



---

# *Journal of Statistical Software*

MMMMMM YYYY, Volume VV, Issue II.

doi: 10.18637/jss.v000.i00

---

## **nonprobsvy – An R package for modern methods for non-probability surveys**

**Łukasz Chrostowski**  
Adam Mickiewicz University

**Piotr Chlebicki**   
Stockholm University

**Maciej Beręsewicz**   
Poznań University of Economics and Business

---

### **Abstract**

The abstract of the article.

*Keywords:* keywords, not capitalized, R.

---

## **1. Introduction**

This template demonstrates some of the basic LaTeX that you need to know to create a JSS article.

### **1.1. Code formatting**

In general, don't use Markdown, but use the more precise LaTeX commands instead:

- `Java`
- `plyr`

One exception is inline code, which can be written inside a pair of backticks (i.e., using the Markdown syntax).

If you want to use LaTeX commands in headers, you need to provide a `short-title` attribute. You can also provide a custom identifier if necessary. See the header of Section 2 for example.

## 2. Methods for non-probability samples R code

### 2.1. Basic setup

Let  $U = \{1, \dots, N\}$  denote the target population consisting of  $N$  labelled units. Each unit  $i$  has an associated vector of auxiliary variables  $\mathbf{x}_i$  (a realisation of the random vector  $\mathbf{X}_i$  in the super-population) and the study variable  $y_i$  (a realisation of the random variable  $Y_i$  in the super-population). Let  $\{(y_i, \mathbf{x}_i), i \in S_A\}$  be a dataset of a non-probability sample of size  $n_A$  and let  $\{(\mathbf{x}_i, \pi_i), i \in S_B\}$  be a dataset of a probability sample of size  $n_B$ , where only information about variables  $\mathbf{X}$  and inclusion probabilities  $\pi$  (which in the super population model are also considered to be random variables) are available. Let  $\delta$  be an indicator of inclusion into non-probability sample. Each unit in the sample  $S_B$  has been assigned a design-based weight given by  $d_i = 1/\pi_i$ . The setting is summarised in Table ..

The goal is to estimate a finite population mean  $\mu_y = \frac{1}{N} \sum_{i=1}^N y_i$  of the target variable  $Y$ . As values of  $y_i$  are not observed in the probability sample, it cannot be used to estimate the target quantity. Instead, one could try combining the non-probability and probability samples to estimate  $\mu_y$ . In this paper we do not consider modifications for the possibly occurring overlap.

### 2.2. Mass Imputation estimators

### 2.3. Inverse Probability Weighting estimators

### 2.4. Doubly Robust estimators

Can be inserted in regular R markdown blocks.

```
R> x <- 1:10
R> x
```

```
[1] 1 2 3 4 5 6 7 8 9 10
```

### 2.5. Features specific to rarticles

- Adding short titles to section headers is a feature specific to **rarticles** (implemented via a Pandoc Lua filter). This feature is currently not supported by Pandoc and we will update this template if **it is officially supported in the future**.
- Using the \AND syntax in the **author** field to add authors on a new line. This is a specific to the **rarticles::jss\_article** format.

## 3. Package contents and implementation

## 4. Practical examples

**Affiliation:**

Lukasz Chrostowski

Pearson

First line

Second line

E-mail: [lukchr@st.amu.edu.pl](mailto:lukchr@st.amu.edu.pl)

URL: <https://posit.co>

Piotr Chlebicki

Stockholm University

Department of Statistics and Mathematics,

Faculty of Biosciences,

Universitat Autònoma de Barcelona

E-mail: [piotr.chlebicki@math.su.se](mailto:piotr.chlebicki@math.su.se)

Maciej Beręsewicz

Statistical Office in Poznań

Department of Statistics,

Institute of Informatics and Electronic Economy,

Poznań University of Economics and Business

E-mail: [maciej.beresewicz@ue.poznan.pl](mailto:maciej.beresewicz@ue.poznan.pl)

URL: <https://posit.co>