Nathan Corwin

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EDUCATION

Northwestern University , Evanston, I	Northwestern	University,	Evanston,	IL
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- **GPA**: 3.15
- **Relevant Coursework**: Robotic Manipulation, Embedded Systems, Dynamic Simulation, Mechatronics, Digital Image Analysis, Feedback Systems, Machine Learning, Optimal Control
- Projects: Designing jamming gripper for Baxter robot, Droplet placement system for PPOD Project

Trniity College, Hartford, CT

Bachelor of Science in Engineering, Mechanical Engineering Concentration......Graduated 2015

- **GPA**: 3.2
- Relevant Coursework: Introduction to Robotics and Design, Statics, Dynamics, Engineering Materials, Mechanics of Materials, Linear Algebra, Linear Circuit Theory, Automatic Control Systems, Introduction to Java Programming, Fluid Dynamics
- Electives: Studio Art, Psychology, Japanese, Tokyo History

SKILLS

- Machine Shop trained: competent in machining, metalworking, woodworking; experience with most power tools.
- Wiring and soldering.
- CAD software (Autodesk Inventor and SolidWorks) and Adobe Photoshop.
- Programming: Python, C, C++, C#, Basic Java, MATLAB, Mathematica, and Labview
- Linux, ROS
- Microsoft Holoense, Unity, Android Programming

LEADERSHIP & WORK EXPERIANCE

AIR, Northwestern University, Evanston, IL

- Engineer/Tech Expert
- Worked on Augmented Reality/Machine Learning combination on Hololense and Android
- Accepted to NU Garage 2016 Wildfire Accelerator

Engineers Without Borders, Trinity College, Hartford, CT

Independent Study 2013-2014

- Design Team: Designed latrines for Tanzanian Pre-school
- Media Team: Designed advertising materials; posters, pamphlets, flyers

Robot Study Team, Trinity College, Hartford, CT

- Placed 3rd in Trinity College Robowaiter International 2012 competition
- Won Connecticut Design award

X-IO, Colorado Springs, CO

Hardware Engineering and Shipping/Receiving Internship......Summer 2014, 2015

- Assisted Hardware team prototype new server components
- Took over duties in Shipping/Receiving