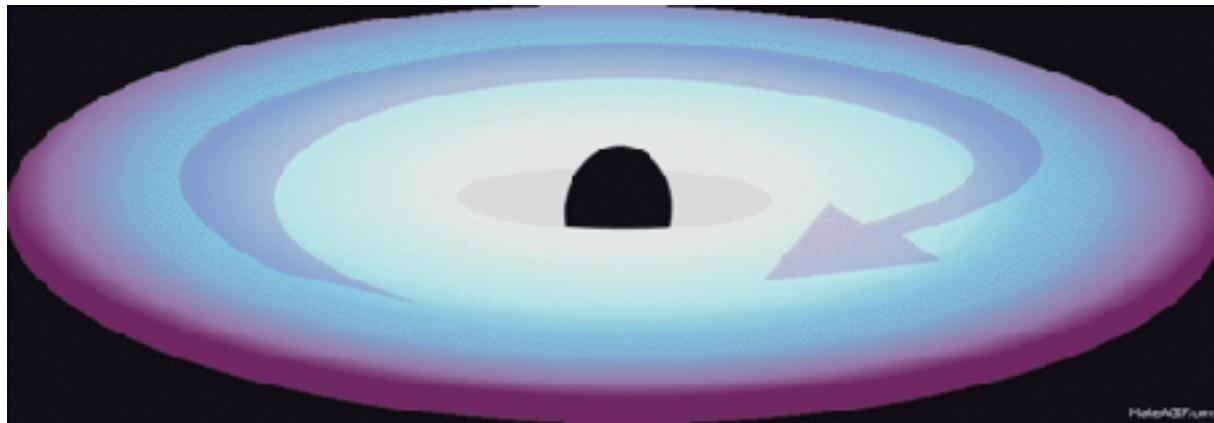
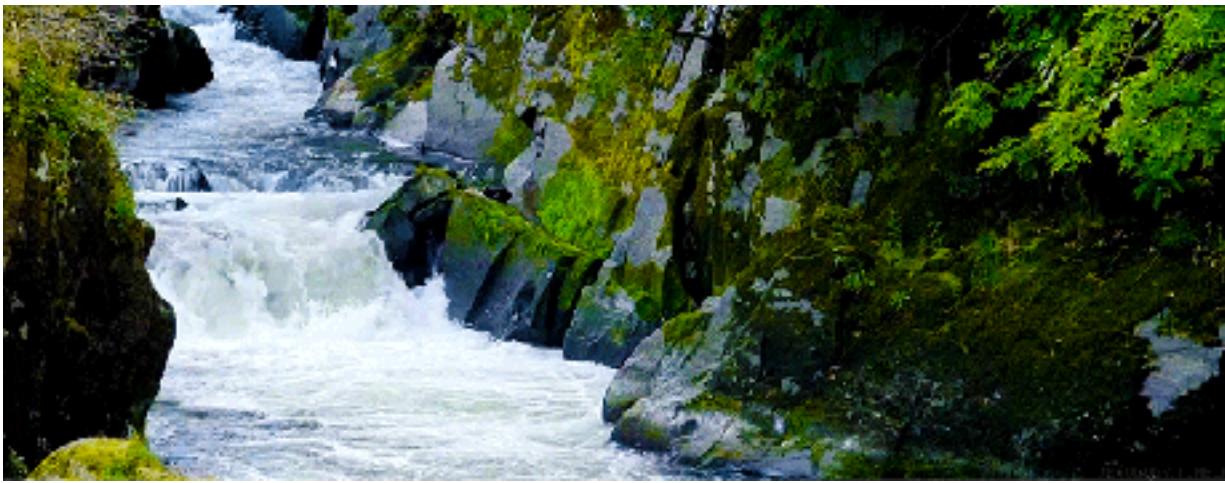


2024 NCTS-TCA summer student program workshop

Astrophysical fluid dynamics a brief introduction

Hung-Yi Pu (National Taiwan Normal University) July 1st 2024



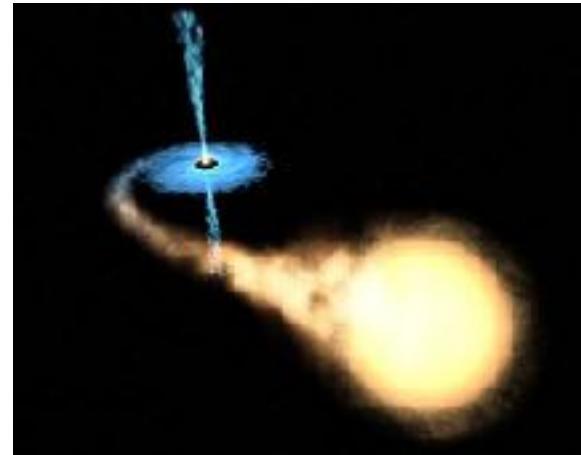
big pictures

- **liquid and gas** as fluid
 - as a collisional continuum
 - as a vector field
 - with thermodynamical properties
 - with viscosity
 - compressible, sound wave, and shock
- **plasma** as fluid
 - with conductivity
 - with EM interaction
- governing equations
 - conservation of mass, momentum, energy
 - continuity equation, $F=ma$, 1st law of thermodynamics

Astrophysical fluid dynamics?

Astrophysical fluid dynamics

- most of the baryonic matter (consists of three quarks) in the Universe can be treated as a fluid
- the liquid phase is less common
- **plasma**: magnetised fluid, interacting via EM interactions
- gravity is important (e.g. accretion)
- large scale



reference

- Astrophysical Flows by Pringle & King
- Principle of astrophysical fluid dynamics by Clarke & Carswell
- The physics of **plasmas** by Boyd & Sanderson
- The physics of fluids and **plasmas** by Choudhuri
- The physics of astrophysics volume II: **gas dynamics** by Shu
- Fluid Mechanics by Frank M. White

outline

- hydrodynamics (HD)
 - shear and viscosity
 - velocity field
 - governing equations
 - continuity
 - momentum
 - energy
 - turbulence and energy cascade
 - shock
- magnetohydrodynamics (MHD)
 - single fluid approach
 - plasma
 - ideal MHD
 - astrophysical applications



a macroscopic approach

“level”	neutral fluids		plasmas	
0	N quantum particles	Schrodinger's eqn	N quantum particles	Schrodinger's eqn
1	N classical particles	Newton's law	N classical particles	Newton's law
2	distribution function	Boltzmann eqn	distribution function	Vlassov eqn
				BBGKY hierarchy
3	continuum model	HD eqn	one-fluid model	MHD eqn

The physics of fluids and **plasmas** by Choudhuri

today we can only cover some key
concepts and conclusions

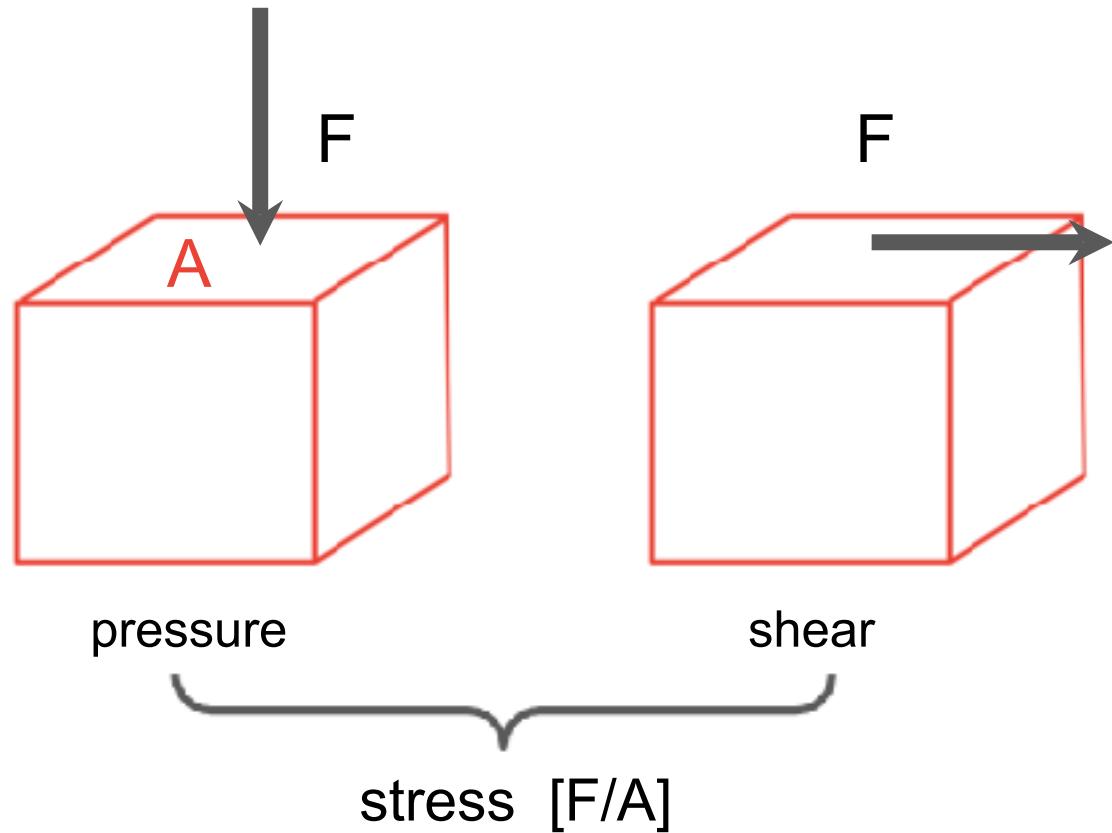
hydrodynamics

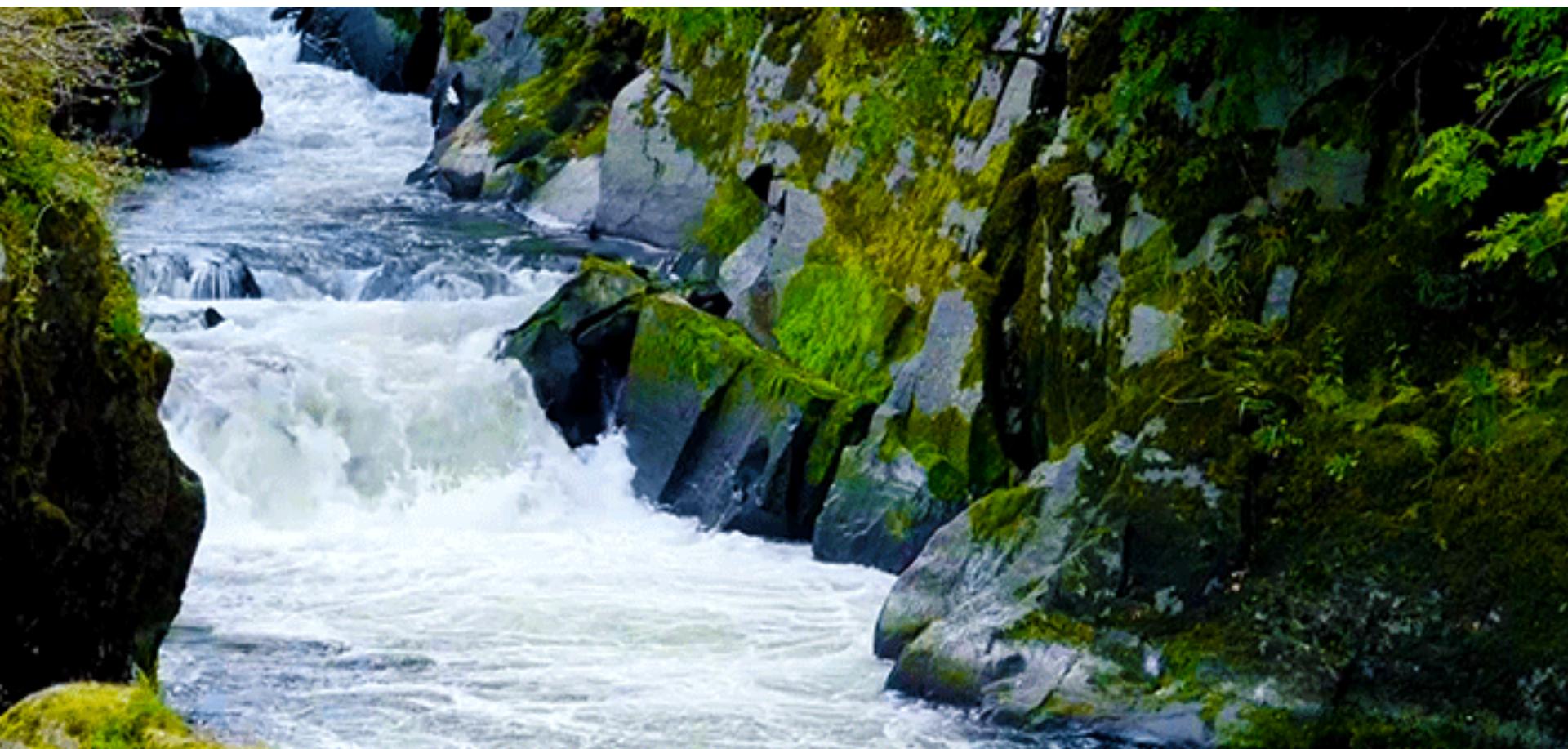
stress and shear

typical definition of fluid:

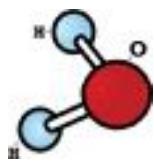
a fluid can move under the action of a **shear stress**, no matter how small that stress may be

materials {
solid
fluid { liquid
gas



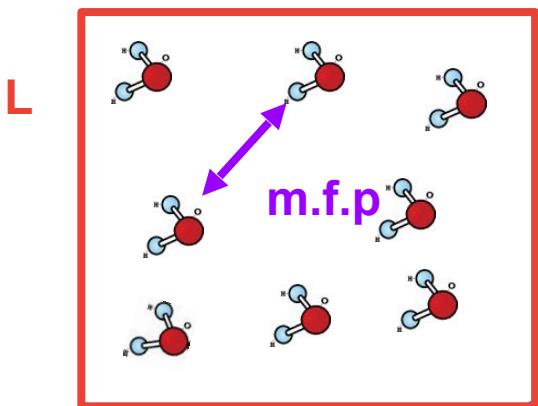


fluid: a macroscopic approach



$$L \gg m.f.p$$

fluid element



from water molecular to river



(not to scale)

mean free path (m.f.p): average distance a particle travels before it collides with another particle

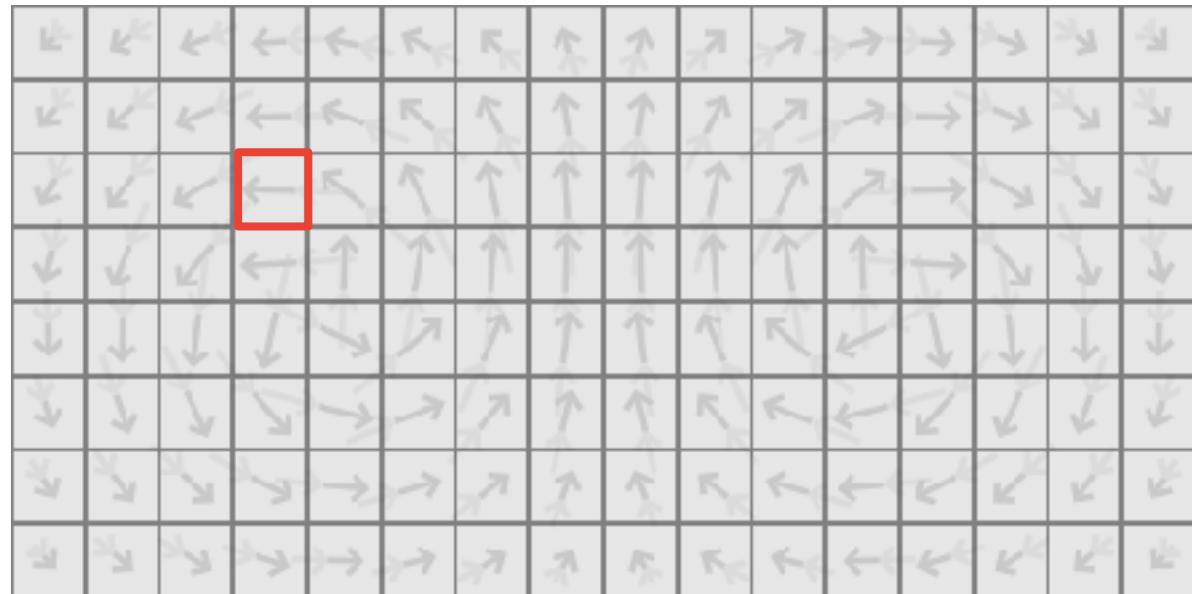
fluid dynamics as velocity field + fluid properties

t1: velocity field

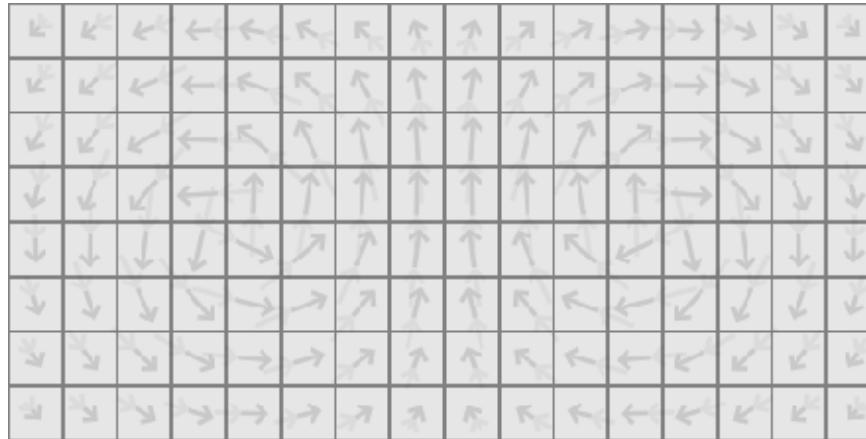


how?

t2: velocity field



velocity field



$$\nabla \cdot \vec{V}$$

relative change in volume per unit time if =0: incompressible

$$\nabla \times \vec{V}$$

vorticity: measure of local rotation if >0: counter-clockwise locally

common notation

- for 3D flow in cartesian coordinate

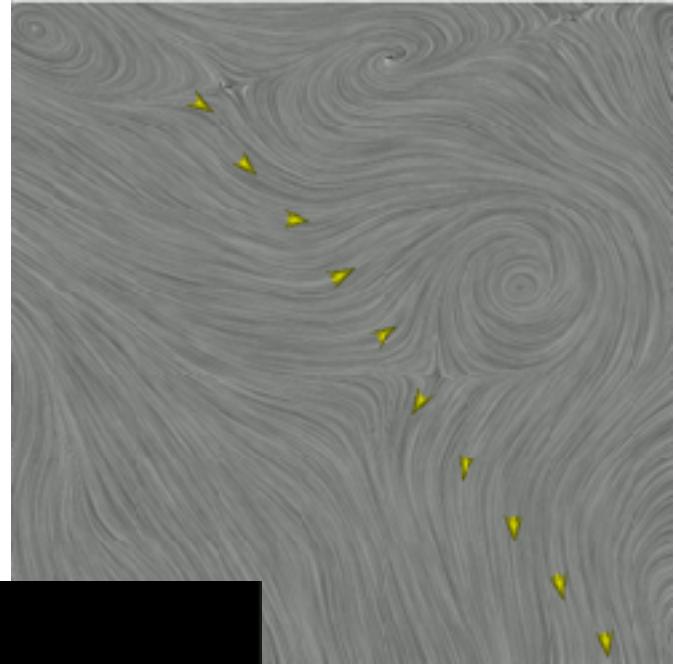
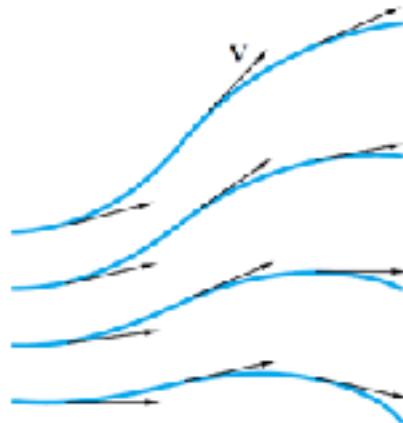
$$(V_x, V_y, V_z) = (u, v, w)$$

- for 2D flow

$$(V_x, V_y) = (u, v)$$

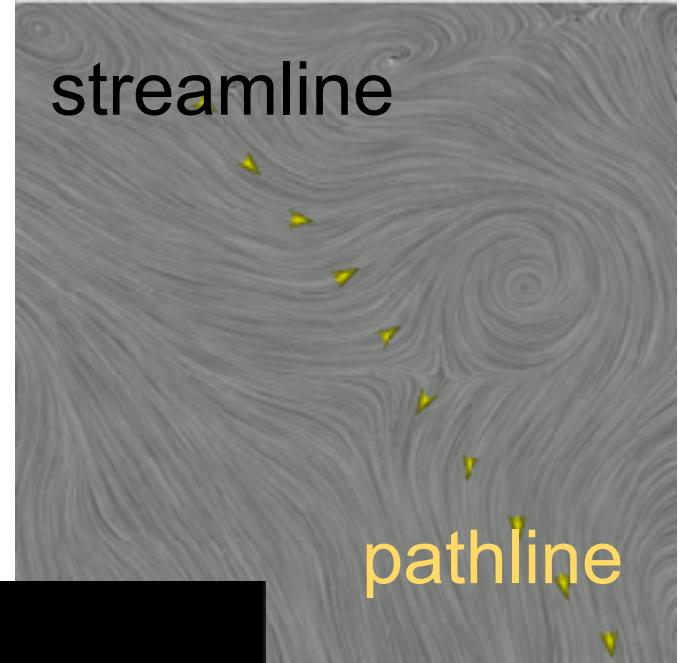
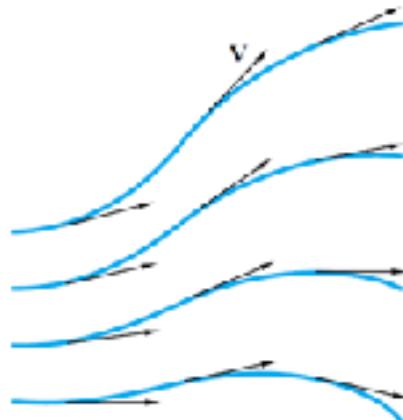
streamline (at the instant t):

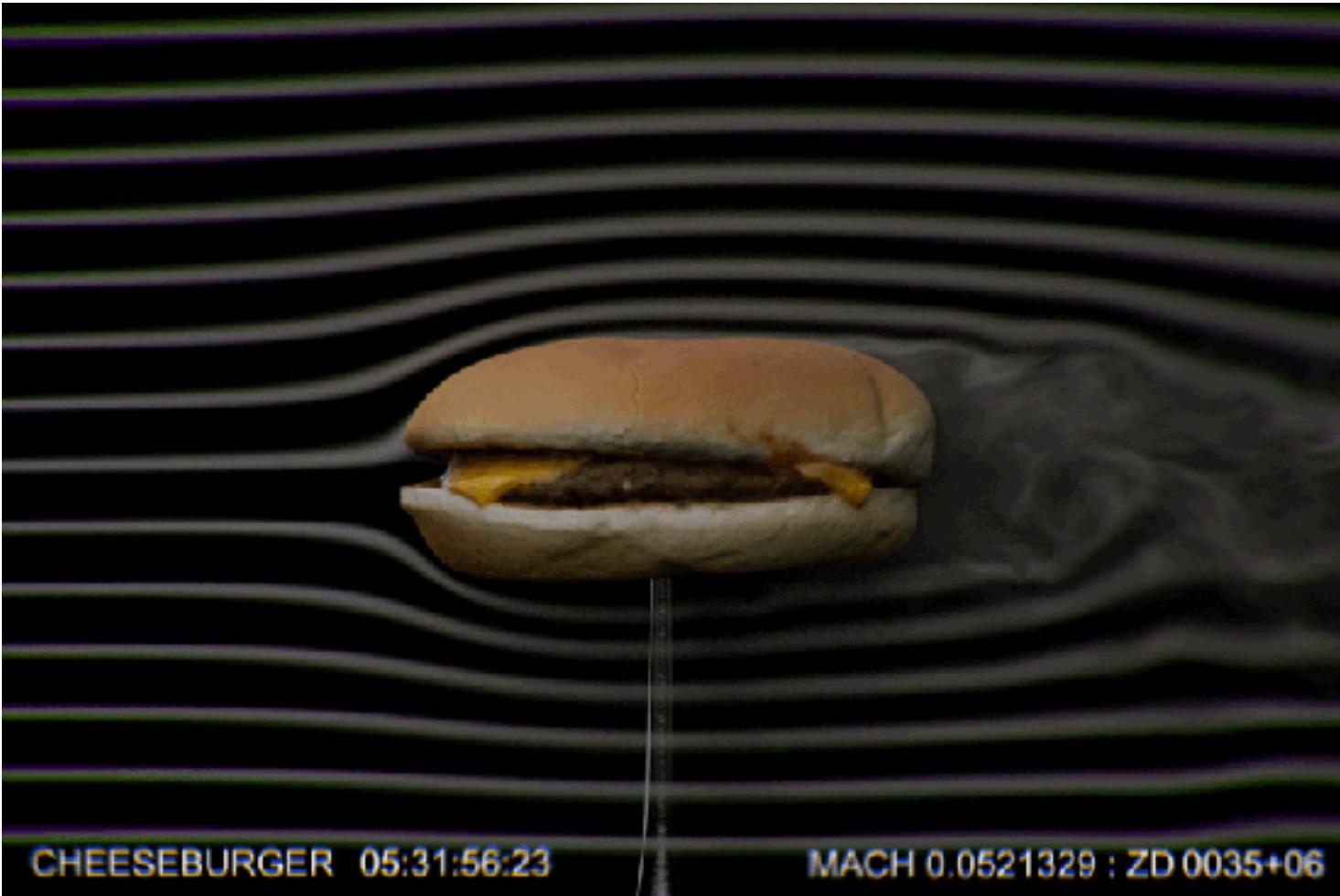
$$\frac{dx}{u} = \frac{dy}{v} = \frac{dz}{w} = \frac{dr}{V}$$



streamline (at the instant t):

$$\frac{dx}{u} = \frac{dy}{v} = \frac{dz}{w} = \frac{dr}{V}$$



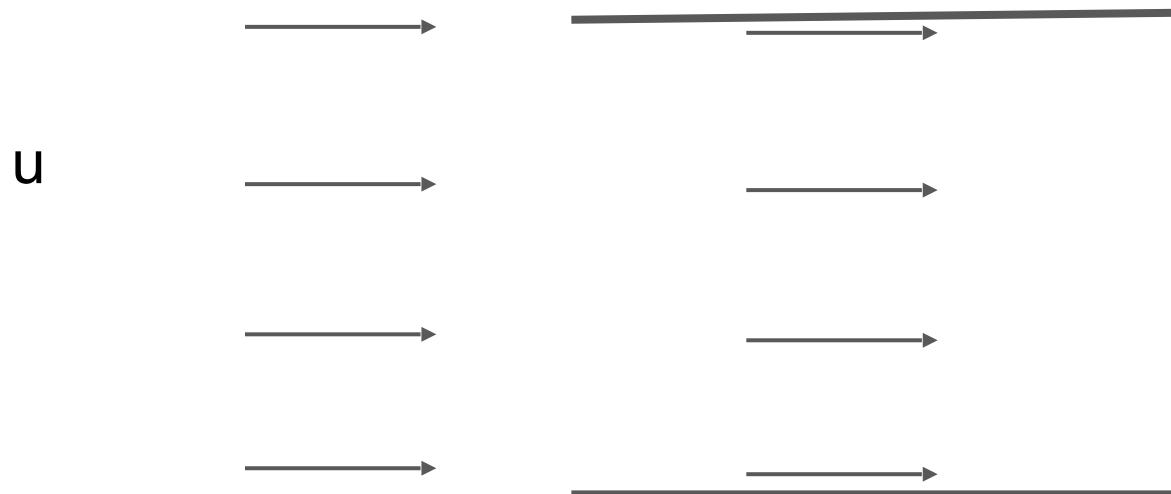


CHEESEBURGER 05:31:56:23

MACH 0.0521329 : ZD 0035+06

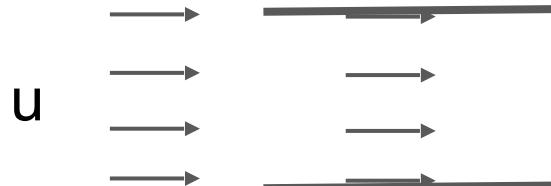
When steady ($\partial/\partial t = 0$),
all three lines are the same

example: velocity field of a steady flow in a pipe



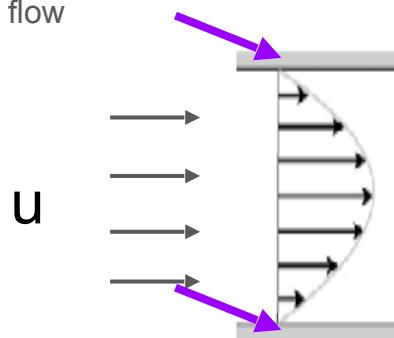
viscous and invicid (steady) flow

invicid flow

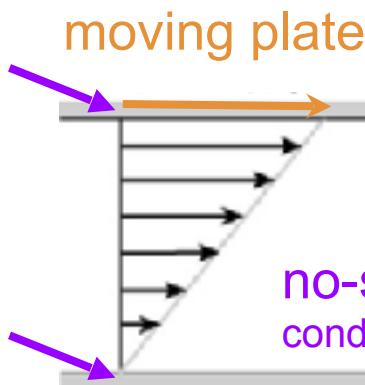


does not exist!

viscous flow



Poiseuille flow



Couette flow

(shear) stress causes strain (via viscosity)

measure of the resistance of a fluid to gradual deformations by shear stress

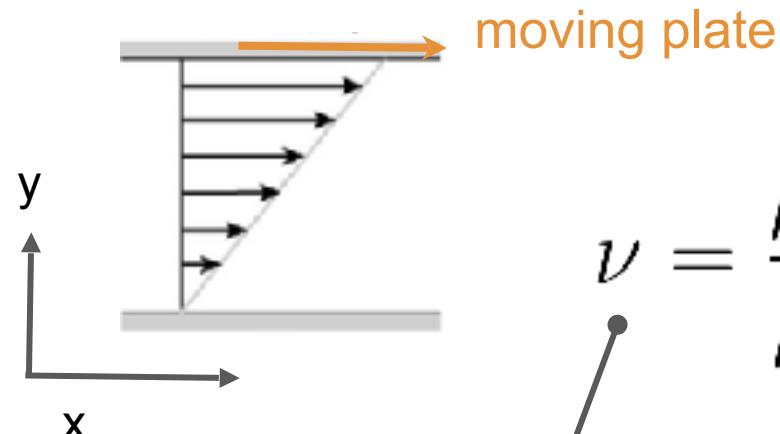
dynamic viscosity

$$\tau = \mu \frac{\partial u}{\partial y}$$

shear stress [F/A]

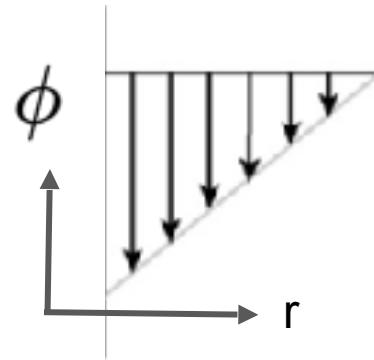
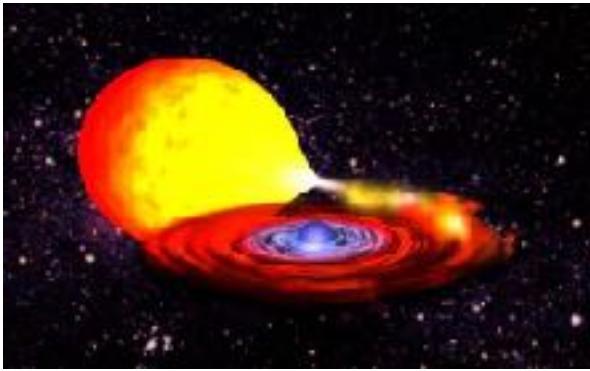
shear/strain rate [1/s]

stress = viscosity x strain



$$\nu = \frac{\mu}{\rho}$$

kinetic viscosity [VL]

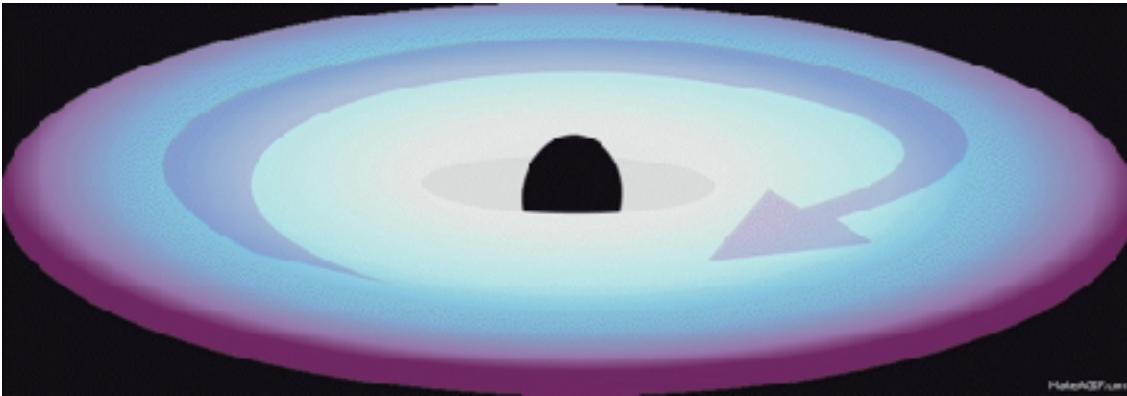


$$\omega_{\text{Kepler}} = \left(\frac{GM}{r^3} \right)^{1/2}$$

α - disk :

$$\nu = \alpha H C_s$$

kinetic viscosity [VL]

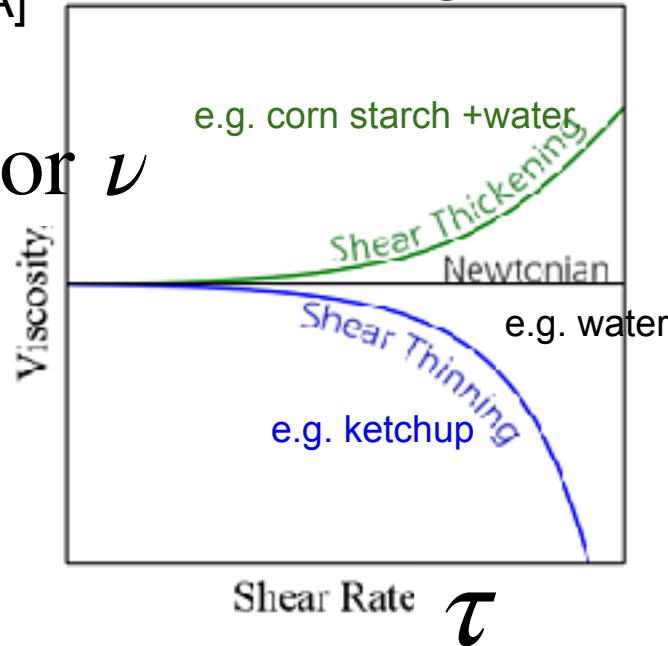


dynamic viscosity

$$\tau = \mu \frac{\partial u}{\partial y}$$

shear stress
[F/A]

μ or ν



shear/strain rate [1/s]



movie credit: 國立台中教育大學 NTCU

shearing
thickening!

Ketchup: shearing thinning!



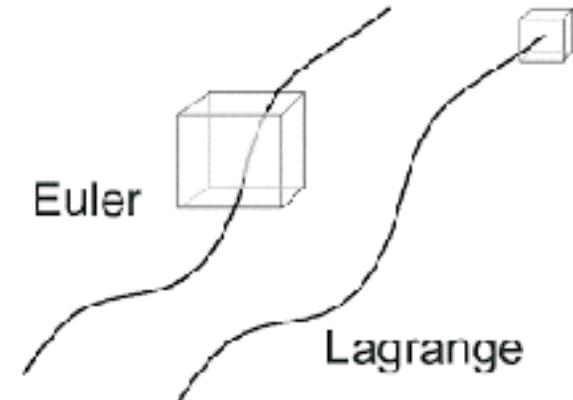
a tale of two views (for everything!)

substantial/material derivative

$$\frac{D}{Dt} \equiv \frac{d}{dt} = \frac{\partial}{\partial t} + (\vec{V} \cdot \nabla)$$

LHS: Lagragian point of view
(ride on the particles)

RHS: Eulerian point of view
(stay at the fixed grid)



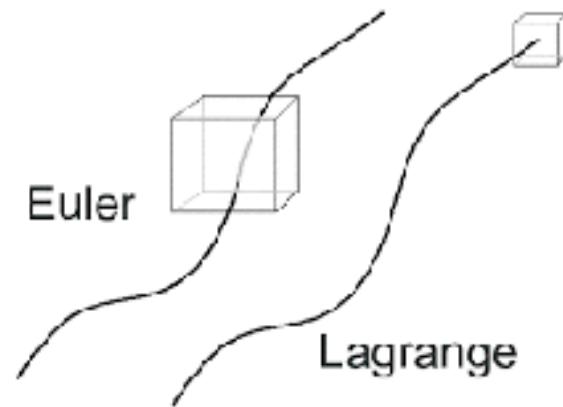
a tale of two views

substantial/**material derivative**

$$\frac{D}{Dt} = \frac{d}{dt} = \frac{\partial}{\partial t} + (\vec{V} \cdot \nabla)$$

proof

$$d\rho(t, x, y, z) = \frac{\partial \rho}{\partial t} dt + \frac{\partial \rho}{\partial x} dx + \frac{\partial \rho}{\partial y} dy + \frac{\partial \rho}{\partial z} dz$$
$$\frac{d}{dt}\rho = \left(\frac{\partial}{\partial t} + \frac{\partial}{\partial x} \frac{dx}{dt} + \frac{\partial}{\partial y} \frac{dy}{dt} + \frac{\partial}{\partial z} \frac{dz}{dt} \right) \rho$$

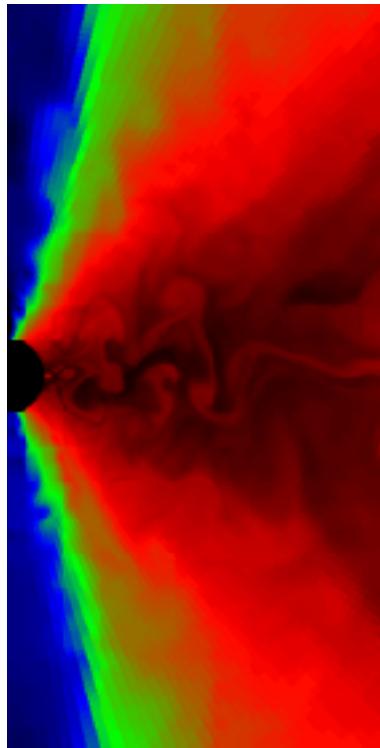


Eulerian

Lagrangian

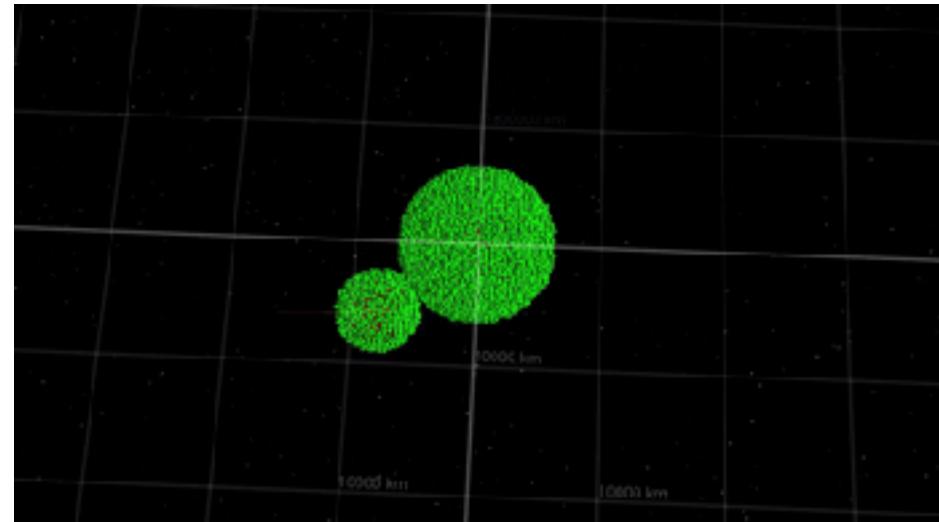


grid-based simulation



movie credit: Stone

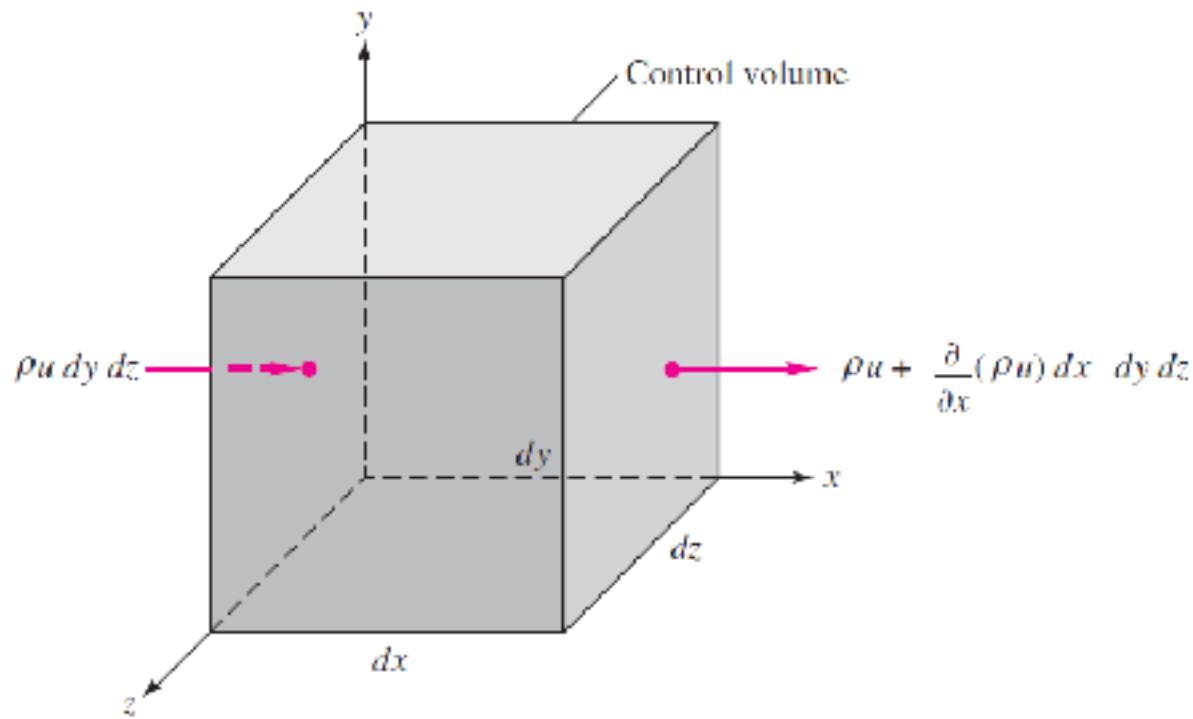
particle-based simulation



governing equation I:

continuity equation (mass conservation)

mass conservation

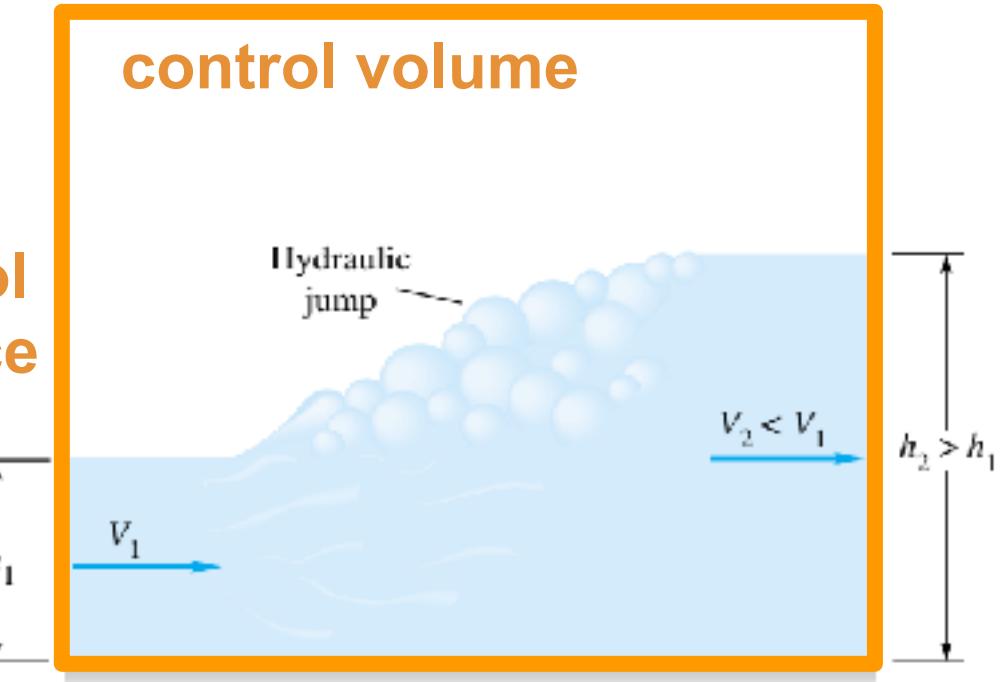


side note: integral form and differential form

hydraulic jump (水躍)

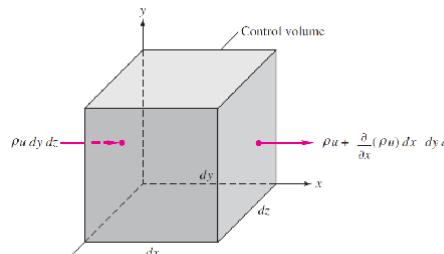


control
surface



control volume → 0 : differential form

mass conservation



Face	Inlet mass flow	Outlet mass flow
x	$\rho u dy dz$	$\left[\rho u + \frac{\partial}{\partial x} (\rho u) dx \right] dy dz$
y	$\rho v dx dz$	$\left[\rho v + \frac{\partial}{\partial y} (\rho v) dy \right] dx dz$
z	$\rho w dx dy$	$\left[\rho w + \frac{\partial}{\partial z} (\rho w) dz \right] dx dy$

conservation of mass (continuity equation): differential form

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{v}) = 0$$

$$\frac{D\rho}{Dt} + \rho(\nabla \cdot \mathbf{v}) = 0$$

$$(\mathbf{v} \cdot \nabla)\rho + \rho(\nabla \cdot \mathbf{v})$$

if incompressible ($\frac{D\rho}{Dt} = 0$) :

$$\nabla \cdot \mathbf{v} = 0$$

$$\nabla \cdot \mathbf{v} = \frac{\frac{d(\delta V)}{dt}}{\delta V} \quad \text{relative change in volume per unit time}$$

not necessarily zero!

if:

$$\frac{D\rho}{Dt} + \rho(\nabla \cdot \mathbf{v}) = 0$$

$\frac{D\rho}{Dt} = 0$ $\nabla \cdot \mathbf{v} = 0$

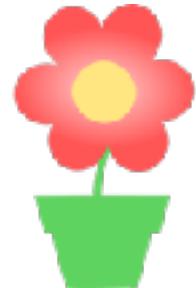
1D, steady, incompressible fluid is trivial!



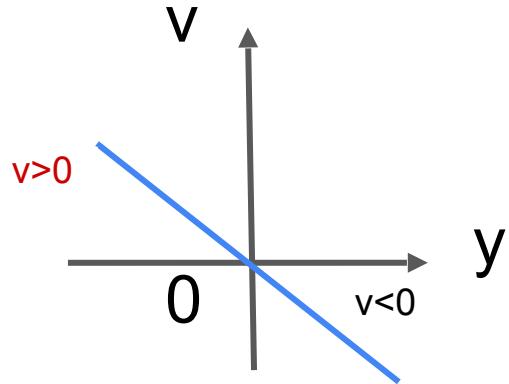
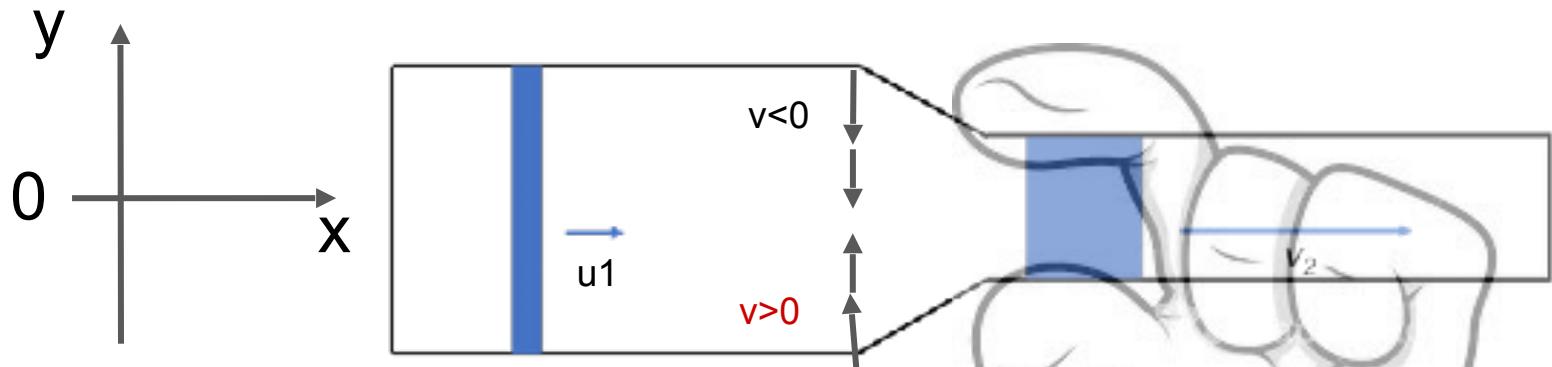
an example: 2D incompressible flow



what will you do?



an example: 2D incompressible flow



$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0$$

>0 <0

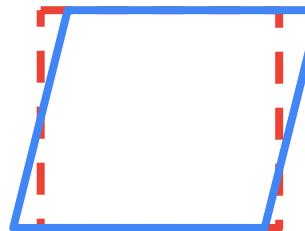
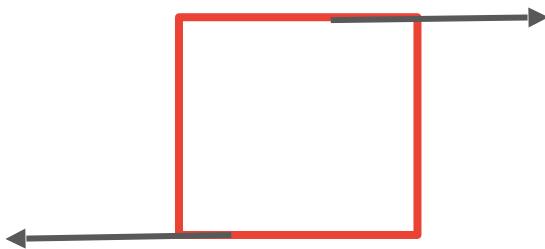
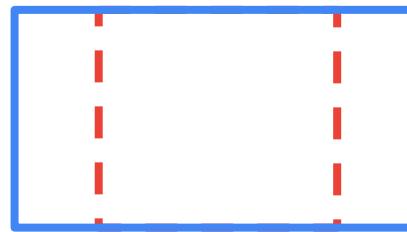
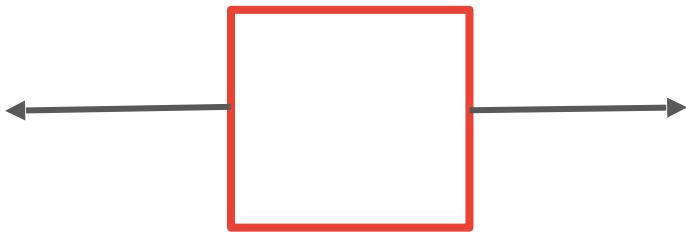
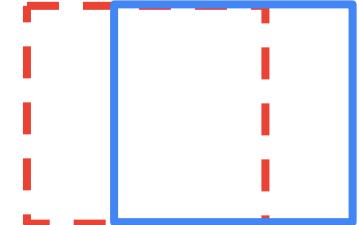
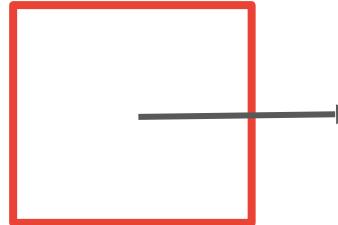
governing equation II:
momentum equation (Newton's 2nd law)

body force (acting on mass; does not require contact of the element)

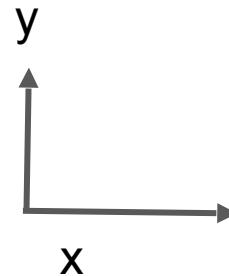
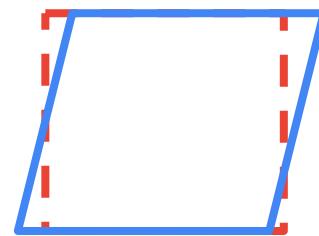
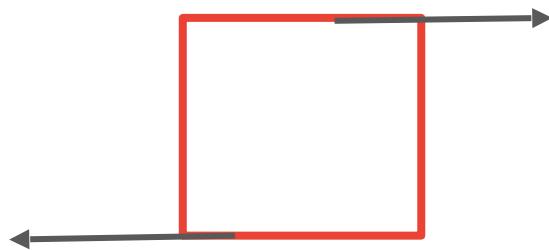
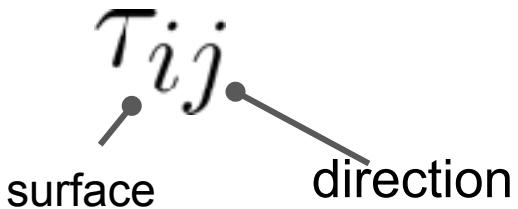
stress as a “surface force”

surface force

(acting on surface; requires contact of the element)



shear tensor



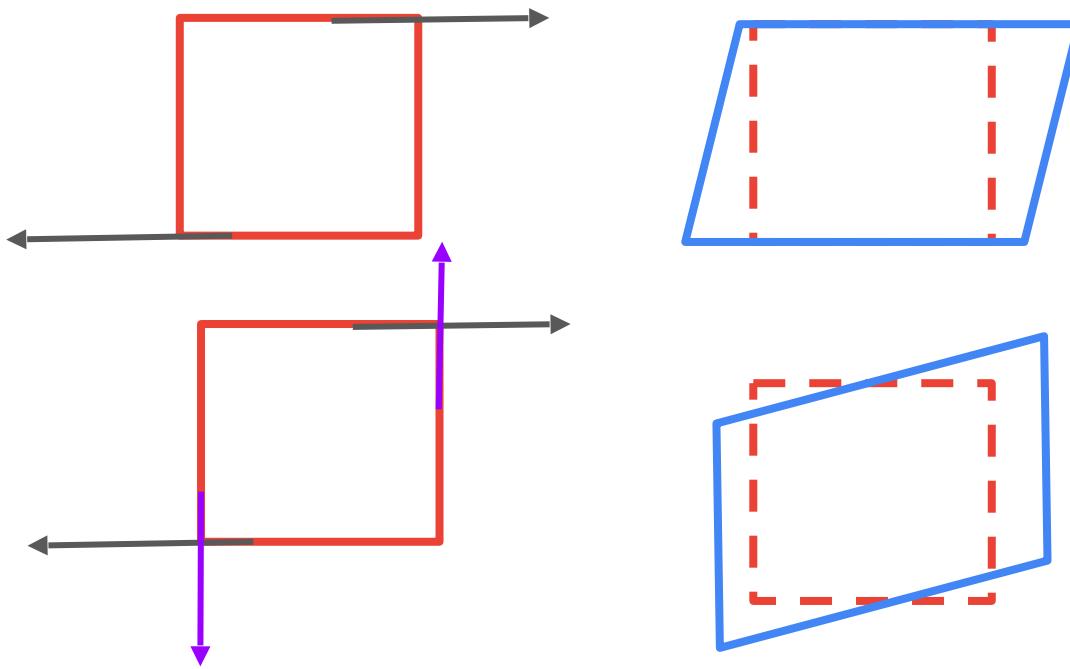
$$\tau_{yx} = \mu \frac{\partial u}{\partial y} \quad ?$$

shear tensor

τ_{ij}

surface

direction



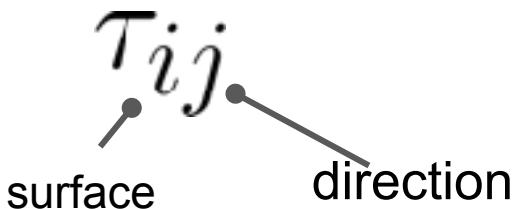
NO!

$$\tau_{yx} = \mu \frac{\partial u}{\partial y} \quad ?$$

$$\begin{aligned}\tau_{yx} \\ = \mu \left(\frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} \right) \\ = \tau_{xy}\end{aligned}$$

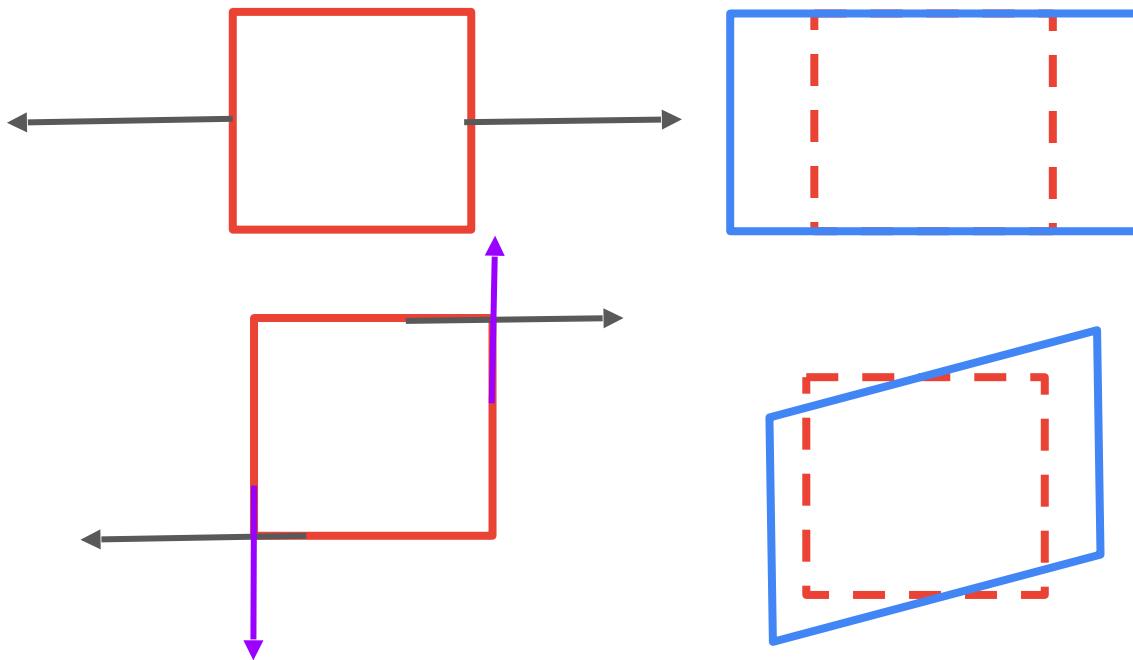
(otherwise the element would rotate like crazy)

shear tensor



net force per
unit volume

$$\nabla \cdot \bar{\tau} = \sum (\nabla_i \tau_{ij})$$



$$\tau_{xx} = 2\mu \frac{\partial u}{\partial x} - \frac{2}{3}(\nabla \cdot \vec{V})$$

$$\begin{aligned}\tau_{yx} &= \mu \left(\frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} \right) \\ &= \tau_{xy}\end{aligned}$$

$$ma = F$$

body force surface force

gravity pressure viscous

EM

$$\begin{bmatrix} -P & 0 & 0 \\ 0 & P & 0 \\ 0 & 0 & -P \end{bmatrix} + \begin{bmatrix} \tau_{11} & \tau_{12} & \tau_{13} \\ \tau_{21} & \tau_{22} & \tau_{23} \\ \tau_{31} & \tau_{32} & \tau_{33} \end{bmatrix}$$

normal shear

Navier-Stokes equations

$$ma = F$$

body force

gravity

EM

surface force

pressure

viscous

$$\begin{aligned} & \rho \frac{d\vec{V}}{dt} \\ &= \rho \vec{g} - \nabla P + \nabla \cdot \vec{\tau} \\ &= \rho \vec{g} - \nabla P + \mu \nabla^2 \vec{V} \end{aligned}$$

viscous term

$$\begin{bmatrix} -P & 0 & 0 \\ 0 & P & 0 \\ 0 & 0 & -P \end{bmatrix} + \begin{bmatrix} \tau_{11} & \tau_{12} & \tau_{13} \\ \tau_{21} & \tau_{22} & \tau_{23} \\ \tau_{31} & \tau_{32} & \tau_{33} \end{bmatrix}$$

normal

shear

if constant viscosity, incompressible fluid

* divergence/laplacian of a vector



$$\frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y} + \frac{\partial v_z}{\partial z} = 0$$

$$\rho \left(\frac{\partial v_x}{\partial t} + v_x \frac{\partial v_x}{\partial x} + v_y \frac{\partial v_x}{\partial y} + v_z \frac{\partial v_x}{\partial z} \right) = - \frac{\partial P}{\partial x} + \mu \left(\frac{\partial^2 v_x}{\partial x^2} + \frac{\partial^2 v_x}{\partial y^2} + \frac{\partial^2 v_x}{\partial z^2} \right) + \rho g_x$$

$$\rho \left(\frac{\partial v_y}{\partial t} + v_x \frac{\partial v_y}{\partial x} + v_y \frac{\partial v_y}{\partial y} + v_z \frac{\partial v_y}{\partial z} \right) = - \frac{\partial P}{\partial y} + \mu \left(\frac{\partial^2 v_y}{\partial x^2} + \frac{\partial^2 v_y}{\partial y^2} + \frac{\partial^2 v_y}{\partial z^2} \right) + \rho g_y$$

$$\rho \left(\frac{\partial v_z}{\partial t} + v_x \frac{\partial v_z}{\partial x} + v_y \frac{\partial v_z}{\partial y} + v_z \frac{\partial v_z}{\partial z} \right) = - \frac{\partial P}{\partial z} + \mu \left(\frac{\partial^2 v_z}{\partial x^2} + \frac{\partial^2 v_z}{\partial y^2} + \frac{\partial^2 v_z}{\partial z^2} \right) + \rho g_z$$

Navier-Stokes equations

$$\left(\frac{\partial}{\partial t} + \vec{V} \cdot \nabla \right) \vec{V} = \vec{g} - \frac{\nabla P}{\rho} + \frac{\mu}{\rho} \nabla^2 \vec{V}$$

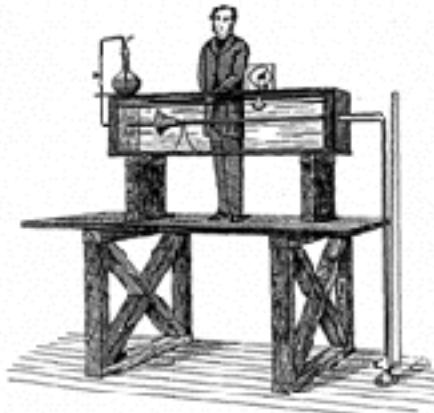
$$Re = \frac{\text{inertia forces}}{\text{viscous forces}}$$

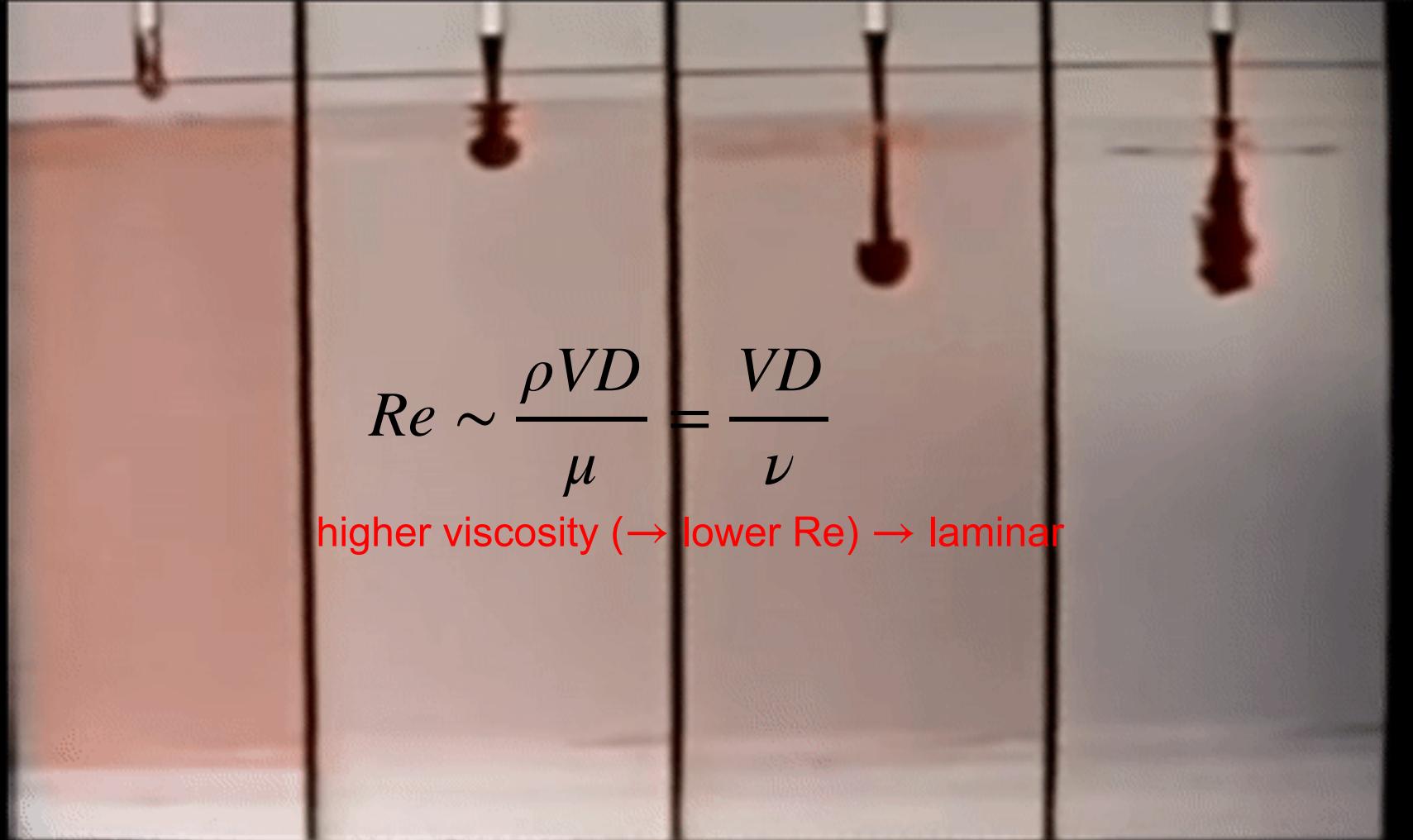
$$Re \sim \frac{\rho V D}{\mu} = \frac{V D}{\nu}$$

turbulence appears when Reynolds number is high enough!

$$Re \sim \frac{\rho VD}{\mu} = \frac{VD}{\nu}$$

Reynolds' pipe experiment




$$Re \sim \frac{\rho VD}{\mu} = \frac{VD}{\nu}$$

higher viscosity (\rightarrow lower Re) \rightarrow laminar

Navier-Stokes equation

$$\left(\frac{\partial}{\partial t} + \vec{V} \cdot \nabla \right) \vec{V} = \vec{g} - \frac{\nabla P}{\rho} + \frac{\mu}{\rho} \nabla^2 \vec{V}$$

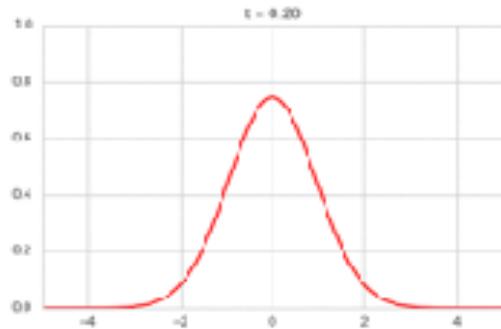
diffusion of “momentum”

convection diffusion equation

$$\frac{\partial f}{\partial t} + U \frac{\partial f}{\partial x} = D \frac{\partial^2 f}{\partial x^2}$$

- linear
 - $U = \text{constant}$
- non-linear
 - $U = f(x, t)$: Burger's equation

D= constant



the **good guy**: diffusion/conduction

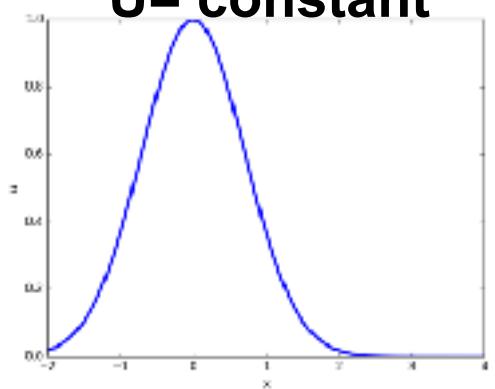
$$\frac{\partial f}{\partial t} + U \cancel{\frac{\partial f}{\partial x}} = D \frac{\partial^2 f}{\partial x^2}$$

the “bad” guy who cause turbulence:

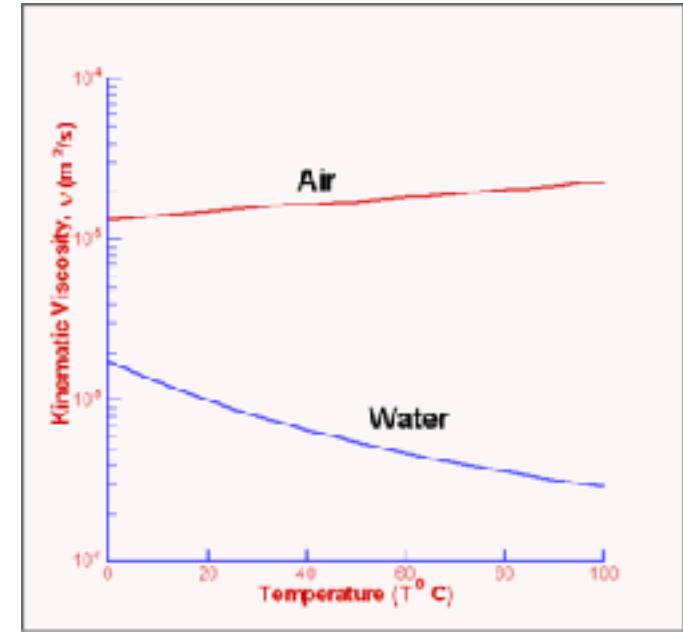
convection/advection

$$\frac{\partial f}{\partial t} + U \frac{\partial f}{\partial x} \cancel{= D \frac{\partial^2 f}{\partial x^2}}$$

U= constant



the ubiquitous nature of turbulence in our (human) daily lives



acceleration \Rightarrow larger Re \Rightarrow Turbulent

$$Re \sim \frac{\rho V D}{\mu} = \frac{V D}{\nu}$$

hydrostatic: Euler equation

$$\cancel{\left(\frac{\partial}{\partial t} + \vec{V} \cdot \nabla \right) \vec{V}} = \vec{g} - \frac{\nabla P}{\rho} + \frac{\mu}{\rho} \cancel{\nabla^2 \vec{V}}$$

v=0, stationary, invicid



a fish tank with special designs

Bernoulli equation for **incompressible** fluid*

$$\cancel{\left(\frac{\partial}{\partial t} + \vec{V} \cdot \nabla\right) \vec{V}} = \vec{g} - \frac{\nabla P}{\rho} + \frac{\mu}{\rho} \cancel{\nabla^2 \vec{V}} \quad \text{stationary, invicid}$$



integration assumption $d\rho = 0$
(incompressible)

$$\boxed{\mathcal{B} = \frac{|\vec{V}|^2}{2} + \frac{P}{\rho} + gz}$$

(along a **streamline**)

$$\mathcal{B}(x_1, y_1, z_1) = \mathcal{B}(x_2, y_2, z_2)$$

*there is Bernoulli equation for **compressible** fluid too! (by taking into account the change of internal energy)

governing equation III:
energy equation (1st law of thermodynamics)

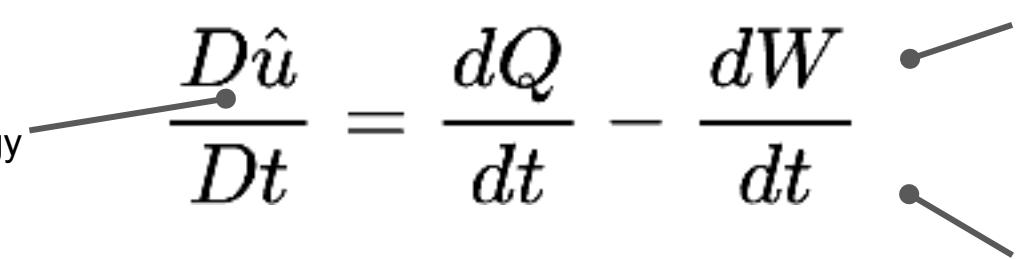
conservation of energy (1st law of thermodynamics)

$$\frac{D\hat{u}}{Dt} = \frac{dQ}{dt} - \frac{dW}{dt}$$

internal energy

viscous work

pressure work



recall:

$$\frac{D\rho}{Dt} + p(\nabla \cdot \mathbf{v}) = 0$$

$$p \frac{dV}{dt} = p \frac{d(\frac{1}{\rho})}{dt} = -\frac{p}{\rho^2} \frac{D\rho}{Dt}$$

$$\rho \frac{d\hat{u}}{dt} + p(\nabla \cdot \vec{v}) = -\dot{Q}_{cool} + \Phi$$

Viscous
dissipation
function

Viscous dissipation function

$$\Phi = \mu [2\left(\frac{\partial u}{\partial x}\right)^2 + 2\left(\frac{\partial v}{\partial y}\right)^2 + 2\left(\frac{\partial w}{\partial z}\right)^2 + \left(\frac{\partial v}{\partial x} + \frac{\partial u}{\partial y}\right)^2 + \left(\frac{\partial w}{\partial y} + \frac{\partial v}{\partial z}\right)^2 + \left(\frac{\partial u}{\partial z} + \frac{\partial w}{\partial x}\right)^2] > 0$$

→ always increase the internal energy (irreversible)

example: the importance of energy equation

$$\dot{Q}^+ \approx \dot{Q}^- (\gg \dot{Q}^{adv})$$

(radiative efficient)



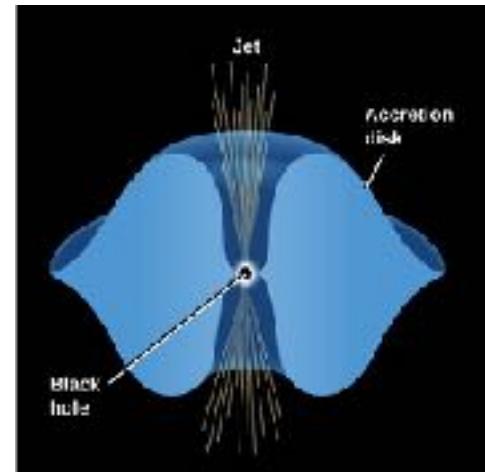
$$TdS = dQ$$

$$\rho T \frac{ds}{dt} = \dot{Q}^+ - \dot{Q}^-$$

$$\boxed{\rho v_r T \frac{ds}{dr} \equiv \dot{Q}^{adv} = \dot{Q}^+ - \dot{Q}^-}$$

(radiative inefficient)

$$\dot{Q}^+ \approx \dot{Q}^{adv} (\gg \dot{Q}^-)$$



conservative form

$$\frac{\partial U}{\partial t} + \frac{\partial F}{\partial x} + \frac{\partial G}{\partial y} + \frac{\partial H}{\partial z} = J$$

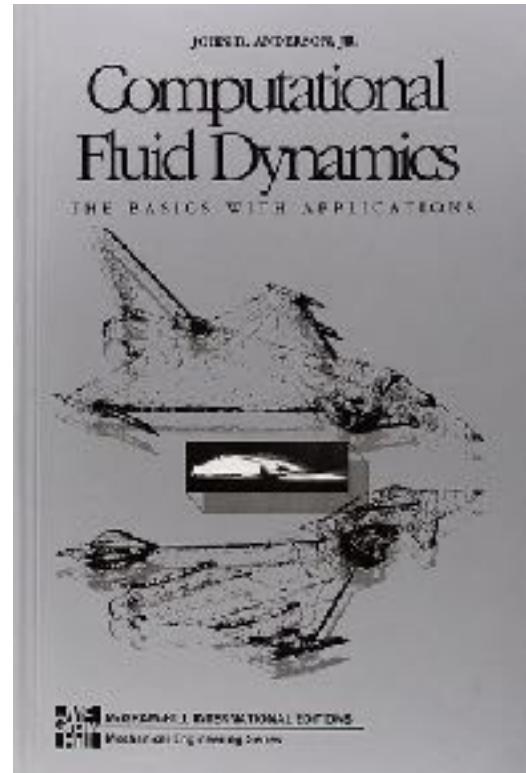
$$U = \begin{Bmatrix} \rho \\ \rho u \\ \rho v \\ \rho w \\ \rho \left(e + \frac{V^2}{2} \right) \end{Bmatrix}$$

$$F = \begin{Bmatrix} \rho u \\ \rho u^2 + p - \tau_{xx} \\ \rho vu - \tau_{xy} \\ \rho uw - \tau_{xz} \\ \rho \left(e + \frac{V^2}{2} \right) u + pu - k \frac{\partial T}{\partial x} - u\tau_{xx} - v\tau_{xy} - w\tau_{xz} \end{Bmatrix}$$

$$G = \begin{Bmatrix} \rho v \\ \rho uv - \tau_{yx} \\ \rho v^2 + p - \tau_{yy} \\ \rho vw - \tau_{yz} \\ \rho \left(e + \frac{V^2}{2} \right) v + pv - k \frac{\partial T}{\partial y} - u\tau_{xy} - v\tau_{yy} - w\tau_{yz} \end{Bmatrix}$$

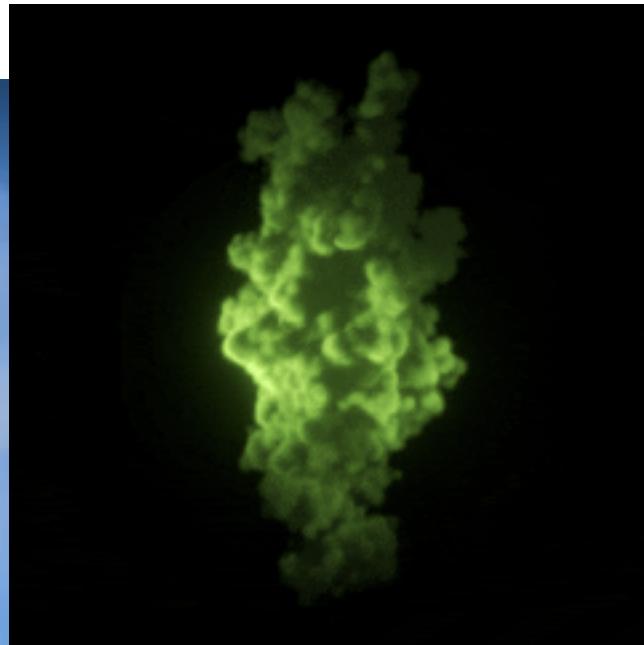
$$H = \begin{Bmatrix} \rho w \\ \rho uw - \tau_{zx} \\ \rho vw - \tau_{zy} \\ \rho w^2 + p - \tau_{zz} \\ \rho \left(e + \frac{V^2}{2} \right) w + pw - k \frac{\partial T}{\partial z} - u\tau_{xz} - v\tau_{yz} - w\tau_{zz} \end{Bmatrix}$$

$$J = \begin{Bmatrix} 0 \\ \rho f_x \\ \rho f_y \\ \rho f_z \\ \rho (uf_x + vf_y + wf_z) + p \dot{q} \end{Bmatrix}$$



understanding turbulent flows....

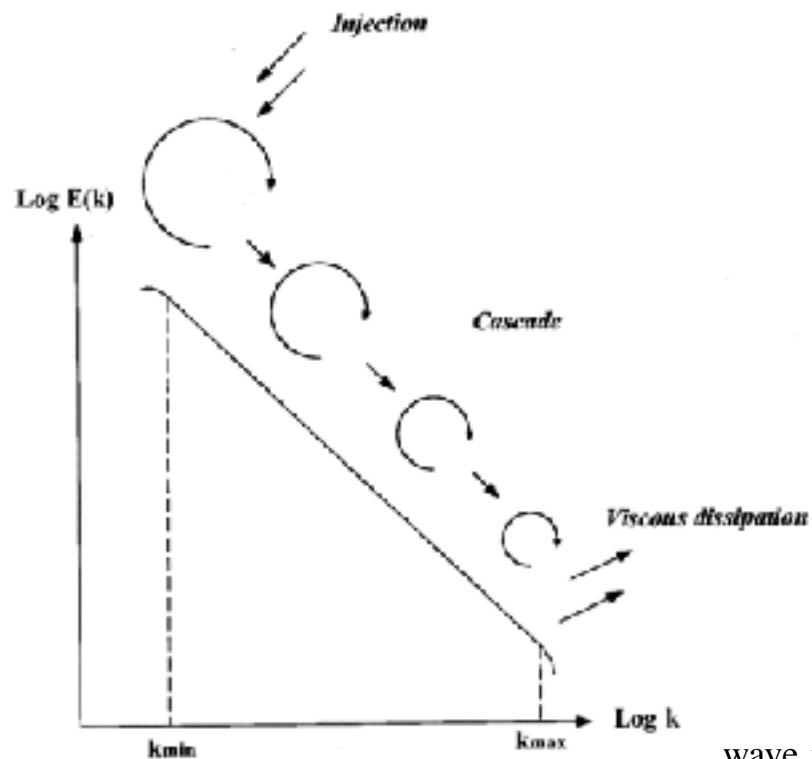
II



self-similar

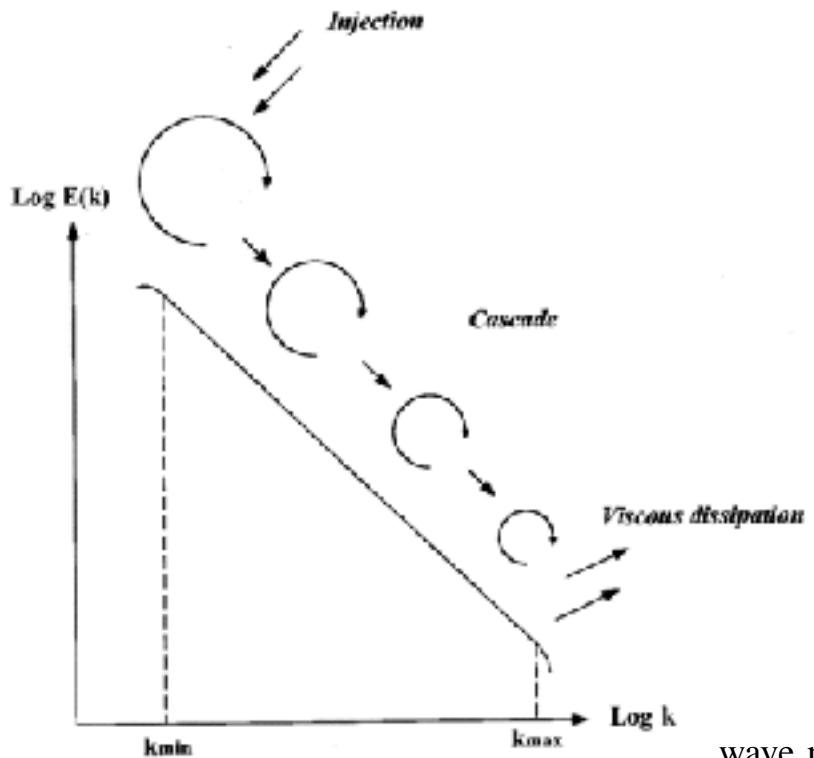


key word: eddies, energy cascade



$$\text{wave number } k = 2\pi/\lambda$$

Komogorov's law for homogenous and isotropic turbulence



roughly no loss of energy

$$E(k) \propto k^{-5/3}$$

energy finally lost due to viscous dissipation

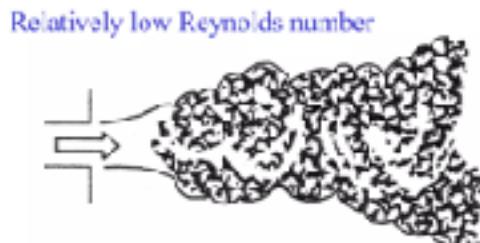
$$\implies \lambda_0 \sim R_e^{-3/4} L$$

$$\text{wave number } k = 2\pi/\lambda$$

Komogorov's law for homogenous and isotropic turbulence

Jets at two different Reynolds numbers

larger ν



roughly no loss of energy

$$E(k) \propto k^{-5/3}$$

smaller ν



energy finally lost due to viscous dissipation

$$\implies \lambda_0 \sim R_e^{-3/4} L$$

Source: Tennekes & Lumley, Page 21.

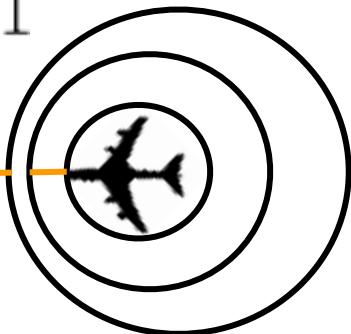
towards to compressible gas

Mach number:

$$\mathcal{M} \equiv \frac{V}{C_s}$$

subsonic

$$\mathcal{M} < 1$$

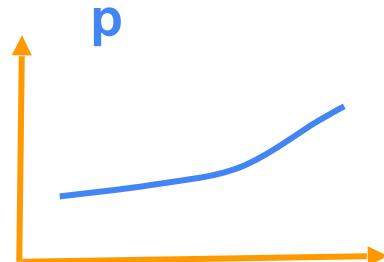


supersonic

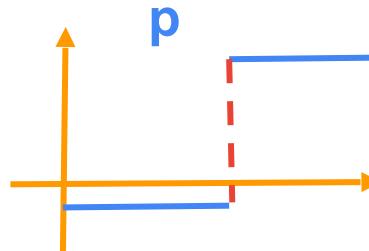
$$\mathcal{M} > 1$$

shock

high density
high pressure
region behind
the shock



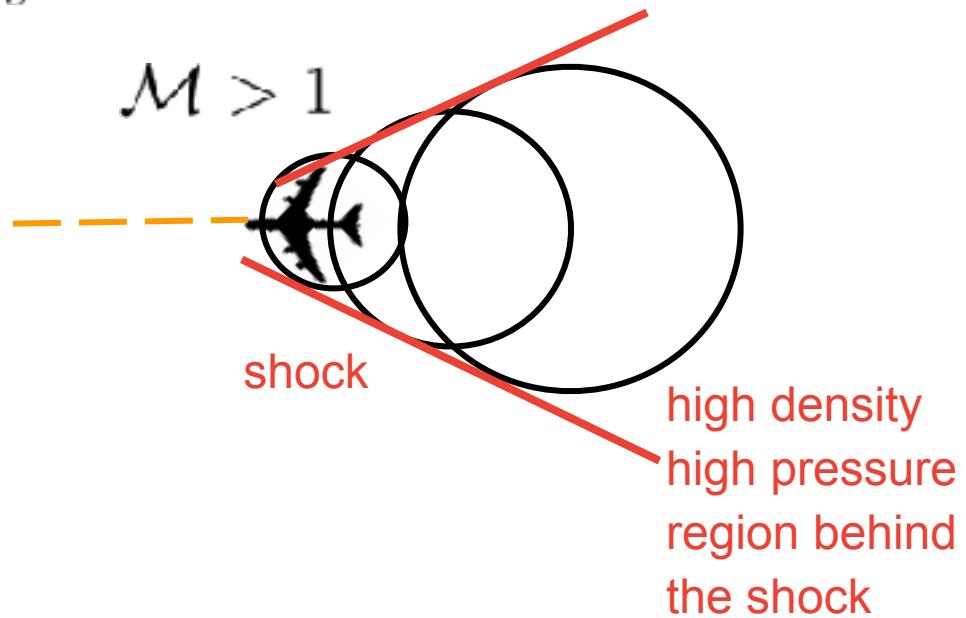
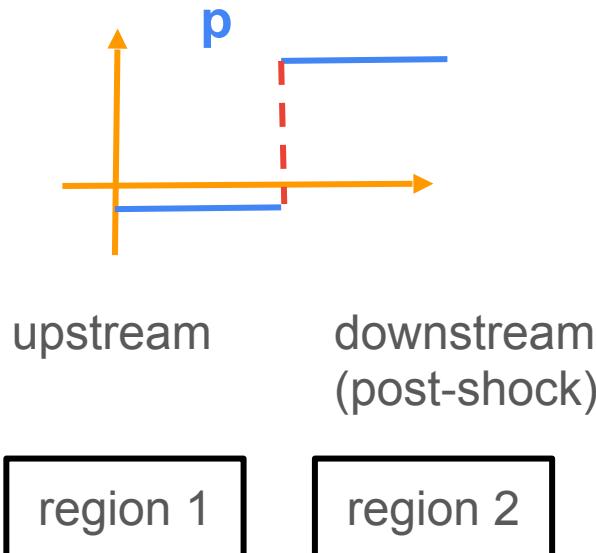
(at the flight-nose frame)



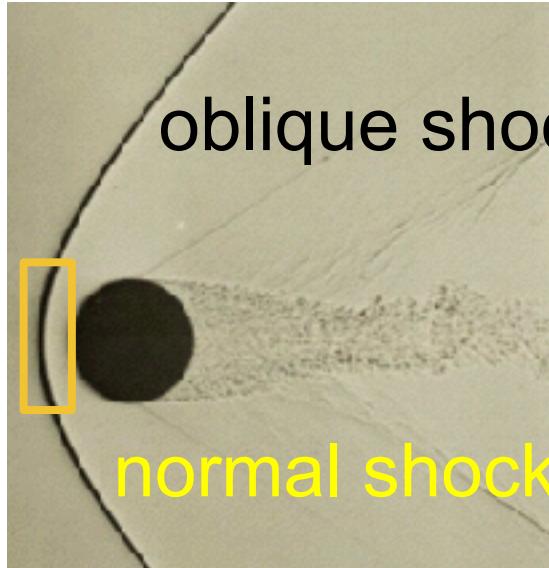
Mach number:

$$\mathcal{M} \equiv \frac{V}{C_s}$$

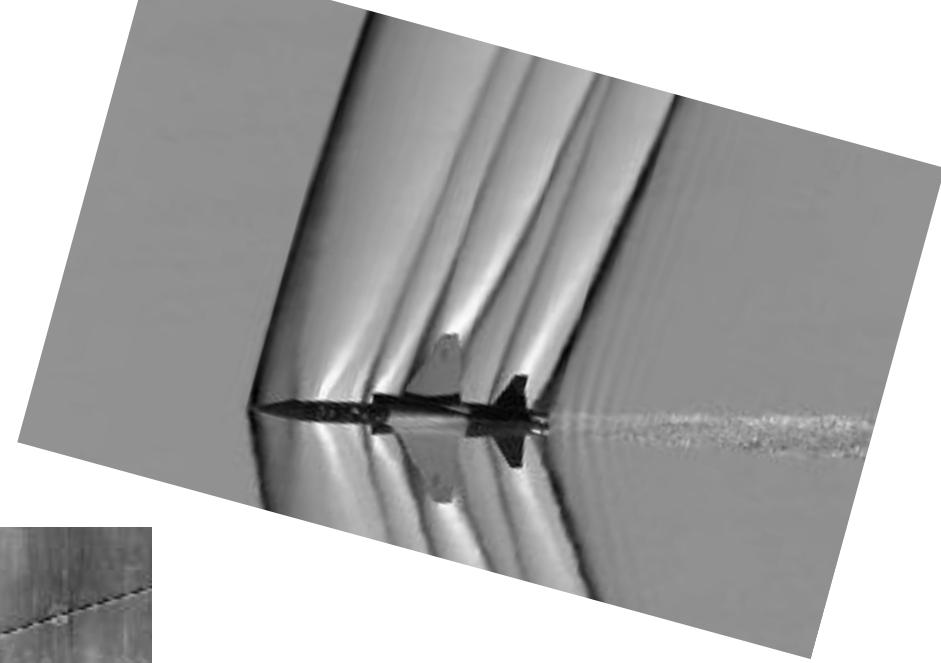
(at the flight-nose frame)



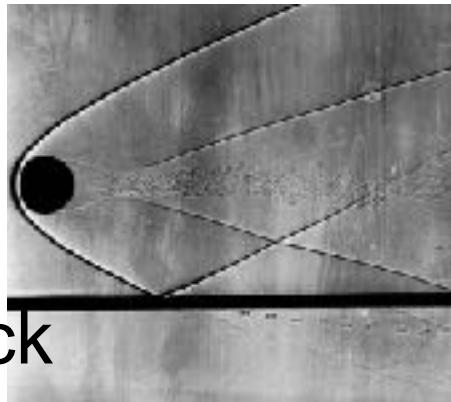
detached shock



attached shock

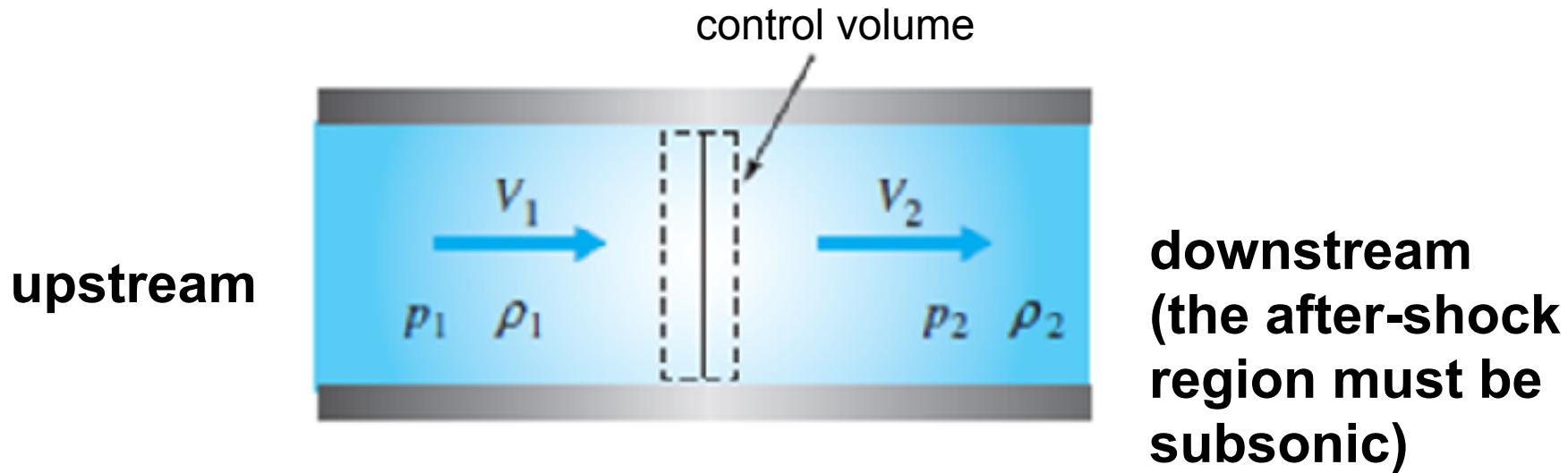


reflection of shock



avoiding bow shock (and
therefore drag)

normal shock: must be a strong shock ($M_2 < 1$)



equation of state (EOS)

barotropic $p(\rho)$

isothermal $p \propto \rho$ $C_s^2 = \frac{dp}{d\rho} = \frac{\rho}{p}$

adiabatic $p \propto \rho^\gamma$ $C_s^2 = \frac{dp}{d\rho} = \gamma \frac{\rho}{p}$

*for air, $\gamma = 1.4$

$$\mathcal{M}_1 > 1 \quad \mathcal{M}_2 < 1$$

$$\begin{array}{c} \rho_1 < \rho_2 \\ p_1 < p_2 \\ u_1 > u_2 \end{array}$$

shock

(adiabatic) **normal shock** and Rankine-Hugoniot relations
*governing equations are written down in integral forms

RH relation at the shock frame $\left(\frac{\partial}{\partial t} = 0\right)$

$$\left\{ \begin{array}{l} \rho_1 u_1 = \rho_2 u_2 \\ \rho_1 u_1^2 + p_1 = \rho_2 u_2^2 + p_2 \\ \frac{1}{2} u_1^2 + \mathcal{E}_1 + \frac{p_1}{\rho_1} = \frac{1}{2} u_2^2 + \mathcal{E}_2 + \frac{p_2}{\rho_2} \end{array} \right.$$

a useful relation for the internal energy of adiabatic flow:

$$\mathcal{E} = \frac{1}{\gamma - 1} \frac{p}{\rho}$$

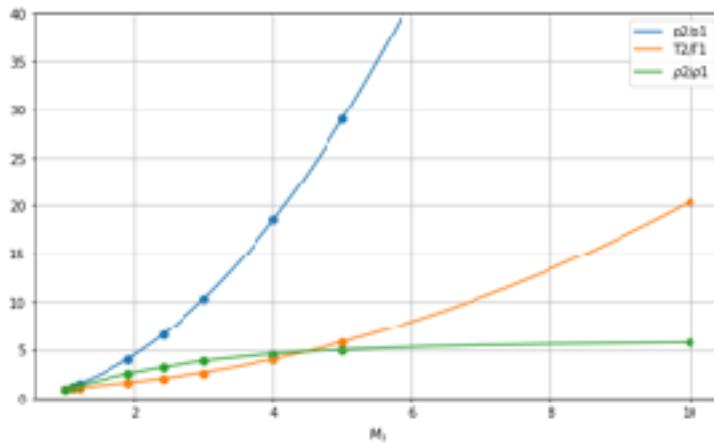
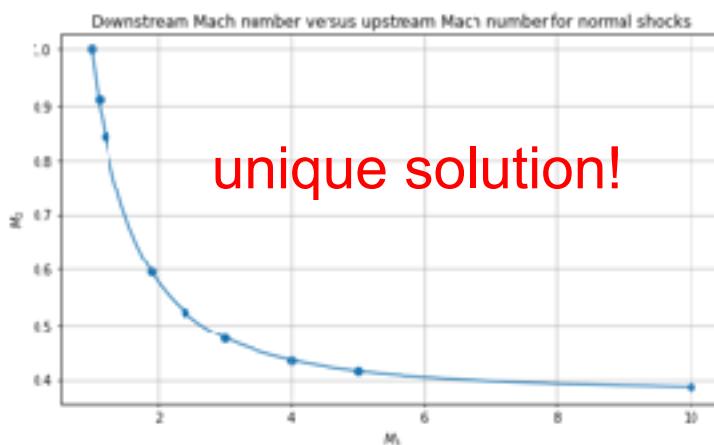
if $\mathcal{M}_1 \rightarrow \infty$

$$\frac{\rho_2}{\rho_1} \rightarrow \frac{\gamma + 1}{\gamma - 1}$$

*for adiabatic shock, density contrast is finite

The (adiabatic) normal shock tables (for air; r γ = 1.4)

M_1	M_∞	$\frac{p_e}{p_i}$	$\frac{\rho_e}{\rho_i}$	$\frac{T_e}{T_i}$
1.00	1.00000	1.0000	1.0000	1.0000
1.10	0.91177	1.2450	1.0691	1.0649
1.20	0.84217	1.5133	1.3416	1.1280
1.30	0.78066	1.8050	1.7157	1.1900
1.40	0.73071	2.1200	1.9596	1.2547
1.50	0.70109	2.4583	1.9621	1.3202
1.60	0.66844	2.8000	2.0317	1.3883
1.70	0.64065	3.2050	2.1877	1.4500
1.80	0.61650	3.6133	2.3652	1.5975
1.90	0.59502	4.0400	2.5457	1.6979
2.00	0.57705	4.5000	2.6666	1.6075
2.10	0.56128	4.9784	2.8110	1.7704
2.20	0.54706	5.4600	2.9712	1.8563
2.30	0.53441	6.0050	3.0646	1.9460
2.40	0.52312	6.5500	3.2119	2.0403
2.50	0.51299	7.1250	3.3333	2.1375
2.60	0.50307	7.7200	3.4468	2.2300
2.70	0.49433	8.3333	3.5550	2.3429
2.80	0.48617	8.9600	3.6630	2.4612
2.90	0.47838	9.6170	3.7609	2.5832
3.00	0.47019	10.333	3.8571	2.6700
4.00	0.42496	18.000	4.7714	4.0468
5.00	0.41593	29.000	5.0000	5.0000
10.00	0.36757	116.00	5.7143	20.300
*	0.37796	*	5.000	*



$$\cancel{\left(\frac{\partial}{\partial t} + \vec{V} \cdot \nabla\right) \vec{V}} = \vec{g} - \frac{\nabla P}{\rho} + \frac{\mu}{\rho} \cancel{\nabla^2 \vec{V}}$$

$$\rho u A = \text{constant}$$

$$\longrightarrow u du + \frac{dp}{d\rho} \frac{d\rho}{\rho} = 0$$

$$\longrightarrow \frac{d\rho}{\rho} + \frac{du}{u} + \frac{dA}{A} = 0$$

$$u^2 \frac{du}{u} = C_s^2 \frac{d\rho}{\rho}$$

$$\frac{d\rho}{\rho} = -\mathcal{M}^2 \frac{du}{u}$$

$$(1 - \mathcal{M}^2) \frac{du}{u} = -\frac{dA}{A}$$

conservation of mass (continuity equation): integral form

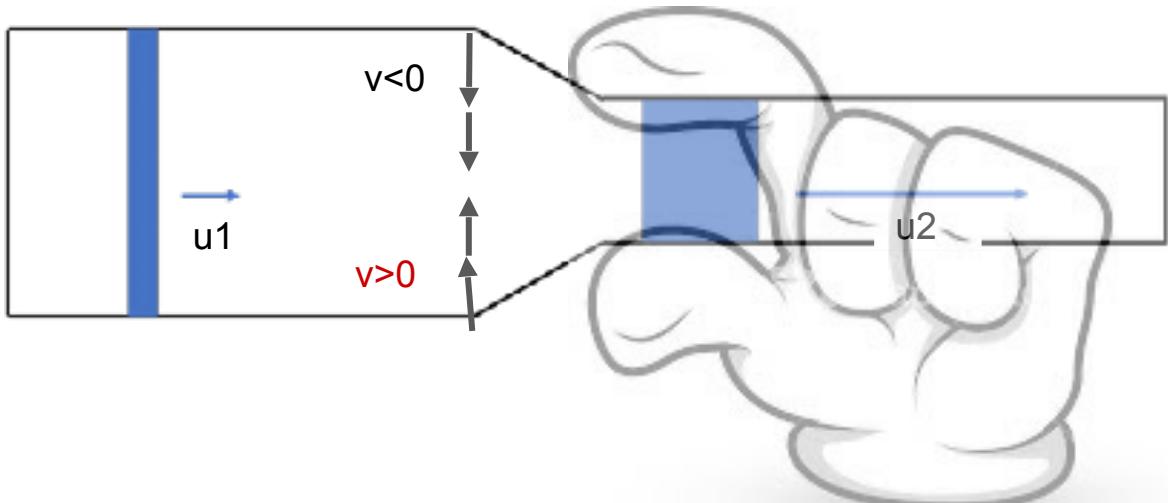
from Reynolds transport theorem: $\rho u A = \text{constant}$



e.g. Fluid Mechanics by Frank M. White

if incompressible: $u A = \text{constant}$

an example: 2D incompressible flow



$$uA = \text{constant}$$

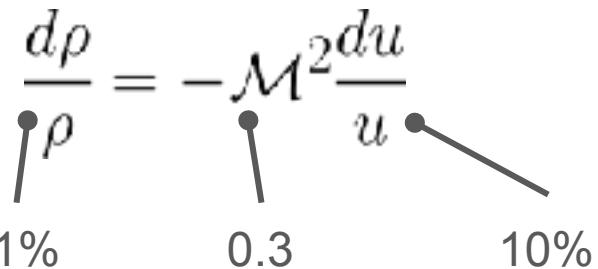
$$\cancel{\left(\frac{\partial}{\partial t} + \vec{V} \cdot \nabla\right) \vec{V}} = \vec{g} - \frac{\nabla P}{\rho} + \frac{\mu}{\rho} \nabla^2 \vec{V}$$

$$\rho u A = \text{constant}$$

$$\longrightarrow u du + \frac{dp}{d\rho} \frac{d\rho}{\rho} = 0$$

$$\longrightarrow \frac{d\rho}{\rho} + \frac{du}{u} + \frac{dA}{A} = 0$$

$$u^2 \frac{du}{u} = C_s^2 \frac{d\rho}{\rho}$$



$$(1 - \mathcal{M}^2) \frac{du}{u} = - \frac{dA}{A}$$

if $\mathcal{M} < 0.3 \rightarrow \text{incompressible fluid}$

incompressible:

$$\nabla \cdot \mathbf{v} = 0$$

or

$$M < 0.3$$

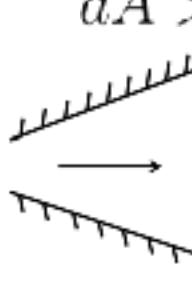
$$(1 - \mathcal{M}^2) \frac{du}{u} = -\frac{dA}{A}$$

subsonic

$$1 - \mathcal{M}^2 > 0$$

supersonic

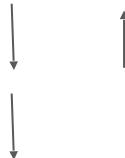
$$1 - \mathcal{M}^2 < 0$$

	$du > 0$	$du < 0$
	$du < 0$	$du > 0$

$$(1 - \mathcal{M}^2) \frac{du}{u} = - \frac{dA}{A}$$

why?

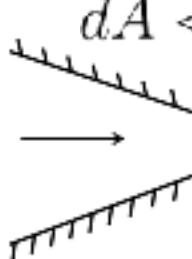
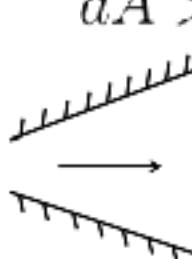
$$\rho u A = \text{constant}$$



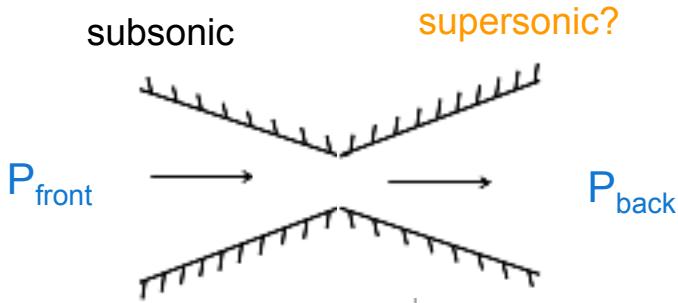
subsonic supersonic

$$1 - \mathcal{M}^2 > 0$$

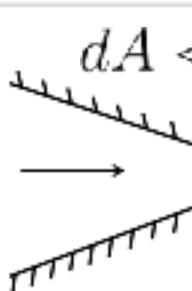
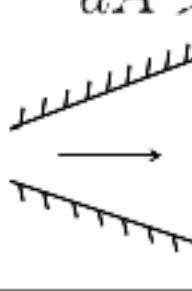
$$1 - \mathcal{M}^2 < 0$$

$dA < 0$	$du > 0$	$du < 0$
		
	$du < 0$	$du > 0$

(convergence-divergence) nozzle flow



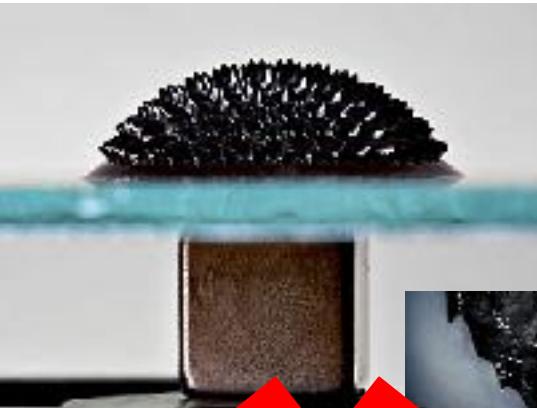
- A supersonic flow can be produced when the back pressure (P_{back}) is low enough
- If the sonic transition does not occur in the nozzle flow, the fluid speed reaches an extremum ($du=0$) when $dA=0$

subsonic	$1 - \mathcal{M}^2 > 0$	supersonic
$dA < 0$ ↓ 	$du > 0$	$du < 0$
$dA > 0$ ↓ 	$du < 0$	$du > 0$

magnetohydrodynamics

MagnetoHydroDynamics (磁流體力學)

credit: wiki



we are **NOT** talking about
ferrofluid (鐵磁流體)



single and many charged particles

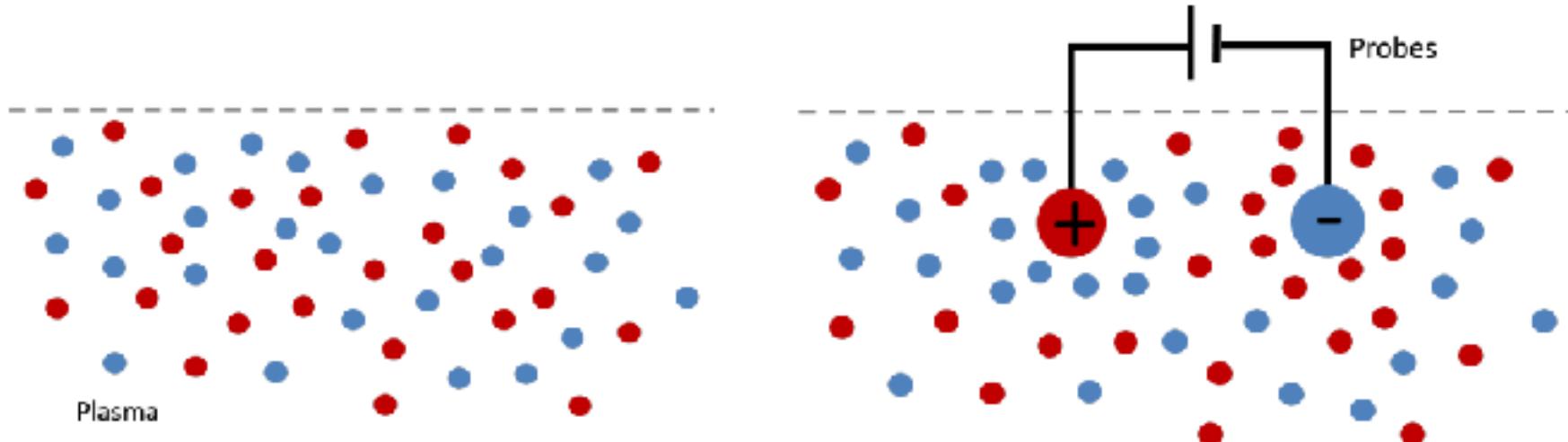
single particle acceleration: related to energetic particle in the Universe (e.g. cosmic ray)

Here we focus on plasma:

A plasma is a quasi-neutral gas consisting of positive and negative charged particles (usually ions & electrons)

*A stricter definition of a plasma is a gas where there are enough freed electrons and ions that they act collectively.

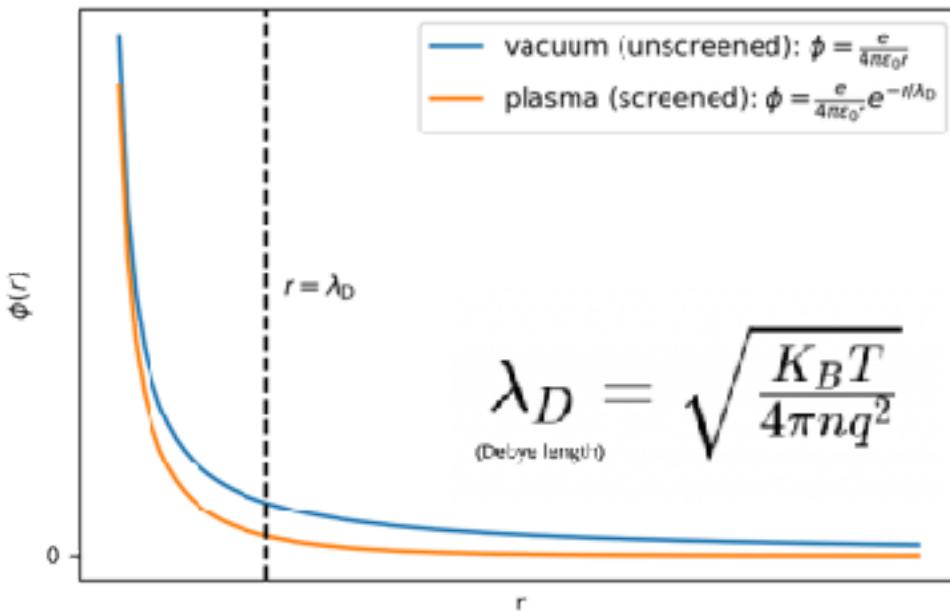
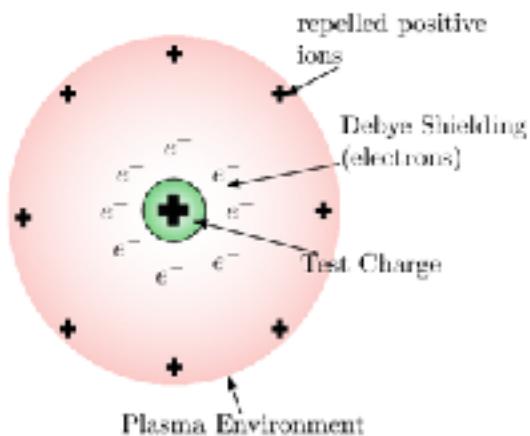
charge imbalances may exist only over a distance (**Debye length**) and a period of time (inverse of **plasma frequency**)



Two important parameters in plasma physics (I)

$$\lambda_D \quad \text{electron Debye length}$$

a measure of the distance over which the electric potential of a point charge is significantly influenced by the surrounding charges.



Two important parameters in plasma physics (II)

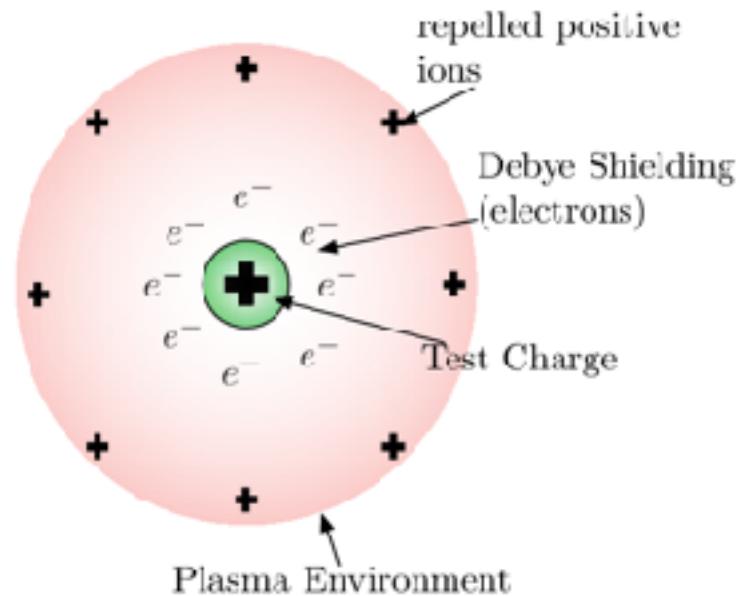
number of electrons in a “Debye cube” or “Debye sphere”:

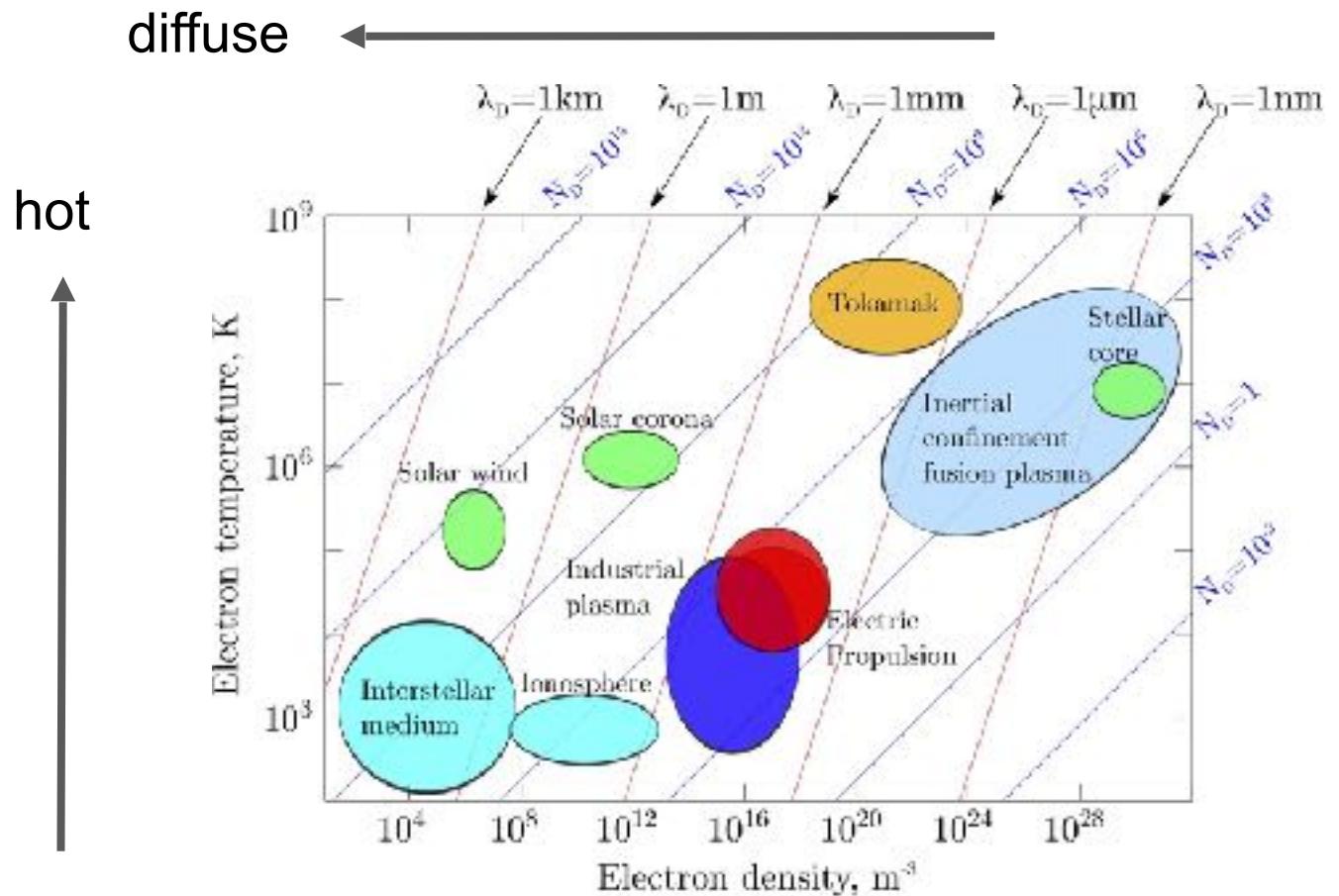
$$N_D (\sim n \lambda_D^3)$$

The condition for an ionized gas to be considered a plasma is

$$N_D \gg 1$$

many charged particles within a Debye cube.

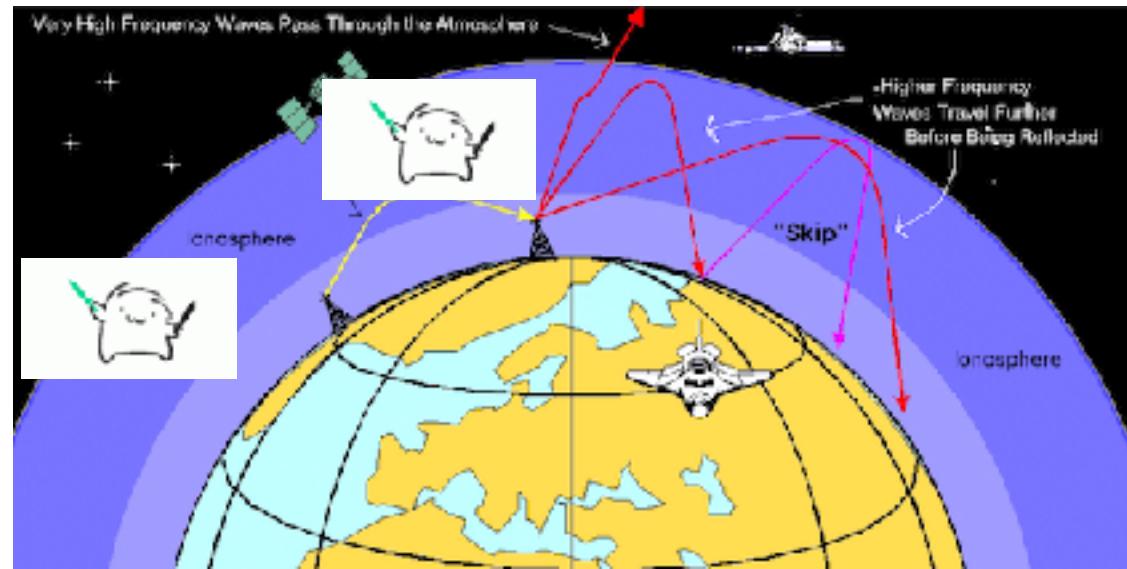




Plasma exist wide range of number densities and temperatures

plasma frequency ($\sim 8980 \times n^{1/2} \text{Hz}$ for electron)

- the **frequency** at which the electrons in the **plasma** naturally oscillate relative to the ions
- For the ionosphere, plasma frequency $\sim 10^7 \text{Hz}$
- $f < 10^7 \text{Hz}$: reflected by ionosphere



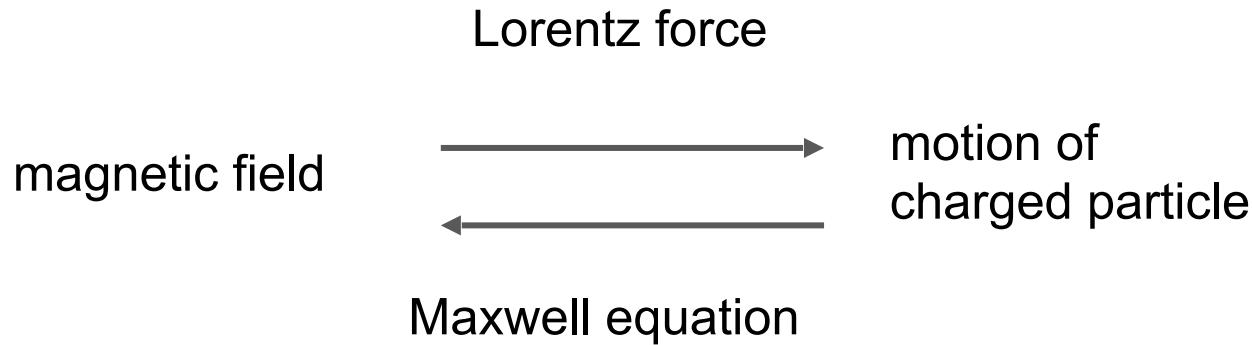
Credit: NASA/GSFC

MHD describes:

the “slow*” evolution of an electrically conducting fluid,
and a region \gg Debye length, Larmor radius

*compare to plasma frequency

collective behavior of fluids composed of charged particles (but electrically neutral!)



*magnetic forces on the particles in the fluid are not isotropic

SI unit

cgs unit

$$\vec{\nabla} \cdot \vec{B} = 0$$

$$\vec{\nabla} \times \vec{E} + \frac{\partial \vec{B}}{\partial t} = 0$$

$$\vec{\nabla} \cdot \vec{E} = \frac{\rho}{\epsilon_0}$$

$$\vec{\nabla} \times \vec{B} - \frac{1}{c^2} \frac{\partial \vec{E}}{\partial t} = \mu_0 \vec{J}$$

$$\vec{\nabla} \cdot \vec{B} = 0$$

$$\vec{\nabla} \times \vec{E} + \frac{1}{c} \frac{\partial \vec{B}}{\partial t} = 0$$

$$\vec{\nabla} \cdot \vec{E} = 4\pi\rho$$

$$\vec{\nabla} \times \vec{B} - \frac{1}{c} \frac{\partial \vec{E}}{\partial t} = \frac{4\pi}{c} \vec{J}$$

SI to gaussian:

$$\epsilon_0 \rightarrow \frac{1}{4\pi}$$

$$B \rightarrow B/c$$

$$\mu_0 \rightarrow \frac{4\pi}{c^2}$$

$$E \rightarrow E$$

MHD: single fluid approach

$$\rho = m^+ n^+ + m^- n^-$$

$$v = \frac{m^+ n^+ v^+ + m^- n^- v^-}{m^+ n^+ + m^- n^-}$$

some initial guess

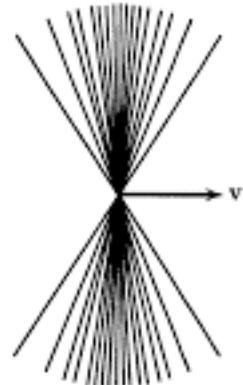
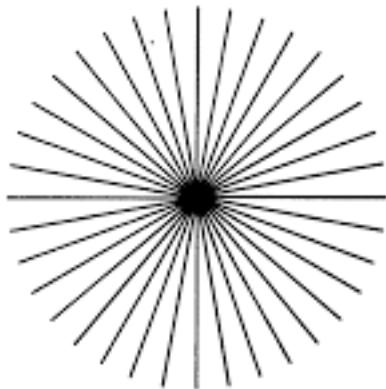
adding Lorentz force (as body force) to momentum equation

$$\rho \left(\frac{\partial}{\partial t} + \mathbf{V} \cdot \nabla \right) \mathbf{V} = \frac{\mathbf{J} \times \mathbf{B}}{c} - \nabla p$$

adding Ohm's law (\mathbf{J}) to close the set of equations

Lab frame: $\mathbf{j} = \sigma \left(\mathbf{E} + \frac{\mathbf{V} \times \mathbf{B}}{c} \right)$

conductivity



$$\mathbf{E}_{\parallel}' = \mathbf{E}_{\parallel}$$

$$\mathbf{B}_{\parallel}' = \mathbf{B}_{\parallel}$$

$$\mathbf{E}_{\perp}' = \gamma (\mathbf{E}_{\perp} + \mathbf{v} \times \mathbf{B})$$

$$\mathbf{B}_{\perp}' = \gamma \left(\mathbf{B}_{\perp} - \frac{1}{c^2} \mathbf{v} \times \mathbf{E} \right)$$

$$\gamma = \frac{1}{\sqrt{1 - \frac{v^2}{c^2}}}$$

some initial guess

$$E/B \sim L/T \sim u$$

$$\text{RHS 2nd term/LHS} \sim u^2/c^2$$

non-relativistic flow ($u \ll c$): ignored
terms related to E !

$$\nabla \cdot \mathbf{E} = \frac{\rho}{\epsilon_0}$$

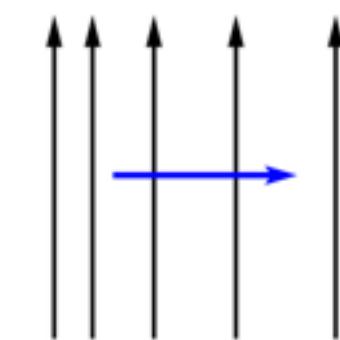
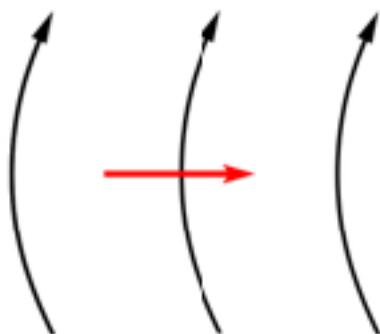
$$\nabla \cdot \mathbf{B} = 0$$

$$\nabla \times \mathbf{E} = - \frac{\partial \mathbf{B}}{\partial t}$$

$$\nabla \times \mathbf{B} = \mu_0 \mathbf{j} + \frac{1}{c^2} \frac{\partial \mathbf{E}}{\partial t}$$

$$\underbrace{\frac{\mathbf{J} \times \mathbf{B}}{c}}_{\text{Lorentz force}} = \frac{(\nabla \times \mathbf{B}) \times \mathbf{B}}{4\pi}$$

$$= \underbrace{\frac{\mathbf{B} \cdot \nabla \mathbf{B}}{4\pi}}_{\sim \text{magnetic tension}} - \underbrace{\nabla \left(\frac{B^2}{8\pi} \right)}_{\sim \text{magnetic pressure}} \quad (20)$$

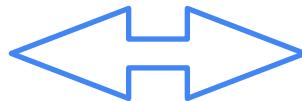


Lab frame:

finite

$$\mathbf{j} = \sigma \left(\mathbf{E} + \frac{\mathbf{V} \times \mathbf{B}}{c} \right)$$

plasma frame: $\mathbf{E}'=0$



ideal MHD:
infinite/perfect conductivity

$$\mathbf{E} + \frac{\mathbf{V} \times \mathbf{B}}{c} = 0 \text{ and } \frac{\partial \mathbf{B}}{\partial t} = -c \nabla \times \mathbf{E}$$

$$\frac{\partial \mathbf{B}}{\partial t} = \nabla \times (\mathbf{V} \times \mathbf{B})$$

$$\mathbf{j} = \sigma (\mathbf{E} + \frac{\mathbf{v} \times \mathbf{B}}{c})$$

finite conductivity

$$\frac{\partial \mathbf{B}}{\partial t} = -\kappa \nabla \times \mathbf{E}$$

magnetic diffusivity

$$\boxed{\frac{\partial B}{\partial t} = \nabla \times (v \times B) + \eta \nabla^2 B}$$

(induction equation)

$$\frac{\partial B}{\partial t} = \nabla \times (v \times B) + \eta \nabla^2 B$$

$$R_m = \frac{UL}{\eta} \sim \frac{\text{induction}}{\text{diffusion}}$$

L - Typical length scale of the flow U - Typical Velocity scale of the flow

R_m - Reynolds Magnetic Number η - Magnetic Diffusivity

usually $\gg 1$ in astrophysics
(ideal MHD is a good approximation)

magnetic tension, magnetic pressure



Lorentz force

magnetic field



motion of
charged particle

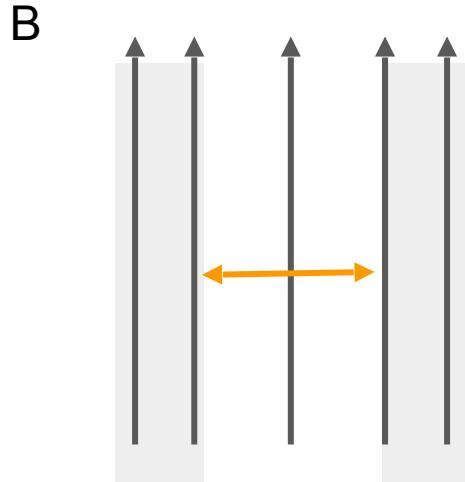
Maxwell equation + Ohm's law



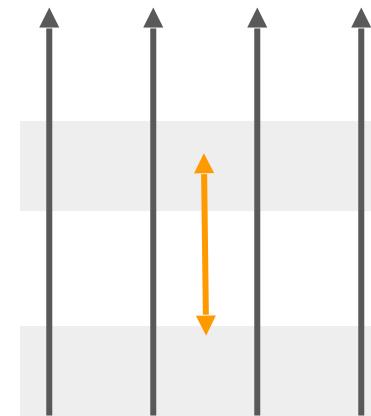
$$\mathbf{E} + \frac{\mathbf{v} \times \mathbf{B}}{c} = 0 \quad (\text{ideal MHD})$$

three MHD waves

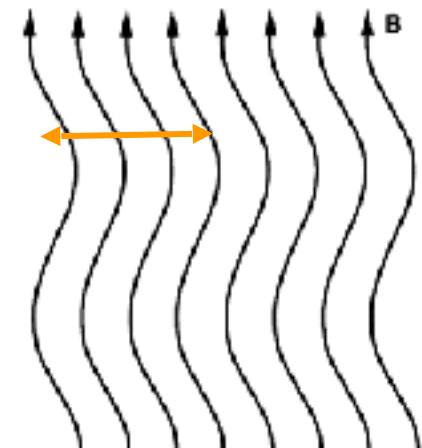
fast
magnetosonic
wave



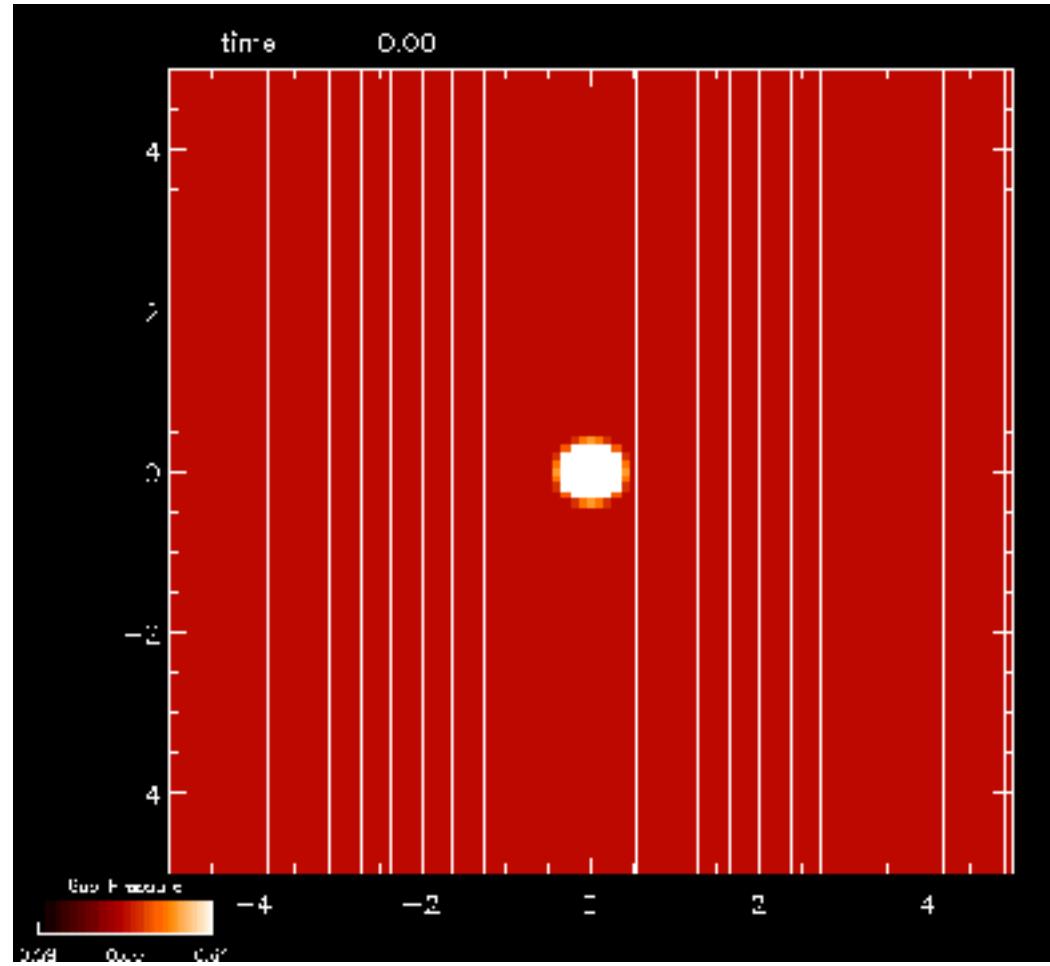
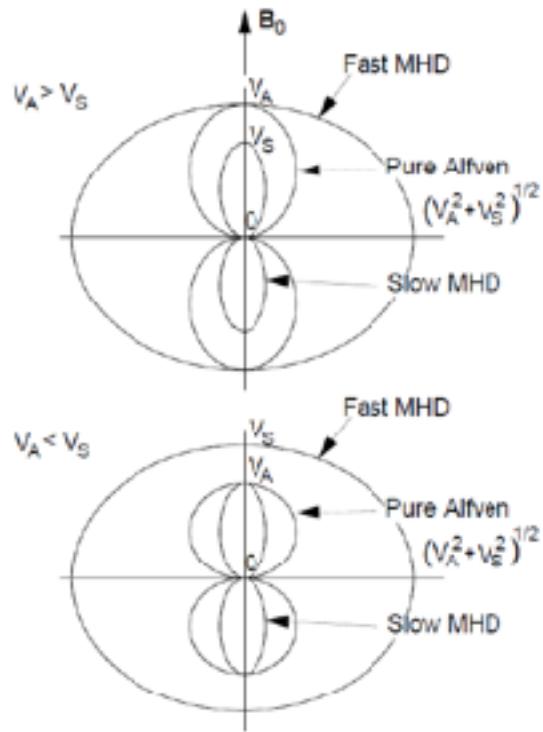
slow
magnetosonic
wave



Afven wave



density enhancement



Continuity Equation

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{V}) = 0$$

Momentum Equation

$$\rho \left(\frac{\partial}{\partial t} + \mathbf{V} \cdot \nabla \right) \mathbf{V} = \frac{\mathbf{J} \times \mathbf{B}}{c} - \nabla p$$

Ampere's law

$$\mathbf{J} = \frac{c}{4\pi} \nabla \times \mathbf{B}$$

Faraday's law

$$\frac{\partial \mathbf{B}}{\partial t} = -c \nabla \times \mathbf{E}$$

Ideal Ohm's law

$$\mathbf{E} + \frac{\mathbf{V} \times \mathbf{B}}{c} = 0$$

Divergence constraint

$$\nabla \cdot \mathbf{B} = 0$$

Adiabatic Energy Equation

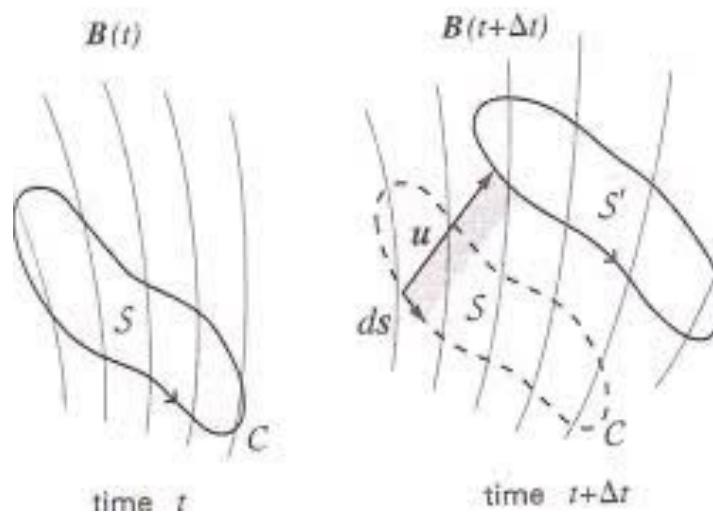
$$\frac{d}{dt} \left(\frac{p}{\rho^\gamma} \right) = 0$$

ideal MHD: flux freezing!

$$\Psi = \int_S \mathbf{B} \cdot d\mathbf{S}.$$

$$\frac{d\Psi}{dt} = - \int_S \nabla \times (\mathbf{E} + \mathbf{V} \times \mathbf{B}) \cdot d\mathbf{S}.$$

$$= 0$$

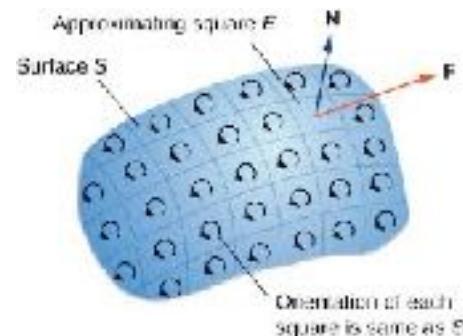


by the help of Stoke thm:

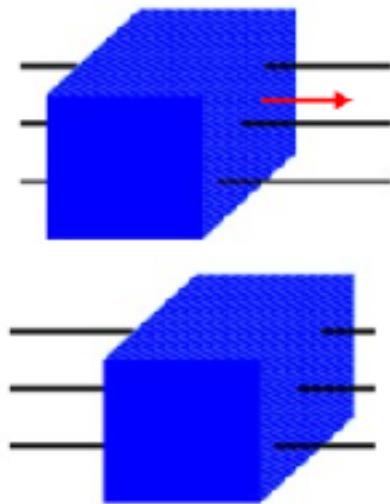
$$\iint_S (\nabla \times \mathbf{F}) \cdot \hat{n} d\Sigma$$

$$= \int_C \mathbf{F} \cdot d\mathbf{r}$$

(apply $\mathbf{F} = \mathbf{v} \times \mathbf{B}$)

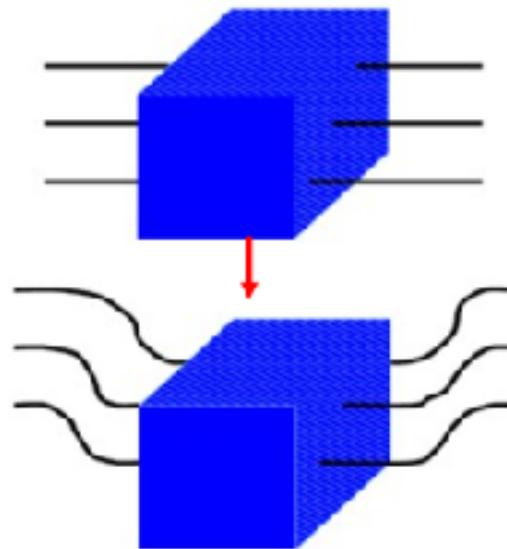


Strong field: matter can only move along given field lines
(beads on a string):



$$\frac{|B|^2}{8\pi} \gg P_{\text{gas}} + \rho|\mathbf{v}|^2$$

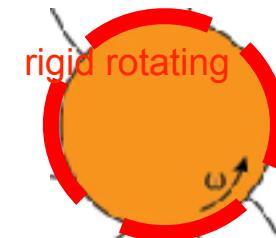
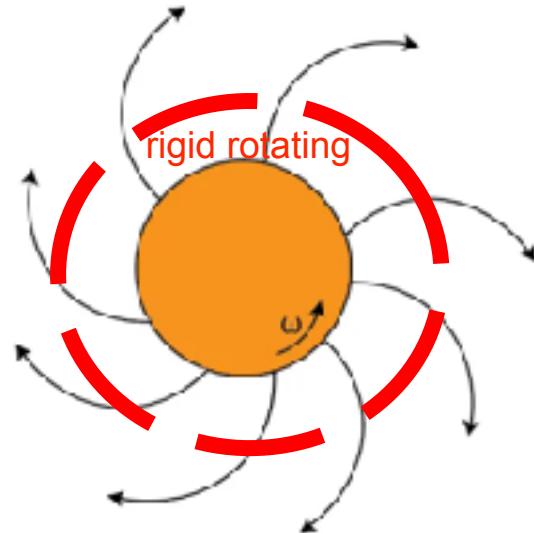
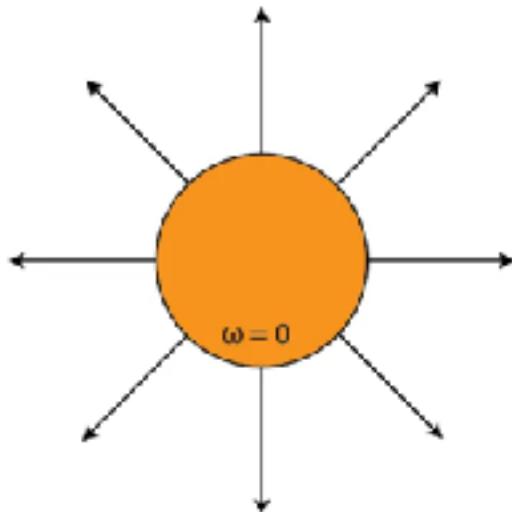
Weak field: field lines are forced to move along with the gas:

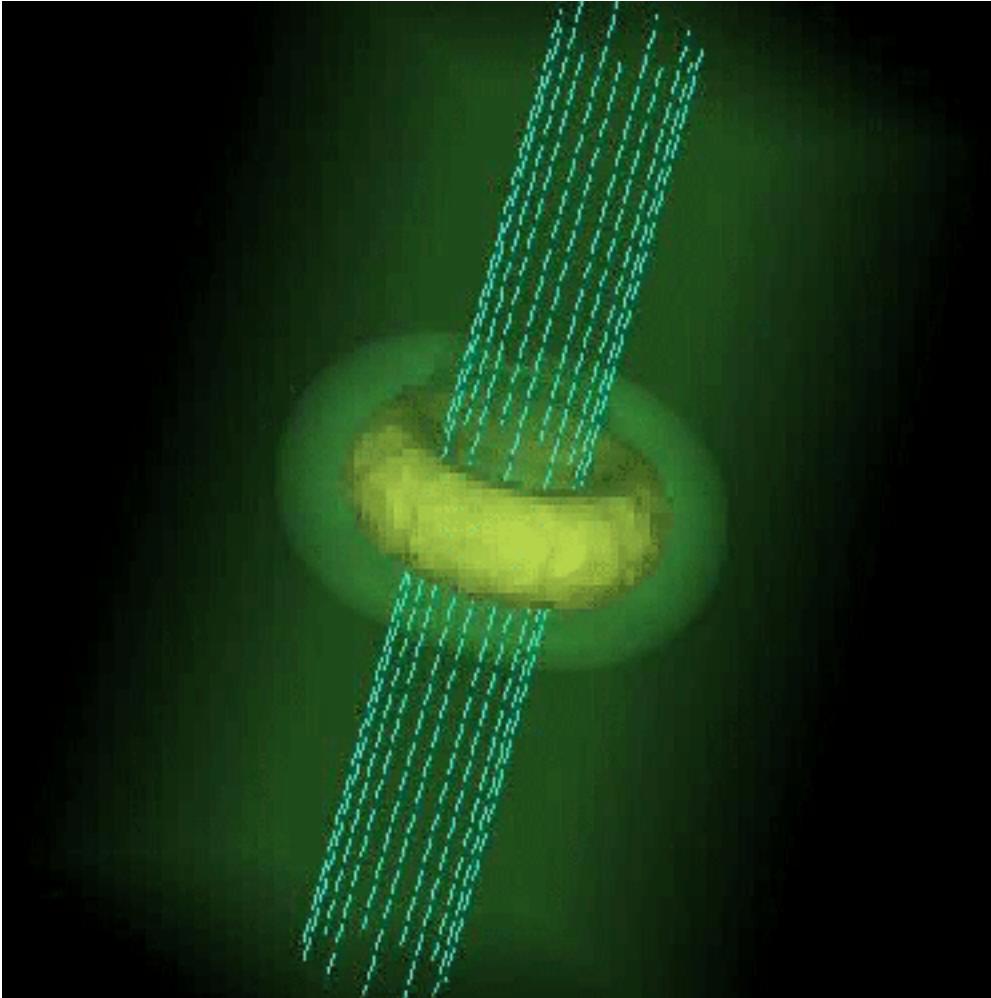


$$\frac{|B|^2}{8\pi} \ll P_{\text{gas}} + \rho|\mathbf{v}|^2$$

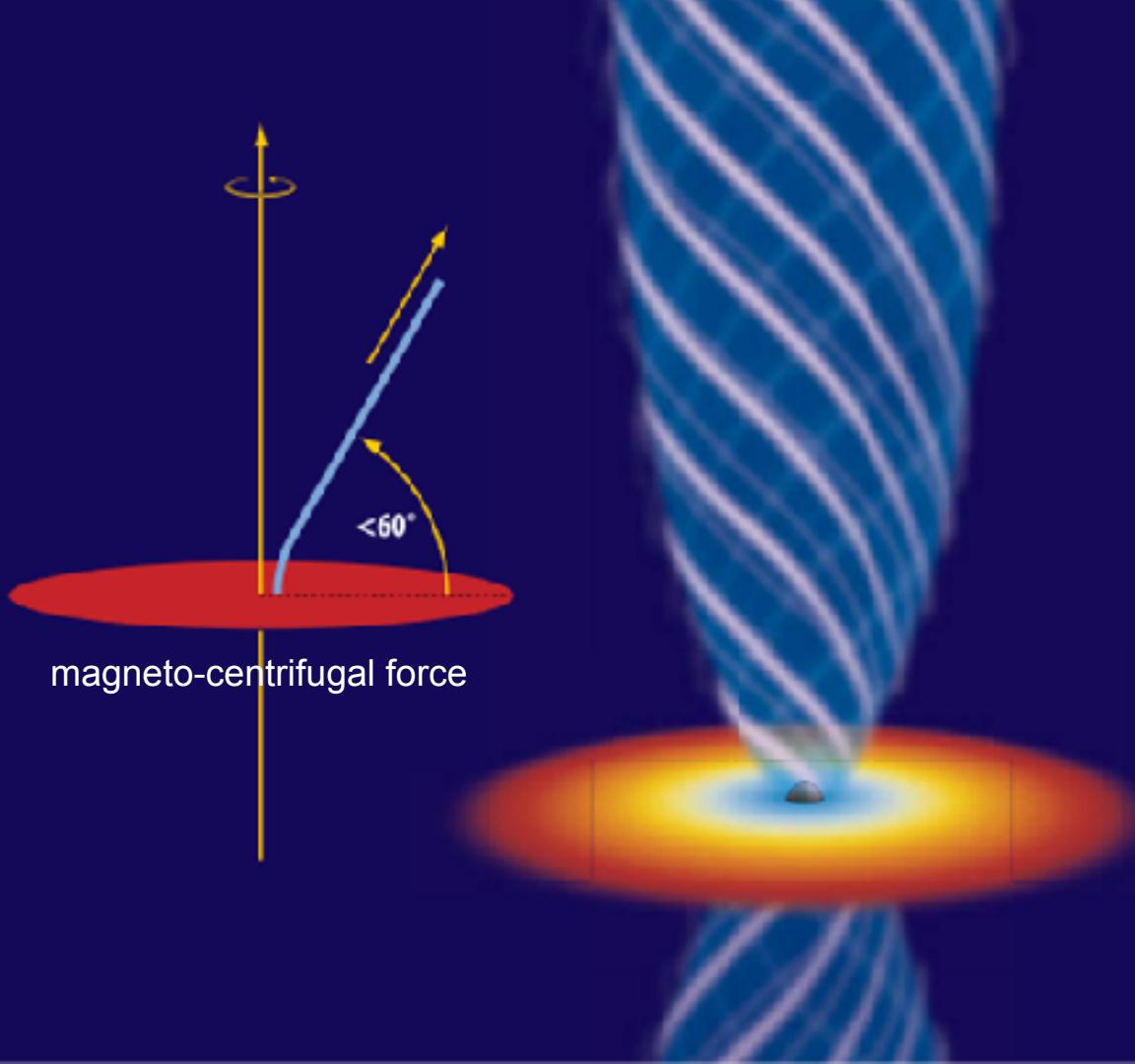
magnetized wind

the plasma rotates approximately like a solid body out to a radius, at where the magnetic energy equals the kinetic energy



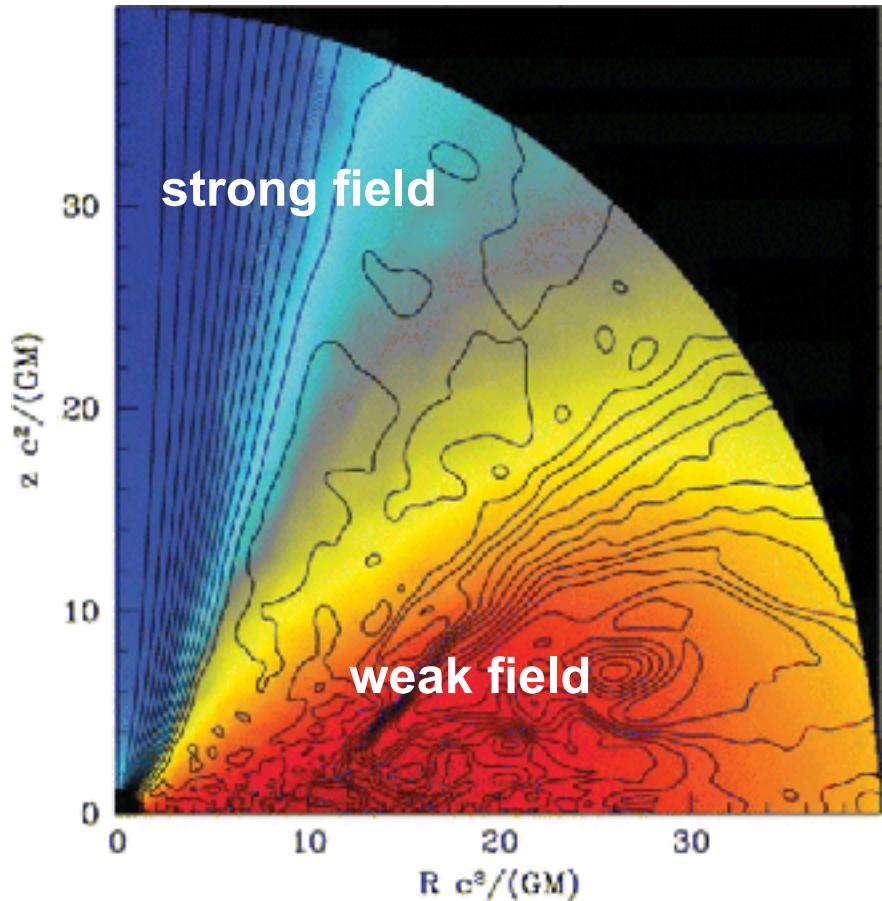


credit: Kuwabara

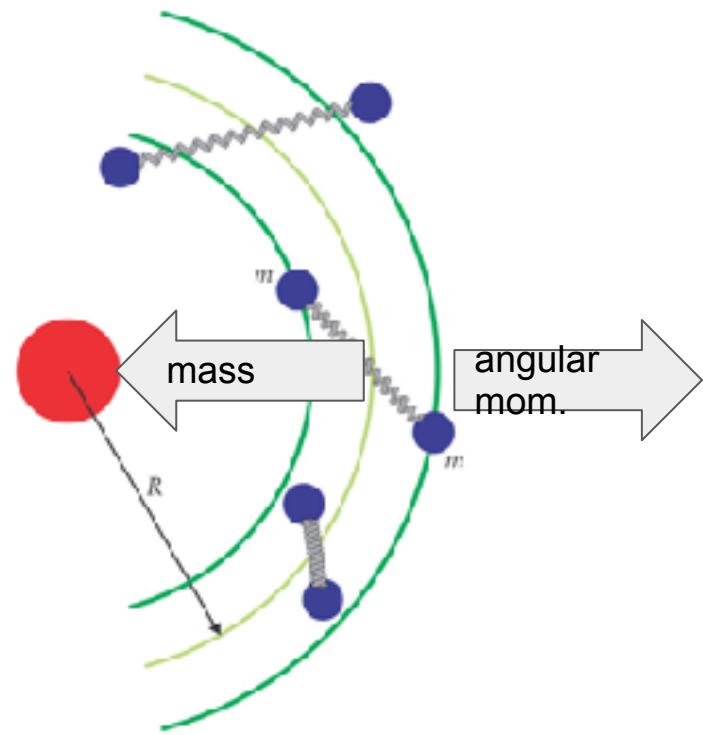


magneto-centrifugal force

<60°



magnetorotational instability

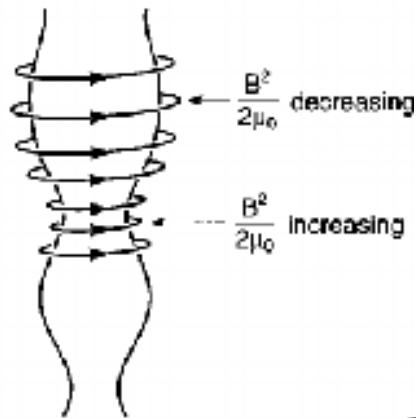


credit: McKinney & Narayan

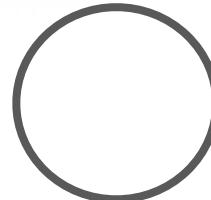
Sausage and Kink instability

$m = 0$ (sausage)

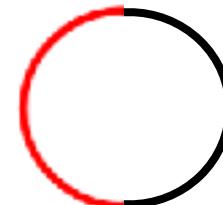
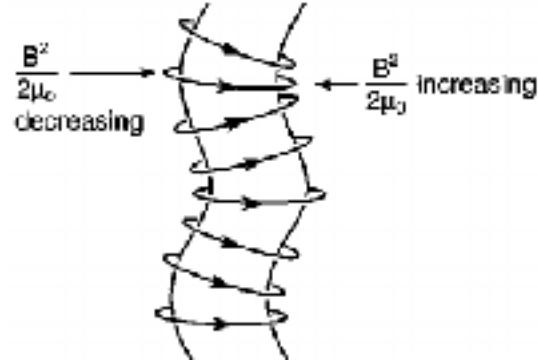
Perturbation $\propto e^{(im\theta + i\omega t + \alpha)}$



m : axial wave number



$m = 1$ (kink)

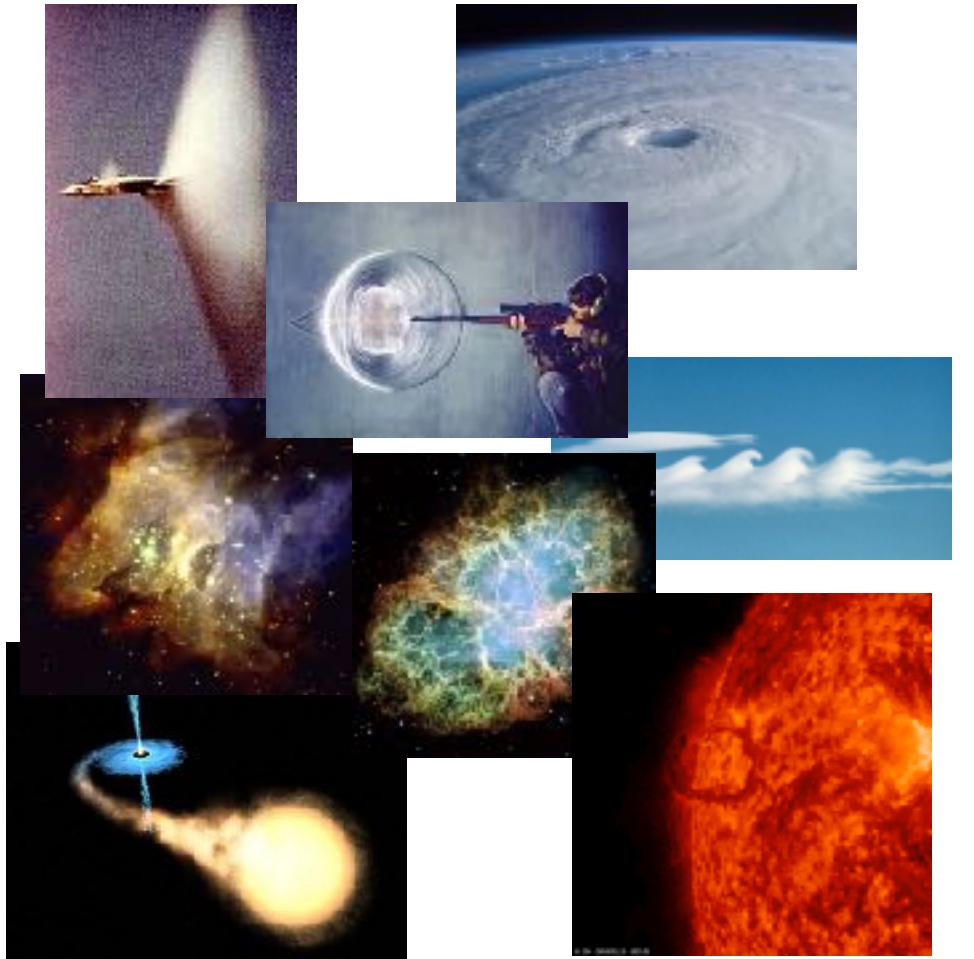


Final remarks

- astrophysical fluid
 - large scale
 - gravity is important
 - radiation cooling
 - MHD, most of the time: ideal MHD
 - multi-phase
- fluid mechanics as a physical problem:
 - governing equations + e.o.s + boundary conditions

summary

- hydrodynamics (HD)
 - shear and viscosity
 - velocity field
 - governing equations
 - continuity
 - momentum
 - energy
 - turbulence and energy cascade
 - shock
- magnetohydrodynamics (MHD)
 - plasma
 - ideal MHD
 - astrophysical applications





“when I meet God, I am going to ask him two questions: Why relativity? and why turbulence?
I really believe he will have an answer for the first.”

W. Heisenberg (1907-1976)