t_1 + t_2 t_3 - t_0 t_1 t_2 t_3, \quad d = 1 - t_0 t_1 - t_2 t_3 - t_0 t_1 t_2 t_3.$$

$$(L_0^1)_{2,3} = \begin{pmatrix} -a' & 0 & 0 & -d' \\ 0 & -b' & -c' & 0 \\ 0 & c' & b' & 0 \\ d' & 0 & 0 & a' \end{pmatrix}, \quad (L_1^0)_{2,3} = \begin{pmatrix} -b' & 0 & 0 & c' \\ 0 & -a' & d' & 0 \\ 0 & -d' & a' & 0 \\ -c' & 0 & 0 & b' \end{pmatrix}, \quad (2)$$

$$a' = -t_1 t_2 - t_0 t_3 + i t_0 t_2 + i t_1 t_3, \quad b' = -t_1 t_2 - t_0 t_3 - i t_0 t_2 - i t_1 t_3,$$

$$c' = -t_1 t_2 + t_0 t_3 + i t_0 t_2 - i t_1 t_3, \quad d' = -t_1 t_2 + t_0 t_3 - i t_0 t_2 + i t_1 t_3.$$

# Parametrization

$$a = \rho_- \operatorname{cd} \lambda_-, \quad b = \rho_- \operatorname{sn} \lambda_-, \quad c = \rho_-, \quad d = \rho_- k \operatorname{cd} \lambda_- \operatorname{sn} \lambda_-,$$

$$a' = \rho_+ \operatorname{cd} \lambda_+, \quad b' = \rho_+ \operatorname{sn} \lambda_+, \quad c' = \rho_+, \quad d' = \rho_+ k \operatorname{cd} \lambda_+ \operatorname{sn} \lambda_+,$$

$$\lambda_{\pm} = \lambda_1 \pm \lambda_2.$$

$$\rho_- = \frac{4(1 - \operatorname{sn} \lambda_-) \operatorname{dn} \lambda_-}{\operatorname{cn} \lambda_- (\operatorname{cn} \lambda_- \operatorname{dn} \lambda_- + (1 - \operatorname{sn} \lambda_-)(1 + k \operatorname{sn} \lambda_-))},$$

$$\rho_+ = -\rho_- \sqrt{\frac{\operatorname{cd}(\lambda_1 - \lambda_2) \operatorname{sn}(\lambda_1 - \lambda_2)}{\operatorname{cd}(\lambda_1 + \lambda_2) \operatorname{sn}(\lambda_1 + \lambda_2)}}$$

The tetrahedron equation becomes

$$\sum_{b_1, b_2, b_3} S_{a_1, a_2, a_3}^{b_1, b_2, b_3} (L_{b_1}^{c_1})_{4,5}(\lambda_1, \lambda_2) (L_{b_2}^{c_2})_{4,6}(\lambda_1, \lambda_3) (L_{b_3}^{c_3})_{5,6}(\lambda_2, \lambda_3) =$$

$$\sum_{b_1, b_2, b_3} (L_{a_3}^{b_3})_{5,6}(\lambda_2, \lambda_3) (L_{a_2}^{b_2})_{4,6}(\lambda_1, \lambda_3) (L_{a_1}^{b_1})_{4,5}(\lambda_1, \lambda_2) S_{b_1, b_2, b_3}^{c_1, c_2, c_3}$$

# Vacuum vectors and Tetrahedral algebra

Vacuum vectors

$$R v \otimes v' \otimes v'' = \lambda v \otimes v' \otimes v''.$$

When  $\theta_1 + \theta_2 + \theta_3 = \pi$ , one can take  $\lambda = 1$  and  $v = v' = v'' = (1, 0)$ .

Applying  $v \otimes v \otimes v$  to the TE from the left

$$\sum_{b_1, b_2, b_3} S_{a_1, a_2, a_3}^{b_1, b_2, b_3} (L_{b_1}^{c_1})_{4,5}(\lambda_1, \lambda_2) (L_{b_2}^{c_2})_{4,6}(\lambda_1, \lambda_3) (L_{b_3}^{c_3})_{5,6}(\lambda_2, \lambda_3) =$$

$$\sum_{b_1, b_2, b_3} (L_{a_3}^{b_3})_{5,6}(\lambda_2, \lambda_3) (L_{a_2}^{b_2})_{4,6}(\lambda_1, \lambda_3) (L_{a_1}^{b_1})_{4,5}(\lambda_1, \lambda_2) S_{b_1, b_2, b_3}^{c_1, c_2, c_3}$$

we get

$$L_{12}^a(\lambda_1, \lambda_2) L_{1,3}^b(\lambda_1, \lambda_3) L_{2,3}^c(\lambda_2, \lambda_3) = \sum_{def} S_{abc}^{def} L_{2,3}^f(\lambda_2, \lambda_3) L_{1,3}^e(\lambda_1, \lambda_3) L_{1,2}^d(\lambda_1, \lambda_2)$$

where  $L_{1,2}^a(\lambda_1, \lambda_2) = (L_0^a)_{1,2}(\lambda_1, \lambda_2)$ , etc.

This is the tetrahedral Zamolodchikov algebra used by Korepanov (1993) to calculate the matrix  $S$  in the static limit.

THANK YOU